

## Main Data Structures Used:

cache\_block: Holds one Cache Block

```
typedef struct cache_block {  
    unsigned long tag;  
    //char*      pData; //2^len_offset bytes of data.  
    int         valid; //Is theBlock valid  
    //int        dirty; //For write_back. Since we only use write through, not needed.  
} cache_block;
```

cache\_set: Holds one cache set. Including array of cache blocks and the index for First In First Out (FIFO) Replacement Algorithm.

```
typedef struct cache_set {  
    cache_block* pCacheBlock; //array of CacheBlock  
    int          index_to_be_reused; //For Replacement algorithm: First In First Out (FIFO)  
} cache_set;
```

counter: Holds the counters for cache performance.

```
typedef struct counter {  
    unsigned int    hit;  
    unsigned int    miss;  
    unsigned int    read;  
    unsigned int    write;  
} counter;
```

Cache\_Spec: Holds the specifications of the cache

```
typedef struct Cache_Spec {  
    int        cache_size;           //how many bytes in total of all blocks  
    int        cache_setsize;        //how many blocks in one set  
    int        block_size;           //how many bytes in one block  
    int        len_address;          //48 bits in this situation  
    int        number_of_blocks;     //# of blocks  
    int        number_of_sets;       //# of sets  
    int        len_offset;           //from block_size  
    int        len_index;            //from cache_setsize  
    int        len_tag;              //len_address - len_offset - len_index  
    int        start_offset;         //always 0  
    int        start_index;          //len_offset  
    int        start_tag;            //len_address - len_offset - len_index  
} Cache_Spec;
```

### Comparison of Type A and Type B cache:

In case of associative, A and B are identical as there is no index.

In all other cases, Type A has better performance than Type B.

In Type A, the index for the cache set is in the least significant bits after the offset. This means that consequent blocks will go to different cache sets. So, the caching is more evenly spread throughout all the cache sets. All cache sets are more heavily utilized.

In Type B, the index for the cache set are in the most significant bits. As a result, the memory is divided into number of sets ( $48\text{bits}: 2^{16} * 4G / \text{number\_of\_set} = 262,144G / \text{number\_of\_set}$ ) and each is assigned to one cache set. For all practical purposes, that means only one cache set is utilized. All other cache sets are idle.