# <u>Agnirva Project Report</u>

Project Report Topic: Ethical Considerations in the Use of Robotics for Space Exploration

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Date: **31-10-2024** 

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#### Introduction

Space stations like the International Space Station (ISS) serve as critical platforms for scientific research and international collaboration in space. However, the unique challenges of assembling and maintaining a large structure in space demand specialized technology. Robotic systems, particularly robotic arms like the *Canadarm2* and *Dextre*, are vital to ensuring the construction and functionality of space stations, making them indispensable tools for the future of space infrastructure.

## Robotic Contribution to Space Station Construction

- Role of the Canadarm2 in ISS Assembly
  - The Canadarm2 is a 17-meter-long robotic arm on the ISS developed by the Canadian Space Agency (CSA). Its primary role is in assembling the station by capturing, moving, and attaching large modules and components with high precision. This allows the station to be constructed more safely and efficiently than would be possible through human labor alone.
- Advantages in Reducing Extravehicular Activities (EVAs)
  - One of the main benefits of using robotics in construction is the reduction in EVAs, commonly known as spacewalks. EVAs are resource-intensive and come with significant risk for astronauts. By enabling remote and autonomous task completion, robotics systems reduce the need for human exposure to the space environment and streamline the construction process.

# Maintenance of Space Stations Using Robotics

- Robotic Arms in Routine Maintenance and Repairs
- The ISS relies heavily on robotic systems like the Canadarm2 and Dextre for ongoing maintenance. These systems are utilized for inspections, repairs, and installation of new equipment. For instance, Dextre specializes in tasks such as battery replacement, instrument swapping, and performing detailed maintenance tasks that are challenging for human astronauts.
- Extended Operation Beyond Human Endurance

Space robots can work for long durations without the limitations associated with human endurance, making them ideal for complex and time-consuming tasks. Their ability to function continuously allows for efficient use of resources and minimizes risks associated with human limitations in the harsh space environment.

## • Robotic Inspection and Monitoring Capabilities

• Exterior Monitoring for Micrometeoroid and Debris Damage

Space robotics play a critical role in inspecting the station's exterior for damage caused by micrometeoroids and space debris. This ongoing surveillance ensures that any damage is detected early, allowing for timely repairs that protect both the station's integrity and the safety of its crew.

Preventative Measures and Repairs

By using robotic systems to identify and address structural weaknesses, small punctures, or other damage, space stations can be proactively maintained. This helps avoid escalation of minor issues into major safety concerns, demonstrating the importance of robotic inspection.

## Cargo Handling and Logistics

Unloading and Storage of Cargo

Space robots streamline the process of unloading and organizing supplies from cargo spacecraft. Robotic arms and automated systems can efficiently move cargo, reducing the physical workload on astronauts and allowing them to focus on scientific experiments and mission-critical tasks.

## • Enhancing Operational Efficiency

The automation of cargo management improves the operational flow within the confined space of the ISS, ensuring that supplies are easily accessible and securely stored. This orderly environment is crucial for effective mission operations and maintaining a productive workspace for the crew.

### Conclusion

Space robotics are essential to the construction, maintenance, inspection, and logistical operations of space stations. Systems like the *Canadarm2* and *Dextre* enhance mission efficiency, reduce risks for astronauts, and ensure the continuous functionality and safety of these complex structures. As the field of space robotics evolves, these technologies will enable even more ambitious projects, facilitating sustainable space exploration and human expansion into deeper space environments.

## • Future Prospects

The integration of advanced robotics in space operations is set to evolve

further. Emerging technologies, including autonomous robots capable of in-situ resource utilization (ISRU) and sophisticated maintenance tasks, are paving the way for more complex and sustainable space missions.

These advancements are essential for future habitats on the Moon and Mars, as well as the construction of large scientific structures in space.

#### • References:

- Canadian Space Agency (CSA) Documentation on the Canadarm2 and Dextre
- o NASA's International Space Station (ISS) Mission Reports
- Studies on Robotic Inspection and Debris Management in Space.