Lecture 3 blackboard notes

We had:

$$2x_1 + 3x_2 - 2x_3 + 5x_4 = 1$$

 $x_1 + 2x_2 - x_3 + 3x_4 = 2$
 $-x_1 - 2x_2 + x_3 - x_4 = 4$

$$\begin{bmatrix} 2 & 3 & -2 & 5 & | & 1 \\ 1 & 2 & -1 & 3 & | & 2 \\ -1 & -2 & 1 & -1 & | & 4 \end{bmatrix}$$

pirot columns => x1, x2, x4 pirot vars x3 free variables

* to get Ax=b.

set x3 =0.

Back - Substitution:

$$2x_{4} = 6 =) x_{9} = \frac{6}{2} = 3$$

 $-x_{2} - x_{4} = -3 =) x_{2} = 0$

$$4 \times 1 + 2 \times 2 - 73 + 3 \times 7 = 2 = 2 \times 1 = -7$$
One solution:
$$\begin{bmatrix} -7 \\ 6 \\ 0 \\ 3 \end{bmatrix}$$

$$N(A)$$
 or half $(A) = {x : Ax = 0}.$

$$[X^3=1]$$

by back substitution.
$$=$$
) $\begin{cases} X_2 = 0 \\ X_4 = 0 \end{cases}$

Solution
$$\begin{pmatrix} 1 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$A\begin{bmatrix} 1\\ 5\\ 5 \end{bmatrix} = 0$$
 $\begin{bmatrix} 1\\ \lambda \end{bmatrix}$

Solution
$$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = 0$$
 $\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} = 0$ $\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} =$

$$N(A) = \left\{ \lambda \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \lambda \in \mathbb{R} \right\}$$

General solution
$$\begin{cases}
X \in \mathbb{R}^4 : X = \begin{bmatrix} -7 \\ 0 \\ 3 \end{bmatrix} + \lambda \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} | \lambda \in \mathbb{R}^3.$$

Mmxn (P)

Exercise Prove that given $A \in \mathbb{R}^{m \times n}$ (m < n), then $A_X = 0$ has infinitely many solutions. System Ax =0 has at least one solution o. ERO: ekmentary row perations. (A · O z O. 7 At most on pivots in R. n 7 m => 3 n-m >/ free variables.=>
=> fx*s.t x*is solution => > x* are solutions (so many). Gauss-Jordan (GJ) nethod/Gaussian elimination [A I In] FROS [In 1 B]. 4 E Maxa (R)

 $\begin{bmatrix} 1 & 0 & -1 & 2 & -1 & 0 \\ 0 & 1 & 2 & -1 & 1 & 0 \\ 0 & 0 & -1 & 1 & -2 & 1 \end{bmatrix}$ (Define Ars(x): add > times row r to rows (rts)) (Mr(x): multiply row r by x LPrs: Suap rour with rows. M2(-1) A -1 $C = \begin{pmatrix} 1 & 3 & 4 \\ 2 & 6 & 9 \\ 4 & 12 & 17 \end{pmatrix} \xrightarrow{Elos} \begin{pmatrix} 1 & 3 & 4 \\ 0 & 0 & 1 \\ A_{12}(-1) & 0 & 0 \\ A_{11}(-4) & 0 & 0 \end{pmatrix}$ reduced to Iz, has no inverse. also boking at rows: row 3 = row2 + 2. cow1, line ash

dependent.

A E Mmxn (R) Lemma i) let B & Mmxm (IR) be invertible. (BA) x = Bb has the same solutions as Ax=b. (proof ut nome). ii) A is invertible. Then Ax = b hon a unique solution [x = A-16. Ex. Ex-1 Ex-2 ... E, A = R. EROS BAX = Bb. Theorem AEMNXA (P) is a square metrix. Then all the state ments we pair wise equirated 1) RREF of A is the identity matrix

ii) the only solution to Ax 20 is the

final Solution x 20.

MOORE - PENROSE INVERSE

A E M mxn (1P)

G is a psudo -inverse for A ij:

AGA = A

GAG = G

(AG) = AG

CA) T=GA.

Under mild conditions for A:

Ax = b.

ATAX = ATB

 $x = (A^T A)^{-1} A^T b.$

Dengo-inverse (noose-ferrod pango inverse)

VECTOR SPACES

Defn

A (real-valued) vector space V is a non-empty Set v together with two operations.

[4] +[3] = [7] - ROJ - J 5[84] - [20]

(i) addition: & X, y & J, then + allows ws to get z +y.

(ii) Scalar multiplication: $\forall x \in V$, then we can get λx

CLOSURE AXIOMS

i) It x, y EU then x+y EU.

ii) If XEV, ZER, then DXEV.

Axions FOR ADDITION

() associationity

(x+y)+ == x + (y+2), + x, y, ZEV.

ii) existence of additire identity (neutral element)

Frestor U=060 s.t.

X+0=0+ X= X1 A XED.

in) existence of udditise inverse V ≠ ∈ V → -× ∈ J 5.+. ₹ + (-×)=0. (1) commutative Y x, y ed (x +y = y+ x) (O, +) is an Abelian group. ATTOMS FOR SCACAR RULTIPLICATION

i) associationly A, YER, XEU $(\lambda \Psi) \times = \lambda (\Psi \times)$ ii) distributionity x++x = x (9+1) x (++y) = >x+ >y. GJ

iv) I of a neutral element 1. Z=Z-(=Z-14XEJ.

Examples

1) (R²: YES)

Mark (1A): TES

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$$A_1 = \begin{pmatrix} \alpha_1 & \alpha_2 \\ \alpha_3 & \alpha_4 \\ \alpha_5 & \alpha_6 \end{pmatrix}$$
 $A_1 + A_2 = \begin{pmatrix} \alpha_1 + b_1 & \alpha_2 + b_2 \\ \alpha_3 + b_3 & \alpha_7 + b_7 \end{pmatrix}$
 $A_1 = \begin{pmatrix} b_1 & b_2 \\ b_3 & b_7 \\ b_5 & b_6 \end{pmatrix}$
 $A_2 = \begin{pmatrix} b_1 & b_2 \\ b_3 & b_7 \\ b_5 & b_6 \end{pmatrix}$
 $A_3 = \begin{pmatrix} \lambda a_1 & \lambda a_1 \\ \lambda a_5 & \lambda a_6 \end{pmatrix}$
 $A_1 + A_2 = A_1 + (A_2 + A_3)$
 $A_1 + A_2 = A_1 + (A_1 + A_2)$
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 A

 $(\lambda \ell)A_1 = \lambda (\ell A_1).$

Vector Subspaces
Proposition (Subspace Criterion)
A non-empty subset U (U CU) of a vector
A non-empty subset $U(U\subset U)$ of a vector space of is a subspace of U if it setisfies:
i) Closure under addition
∀≥y∈W, z+y∈W.
ii) closure under scolor multiplication
$Y \times \in U$, then $\lambda \times \in U$.
m) existence of a noorigin vector of EU.
Ar =0
$(N(A)) = \{ \times : A \times = 0 \}$
X: A x1 =0. A.0 =0!
X2: Ax220.
A (X1+ X21=0
Xq. Ax120 ()

A XX1 = X0 20. (XXI) is also a solution. Ax=b (b + 0)Linear combination Let XI...., XK E J A linear combination is a vector + > Xx U= > 72 x2+.-= 5 x; x; 1 x; ell Span (X11 ... xk) = } > > 1 > 1 x1 + > 2 x2 ... + > 2 x k $\lambda_0, \dots, \lambda_k \in \mathbb{R}_{2}$ lemma let x... Xx be k vectors in J. Then Span (XI ... Xx) is a vector subspace of

$$\begin{array}{l}
x_1 = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
x_2 = \begin{bmatrix} 3 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
x_3 = \begin{bmatrix} 2 \\ 2 \end{bmatrix} \\
x_1 \\
x_2 \\
x_3 = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

$$\angle 2 = 3 \angle 1$$

$$A_{1} = \begin{pmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 1 \end{pmatrix} \qquad A_{2} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\begin{array}{c} -1 \\ -1 \\ \end{array} \begin{array}{c} 2 \\ 0 \\ 0 \\ \end{array} \begin{array}{c} 0 \\ 0 \\$$

$$\begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_1 \end{pmatrix} + \begin{pmatrix} 0 & \lambda_1 \\ \lambda_2 & 0 \\ 0 & \lambda_1 \end{pmatrix} + \begin{pmatrix} 0 & \lambda_2 \\ \lambda_2 & 0 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & \lambda_2 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & 0 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \\ 0 & \lambda_3 \end{pmatrix} - \begin{pmatrix} 0 & \lambda_2 \\ 0 & \lambda_3 \\ 0 & \lambda_3$$

Proposi from let z... Zx EJ be vectors. let u EU s.t. M & Span (XIII 71, ×2... 1 × × 1 W are linearly independent. Basis of vectors } XI... Xe from a basisis. 1) if \(\chi_1...\chi_2\) Span tom vector space U. ti) they are linearly independent.