

## User mode & Kernel mode

→ They are two distinct worlds within an OS.

→ Kernel mode has direct hardware access while user mode interacts with users

→ When CPU is in user mode it only does user mode work and when it is in kernel mode it only does kernel mode work.

→ CPU switch between user mode and kernel mode by software interrupt.

→ As user mode and kernel mode are also kept separate.

eg:- when in CLI we write command mkdir

↓  
it will decode mkdir and will understand that a new folder or directory needs to be created

↓  
Switches to kernel mode and goes to file management department and will make a directory.

↓  
Then returns feedback that directory is created.

## Definitions

**User mode:** A restricted CPU mode where user applications run with limited access to system resources and cannot directly interact with hardware.

**Kernel mode:** A privileged CPU mode where the OS runs with full access to hardware and system resources.

**Interrupt:** An interrupt is a signal sent to the CPU that temporarily halts the current process to attend to an urgent task after which normal execution resumes.

## Interrupt

### Hardware interrupt

→ Generated by hardware devices to signal the CPU.

### Software interrupt

→ Generated by a program using a special instruction  
→ Used to request services from the OS.



Extra

## Interrupt processing

→ The basic method of interrupting the CPU is done by activating a control lines that connects the interrupt source to the CPU.

- CPU ⇒
- recognizes the presence of interrupt
  - execute a specific interrupt handling program
  - determines the source of interrupt
  - determines the address of the interrupt handling program

## Interrupt Service Routine (ISR)

→ It is a software routine that is executed in response to an interrupt.

→ It is designed to handle the interrupt and restore the system to its normal state.

→ Functions :

- Handling the interrupt
- Restore to normal state after handling.
- Perform necessary actions to ensure system stability/performance.

## → Types

- Hardware ISR for Hardware interrupts
- Software ISR for Software interrupts

→ Benefits :

- ① System stability
- ② System performance.

Extra

### Interrupt vector table

→ It is a data structure used in computer systems to manage interrupts.

→ It is a table that contains memory address of ISR

[Interrupt occurs]

↓  
[Processor saves state]

↓  
[Processor fetch interrupts]

↓  
[Processor jumps to ISR]

↓  
[ISR handles interrupt]

↓  
[Processor resume execution]

### Interview Question

① User mode & Kernel mode communication??

→ There is a method provided by OS itself (in process

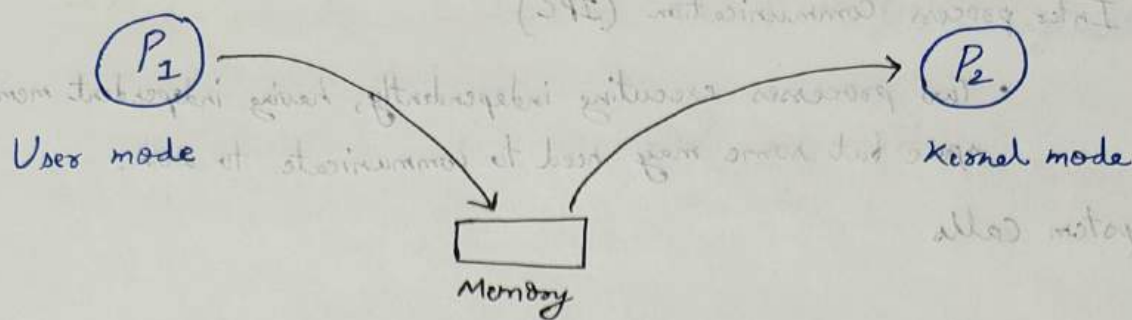
management) which is called interprocess communication (IPC)

or done

through

→ A mechanism that allows processes to communicate. It helps processes synchronize their activities, share information and avoid conflicts while accessing shared resources.





Shared memory

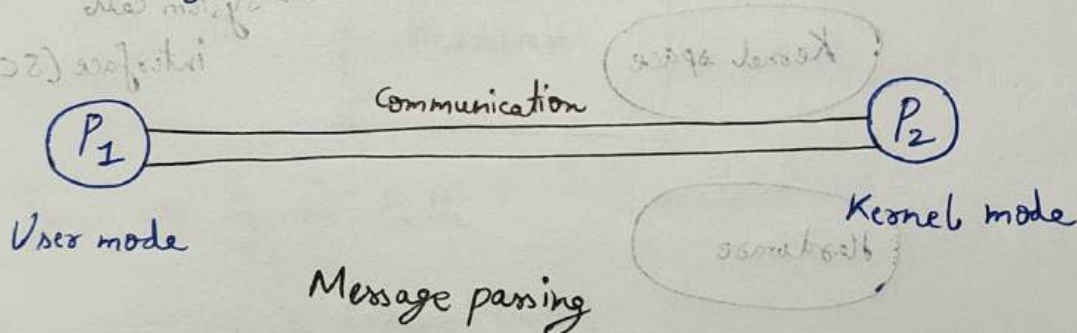
→  $P_1$  process is executing in user mode and  $P_2$  process is executing in kernel mode.

→ So they can communicate by shared memory.

→ If  $P_1$  wants to communicate to  $P_2$  it writes on a shared memory (shared by  $P_1$  &  $P_2$ ).

→  $P_2$  then reads from that memory the message given by  $P_1$ .

→ Thus they communicate via shared memory.



→ In this OS provides methods, functions or calls to communicate between  $P_1$  &  $P_2$ .

→ A logical pipe is established between processes as a channel for them to communicate.

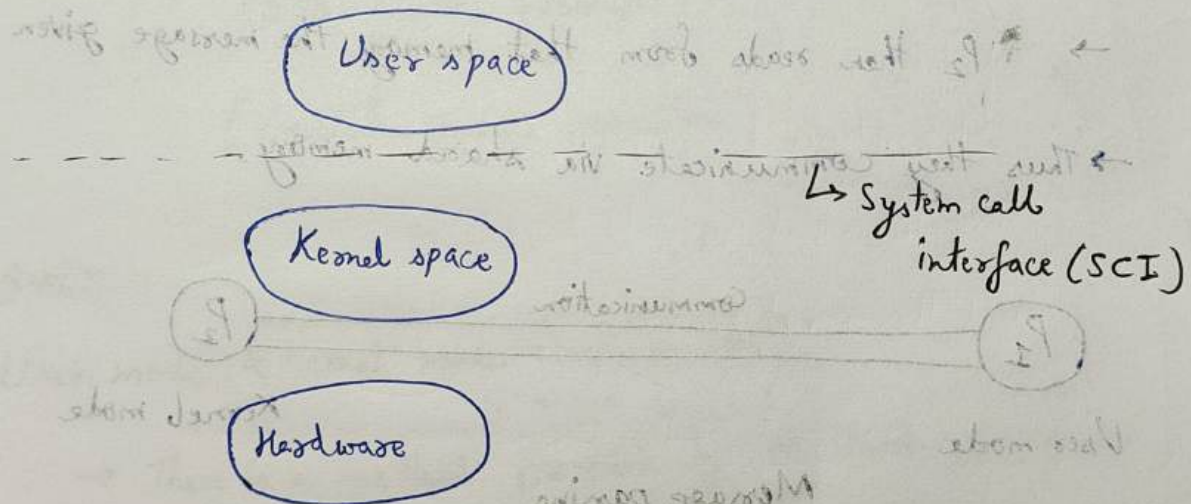
→ System calls are used and there are some protocol or calls or policies through which they communicate.

## Inter process Communication (IPC)

- Two processes executing independently, having independent memory space but some may need to communicate to work.

## System calls

- Using system calls apps interact with kernel.
- A system call is a mechanism using which a user program can request a service from the kernel for which it does not have the permission to perform.
- System calls are the only way through which a process can go into kernel mode from user mode.
- System calls are implemented in C.



eg:- for command `mkdir` movies.

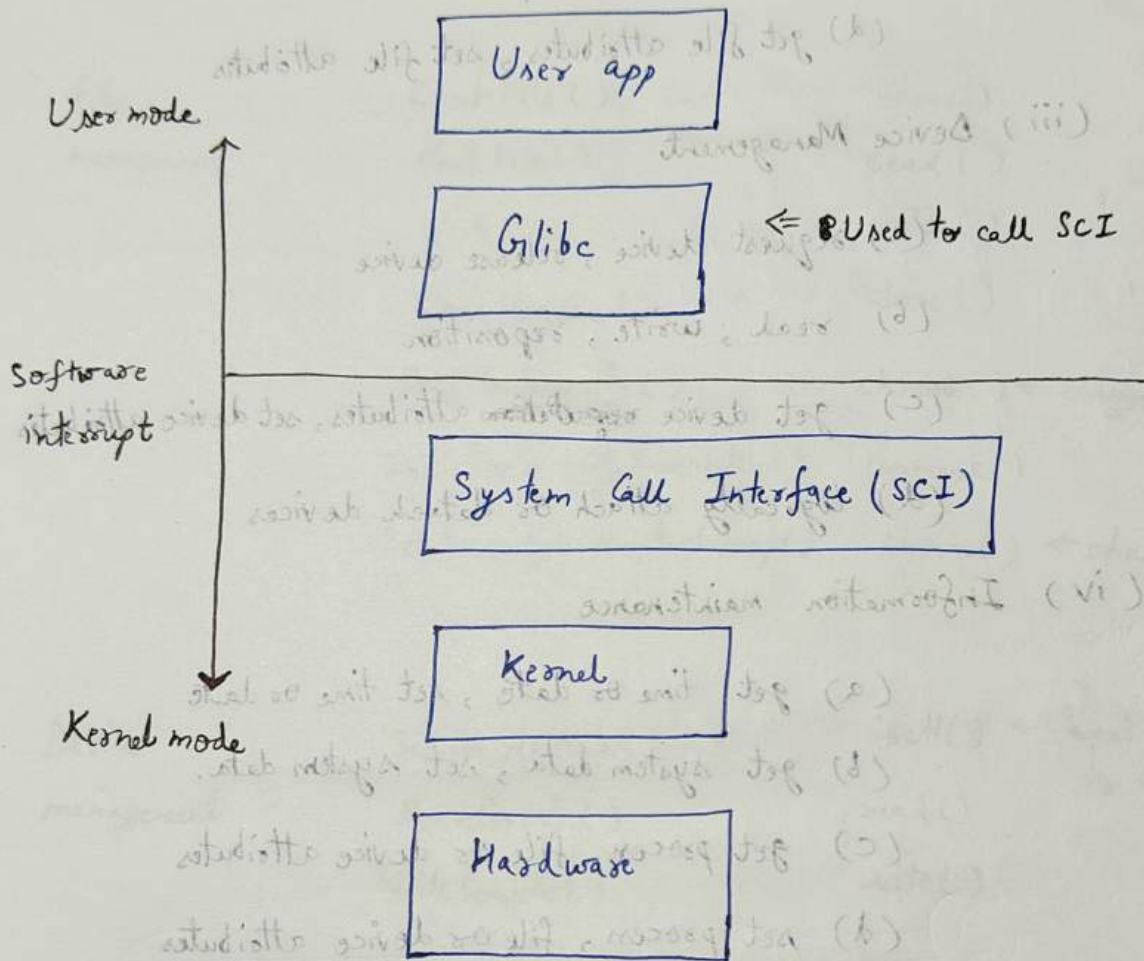
This command goes to SCI to take it to that space in kernel where implementation of `mkdir` is written.

SCI will tell to look for this implementation in kernel space and then kernel ~~space~~ will run this implementation <sup>space</sup>

then a directory is created.



- Mkdir indirectly calls kernel and asked the file management module to create a new directory.
- Mkdir is just a wrapper of actual system calls.
- Mkdir interacts with kernel using system calls.



## Types of System calls

### (i) Process Control

(a) end, abort

(b) load, execute

(c) create process, terminate process

(d) get process attributes, set process attributes

(e) Wait for time

(f) wait event, signal event

(g) allocate and free memory.

## (ii) File Management

(a) create file, delete file

(b) open, close

(c) read, write, reposition

(d) get file attributes, set file attributes

## (iii) Device Management

(a) request device, release device

(b) read, write, reposition

(c) get device ~~request~~ attributes, set device attributes

(d) logically attach or detach devices

## (iv) Information maintenance

(a) get time or date, set time or date

(b) get system data, set system data.

(c) get process, file or device attributes

(d) set process, file or device attributes

## (v) Communication management

(a) create, delete communication connection

(b) send, receive messages.

(c) transfer status information

(d) attach or detach remote devices

Examples



## Category

## Windows

## Unix

### Process control

CreateProcess()

ExitProcess()

WaitForSingleObject()

fork() ← used to create child process

exit()

wait()

### File management

CreateFile()

ReadFile()

WriteFile()

CloseHandle()

open()

read()

write()

close()

SetFileSecurity()

InitializeSecurityDescriptors()

SetSecurityDescriptorGroup()

chmod() ← change mode of file

chmod()

chown() ← change ownership of file

### Device management

SetConsoleMode()

ReadConsole()

WriteConsole()

ioctl() ← input output control. Used to talk to device drivers

read()

write()

### Information management

GetCurrentProcessID()

SetTimer()

Sleep()

getpid()

alarm()

sleep()

### Communication

CreatePipe()

CreateFileMapping()

MapViewOfFile()

pipe() ← used to implement message passing

shmget() ← used to implement shared memory

mmap()

[ User program wants to request a service from the OS ]

[ It uses system call ]

[ This system call triggers a software interrupt or trap ]

[ This interrupt signals CPU to switch from user mode to kernel mode ]

[ The OS handles the request inside kernel mode ]

[ Once done, it returns control back to user mode ]

SCI maps this  
to a system call  
number, eg: - 1  
for write().

{ basically looking  
where the definition  
of system call is }

command used is