

# Seneca



## CVI620/ DPS920 Introduction to Computer Vision

### Performance Evaluation

Seneca College

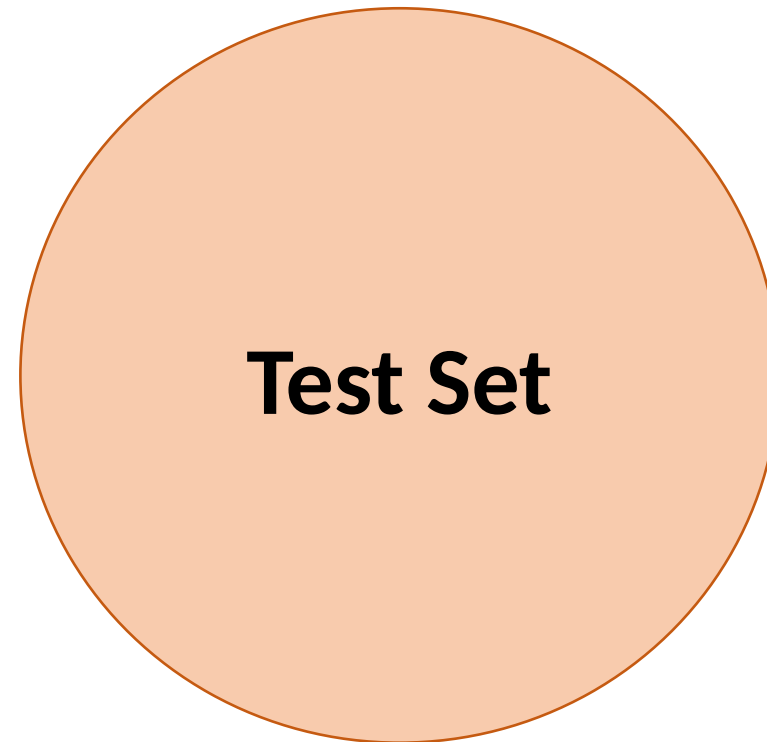
Vida Movahedi

# Overview

- Dataset Splits
- Overfitting vs Underfitting
- Performance Evaluation
  - Classification
  - Regression
  - ROI-based

# Training / Test Sets

- Learning from training data
- Choose methods and models
- Set parameters
- Testing the trained method(s)
- Compare with competition
- Unknown until evaluation

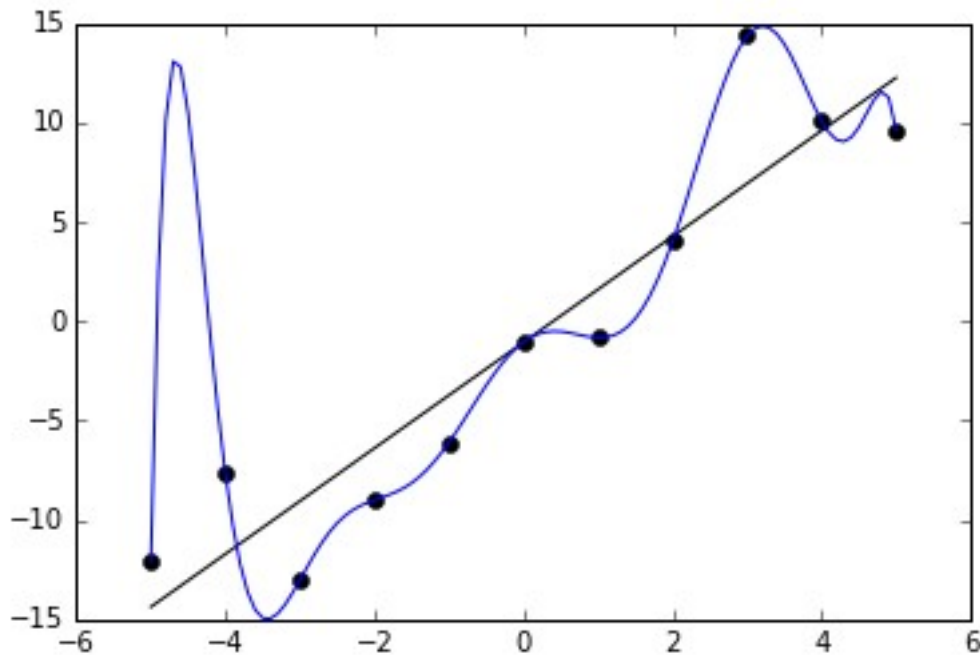


# Low Performance

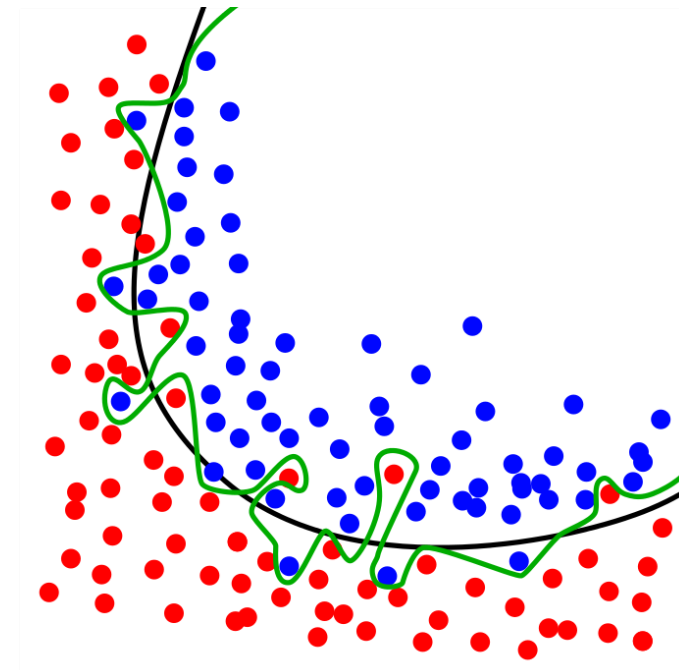
- Measuring Performance
- Error
- Possible reasons for low performance?
  - Not enough data, or useful data (not separable when classifying?)
  - Not a suitable learning algorithm
  - Not enough computing to run the algorithm longer (need for more iterations)
  - **Overfitting / Underfitting**

# Overfitting

- Corresponding too closely or exactly to the training data
- Not generalizing ☾ Poor performance when seeing new data / test data



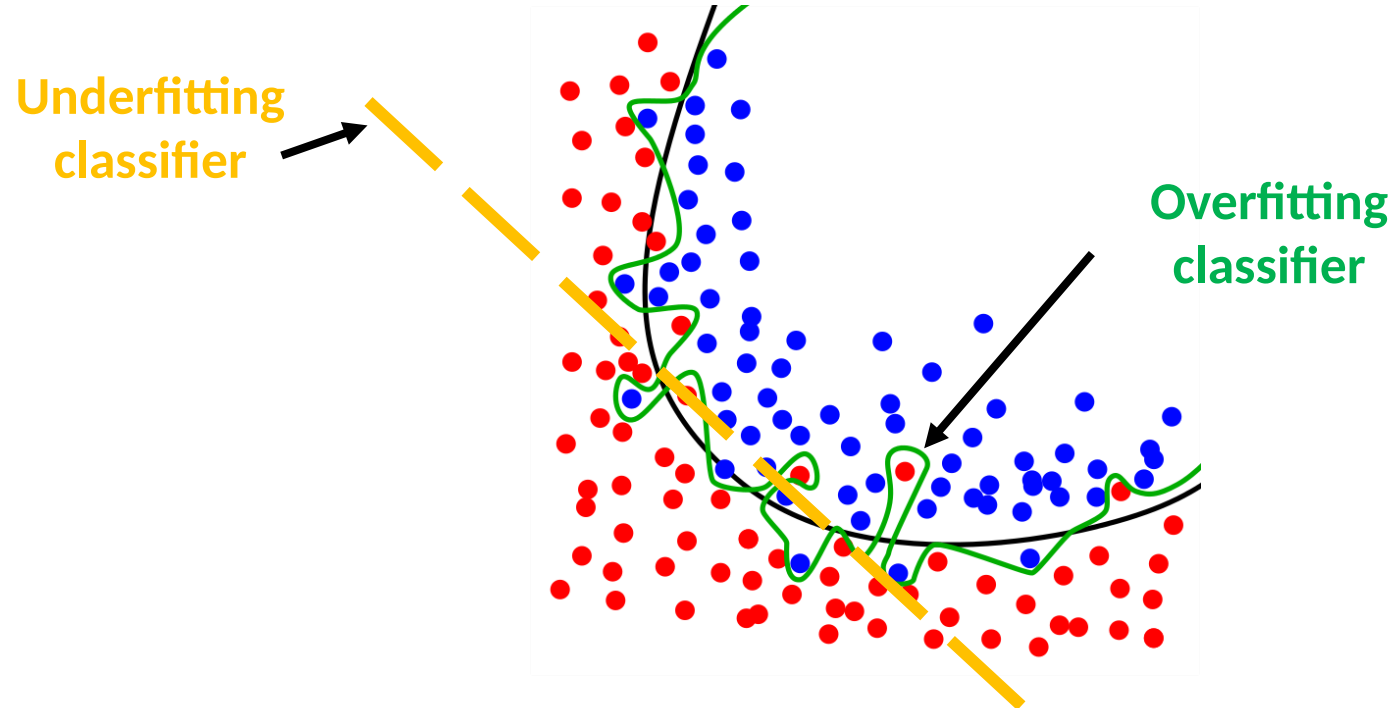
[Wikipedia] Overfitting in regression



[Wikipedia] Overfitting in classification

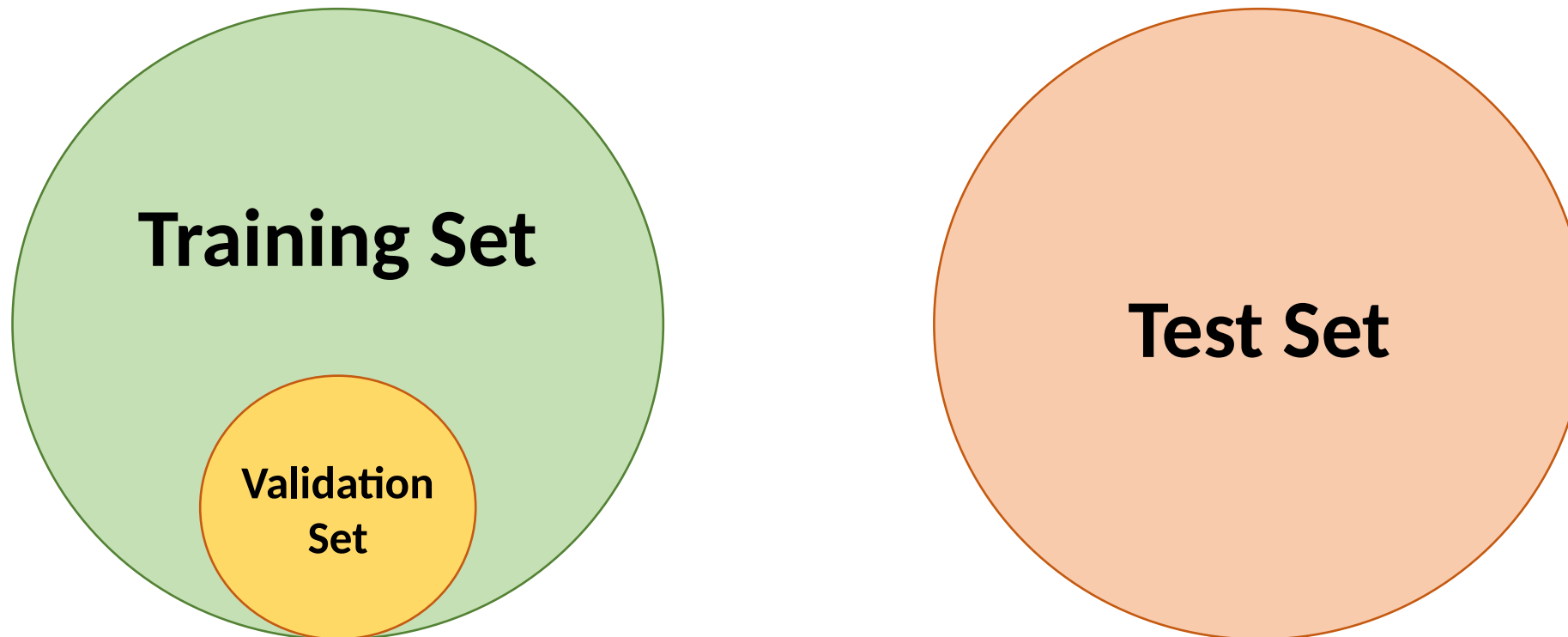
# Underfitting

- The learned model, being too simple/ too general
- Not learning the details



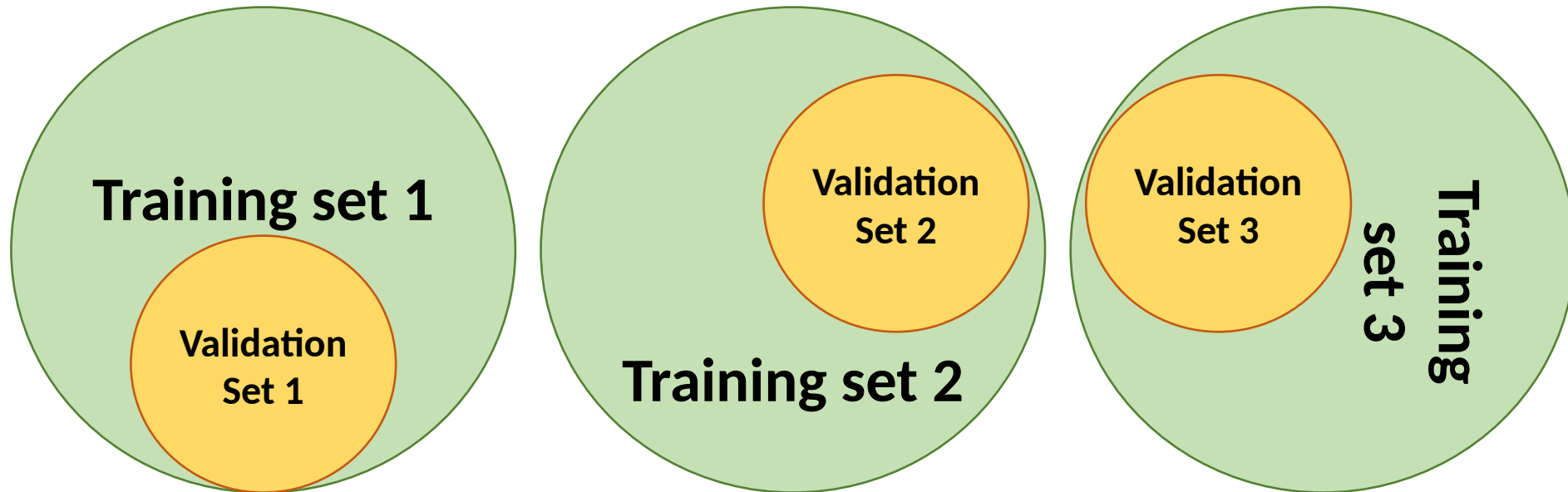
# Validation Set

- A subset of training set
- Avoid overfitting by choosing methods / models / parameters that perform best on validation set



# Cross Validation

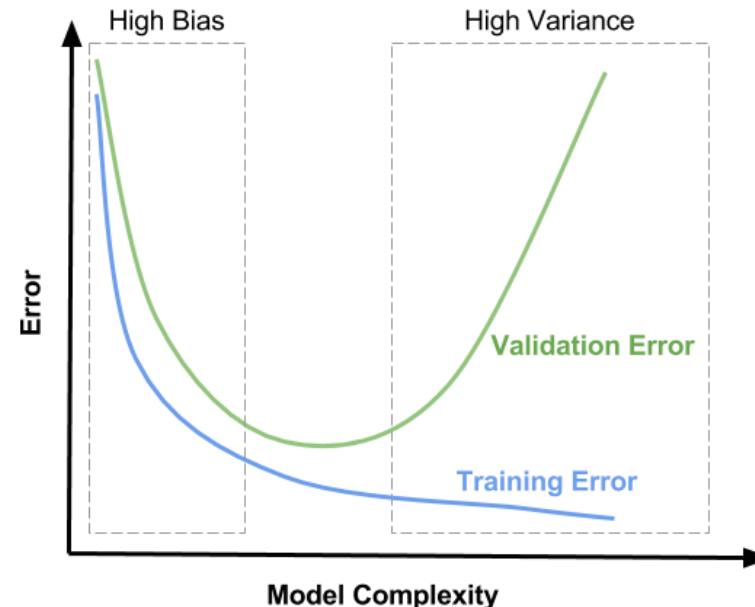
- Choose different **subsets** of training set as validation sets, and train on remaining data
- Avoid overfitting by choosing methods / models / parameters that on average perform best on various validation sets





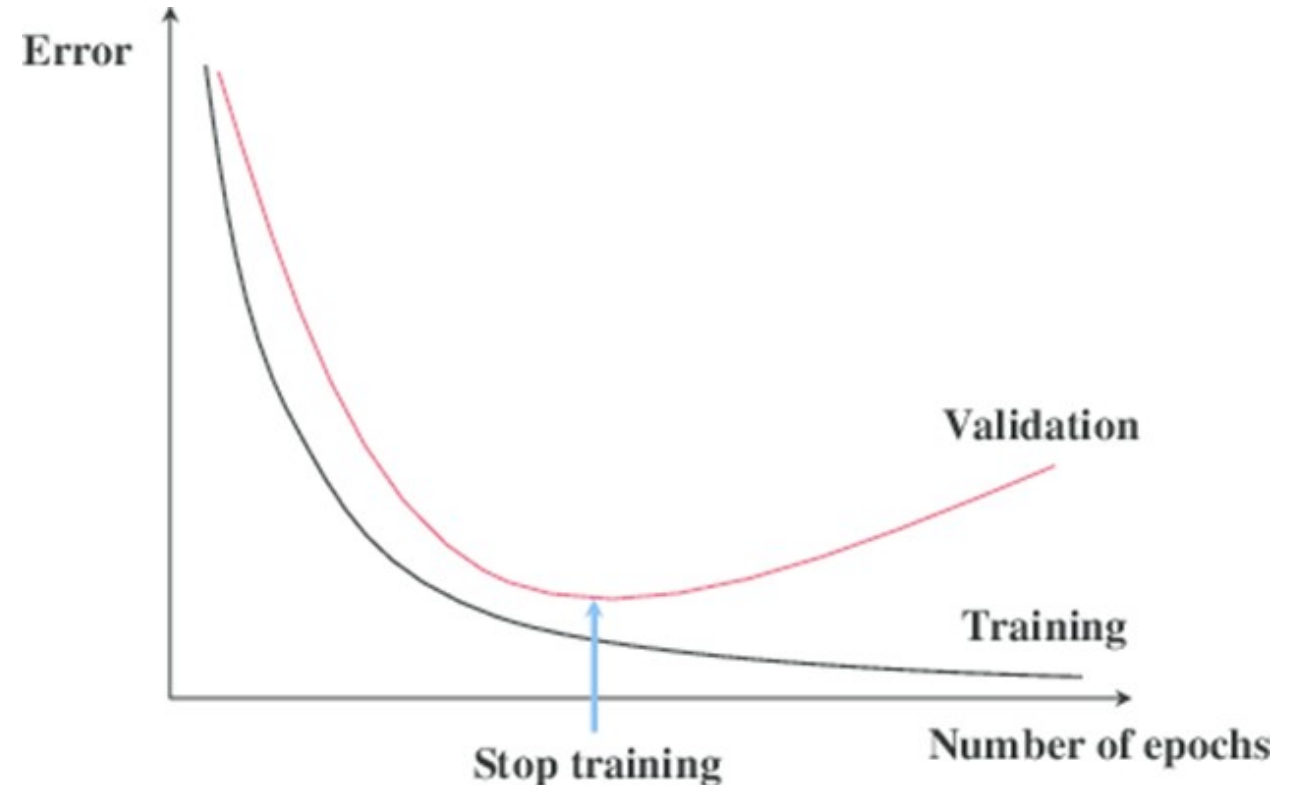
# Validation Set

- Optimize parameters based on data not used in training
- Validation set
  - A randomly selected subset of the training set
  - To avoid under or overfitting when optimizing classifiers or regressors
- Cross validation
  - Leave-1-out
  - Leave-p-out
  - **Repeat and take average**



# Validation Sets for Neural Network Training

- Neural networks must be trained over many iterations (epochs). To ensure an optimum number of epochs, the performance error is measured on the training and validation sets.



[Ref: <http://fouryears.eu/tags/theory/>]

# Ground Truth [3]

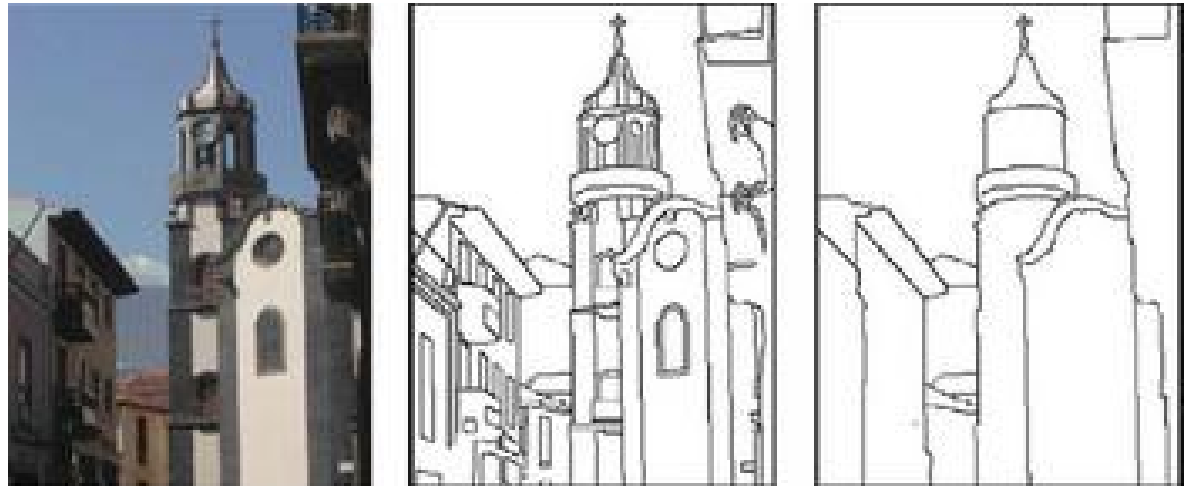
- In simple words, ground truth is the perfect answer
- Sometimes not possible to calculate/ measure
- Often annotated/ provided / labelled by multiple human subjects (e.g. Amazon Mechanical Turk)
- The more human subjects, the less it will be considered as 'subjective'

Example:

Berkeley segmentation and boundary detection dataset

30 human subjects

<https://www2.eecs.berkeley.edu/Research/Projects/CS/vision/bsds/>



# Performance Evaluation

# How well is the algorithm working?

- After implementing an algorithm, we want to know
  - How well it is working?
  - How does it compare with other algorithms
- **Qualitative** Performance Evaluation
  - Show the performance of the algorithm (by examples)
  - Show cases where it works well (or better than competition)
  - Show cases where it fails
- **Quantitative** Performance Evaluation
  - Not subjective, based on a test set and an evaluation measure
  - Fair to all methods being compared

# Assessing Classification Models

# Example: (House) Cat-Finder!

Is there a cat in the image?



Correct Answer (ground truth):

Yes

No

Yes

No

Algorithm's output:

Yes

No

Yes

No

TP

FN

FP

TN

# Metrics for Recognition/Classification

- TP (True Positives):
  - Number of samples identified correctly as belonging to a class / category
- FP (False Positive): (False Alarms)
  - Number of samples identified incorrectly as belonging to a class / category
- TN (True Negative):
  - Number of samples identified correctly as NOT belonging to a class / category
- FN (False Negatives): (False Dismissal)
  - Number of samples identified incorrectly as NOT belonging to a class / category
- **Total number of samples = TP + FP + TN + FN**



# Binary Classification Accuracy Metrics

Percent Correct Classification (PCC)

$$PCC = (t_n + t_p) / (t_p + t_n + f_p + f_n)$$

Confusion Matrix		Predicted Class		
		0 (predicted value is negative)	1 (predicted value is positive)	Total Actual (down)
Actual Class	0 (actual value is negative)	$t_n$ (true negative)	$f_p$ (false positive, false alarm)	Total actual negatives $tn + fp$
	1 (actual value is positive)	$f_n$ (false negative, false dismissal)	$t_p$ (true positive)	Total actual positives $tp + fn$
Total Predicted (across)		Total negative predictions $tn + fn$	Total positive predictions $tp + fp$	Total Examples $tp + tn + fp + fn$

For a highly- performing model, which cells should contain larger values?

# Precision / Recall

- Recall: Percentage of objects successfully identified

$$Recall = \frac{TP}{TP + FN}$$

- Precision: Percentage of identified objects which are actually correct (not false alarms)

$$Precision = \frac{TP}{TP + FP}$$

- F- measure:

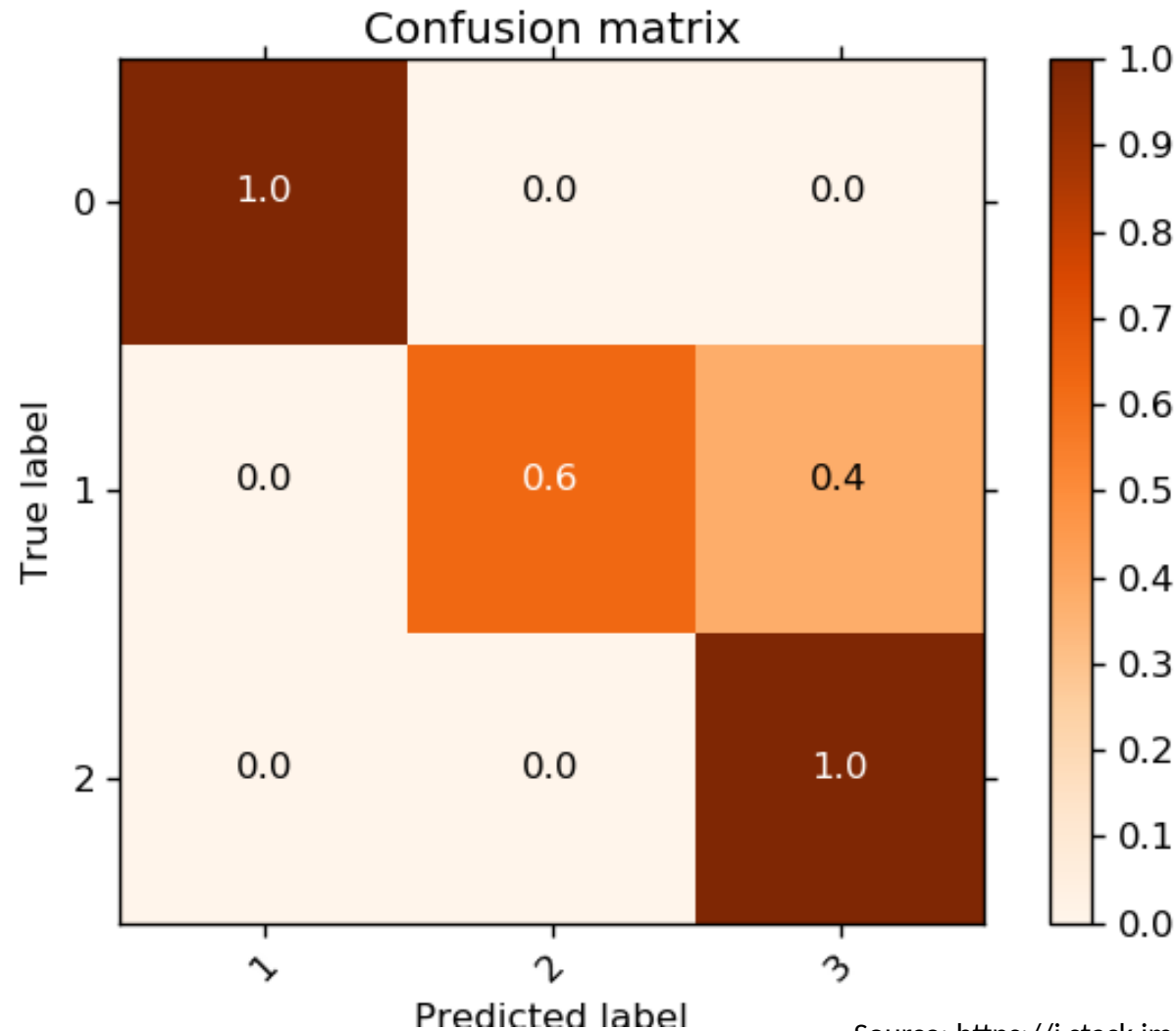
$$F_{\beta} = (1 + \beta^2) \cdot \frac{Precision \cdot Recall}{(\beta^2 \cdot Precision) + Recall}$$

$F_1$  ( $\beta=1$ ) is the most commonly used

		Predicted Class		
		Positive	Negative	
Actual Class	Positive	True Positive (TP)	False Negative (FN) <b>Type II Error</b>	<b>Sensitivity</b> $\frac{TP}{(TP + FN)}$
	Negative	False Positive (FP) <b>Type I Error</b>	True Negative (TN)	<b>Specificity</b> $\frac{TN}{(TN + FP)}$
		<b>Precision</b> $\frac{TP}{(TP + FP)}$	<b>Negative Predictive Value</b> $\frac{TN}{(TN + FN)}$	<b>Accuracy</b> $\frac{TP + TN}{(TP + TN + FP + FN)}$

<https://stats.stackexchange.com/questions/122225/what-is-the-best-way-to-remember-the-difference-between-sensitivity-specificity>

# Confusion Matrix for Multi-Class Classification



# Assessing Regression Models

# Residuals, Errors

Actual Target Value ( )	Predicted Target Value ( )	Residual or Error ( )
5.2	5.8	-0.6
6.5	6.2	0.3
8.2	8	0.2
10.5	10.2	0.3
4.8	5.8	-1
2.7	8	-5.3
3.4	6.5	-3.1
5.8	6	-0.2
9.7	8.2	1.5
6.3	6.1	0.2

# Mean Squared Error (MSE)

- Low MSE ☾ good prediction
- High MSE ☾ bad prediction

# R-Squared Measure

- 1 minus the ratio of the **variance of the residuals** and the **variance of the target variable** (total variance explained by model / total variance)
- The proportion of the variance in the dependent variable that is predictable (explained) from the independent variable(s).

It varies from 0% to 100%

- High  $R^2$  indicates a clear trend ☾ good prediction
- Low  $R^2$  (close to zero) indicates randomness ☾ bad prediction

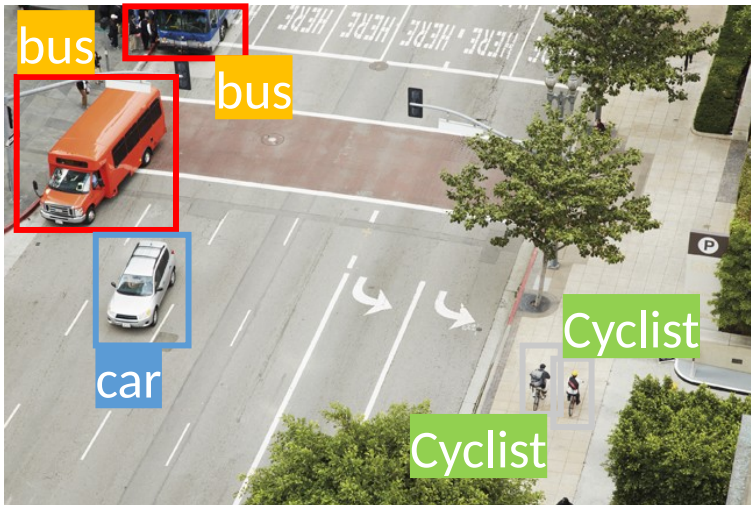


# Assessing ROI-Based Methods

# Region of Interest (ROI)

- A region in the image, often specified by a rectangle

Object Detection



Face Detection & Recognition



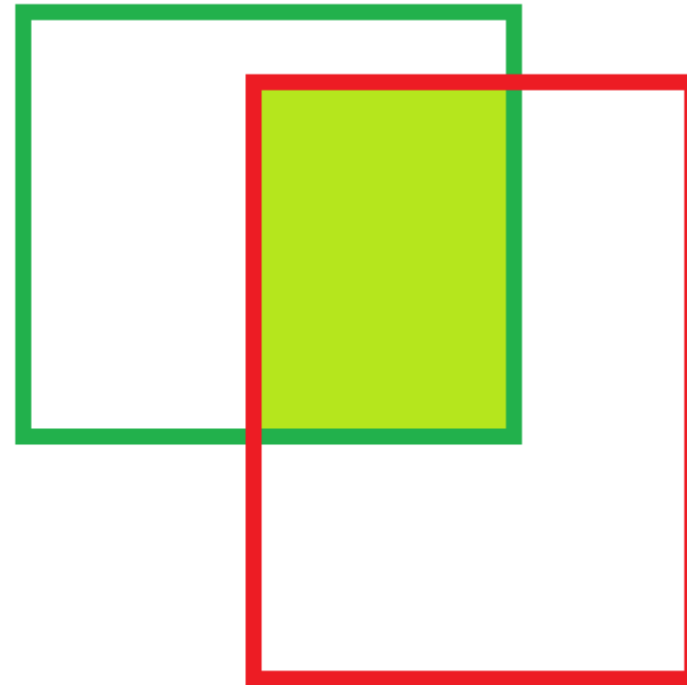
Optical Character Recognition



# Intersection-over-Union (IoU)

- G: Ground Truth Region
- A: Predicted Region by Algorithm

Ground Truth



Predicted (A)

# From IoU to Precision & Recall

- By choosing a threshold, IoU can be translated to a hit (True Positive) or miss (False Positive)
- <https://www.jeremyjordan.me/evaluating-image-segmentation-models/>



# Precision / Recall

- Recall: Percentage of objects successfully identified

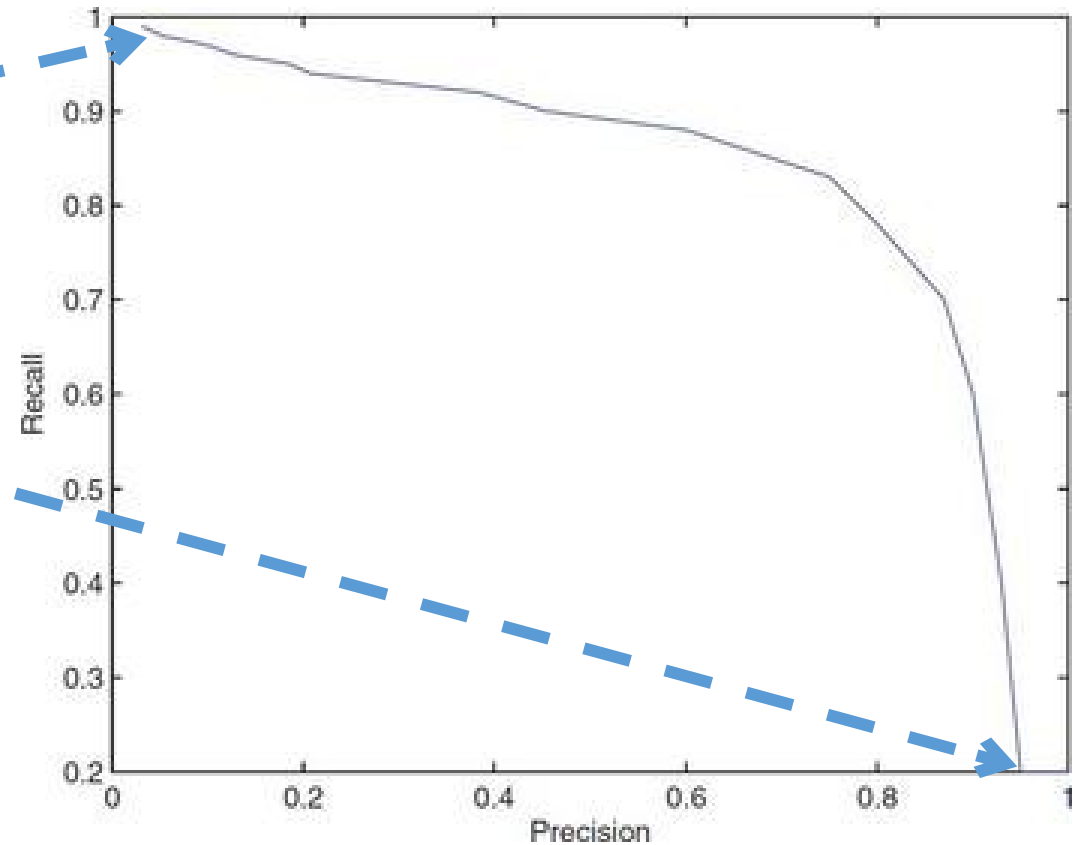
$$Recall = \frac{TP}{TP + FN}$$

- Precision: Percentage of identified objects which are actually correct (not false alarms)

$$Precision = \frac{TP}{TP + FP}$$

# Precision-Recall (PR) Curves

- Low threshold (close to 0) – high recall, low precision
- High threshold (close to 1) – low recall, high precision
- A common performance measure: Area under the PR curve (or ROC curve)



# Summary

- In order to obtain models that perform well on future samples, datasets are often split into training, test and validation sets. Only the training dataset is used for training models.
- In addition to evaluating the performance of an algorithm **qualitatively** and **subjectively** (by looking at sample output), it is better to use **quantitative** and **objective** performance measures.
- There are general performance measures for classification and regression. Vision-based measures (e.g. ROI-based IoU) are also used.

# References

- [1] Computer Vision: Algorithms and Applications, R. Szeliski (<http://szeliski.org/Book>)
- [2] Learning OpenCV 3, A. Kaehler & G. Bradski
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  - [https://senecacollege-primo.hosted.exlibrisgroup.com/primo-explore/fulldisplay?docid=01SENC\\_ALMA5153244920003226&context=L&vid=01SENC&search\\_scope=default\\_scope&tab=default\\_tab&lang=en\\_US](https://senecacollege-primo.hosted.exlibrisgroup.com/primo-explore/fulldisplay?docid=01SENC_ALMA5153244920003226&context=L&vid=01SENC&search_scope=default_scope&tab=default_tab&lang=en_US)
- [3] Practical introduction to Computer Vision with OpenCV, Kenneth Dawson-Howe
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