### CS6462 Probabilistic and Explainable AI

# Lesson 16 Bayesian Nonparametric Models \*

Dirichlet Process Models for Clustering





#### Clustering:

- grouping similar data into clusters
- data mining technique data analytics for marketing, security, or sciences
- problem we don't know the number of clusters to be discovered
- Dirichlet Process Mixture (DPM) automatically detects the number of clusters

#### *Mixture Modeling in ML:*

 machine learning algorithms used to classify data into different categories based on probability distribution

#### Clustering with Mixture Models:

- traditional mixture modeling approach to clustering requires the number of clusters to be specified in advance of analyzing the data
- Bayesian nonparametric approach estimates the number of needed clusters automatically and allows more clusters to be discovered if needed





#### Bayesian nonparametric generalization of mixture models:

- estimates the number of components in a mixture model
- estimates the parameters of the individual mixture components

#### Finite Mixture Models:

• probability density function

$$P_X(x) = \sum_{k=1}^{\infty} \pi_k p(x|\Theta_k)$$

- X random variable vector
- K the number of components in the mixture model
- $\Theta_k$  set of parameters associated with component k
- $\pi_k$  mixing proportion of the k component: the probability that observation x belongs to the k component of the mixture model

# Clustering with Mixture Models (cont.)

#### Finite Mixture Models:

• probability density function: sum of the conditional probability that the observation x

belongs to the k component considering  $\Theta_k$ 

$$P_X(x) = \int p(x|\Theta) * G(\Theta) * d\Theta$$

$$G(\Theta) = \sum_{k=1}^K \pi_k \delta_{\Theta_k}$$
 Bayesian nonparametric mixtures us mixing distributions consisting of a countably infinite number of atoms.

$$P_X(x) = \sum_{k=1}^{K} \pi_k p(x|\Theta_k)$$

Bayesian nonparametric mixtures use

- $G(\Theta)$  a discrete mixing distribution encapsulating all the parameters  $\Theta$  of the mixture model
- $\delta_{\Theta_k}$  is a dirac delta distribution\* (atom) centered at  $\Theta_k$  (set of parameters associated with component k)

$$\int_{-\infty}^{\infty} \delta(\Theta_k) * d\Theta_k = 1, \delta(\Theta_k) = 0 \text{ if } \Theta_k \neq 0$$

<sup>\*</sup> Dirac Distribution at http://nlab-pages.s3.us-east-2.amazonaws.com/nlab/show/Dirac+distribution





#### **Dynamism of Mixture Models:**

- applied to a finite training set only a finite (but varying) number of components will be used to model the data
- one component k is associated with many data items X (random variables), but a data item x is associated with one component k only
- inference in the model automatically provides the number of components to use and the parameters of the components  $G(\Theta) = \sum_{k=1}^{\infty} \pi_k \delta_{\Theta_k}$

#### Dirichlet Process Mixture:

- Dirichlet Process (DP) is a probability distribution over distributions
- $G(\Theta) \sim DP(\alpha, G_0(\Theta))$  where  $\alpha$  positive scaling parameter,  $G_0$  base distribution
- Bayesian approach requires a **prior** distribution over the mixing distribution  $G(\Theta)$
- Dirichlet process (DP) the most common *prior* distribution to use

# \*

# Dirichlet Process Mixture Models (cont.)

#### Formal definition of DP:

• we observe a sample  $X = \{X_1, X_2, ..., X_n\}$  from a mixture of distributions controlled by the DP considering the parameters  $\Theta$ :

$$G(\Theta) \sim DP(\alpha, G_0(\Theta))$$

- $\Theta = \{\theta_1, \theta_2, ..., \theta_k\}$  finite partition of the parameter space (K clusters)
- $G_0$  is a **prior** distribution over distributions (probability measures)  $G(\Theta)$
- $G(\Theta) = \{G(\theta_1), G(\theta_2), ..., G(\theta_k)\}$  induced random vector of discrete mixing distributions
- $DP(\alpha * G_0(\theta_1), \alpha * G_0(\theta_2), ..., \alpha * G_0(\theta_k))$  Dirichlet process with parameters

$$\{G(\theta_1), G(\theta_2), \dots, G(\theta_k)\} = DP(\alpha * G_0(\theta_1), \alpha * G_0(\theta_2), \dots, \alpha * G_0(\theta_k))$$

#### Chinese Restaurant Process:

• DP induces a distribution over partitions of integers that describes the prior





Bayesian Nonparametric Models – Dirichlet Process Models for Clustering

Clustering

Mixture Modeling in ML

Clustering with Mixture Models

- Bayesian nonparametric generalization of mixture models
- Finite Mixture Models

$$P_X(x) = \int p(x|\Theta) * G(\Theta) * d\Theta$$

Dirichlet Process Mixture  $G(\Theta) \sim DP(\alpha, G_0(\Theta))$ 

#### Next Lesson:

Bayesian Networks - Theoretical Foundations of Bayesian Networks

## Thank You!

Questions?