## SOC checkpoint 1

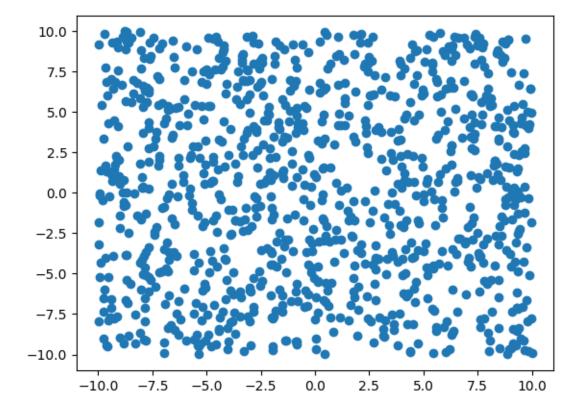
June 25, 2024

```
[1339]: import numpy as np
import matplotlib.pyplot as plt

[1340]: #multilayer perceptron

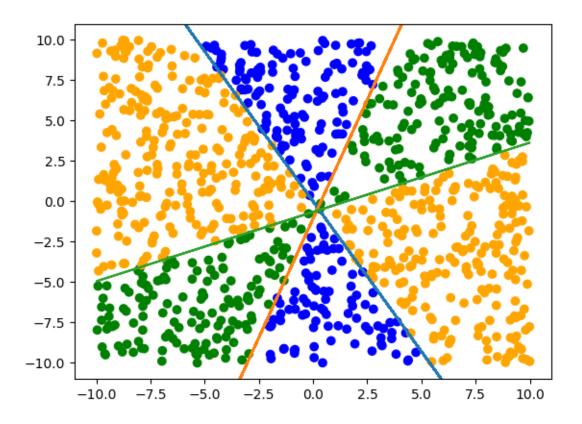
#creating dataset
x=np.random.uniform(-10,10,1000)
y=np.random.uniform(-10,10,1000)
plt.scatter(x,y)
```

[1340]: <matplotlib.collections.PathCollection at 0x16c43e8c0>



```
[1341]: #random bias
        b=np.random.uniform(-2,2,3)
        #random slopes
        w=np.random.uniform(-3,3,3)
        #creating labels
        labels=[]
        ylabels=[]
        for i in range(len(x)):
             if((w[0]*x[i]+b[0]<=y[i] \text{ and } w[1]*x[i]+b[1]<=y[i] \text{ and } w[2]*x[i]+b[2]<=y[i])_{\bot}
          \neg or (w[0]*x[i]+b[0]>=y[i] and w[1]*x[i]+b[1]>=y[i] and w[2]*x[i]+b[2]>=y[i])):
                 labels.append('blue')
             elif((w[0]*x[i]+b[0]>=y[i] \text{ and } w[1]*x[i]+b[1]<=y[i] \text{ and}_{\sqcup}
          \psi[2]*x[i]+b[2]<=y[i]) or (w[0]*x[i]+b[0]<=y[i] and (w[1]*x[i]+b[1])>=y[i]
          \rightarrowand w[2]*x[i]+b[2]>=y[i])):
                 labels.append('orange')
             else:
                 labels.append('green')
             if(labels[i]=='blue'):
                 ylabels.append(0)
             elif(labels[i] == 'green'):
                 ylabels.append(1)
             else:
                 ylabels.append(2)
        labels=np.array(labels)
        color=['blue','orange','green']
        yinlabels=np.array(ylabels)
        plt.scatter(x,y,color=labels)
        plt.plot(x,w[0]*x+b[0],label='line1')
        plt.plot(x,w[1]*x+b[1],label='line2')
        plt.plot(x,w[2]*x+b[2],label='line2')
        plt.ylim(-11,11)
        plt.xlim(-11,11)
```

[1341]: (-11.0, 11.0)



```
[1342]: #now making a classifier multi class perceptron to
        #estimate those lines just by giving input as scatterpoints and labels
        #2 feature input x,y
        # since there are 3 option we can go with a hidden linear layer with 3 nodes \Box
        ⇔and activation function as ReLU
        X=x,y # making input as one matrix
        X=np.transpose(X)
        print(yinlabels)
        yinlabels[:,np.newaxis]
        y0=[]
        for i in range(len(yinlabels)):
            if(yinlabels[i]==0):
                y0.append([1,0,0])
            elif(yinlabels[i]==1):
                y0.append([0,1,0])
            else:
                y0.append([0,0,1])
        ylabels=y0
        ylabels=np.array(ylabels)
        print(ylabels)
```

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[1343]: class hidden(object):
         def __init__(self):
            print('hidden layer constructor called')
            self.hidden=6
            self.labels=ylabels
         def params_init(self):
            self.nodes=6
            self.b=np.zeros(shape=(1,self.hidden))
            self.W=np.random.randn(self.hidden,2)
            self.dW=np.zeros(shape=(self.hidden,2))
            self.db=np.zeros(shape=(1,self.hidden))
```

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```
self.lr=0.0001
print("param_init_called")
return 1

def forward(self,X): # X: batch_size,2
    # return (batch_size,6)
    self.X=X
    return np.dot(X,self.W.T)+self.b

def backward(self,delta): # delta: batch_size,6
    self.dW= np.dot(np.transpose(delta),self.X)
    self.db= np.sum(delta,axis=0)
    return np.dot(delta,self.W)

def gd_update(self):
    self.W=self.W-np.multiply(self.lr,self.dW)
    self.b=self.b-np.multiply(self.lr,self.db)
```

```
[1344]: class hidden2(object):
            def __init__(self):
                print('hidden2 layer constructor called')
                self.hidden=6
                self.labels=ylabels
            def params init(self):
                self.nodes=3
                self.b=np.zeros(shape=(1,3))
                self.W=np.random.randn(3,self.hidden)
                self.dW=np.zeros(shape=(3,self.hidden))
                self.db=np.zeros(shape=(1,3))
                self.lr=0.0001
                print("param_init_called")
                return 1
            def forward(self,X): # X: batch_size,6
                # return (batch_size,6)
                self.X=X
                return np.dot(X,self.W.T)+self.b
            def backward(self,delta): # delta: batch size,6
                self.dW= np.dot(np.transpose(delta),self.X)
                self.db= np.sum(delta,axis=0).reshape(1,3)
                return np.dot(delta,self.W)
            def gd_update(self):
                self.W=self.W-(self.lr*self.dW)
                self.b=self.b-(self.lr*self.db)
```

```
[1346]: class softmax:
            def __init__(self, ylabels):
                print('Softmax constructor called')
                self.nodes = 3
                self.labels = ylabels
                self.softmax = None
            def forward(self, X):
                max_scores = np.max(X, axis=1, keepdims=True)
                exp scores = np.exp(X -max scores)
                self.softmax = exp_scores / np.sum(exp_scores, axis=1, keepdims=True)
                return self.softmax
            def backward(self,delta):
                return (self.softmax - self.labels)
[1347]: class crossentropy:
            def __init__(self):
                print("Cross Entropy constructor called")
                self.y_true = None
                self.y_pred = None
            def forward(self, y_pred, y_true):
                self.y_pred = y_pred
                self.y_true = y_true
                log_y_pred = np.log(y_pred + 1e-10) # Adding a small value to avoid_
         \hookrightarrow log(0)
                return -np.sum(y_true * log_y_pred) / y_pred.shape[0]
            def backward(self):
                return -self.y_true / (self.y_pred + 1e-10) # Adding a small value to_
         →avoid division by zero
[1348]: class Linking_Networks:
            def __init__(self,X,ylabels):
                print('Training Started')
                self.hidden = hidden()
                self.hidden.params_init()
                self.hidden2 = hidden2()
                self.hidden2.params_init()
                self.output = output()
                self.output.params_init()
                self.X=X
                self.labels=ylabels
```

```
self.softmax=softmax(ylabels)
    self.crossentropy=crossentropy()
def forward(self):
    hidden_layer_output=self.hidden.forward(self.X)
    hidden_layer_output2=self.hidden2.forward(hidden_layer_output)
    output1=self.output.forward(hidden_layer_output2)
    softmax output=self.softmax.forward(output1)
    output=self.crossentropy.forward(softmax_output,ylabels)
    return output
def backward(self):
    cross_back=self.crossentropy.backward()
    soft_back=self.softmax.backward(cross_back)
    out1=self.output.backward(soft_back)
    hidden2_back=self.hidden2.backward(out1)
    hidden_back=self.hidden.backward(hidden2_back)
    return hidden_back
def update(self):
    self.hidden2.gd_update()
    self.hidden.gd_update()
def forward test(self):
    hidden_layer_output=self.hidden.forward(self.X)
    hidden layer output2=self.hidden2.forward(hidden layer output)
    output1=self.output.forward(hidden_layer_output2)
    softmax_output=self.softmax.forward(output1)
    return softmax_output
```

```
[1349]: Model=Linking_Networks(X,ylabels)
for i in range(1000):
    loss=np.sum(Model.forward())
    if(i==0):
        print("initial loss:",loss)
# print(loss)
# print(Model.hidden.W)
    Model.backward()
    Model.update()
print('final loss:',loss)
```

Training Started hidden layer constructor called

param\_init\_called hidden2 layer constructor called param\_init\_called hidden2 layer constructor called param\_init\_called Softmax constructor called Cross Entropy constructor called initial loss: 10.669897920998176 final loss: 1.0459990733623967

## []: