

CONSISTENCY CRITERIAN

A system of Linear algebraic equations $AX = B$ or $AX = 0$ is called consistent if it has a solution. Otherwise called inconsistent. For example

1. Consistency Criteria for the Non-Homogeneous System of Linear Equations

(a) When the system of linear equations $Ax = b$ is a square system and

- i. The Rank of $A = \text{Rank of } A_b = n$ (where n is number of unknowns or equations) then the system has unique solution.
- ii. The Rank of $A = \text{Rank } A_b < n$ then the system has infinite solutions.
- iii. The Rank $A \neq \text{Rank } A_b$ the system is said to be inconsistent and hence has no solution.

(b) When the system of linear equations $Ax = b$ is rectangular system and

- i. The Rank of $A = \text{Rank of } A_b$, then the system has an infinite number of solutions.
- ii. The Rank $A \neq \text{Rank } A_b$, then the system is said to be inconsistent and hence has no solution.

2. Consistency Criteria for Homogenous System of Linear Equations

(a) When the homogeneous system $Ax = 0$ is a square system and

- i. The Rank of matrix $A = n$, the system has only a trivial/zero solution.
- ii. The Rank $A < n$ then the system has infinite many solutions.

(b) When the homogeneous system $Ax = 0$ is a rectangular system and

- i. The Rank of $A = n$, where n is the number of unknowns or variables, then the system has an infinite solutions.

The following flowchart shows the systematic “*Consistency Criterion*” for the system of linear equations.



EXAMPLE 01: Show that the system of equations $2x + 6y = -11$, $6x + 20y - 6z = -3$, $6y - 18z = -1$ is not consistent ($m = n$).

Solution: The augmented matrix for the above system of equations is

$$A_b = \begin{bmatrix} 2 & 6 & 0 & -11 \\ 6 & 20 & -6 & -3 \\ 0 & 6 & -18 & -1 \end{bmatrix}.$$

Now we reduce the matrix into echelon form using elementary row operations:

$$A_b = \begin{bmatrix} 2 & 6 & 0 & -11 \\ 6 & 20 & -6 & -3 \\ 0 & 6 & -18 & -1 \end{bmatrix} R_2 + (-3)R_1 \approx \begin{bmatrix} 2 & 6 & 0 & -11 \\ 0 & 2 & -6 & 30 \\ 0 & 6 & -18 & -1 \end{bmatrix} \left(-\frac{1}{2} \right) R_2$$

$$\approx \begin{bmatrix} 2 & 6 & 0 & -11 \\ 0 & 1 & -3 & 15 \\ 0 & 6 & -18 & -1 \end{bmatrix} R_3 + (-6)R_2 \approx \begin{bmatrix} 2 & 6 & 0 & -11 \\ 0 & 1 & -3 & 15 \\ 0 & 0 & 0 & -91 \end{bmatrix}.$$

From the last matrix we can easily observe that $\text{Rank } A = 2$ and $\text{Rank } A_b = 3$.

$\therefore \text{Rank } A \neq \text{Rank } A_b$, (Since $0x + 0y + 0z = -91$, that is, $0 = -91$ is not possible.)

Therefore the given equations are “inconsistent”.

EXAMPLE 02: Discuss the consistency of the following system of equations

$$2x + 3y + 4z = 11, \quad x + 5y + 7z = 15, \quad 3x + 11y + 13z = 25.$$

If found consistent, solve it ($m = n$).

Solution: The augmented for the above system of equations is:

$$A_b = \begin{bmatrix} 2 & 3 & 4 & 11 \\ 1 & 5 & 7 & 15 \\ 3 & 11 & 13 & 25 \end{bmatrix}.$$

Now we reduce the matrix into echelon form using elementary row operations:

$$\begin{aligned} A_b &= \begin{bmatrix} 2 & 3 & 4 & 11 \\ 1 & 5 & 7 & 15 \\ 3 & 11 & 13 & 25 \end{bmatrix} R_{12} \\ &\approx \begin{bmatrix} 1 & 5 & 7 & 15 \\ 2 & 3 & 4 & 11 \\ 3 & 11 & 13 & 25 \end{bmatrix} R_2 + (-2)R_1, R_3 + (-3)R_1 \\ &\approx \begin{bmatrix} 1 & 5 & 7 & 15 \\ 0 & -7 & -10 & -19 \\ 0 & -4 & -8 & -20 \end{bmatrix} \left((-1)R_2, \left(-\frac{1}{4} \right)R_3 \right) \\ &\approx \begin{bmatrix} 1 & 5 & 7 & 15 \\ 0 & 7 & 10 & 19 \\ 0 & 1 & 2 & 5 \end{bmatrix} R_{23} \approx \begin{bmatrix} 1 & 5 & 7 & 15 \\ 0 & 1 & 2 & 5 \\ 0 & 7 & 10 & 19 \end{bmatrix} R_3 + (-7)R_2 \end{aligned}$$

$$\approx \begin{bmatrix} 1 & 5 & 7 & 15 \\ 0 & 1 & 2 & 5 \\ 0 & 0 & -4 & -16 \end{bmatrix} \left(-\frac{1}{4} \right) R_3 \approx \begin{bmatrix} 1 & 5 & 7 & 15 \\ 0 & 1 & 2 & 5 \\ 0 & 0 & 1 & 4 \end{bmatrix}.$$

From the last matrix we can easily observe that $\text{Rank } A = \text{Rank } A_b = 3$. Therefore the given system is consistent and has a unique solution. Also, we have

$$\begin{aligned} x + 5y + 7z &= 15 & (i) \\ y + 2z &= 5 & (ii) \\ z &= 4 & (iii) \end{aligned}$$

Solving, we have

$$x = 2, y = -3, z = 4$$

as a solution of the given system.

EXAMPLE 03: Test for consistency and solve the following system of linear equations

$$5x + 3y + 7z = 4, 3x + 26y + 2z = 9, 7x + 2y + 10z = 5 \quad (m = n)$$

Solution: The augmented for the above system of equations is:

$$A_b = \begin{bmatrix} 5 & 3 & 7 & 4 \\ 3 & 26 & 2 & 9 \\ 7 & 2 & 10 & 5 \end{bmatrix}.$$

Now we reduce the matrix into echelon form using elementary row operations:

$$\begin{aligned} A_b &= \begin{bmatrix} 5 & 3 & 7 & 4 \\ 3 & 26 & 2 & 9 \\ 7 & 2 & 10 & 5 \end{bmatrix} R_3 + (-2)R_2 \approx \begin{bmatrix} 5 & 3 & 7 & 4 \\ 3 & 26 & 2 & 9 \\ 1 & -50 & 6 & -13 \end{bmatrix} R_{13} \\ &\approx \begin{bmatrix} 1 & -50 & 6 & -13 \\ 3 & 26 & 2 & 9 \\ 5 & 3 & 7 & 4 \end{bmatrix} R_2 + (-3)R_1, R_3 + (-5)R_1 \\ &\approx \begin{bmatrix} 1 & -50 & 6 & -13 \\ 0 & 176 & -16 & 48 \\ 0 & 253 & -23 & 69 \end{bmatrix} \left(\frac{1}{16} \right) R_2, \left(\frac{1}{23} \right) R_3 \\ &\approx \begin{bmatrix} 1 & -50 & 6 & -13 \\ 0 & 11 & -1 & 3 \\ 0 & 11 & -1 & 3 \end{bmatrix} R_3 + (-1)R_2 \approx \begin{bmatrix} 1 & -50 & 6 & -13 \\ 0 & 11 & -1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}. \end{aligned}$$

From the last matrix we can easily observe that

$$\text{Rank } A = \text{Rank } A_b = 2 < 3 \rightarrow \text{No. of unknowns.}$$

Thus the system is “consistent having infinite solutions”. From the last matrix we have

$$x - 50y + 6z = -13 \quad (i)$$

$$11y - z = 3 \quad (ii)$$

From (ii), we have $y = (3 + z)/11$. Substituting it into (i), we have

$$x - \frac{50}{11}(3 + z) + 6z = -13 \rightarrow x - \frac{50}{11}z - \frac{150}{11} + 6z = -13$$

$$x + \left(\frac{-50 + 66}{11}\right)z = \frac{150}{11} - 13 \rightarrow x + \frac{16}{11}z = \frac{7}{11} \rightarrow x = \frac{1}{11}(7 - 16z).$$

Let $z = k$ then, $x = (7 - 16k)/11$, $y = (3 + k)/11$.

EXAMPLE 04: Examine the following system for a non-trivial solution ($m < n$)

$$x_1 - x_2 + 2x_3 + x_4 = 0$$

$$3x_1 + 2x_2 + x_4 = 0$$

$$4x_1 + x_2 + 2x_3 + 2x_4 = 0$$

Solution: The matrix of the coefficients is: $A = \begin{bmatrix} 1 & -1 & 2 & 1 \\ 3 & 2 & 0 & 1 \\ 4 & 1 & 2 & 2 \end{bmatrix}$.

Now we reduce the matrix into echelon form using elementary row operations:

$$A = \begin{bmatrix} 1 & -1 & 2 & 1 \\ 3 & 2 & 0 & 1 \\ 4 & 1 & 2 & 2 \end{bmatrix} R_2 + (-3)R_1, R_3 + (-4)R_1$$

$$\approx \begin{bmatrix} 1 & -1 & 2 & 1 \\ 0 & 5 & -6 & -2 \\ 0 & 5 & -6 & -2 \end{bmatrix} R_3 + (-1)R_2 \approx \begin{bmatrix} 1 & -1 & 2 & 1 \\ 0 & 5 & -6 & -2 \\ 0 & 0 & 0 & 0 \end{bmatrix} \left(\frac{1}{5}\right)R_2$$

$$\approx \begin{bmatrix} 1 & -1 & 2 & 1 \\ 0 & 1 & -6/5 & -2/5 \\ 0 & 0 & 0 & 0 \end{bmatrix} R_1 + R_2 \approx \begin{bmatrix} 1 & 0 & 4/5 & 3/5 \\ 0 & 1 & -6/5 & -2/5 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

The rank of A is $2 < 4$ (the number of variables), therefore, the system of equations is consistent having infinite number of “non-trivial solutions”. The first two rows of the last matrix give the following relations:

$$x_1 + \frac{4}{5}x_3 + \frac{3}{5}x_4 = 0 \quad (i)$$

$$x_2 - \frac{6}{5}x_3 - \frac{2}{5}x_4 = 0 \quad (ii)$$

From (i) and (ii), we have

$$x_1 = -\left(\frac{4}{5}x_3 + \frac{3}{5}x_4\right) \text{ and } x_2 = \frac{6}{5}x_3 + \frac{2}{5}x_4, \text{ where } x_3 \text{ and } x_4 \text{ are arbitrary.}$$

Let $x_3 = k_1$ and $x_4 = k_2$, then

$$x_1 = -\left(\frac{4}{5}k_1 + \frac{3}{5}k_2\right) \text{ and } x_2 = \frac{6}{5}k_1 + \frac{2}{5}k_2.$$

Hence, we have

$$x_1 = -\left(\frac{4}{5}k_1 + \frac{3}{5}k_2\right), \quad x_2 = \frac{6}{5}k_1 + \frac{2}{5}k_2, \quad x_3 = k_1 \text{ and } x_4 = k_2.$$

We can get an infinite number of solutions by giving different values to k_1 and k_2 .

EXAMPLE 05: Find the values of k such that the system of equations

$x + ky + 3z = 0$, $4x + 3y + kz = 0$, $2x + y + 2z = 0$
has a non – trivial solution (m = n).

Solution: The matrix of coefficients is

$$A = \begin{bmatrix} 1 & k & 3 \\ 4 & 3 & k \\ 2 & 1 & 2 \end{bmatrix}.$$

Now we reduce the matrix into echelon form using elementary row operations:

$$\begin{aligned} A &= \begin{bmatrix} 1 & k & 3 \\ 4 & 3 & k \\ 2 & 1 & 2 \end{bmatrix} R_2 + (-4)R_1, R_3 + (-2)R_1 \approx \begin{bmatrix} 1 & k & 3 \\ 0 & 3-4k & k-12 \\ 0 & 1-2k & -4 \end{bmatrix} R_2 + (-2)R_3 \\ &\approx \begin{bmatrix} 1 & k & 3 \\ 0 & 1 & k-4 \\ 0 & 1-2k & -4 \end{bmatrix} R_3 + \{(1-2k)\}R_2 \approx \begin{bmatrix} 1 & k & 3 \\ 0 & 1 & k-4 \\ 0 & 0 & 2k^2-9k \end{bmatrix}. \end{aligned}$$

For non – trivial solution $2k^2 - 9k = 0 \Rightarrow k(2k - 9) = 0 \Rightarrow k = 0$ or $k = \frac{9}{2}$.

The system has only trivial solution if $2k^2 - 9k \neq 0$

EXAMPLE 06: Determine for what values of λ and μ the following system of equations

$$x + y + z = 6, \quad x + 2y + 3z = 10, \quad x + 2y + \lambda z = \mu$$

has (i) no solution (ii) a unique solution (iii) infinite number of solutions.
 $R(A) \neq R(Ab)$ $R(A) = R(Ab) = n$ $R(A) = R(Ab) < n$

Solution: The augmented matrix for the above system of equations is:

$$A_b = \begin{bmatrix} 1 & 1 & 1 & 6 \\ 1 & 2 & 3 & 10 \\ 1 & 2 & \lambda & \mu \end{bmatrix}.$$

Now we reduce the matrix into echelon form using elementary row operations:

$$A_b = \begin{bmatrix} 1 & 1 & 1 & 6 \\ 1 & 2 & 3 & 10 \\ 1 & 2 & \lambda & \mu \end{bmatrix} \xrightarrow{R_2 + (-1)R_1, \quad R_3 + (-1)R_1} \begin{bmatrix} 1 & 1 & 1 & 6 \\ 0 & 1 & 2 & 4 \\ 0 & 1 & \lambda - 1 & \mu - 6 \end{bmatrix} \xrightarrow{R_3 + (-2)R_2} \begin{bmatrix} 1 & 1 & 1 & 6 \\ 0 & 1 & 2 & 4 \\ 0 & 0 & \lambda - 3 & \mu - 10 \end{bmatrix}.$$

(i) There is no solution if $\text{Rank } A \neq \text{Rank } A_b$

i.e. $\lambda - 3 = 0 \Rightarrow \lambda = 3$ and $\mu - 10 \neq 0 \Rightarrow \mu \neq 10$.

(ii) There is a unique solution if $\text{Rank } A = \text{Rank } A_b = 3$

i.e. $\lambda - 3 \neq 0 \Rightarrow \lambda \neq 3$ and μ may have any value.

(iii) There are infinite solutions if $\text{Rank } A = \text{Rank } A_b < 3$

i.e. $\lambda - 3 = 0 \Rightarrow \lambda = 3$ and $\mu - 10 = 0 \Rightarrow \mu = 10$.

EXAMPLE 7: For what value of λ the system of linear equations

$$(3 - \lambda)x_1 - x_2 + x_3 = 0$$

$$x_1 - (1 - \lambda)x_2 + x_3 = 0$$

$$x_1 - x_2 + (1 - \lambda)x_3 = 0$$

has a non-trivial solutions. Find these solutions.

Solution: The matrix of the coefficients is

$$A = \begin{bmatrix} (3-\lambda) & -1 & 1 \\ 1 & -(1-\lambda) & 1 \\ 1 & -1 & (1-\lambda) \end{bmatrix}.$$

We reduce this matrix to the echelon form by applying elementary row operations:

$$\begin{aligned} A &= \begin{bmatrix} (3-\lambda) & -1 & 1 \\ 1 & -(1-\lambda) & 1 \\ 1 & -1 & (1-\lambda) \end{bmatrix} R_{12} \\ &\approx \begin{bmatrix} 1 & -(1-\lambda) & 1 \\ (3-\lambda) & -1 & 1 \\ 1 & -1 & (1-\lambda) \end{bmatrix} R_2 + \{(3-\lambda)\}R_1, \quad R_3 + (-1)R_1 \\ &\approx \begin{bmatrix} 1 & -(1-\lambda) & 1 \\ 0 & 2-4\lambda+\lambda^2 & \lambda-2 \\ 0 & -\lambda & -\lambda \end{bmatrix} (-1)R_3 \\ &\approx \begin{bmatrix} 1 & \lambda-1 & 1 \\ 0 & 2-4\lambda+\lambda^2 & \lambda-2 \\ 0 & \lambda & \lambda \end{bmatrix} \left(\frac{1}{\lambda}\right)R_3; \quad \lambda \neq 0 \approx \begin{bmatrix} 1 & \lambda-1 & 1 \\ 0 & 2-4\lambda+\lambda^2 & \lambda-2 \\ 0 & 1 & 1 \end{bmatrix} R_{23} \\ &\approx \begin{bmatrix} 1 & \lambda-1 & 1 \\ 0 & 1 & 1 \\ 0 & 2-4\lambda+\lambda^2 & \lambda-2 \end{bmatrix} R_1 + \{-(\lambda-1)\}R_2, \quad R_3 + \left\{-\left(2-4\lambda+\lambda^2\right)\right\}R_2 \\ &\approx \begin{bmatrix} 1 & 0 & 2-\lambda \\ 0 & 1 & 1 \\ 0 & 0 & -4+5\lambda-\lambda^2 \end{bmatrix}. \end{aligned}$$

For non-trivial solutions rank of $A < 3$ (the number of unknowns), so we must have

$$-4+5\lambda-\lambda^2=0 \quad \text{or} \quad \lambda^2-5\lambda+4=0 \Rightarrow \lambda-4=0 \quad \text{or} \quad \lambda-1=0 \Rightarrow \lambda=1, 4.$$

Now when $\lambda=1$, then from the last matrix, we have

$$x_1 + x_3 = 0 \Rightarrow x_1 = -x_3 \quad \text{and} \quad x_2 + x_3 = 0 \Rightarrow x_2 = -x_3.$$

When $\lambda=4$,

$$x_1 - 2x_3 = 0 \Rightarrow x_1 = 2x_3 \quad \text{and} \quad x_2 + x_3 = 0 \Rightarrow x_2 = -x_3.$$

Hence, for $\lambda=1$, $x_1 = x_2 = -x_3$: for $\lambda=4$, $x_1 = 2x_3$, $x_2 = -x_3$.