	Marwadi University	
		Faculty of Technology
		Department of Information and Communication Technology
Subject: Artificial Intelligence (01CT0616)	Aim: To understand the process of convolution over the image and apply over the classification problem	
Experiment No: 4	Date:	Enrolment No: 92200133030

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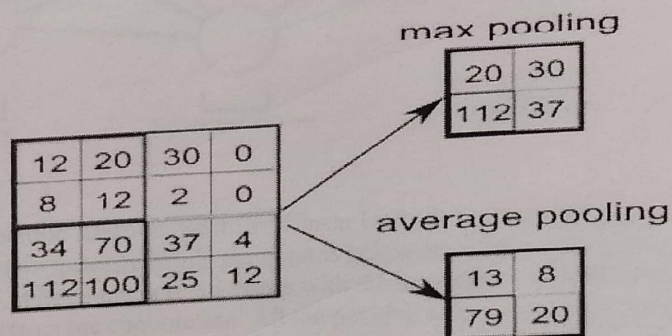
IDE: Google Colab

Theory:

Convolutional Neural Networks (CNN) are complex feed forward neural networks. CNNs are used for image classification and recognition because of its high accuracy. There are three types of layers in a convolutional neural network: i. Convolutional layer ii. Pooling layer iii. Fully connected layer. Each of these layers has different parameters that can be optimized and performs a different task on the input data.


What is Pooling Layer?

Pooling layer is responsible for reducing the spatial size of the Convolved Feature. This is to decrease the computational power required to process the data through dimensionality reduction. There are two types of Pooling i. Average Pooling. ii. Max Pooling. Max Pooling returns the maximum value from the portion of the image covered by the Kernel. On the other hand, Average Pooling returns the average of all the values from the portion of the image covered by the Kernel. Max Pooling also performs as a Noise Suppressant. It discards the noisy activations altogether and also performs de-noising along with dimensionality reduction. On the other hand, Average Pooling simply performs dimensionality reduction as a noise suppressing mechanism. Hence, we can say that Max Pooling performs a lot better than Average Pooling.



What is Convolutional Layer?

Convolutional layers are the major building blocks used in convolutional neural networks. A convolution is the simple application of a filter to an input that results in an activation. Repeated application of the same filter to an input results in a map of activations called a feature map, indicating the locations and strength of a detected feature in an input, such as an image. A convolutional layer contains a set of filters whose parameters need to be learned. The height and weight of the filters are smaller than those of the input volume. Each filter is convolved with the input volume to compute an activation map made of neurons.

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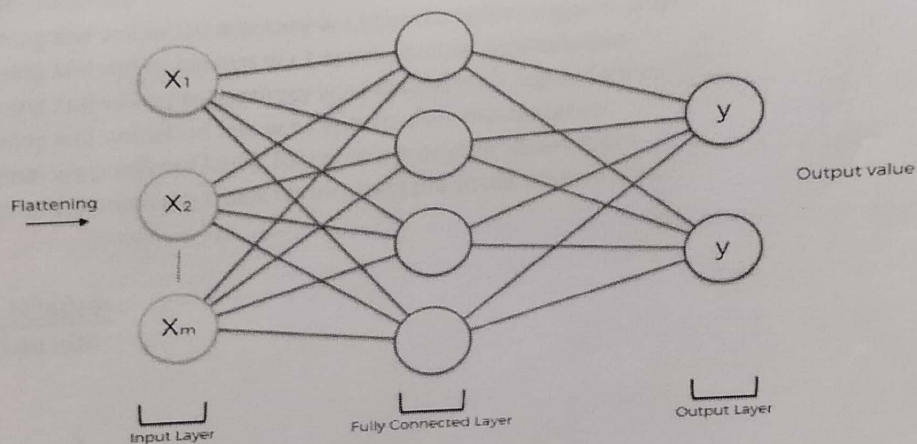
What is Fully Connected Layer?

A fully connected layer that takes the output of convolution/pooling and predicts the best label to describe the image. We have three layers in the full connection step i. Input layer ii. Fully-connected layer iii. Output layer

Input Layer: It takes the output of the previous layers, "flattens" them and turns them into a single vector that can be an input for the next stage.

Fully Connected Layer: It takes the inputs from the feature analysis and applies weights to predict the correct label.


Output Layer: It gives the final probabilities for each label.



ReLU Layer: ReLU is an activation function. Rectified Linear Unit (ReLU) transform function only activates a node if the input is above a certain quantity, while the input is below zero, the output is zero, but when the input rises above a certain threshold, it has a linear relationship with the dependent variable. The main aim is to remove all the negative values from the convolution. All the positive values remain the same but all the negative values get changed to zero.

Methodology:

1. Load the basic libraries and packages
2. Load the dataset
3. Analyse the dataset
4. Normalize the data
5. Pre-process the data
6. Visualize the Data

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7. Write the CNN model function
8. Write the Cost Function
9. Write the Gradient Descent optimization algorithm
10. Apply the training over the dataset to minimize the loss
11. Observe the cost function vs iterations learning curve

Results:

To be attached with

- a. Training dataset
- b. Model summary
- c. Training and validation accuracy w.r.t epochs before regularization
- d. Training and validation loss w.r.t epochs before regularization
- e. Training and validation accuracy w.r.t epochs after regularization
- f. Training and validation loss w.r.t epochs after regularization
- g. Original v/s predicted labels for correct predicted observations
- h. Original v/s predicted labels for incorrect predicted observations

Program (Code):

To be attached with



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Pre Lab Exercise:

- a. What is Convolution process? Explain giving example.

The convolution process in CNN is a mathematical operation where a kernel slides over the input data to extract features.

- b. What are different layers in CNN model?

Layers in CNN model → 1) Convolution Layer
2) Pooling Layer 3) ReLU Activation Layer
4) Fully connected Layer 5) Dropout Layer

- c. What is the requirement of the pooling layer in the CNN model?

The Pooling layer is essential for → 1) Reducing Dimensionality 2) Preventing overfitting
3) Enhancing Invariance.

- d. What is the requirement of the use of ReLU activation function after convolution step?

The Requirement of the ReLU activation function is it introduces non-linearity. 2) It prevent vanishing gradient


Observation and Result Analysis:

- e. Nature of the dataset

The dataset consists of Images with 28×28 pixel size. It is consisting 55000 images as training data and 5000 images as testing data.

- f. Training Process without regularization

The model may memorize the training data, reducing generalization, the model performs well on training data but poorly on unseen data.

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g. After regularization in the training Process

After the regularization, the model performs better on unseen data. Techniques like L2 regularization and dropout preventing overfitting.

h. Observation over the Learning Curves

Without Regularization the training accuracy increases but the validation accuracy stagnates or decreases and in the case of Regularization both increase.

Post Lab Exercise:

a. Why CNN is preferred over ANN for images

1) CNN preserves the spatial relationship 2) CNN uses shared weights reducing the number of parameters 3) It automatically extracts hierarchical features

b. Can CNN be applied over Text data? If yes, then how. If no, then why?

Yes, It can be implemented by treating text as a sequential data. We can tokenize the word then convolution then pooling and fully connected layers

c. What is the role of dropout layer?

It prevents overfitting by randomly drops a fraction of neurons, then it makes the model robust and reduce the overfitting

d. What will happen if maxpooling is replaced with minpooling?

It may result into the loss of important features and reduced model performance

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