

# Sketch: Accuracy vs. Corruption Probability in Pixel Replacement

## Setup

Let  $x \in [0, 1]^d$  be an input image and  $y \in \{1, \dots, 10\}$  the label. We define a corruption operator  $\mathcal{C}_p$  that independently replaces each pixel with probability  $p$ :

$$(\mathcal{C}_p(x))_i = \begin{cases} u_i, & \text{with probability } p, \\ x_i, & \text{with probability } 1 - p, \end{cases} \quad u_i \sim \text{Uniform}(0, 1).$$

Training uses corrupted inputs  $\tilde{x} = \mathcal{C}_p(x)$  and clean labels  $y$ . We study the test accuracy  $A(p)$  of a network trained at corruption strength  $p$ .

## Corruption as Attenuation + Noise

Let  $M_i \sim \text{Bernoulli}(p)$  and  $u_i \sim \text{Uniform}(0, 1)$ , independent. Then

$$\tilde{x} = (1 - M) \odot x + M \odot u.$$

Conditioned on  $x$ ,

$$\mathbb{E}[\tilde{x} | x] = (1 - p)x + \frac{p}{2}\mathbf{1}, \quad \text{Var}(\tilde{x}_i | x) = p(1 - p)(x_i - \frac{1}{2})^2 + \frac{p}{12}.$$

So corruption both shrinks the signal by  $(1 - p)$  and injects noise of scale  $\sqrt{p}$ .

For a generic scalar score function  $s(x)$  (e.g., a logit margin), a first-order expansion gives

$$s(\tilde{x}) \approx s(x) + \nabla_x s(x)^\top (\tilde{x} - x).$$

This is a local but exact linearization of the trained network. The gradient  $g(x) = \nabla_x s(x)$  is a measurable sensitivity vector.

## Margin Criterion for a Sharp Drop

Define the margin for example  $(x, y)$  as

$$\gamma(x) = f_y(x) - \max_{k \neq y} f_k(x),$$

where  $f_k$  is the logit for class  $k$ . A sufficient condition for label flip is  $\gamma(\tilde{x}) < 0$ . Using the linearization above,

$$\Delta\gamma \approx g(x)^\top (\tilde{x} - x).$$

Because the corruption is iid across pixels,  $\Delta\gamma$  concentrates with variance

$$\text{Var}(\Delta\gamma | x) \approx \sum_i g_i(x)^2 \text{Var}(\tilde{x}_i | x).$$

This suggests a threshold when typical fluctuations match the clean margin:

$$\gamma(x) \approx c \sqrt{\text{Var}(\Delta\gamma | x)}.$$

Aggregating over the data distribution yields a population-level crossover  $p^*$ . As model size increases, the margin distribution can shift and sharpen, causing a steeper drop in accuracy as  $p$  passes  $p^*$ .

## Finite-Size Scaling Hypothesis

Let  $A(p)$  be the test accuracy when training with corruption  $p$ . We hypothesize:

- **Shift:** the midpoint  $p^*$  of the accuracy drop increases with model size or data size, reflecting improved margins.
- **Sharpening:** the slope  $|A'(p^*)|$  increases with size, producing an apparently “critical” knee.
- **Collapse:** when plotted against an effective SNR proxy (e.g.,  $(1 - p)/\sqrt{p}$  or a measured margin-to-noise ratio), curves for different sizes align.

This is a finite-size crossover that can mimic a phase transition in the large-system limit.

## Testable Predictions

1. Fit  $A(p)$  with a sigmoid to estimate  $p^*$  and the slope; study scaling vs. width.
2. Compute  $g(x) = \nabla_x \gamma(x)$  on a held-out set; test whether  $\gamma(x)/\sqrt{\text{Var}(\Delta\gamma | x)}$  predicts failures.
3. Compare MLP vs. CNN: CNNs should tolerate larger  $p^*$  due to inductive bias.
4. Test curve collapse using an empirical SNR proxy derived from margins and gradients.