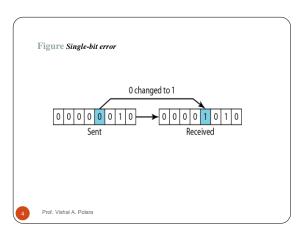
Unit-3.1 Error Correction and Detection Prepared By: Prof. Vishal A. Polara Assistant Professor Information Technology Department Birla Vishvakarma Mahavidyalaya Engineering College

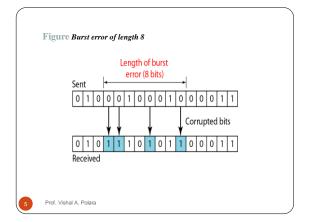


Outline

- Types of Errors
- Block coding
- · Linear block codes
- · Cyclic codes
- Checksum



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1. Types of errors

- There are two types of errors
- Single bit errors : Only one bit in data unit has changed
- multi bit errors: It is also known as burst error where more than two bit in data unit has changed
- Here 0 changes to 1 and 1 changes to 0.
- Single bit errors are normally seen least in serial data transmission.
- Burst error is more likely to occur than a single bit error. It
 occurs due to noise because duration of noise is longer than
 the duration of 1 bit. So noise affect more numbers of data.



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Error correction and detection using

Redundancy

- To detect or correct errors we need to send some extra bits with our data.
- These redundant bits are added by the sender and removed by the receiver. It allows receiver to detect or correct corrupted bits.
- Error detection means we have to change if bit changed or not.
- While in case of error correction we need to know the exact number of bits that are corrupted and their location in the message.
- If we need to correct one single error in an 8-bit data unit we need to consider eight possible error locations, if we need to correct two errors in a data unit of the same size we need to consider 28 possibilities.
- Redundancy achieve using various coding schemes. The sender adds the redundant bits through a process that creates relationship between the redundant bits and the actual data bits.

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- Redundancy achieve using various coding schemes. The sender adds the redundant bits through a process that creates relationship between the redundant bits and the actual data bits.
- The receiver checks the relationships between the two sets of bits to detect or correct the errors.
- · There are two coding schemes available:
- Block coding
- Convolution coding

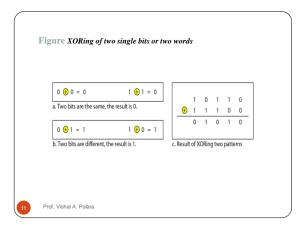


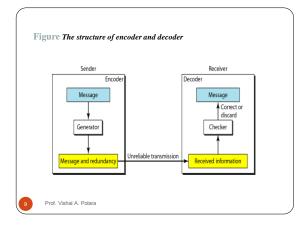
In modulo-N arithmetic, we use only the integers in the range 0 to N -1, inclusive.

Method of correction

- There are two main methods of error correction.
- Forward error correction
- Retransmission
- Forward error correction is the process in which the receiver tries to guess the message by using redundant bits.
 If the number of errors is small
- Retransmission is a technique in which the receiver detects the occurrence of an error and asks the sender to resend the message.

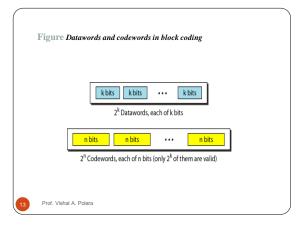


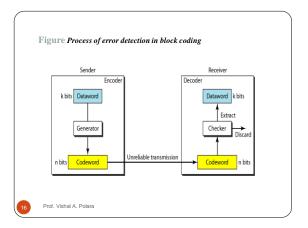




2. Block Coding

- In block coding, we divide our message into blocks, each of k bits, called datawords. We add r redundant bits to each block to make the length n=k+r. The resulting n-bit blocks are called codewords.
- With k bits we can create a combination of 2^k data words and with n bits we can create a combination of 2^k codewords.
- In block coding same data word is always encoded using same code words that mean 2ⁿ - 2^k codewords are not used. It is known as invalid or illegal codewords.
- Error Detection
- Error Correction
- · Hamming Distance
- · Minimum Hamming Distance





Example

The 4B/5B block coding discussed in previous unit is a good example of this type of coding. In this coding scheme, k=4 and n=5. As we saw, we have $2^k=16$ datawords and $2^n=32$ codewords. We saw that 16 out of 32 codewords are used for message transfer and the rest are either used for other purposes or unused.



Example

Let us assume that k = 2 and n = 3. Table shows the list of datawords and codewords. Later, we will see how to derive a codeword from a dataword.

Assume the sender encodes the dataword 01 as 011 and sends it to the receiver. Consider the following cases:

1. The receiver receives 011. It is a valid codeword. The receiver extracts the dataword 01 from it.

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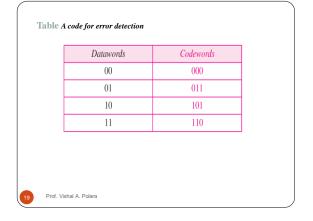
Error Detection

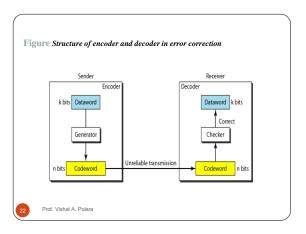
- In Block coding error detection is possible if following two condition met
- The receiver has a list of valid codewords
- The original codeword has changed to an invalid one
- The sender creates codewords out of datawords by using a generator that applies the rules and procedures of encoding.
- Each codeword sent to the receiver may change during transmission.
- If it is same than accepted else received codeword is not valid, it is discarded.
- If it is corrupted but still matched with a valid codeword the errors remain undetected.



Example (continued)

- The codeword is corrupted during transmission, and 111 is received. This is not a valid codeword and is discarded.
- 3. The codeword is corrupted during transmission, and 000 is received. This is a valid codeword. The receiver incorrectly extracts the dataword 00. Two corrupted bits have made the error undetectable.





An error-detecting code can detect only the types of errors for which it is designed; other types of errors may remain undetected.

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Example

Let us add more redundant bits to previous example to see if the receiver can correct an error without knowing what was actually sent. We add 3 redundant bits to the 2-bit dataword to make 5-bit codewords. Table shows the datawords and codewords. Assume the dataword is 01. The sender creates the codeword 01011. The codeword is corrupted during transmission, and 01001 is received. First, the receiver finds that the received codeword is not in the table. This means an error has occurred. The receiver, assuming that there is only 1 bit corrupted, uses the following strategy to guess the correct dataword.

Error Correction

· In error correction we need more redundant bits.

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Example

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- Comparing the received codeword with the first codeword in the table (01001 versus 00000), the receiver decides that the first codeword is not the one that was sent because there are two different bits.
- 2. By the same reasoning, the original codeword cannot be the third or fourth one in the table.
- 3. The original codeword must be the second one in the table because this is the only one that differs from the received codeword by 1 bit. The receiver replaces 01001 with 01011 and consults the table to find the dataword 01.

Table A code for error correction

Codeword
00000
01011
10101
11110



Example

Let us find the Hamming distance between two pairs of words.

1. The Hamming distance d(000, 011) is 2 because

000

011 is 011 (two 1s)

2. The Hamming distance d(10101, 11110) is 3 because

10101

11110 is 01011 (three 1s)



Hamming Distance

- The Hamming distance between two words is the number of differences between corresponding bits.
- The hamming distance cab be found by applying the XOR operation on the two words and count the number of 1s in the result. It must be greater than zero.
- Minimum hamming distance is the smallest hamming distance between all possible pairs.
- It requires to define minimum hamming distance in coding scheme.
- To decide this we find the hamming distances between all words and select the smallest one.
- Any coding scheme required three parameters codeword size n, data word size k, and minimum hamming distance dmin.
- If our code is to detect upto S errors the minimum hamming distance between the valid codes must be S+1 so that the received codeword does not match the valid codeword



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Example

Find the minimum Hamming distance of the coding scheme

Solution

We first find all Hamming distances.

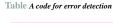
The d_{min} in this case is 2.



Hamming Distance

 $\begin{tabular}{ll} \bullet & The minimum hamming distance for error correction is $dmin = 2t+1. \end{tabular}$





Datawords	Codewords
00	000
01	011
10	101
11	110

Table A code for error correction

Dataword	Codeword	
00	00000	
01	01011	
10	10101	
11	11110	

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Example

A code scheme has a Hamming distance $d_{min} = 4$. What is the error detection and correction capability of this scheme?

Solution

This code guarantees the detection of up to three errors (s = 3), but it can correct up to one error. In other words, if this code is used for error correction, part of its capability is wasted. Error correction codes need to have an odd minimum distance (3, 5, 7, . . .).



Example

Find the minimum Hamming distance of the coding scheme

Solution

We first find all the Hamming distances.



The d_{min} in this case is 3.



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Linear Block codes

- · The use of nonlinear block codes for error detection and correction is not widespread because of their structure.
- · A linear block code is a code in which the exclusive OR of two valid codewords creates another valid codeword.
- The minimum hamming distance is the number of 1s in the nonzero valid codeword with the smallest number of 1s.
- · Simple parity check code:
- It is used to detect single bit error.
- In this technique codeword is get replace by adding extra bit which is parity bit to make total number of 1s in the codeword even.
- At receiver side addition is done over all 5 bits. It is called syndrome. If it is 0 when the number of 1s in the received codeword is even otherwise it is 1.



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Example

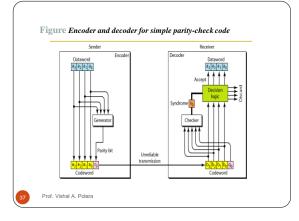
The minimum Hamming distance for our first code scheme is 2. This code guarantees detection of only a single error. For example, if the third codeword (101) is sent and one error occurs, the received codeword does not match any valid codeword. If two errors occur, however, the received codeword may match a valid codeword and the errors are not detected.



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Table Simple parity-check code C(5, 4)

Datawords	Codewords	Datawords	Codewords
0000	00000	1000	10001
0001	00011	1001	10010
0010	00101	1010	10100
0011	00110	1011	10111
0100	01001	1100	11000
0101	01010	1101	11011
0110	01100	1110	11101
0111	01111	1111	11110



2. Linear Block codes

Hamming Codes:

- It is used for error correction with dmin = 3 which means it can detect upto two errors or correct one single error.
- It requires to chose m>=3. the value of n and k are then calculated from m as $n=2^{m-1}$ and k=n-m, the number of check bits r=m.
- For example if m=3 then n=7 and k=4.
- A copy of a 4-bit dataword is fed into the generator that creates three parity checks r0.r1,r2
- $r0 = a2 + a1 + a0 \mod 2$
- r1= a3+a2+a1 modulo-2
- $r2 = a1 + a0 + a3 \mod 2$
- The checker in the decoder creates a 3-bit syndrome(s2s1s0) in which each bit is the parity check for 4 out of the 7 bits in the received codeword.



Example

Let us look at some transmission scenarios. Assume the sender sends the dataword 1011. The codeword created from this dataword is 10111, which is sent to the receiver. We examine five cases:

- 1. No error occurs; the received codeword is 10111. The syndrome is 0. The dataword 1011 is created.
- 2. One single-bit error changes a₁ . The received codeword is 10011. The syndrome is 1. No dataword is created.
- 3. One single-bit error changes r_0 . The received codeword is 10110. The syndrome is 1. No dataword is created.



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Hamming code

- The checker in the decoder creates a 3-bit syndrome(s2s1s0) in which each bit is the parity check for 4 out of the 7 bits in the received codeword.
- $s0 = b2 + b1 + b0 + q0 \mod 2$
- s1=b3+b2+ b1+q1 modulo-2
- $s2=b1+b0+b3+q2 \mod 10-2$
- The equation used by checker is same as used by generator with the parity check bits added to the right hand side of the equation.
- The 3 bit syndrome creates eight different bit patterns than can represent eight different conditions.
- The condition define a lack of error or an error in 1 of the 7 bits of the received codeword.



Example

- 4. An error changes r_0 and a second error changes a_3 . The received codeword is 00110. The syndrome is 0. The dataword 0011 is created at the receiver. Note that here the dataword is wrongly created due to the syndrome value.
- 5. Three bits—a₃, a₂, and a₁—are changed by errors. The received codeword is 01011. The syndrome is 1. The dataword is not created. This shows that the simple parity check, guaranteed to detect one single error, can also find any odd number of errors.

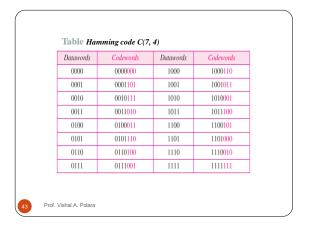


Hamming code

- Performance:

- It can only correct a single error or detect a double error. It can also detect burst error.
- The key is to split a burst error between several codewords one error for each codeword.

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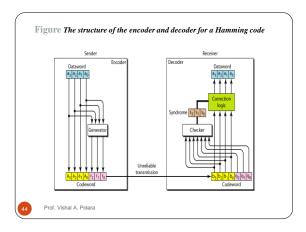


Example

Let us trace the path of three datawords from the sender to the destination:

- 1. The dataword 0100 becomes the codeword 0100011. The codeword 0100011 is received. The syndrome is 000, the final dataword is 0100.
- 2. The dataword 0111 becomes the codeword 0111001. The syndrome is 011. After flipping b₂ (changing the 1 to 0), the final dataword is 0111.
- 3. The dataword 1101 becomes the codeword 1101000. The syndrome is 101. After flipping b₀, we get 0000, the wrong dataword. This shows that our code cannot correct two errors.





Example

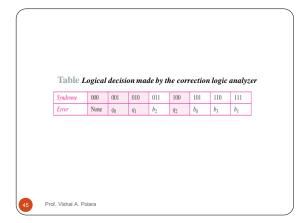
We need a dataword of at least 7 bits. Calculate values of k and n that satisfy this requirement.

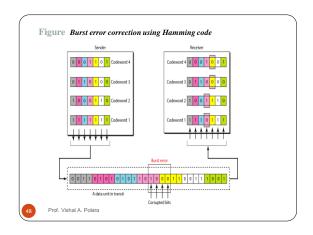
Solution

We need to make k = n - m greater than or equal to 7, or $2m - 1 - m \ge 7$.

- 1. If we set m = 3, the result is n = 23 1 and k = 7 1
- 3, or 4, which is not acceptable.
- 2. If we set m = 4, then n = 24 1 = 15 and k = 15 15
- 4 = 11, which satisfies the condition. So the code is

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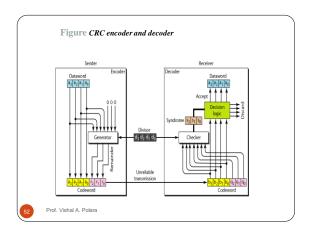




3. Cyclic code

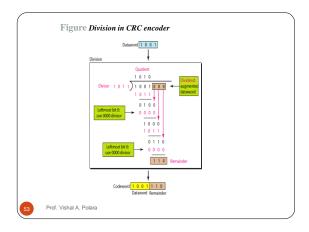
- Cyclic codes are special linear block codes with one extra property. In a cyclic code, if a codeword is cyclically shifted (rotated), the result is another codeword.
- · It is used to correct error. It is used in LAN and WAN.
- In the encoder the dataword has k bits, the code word has n bits.
- The size of the dataword is augmented by adding n-k 0s to the right hand side of the word.
- The n-bit result is fed into the generator. The generator uses a divisor of size=n-k+1(4 bits), which is predefined and agreed upon.
- The generator divides the augmented dataword by the divisor(modulo-2 division).
- The remainder(r2r1r0) is appended to the dataword to create the codeword.

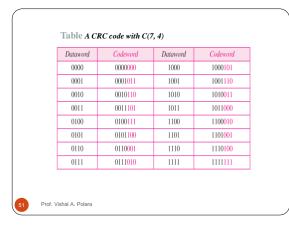


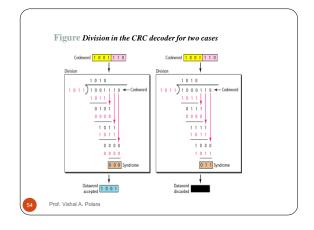


3. Cyclic code

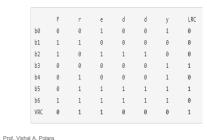
- Decoder receive the codeword. Checker generate the remainder which is called syndrome of n-k bits, which is fed to the decision logic analyzer.
- The analyzer has a simple function. If the syndrome bits are all 0s, the 4 leftmost bits of the code word are accepted as the data word otherwise the 4 bits are discarded.

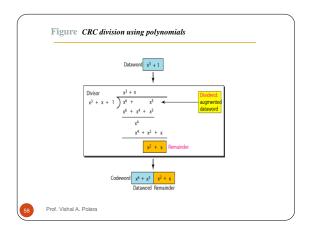






 It is normally used for serial communication. In case of VRC odd parity bit scheme is used while for LRC even parity scheme is used.

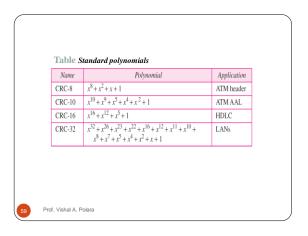


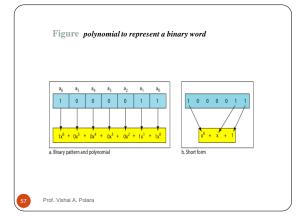


3. Cyclic code in polynomial form

- A pattern of 0s and 1s can be represented as a polynomial with coefficients of 0 and 1.
- The power of each term shows the position of the bit, the coefficient shows the value of the bit.
- The degree of the polynomial is 1 less than the number of bits in the pattern.
- In example to find the augmented dataword we have left shifted the dataword 3 bits by multiplying by x3.







4. Check sum

- In checksum receiver send addition of all number with actual number
- · Here addition is send as negative value.
- At receiver side again addition of actual value is done if some is 0 that means data are correct else there is an error in data.
- One's complement:
- In this technique the number has more than n bits, the extra leftmost bits need to be added to the n rightmost bits(wrapping).

Example

Suppose our data is a list of five 4-bit numbers that we want to send to a destination. In addition to sending these numbers, we send the sum of the numbers. For example, if the set of numbers is (7, 11, 12, 0, 6), we send (7, 11, 12, 0, 6, 36), where 36 is the sum of the original numbers. The receiver adds the five numbers and compares the result with the sum. If the two are the same, the receiver assumes no error, accepts the five numbers, and discards the sum. Otherwise, there is an error somewhere and the data are not accepted.



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Example

How can we represent the number -6 in one's complement arithmetic using only four bits?

Solution

In one's complement arithmetic, the negative or complement of a number is found by inverting all bits. Positive 6 is 0110; negative 6 is 1001. If we consider only unsigned numbers, this is 9. In other words, the complement of 6 is 9. Another way to find the complement of a number in one's complement arithmetic is to subtract the number from $2^n - 1$ (16 -1 in this case).



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Example

We can make the job of the receiver easier if we send the negative (complement) of the sum, called the checksum. In this case, we send (7, 11, 12, 0, 6, -36). The receiver can add all the numbers received (including the checksum). If the result is 0, it assumes no error; otherwise, there is an error.



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Example

Let us redo previous exercise using one's complement arithmetic. Figure shows the process at the sender and at the receiver. The sender initializes the checksum to 0 and adds all data items and the checksum (the checksum is considered as one data item and is shown in color). The result is 36. However, 36 cannot be expressed in 4 bits. The extra two bits are wrapped and added with the sum to create the wrapped sum value 6. In the figure, we have shown the details in binary. The sum is then complemented, resulting in the checksum value 9 (15 – 6 = 9). The sender now sends six data items to the receiver including the checksum 9.



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Example

How can we represent the number 21 in one's complement arithmetic using only four bits?

Solution

The number 21 in binary is 10101 (it needs five bits). We can wrap the leftmost bit and add it to the four rightmost bits. We have (0101 + 1) = 0110 or 6.

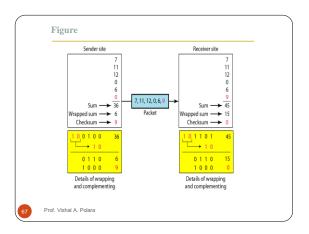


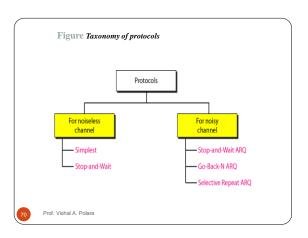
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Example

The receiver follows the same procedure as the sender. It adds all data items (including the checksum); the result is 45. The sum is wrapped and becomes 15. The wrapped sum is complemented and becomes 0. Since the value of the checksum is 0, this means that the data is not corrupted. The receiver drops the checksum and keeps the other data items. If the checksum is not zero, the entire packet is dropped.







5. Flow Control

- Flow control refers to a set of procedures used to restrict the amount of data that the sender can send before waiting for acknowledgment.
- Error control in the data link layer is based on automatic repeat request, which is the retransmission of data.
- Data link layer is responsible for creating frame which contain address of sender and receiver respectively.
- Two types of framing is possible:
- Fixed size framing: no need to define boundaries
- Variable size framing: it requires to define beginning and end of frame.
- Two way we can define boundary using character oriented protocols and bit oriented protocols.

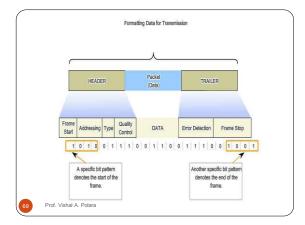


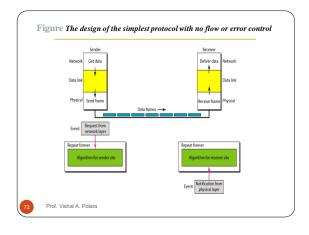
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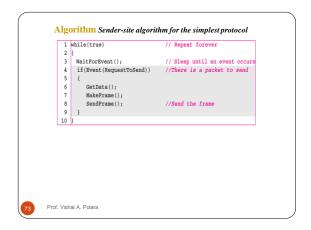
6. Noiseless Channel

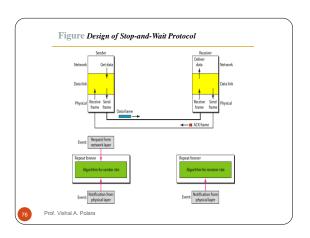
- It can support two protocols.
- Simplest Protocol:
- It is unidirectional protocol in which data frames are traveling in only one direction from sender to receiver.
- There is no need for flow control in this scheme.
- In this protocol sender side cannot send a frame until its network layer has a data packet to send.
- The receiver site cannot deliver a data packet to its network layer until a frame arrives.
- If the protocol is implemented as procedure we need to introduce the idea of events in the protocol.

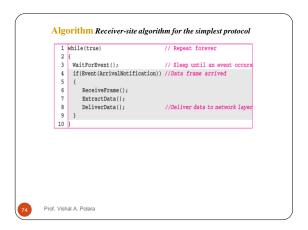












```
Algorithm Sender-site algorithm for Stop-and-Wait Protocol
     1 while(true)
     2 canSend = true
                                       //Allow the first frame to go
         WaitForEvent();
                                       // Sleep until an event occur
         if(Event(RequestToSend) AND canSend)
            GetData();
            MakeFrame();
            SendFrame();
                                       //Send the data frame
    10
            canSend = false;
                                       //Cannot send until ACK arrives
    11
         WaitForEvent();
         if (Event (Arrival Notification) // An ACK has arrived
    13
    14
    15
16
            ReceiveFrame();
                                       //Receive the ACK frame
            canSend = true;
    17
    18 }
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```

```
Stop and wait Protocol:

It is used to overcome loss of frame when receiver is not capable to handle to much frame so frame get lost.

In this protocol sender sends one frame, stops until it receives confirmation from the receiver and then sends the next frame.

It also has unidirectional communication for data frames but auxiliary ACK frames from the other direction.

In this protocol flow control is added.
```

7. Noisy Channel

- · It has three protocol
- Stop-and-Wait Automatic Repeat Request
- In this protocol flow control and error control is added.
- · To detect and correct corrupted frames redundancy is added.
- In this protocol sender sends the frame and waits for the acknowledgement if he will not receive and ACK timer is set for particular frame so sender assumes that frame is discarded and he will resend it if ACK is not received.
- · Sequence number is assigned to each frame.
- The sequence numbers start from 0 go to 2^m-1 and then are repeated.
- Receiver send an acknowledgement based on next frame. If 0 is arrive safe it send 1 means he require next frame.



```
Algorithm Sender-site algorithm for Stop-and-Wait ARQ
                                       // Frame 0 should be sent first
     2 canSend = true;
                                      // Allow the first request to go
     3 while(true)
                                      // Repeat forever
          WaitForEvent();
                                      // Sleep until an event occurs
          if (Event (RequestToSend) AND canSend)
             GetData();
             MakeFrame(S<sub>n</sub>);
                                                //The seqNo is S_{\rm n}
             StoreFrame(S_n);
                                                //Keep copy
    11
             SendFrame(S<sub>n</sub>);
    12
             StartTimer();
    13
             S_n = S_n + 1;
             canSend = false;
    14
    15
    16
          WaitForEvent();
                                                // Sleep
                                                            (continued)
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```

Stop-and-Wait ARQ Protocol OR One-bit Sliding Window Protocol

- Error correction in Stop-and-Wait ARQ is done by keeping a copy of the sent frame and retransmitting of the frame when the timer expires.
- In Stop-and-Wait ARQ, we use sequence numbers to number the frames.
- The sequence numbers are based on modulo-2 arithmetic (0,1,0,1,...).
- In Stop-and-Wait ARQ, the acknowledgment number always announces in modulo-2 arithmetic the sequence number of the next frame expected.



```
Algorithm Sender-site algorithm for Stop-and-Wait ARQ (COntinued)
                    if(Event(ArrivalNotification) // An ACK has arrived
           18
            19
           20
                       if(not corrupted AND ackNo == S_n) //Valid ACK
            21
                           PurgeFrame(S<sub>n-1</sub>);
canSend = true;
            23
                                                            //Copy is not needed
            24
            25
26
            28
29
                    if (Event (TimeOut)
                                                            // The timer expired
                     StartTimer();
            31
                     \texttt{ResendFrame}\left( \texttt{S}_{n-1} \right);
                                                            //Resend a copy check
            32
           33
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```

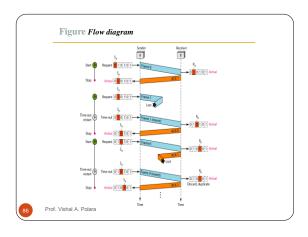
```
Figure Design of the Stop-and-Wait ARQ Protocol

S, Note there to the stop of the Stop-and-Wait ARQ Protocol

South to the stop of the Stop-and-Wait ARQ Protocol

South to the stop of th
```

```
Algorithm Receiver-site algorithm for Stop-and-Wait ARQ Protocol
                                  // Frame 0 expected to arrive first
     2 while(true)
          WaitForEvent();
                                 // Sleep until an event occurs
          if(Event(ArrivalNotification)) //Data frame arrives
             ReceiveFrame();
             if(corrupted(frame));
               sleep();
    10
             if(seqNo == Rn)
                                          //Valid data frame
    11
    12
              ExtractData():
    13
               DeliverData();
                                          //Deliver data
    14
15
               R_n = R_n + 1;
                                          //Send an ACK
    17
    18
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```



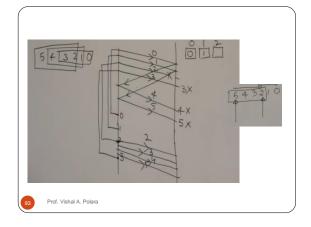
- There is a relationship between sequence number and window size is important.
- Due to lost of acknowledgment there is a chance of receiving duplicate packet.
- If sender window size is 4, receiver window size is 1, we normally need 5 sequence number.

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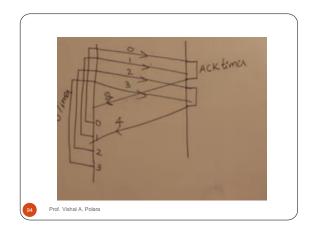
Go-Back-N Protocol

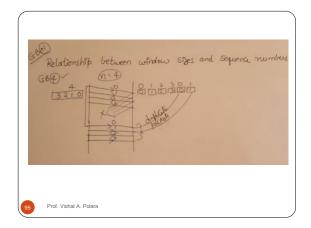
- In the Go-Back-N Protocol, the sequence numbers are modulo 2^m, where m is the size of the sequence number field in bits.
- The send window is an abstract concept defining an imaginary box of size 2^m - 1 with three variables: Sf, Sn, and S_{size}.
- The send window can slide one or more slots when a valid acknowledgment arrives.
- The receive window is an abstract concept defining an imaginary box of size 1 with one single variable Rn. The window slides when a correct frame has arrived; sliding occurs one slot at a time.

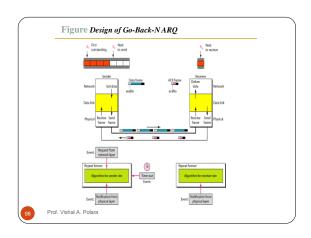


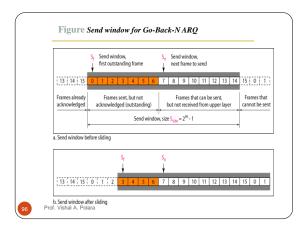


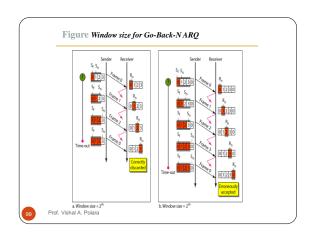
- Sliding window is theoretical protocol. It can be implemented using GBN (Go back N)and SR (selective repeat).
- In GBN N>1 is always greater than 1 else it is stop and wait.
- Receiver window size is always 1. because it will wait for one packet only.
- It will accept packet in order only packet out of order will be discarded.
- 1. If packet lost in Go back N in that case all packet from last to unacknowledged will re transmitted if the time period expires.
- 2. acknowledgement lost: it normally send acknowledgment for many packet at a time (It works on acknowledgment timer once timer expire all packet received within ack time for that packet ack will send).
- Time out timer of data should be larger than ack timer.
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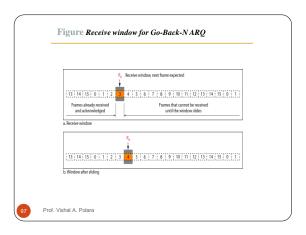






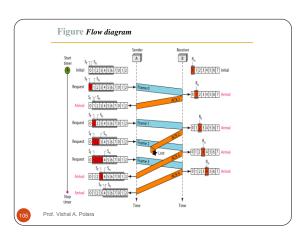


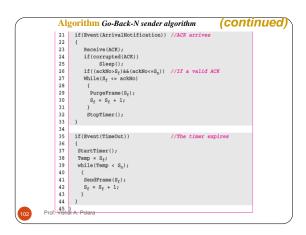


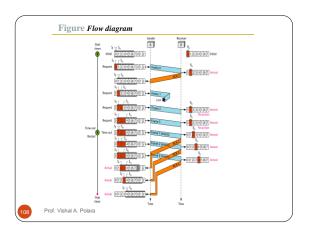


In Go-Back-N ARQ, the size of the send window must be less than 2^m; the size of the receiver window is always 1.

```
Algorithm Go-Back-N sender algorithm
        1 S<sub>w</sub> = 2<sup>m</sup> - 1;
        2 S<sub>f</sub> = 0;
        3 S<sub>n</sub> = 0;
        5 while (true)
             WaitForEvent();
             if(Event(RequestToSend))
                                                          //A packet to send
                  \mathtt{if}(\mathbb{S}_{\mathtt{n}}\text{-}\mathbb{S}_{\mathtt{f}} \; >= \; \mathbb{S}_{\mathtt{w}})
                                                          //If window is full
      11
12
                           Sleep();
                  GetData();
       13
                  MakeFrame(S_n);
      14
                  StoreFrame(Sn);
       15
                  SendFrame(Sn);
                  S<sub>n</sub> = S<sub>n</sub> + 1;
if(timer not running)
      16
      17
                         StartTimer();
       19
       20
                                                                                  (continued)
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```







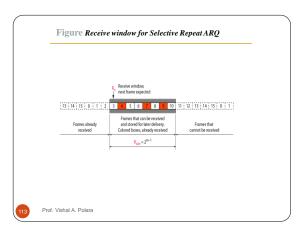
```
Algorithm 11.8 Go-Back-N receiver algorithm
      1 R<sub>n</sub> = 0;
      3 while (true)
          WaitForEvent();
          if(Event(ArrivalNotification)) /Data frame arrives
             Receive(Frame);
    10
             if(corrupted(Frame))
                   Sleep();
    12
13
             if(seqNo == R_n)
                                            //If expected frame
    14
                DeliverData();
                                            //Deliver data
    15
16
               R_n = R_n + 1;
SendACK(R_n);
                                            //Slide window
    17
18
         }
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```

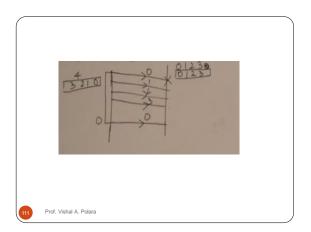
Stop-and-Wait ARQ is a special case of Go-Back-N ARQ in which the size of the send window is 1.

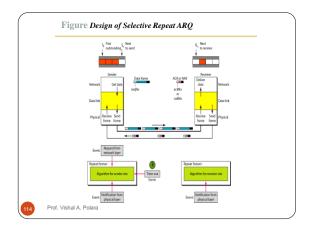
Selective Repeat Protocol

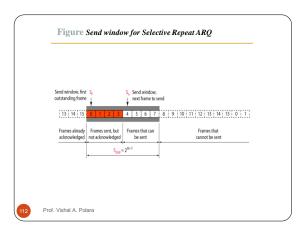
- It is also sliding window protocol. Here also sender window size is >1.
- Here sender window size and receiver window size is same. In go back N receiver window size is 1.
- In selective repeat no order delivery of packet is required.
 The packet which arrive as per the window will accepted.
- If packet is lost from 0 to 3 like 0 is lost remaining will accepted and after time out of 0 packet it will be retransmitted. Same with the loss of ack.
- · Here retransmission is less compare to go back N.
- If in receive packet bit is corrupted it will send negative acknowledgment.
- · It require to do sorting so cpu requirement is high.

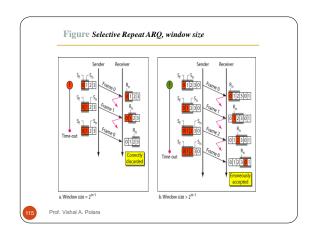












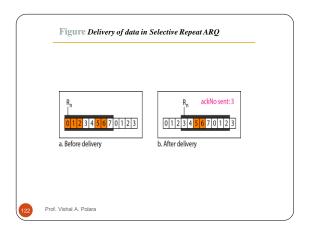
```
In Selective Repeat ARQ, the size of the sender and receiver window must be at most one-half of 2<sup>m</sup>.
```

```
Algorithm Sender-site Selective Repeat algorithm
     1 S_w = 2^{m-1};
2 S_f = 0;
3 S_n = 0;
     5 while (true)
                                            //Repeat forever
          WaitForEvent();
          if (Event (RequestToSend))
                                           //There is a packet to send
            if(S_n-S_f >= S_w)
                                           //If window is full
    11
                   Sleep();
             GetData():
    12
    13
             MakeFrame(S_n);
    14
15
             StoreFrame(S_n);
             SendFrame(S_n);
             S_n = S_n + 1;
    17
18
             StartTimer(S<sub>n</sub>);
    19
                                                             (continued)
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```

```
Algorithm Receiver-site Selective Repeat algorithm
 2 NakSent = false;
 4 Repeat (for all slots)
        Marked(slot) = false;
      WaitForEvent();
     if(Event(ArrivalNotification))
                                               /Data frame arrives
12
         Receive(Frame);
if(corrupted(Frame))&& (NOT NakSent)
14
15
16
          SendNAK(R<sub>n</sub>);
         NakSent = true;
Sleep();
17
18
         if(seqNo <> Rn)&& (NOT NakSent)
21
22
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```

```
(continued)
Algorithm Sender-site Selective Repeat algorithm
          20 if(Event(ArrivalNotification)) //ACK arrives
          21
          22
                     Receive(frame);
                                                           //Receive ACK or NAK
                     if(corrupted(frame))
          23
                           Sleep();
                     if (FrameType == NAK)
          25
                         if (nakNo between S_f and S_n)
          27
          29
                          StartTimer(nakNo);
          30
                    \label{eq:frameType} \begin{array}{ll} \text{if (FrameType == ACK)} \\ & \text{if (ackNo between } S_{f} \text{ and } S_{n}) \end{array}
          31
          32
          33
34
                            while(s_f < ackNo)
          35
36
                             Purge(s<sub>f</sub>);
                             StopTimer(s<sub>f</sub>);
S<sub>f</sub> = S<sub>f</sub> + 1;
          37
          38
          39
          40
          41
                                                                                  (continued)
```

```
Algorithm Receiver-site Selective Repeat algorithm
              NakSent = true;
if ((seqNo in window)&&(!Marked(seqNo))
25
               StoreFrame(seqNo)
27
               Marked(seqNo) = true;
               while(Marked(R_n))
29
30
31
32
33
                 DeliverData(Rn);
                Purge(R<sub>n</sub>);
R<sub>n</sub> = R<sub>n</sub> + 1;
AckNeeded = true;
34
35
36
37
38
39
40
                 if(AckNeeded);
                AckNeeded = false;
NakSent = false;
41
42
43
       }
```



Piggybacking

- In all previous example we have seen unidirectional communication.
- If we wants to do bidirectional communication then there must be some mechanism to do flow control.
- We can do by using two window at both the side sender as well as receiver side.
- Here sender is sending data to receiver and receiver is sending to sender vice versa. But receiver or sender will not send an acknowledgement directly after receiving frame. They will wait for next frame and hooked acknowledgement with next outgoing frame
- Hooking of acknowledgement with next going frame is called piggybacking.



