<u>Agnirva Project Report</u>

Project Report Topic: Ethical Considerations in the Use of Robotics for Space Exploration

Internship Organisation: The Agnirva Space Internship program

Intern: Aryan Dnyaneshwar Wankhade.

Email: aryanwankhade0gmail.com

Date: **28-10-2024**

Table of Contents

- Introduction
- Exploration of hostile Environments
 - Role of Rovers in Planetary Exploration
 - Key Missions: Curiosity and Perseverance on mars
- Satellite servicing and Maintenance
 - Importance of Satellite Maintenance
 - Robotic Arms: The Canadarm2 on the ISS
 - Satellite Servicing Missions
- Assembly and Construction of Space Infrastructure
 - Role of Robots in ISS Assembly
 - Future Applications: Lunar and Martian Habitats
- Scientific Research on Celestial Bodies
 - Probes and Landers in Scientific Missions
 - o Case Study: Rosetta and Philae Mission
- Space Debris Management
 - Growing Concerns Over Space Debris
 - Active Debris Removal Missions
 - o Future Debris Management Technologies
- Future Prospects
 - Autonomous Robots for Future Exploration
 - o Potential for In-Situ Resource Utilisation (ISRU)
 - o Evolving Role of Space Robots in Human Space Expansion
- Conclusion
- Reference

Introduction

The exploration of space has historically relied on human ingenuity and increasingly on robotic systems to achieve more ambitious goals. With advancements in technology, space robots have become integral in performing complex tasks in hostile environments, enabling humanity to extend its reach into space. This report examines the primary functions of space robots and their contributions to various space missions.

• Exploration of Hostile Environments

One of the primary roles of space robots is to explore environments too extreme for humans. Notably, robotic rovers like NASA's *Curiosity* and *Perseverance* have explored Mars to analyse its soil, rocks, and atmosphere for signs of life. Equipped with advanced scientific tools, these rovers can traverse challenging terrains and relay crucial data to Earth, greatly expanding our understanding of the Martian environment. Their autonomous capabilities allow them to make navigation decisions, enabling scientists on Earth to focus on scientific objectives rather than micromanaging each movement.

Key Missions:

- Curiosity Rover (Mars Science Laboratory, NASA)
- Perseverance Rover (Mars 2020 Mission, NASA)

• Satellite Servicing and Maintenance

Space robots play a significant role in extending the life and capabilities of satellites. Robotic arms like the *Canadarm2* on the International Space Station (ISS) are used to perform repairs, upgrades, and capture visiting spacecraft. This servicing ability reduces the need for risky extravehicular activities (EVAs) by

astronauts, ensuring safety and maximising the operational life of valuable assets in space.

Key Missions:

- Canadarm2 on ISS (NASA/CSA)
- Robotic Refuelling Mission (NASA)

Assembly and Construction of Space Infrastructure

Space robots are crucial in the construction and maintenance of large structures in space, an ability critical for missions involving building habitats on celestial bodies. For example, the ISS was assembled with the help of robotic arms that pieced together its various modules in orbit. This assembly capability is key to future endeavors, such as the construction of space telescopes, lunar bases, and potential habitats on Mars.

Key Examples:

- ISS Assembly (NASA/ESA/Roscosmos/JAXA)
- Upcoming lunar and Martian habitats (conceptual)

• Scientific Research on Celestial Bodies

Robots are also deployed as probes, orbiters, and landers for in-depth scientific research. ESA's *Rosetta* mission, featuring the *Philae* lander, succeeded in landing on a comet and conducting unprecedented studies of its composition. These missions provide data that would be impossible for humans to gather due to distance, time, and environmental challenges.

Key Missions:

- Rosetta and Philae Lander (ESA)
- Voyager Probes (NASA)

• Space Debris Management

With the proliferation of satellites and space missions, space debris has become a significant concern. Space robots are being developed to address this problem by capturing and removing defunct satellites and other debris, minimising the risk of damaging operational spacecraft. These developments are essential to maintaining the safety and sustainability of space operations.

Key Examples:

- Active Debris Removal Missions (conceptual)
- ESA's ClearSpace-1 (planned mission for debris removal)

• Future Prospects

Future missions will likely involve even more sophisticated robots, with capabilities such as autonomous decision-making, in-situ resource utilization, and enhanced adaptability for building and maintaining human habitats on the Moon and Mars. The evolution of space robotics will expand human capabilities, allowing us to push deeper into space while minimizing risk to human life.

Conclusion

Space robots are indispensable in contemporary space exploration,

facilitating exploration, maintenance, construction, research, and space debris management. These machines enhance mission safety and efficiency, empowering humans to achieve ambitious objectives. With further advancements, space robots will continue to play an essential role in the pursuit of knowledge and the sustainable expansion of human activities in space.

• References:

- NASA Mars Missions: Curiosity and Perseverance Rovers
 https://science.nasa.gov/mission/msl-curiosity/
- International Space Station Assembly Missions, NASA and CSA

https://www.nasa.gov/international-space-station/s pace-station-facts-and-figures/

European Space Agency (ESA)

https://www.esa.int/