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מרצה: פרופסור יוסף בן-עזרא

מגישים: טימור ליידרמן ואסף קסלסי

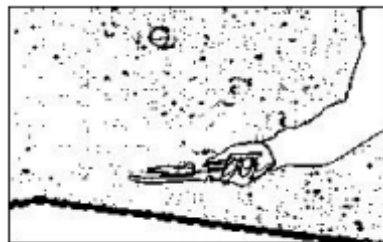
מכון טכנולוגי חולון
Holon Institute of Technology **Hit**

A New Algorithm Based Entropic Threshold for Edge Detection in Images

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Original image



Proposed method

Abstract

Edge detection is one of the most critical tasks in automatic image analysis. There exists no universal edge detection method which works well under all conditions. This paper shows the new approach based on the one of the most efficient techniques for edge detection, which is entropy-based thresholding. The main advantages of the proposed method are its robustness and its flexibility.

Edges are mostly detected using either the first derivatives, called gradient or the second derivatives, called Laplacien

-1	0	1
-2	0	2
-1	0	1

Horizontal

-1	-2	-1
0	0	0
-1	-2	-1

Vertical

0	-1	0
-1	4	-1
0	-1	0

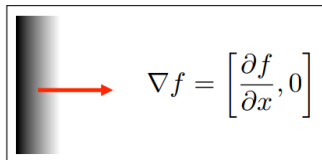
The laplacian operator

-1	-1	-1
-1	8	-1
-1	-1	-1

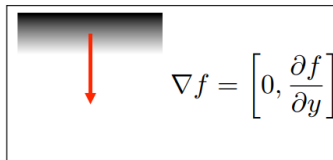
The laplacian operator (include diagonals)

Kernels used in the Sobel edge detection

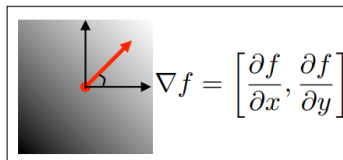
Gradient in x only



Gradient in y only



Gradient in both x and y



Gradient direction

$$\theta = \tan^{-1} \left(\frac{\partial f}{\partial y} / \frac{\partial f}{\partial x} \right)$$

Gradient magnitude

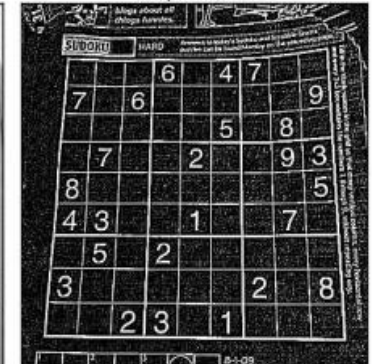
$$\|\nabla f\| = \sqrt{\left(\frac{\partial f}{\partial x}\right)^2 + \left(\frac{\partial f}{\partial y}\right)^2}$$



Original



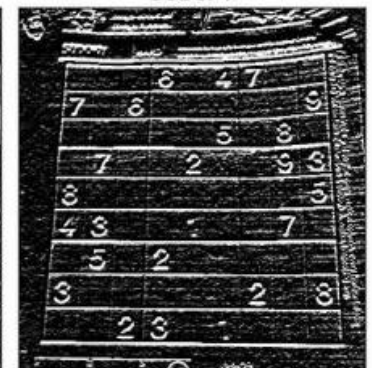
Laplacian



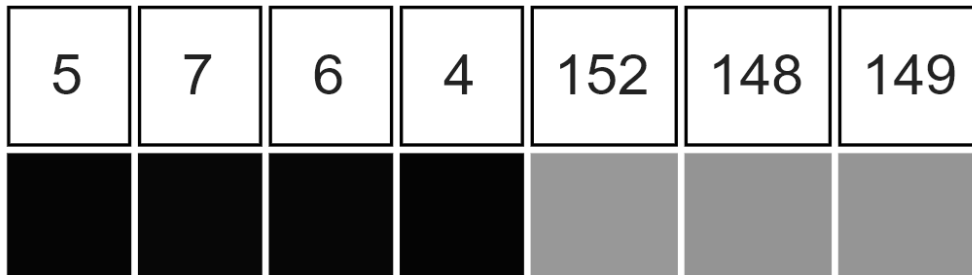
Sobel X



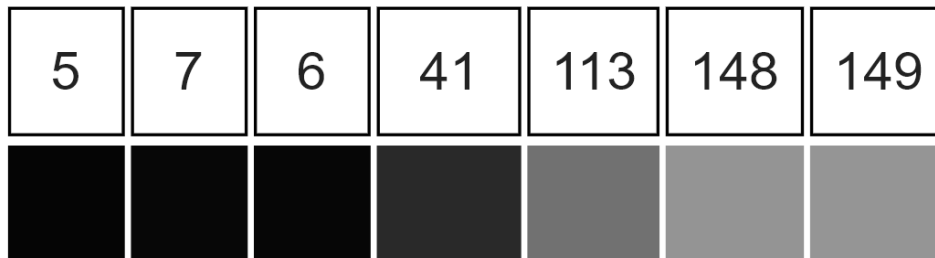
Sobel Y



To illustrate why edge detection is not a trivial task, consider the problem of detecting edges in the following one-dimensional signal. Here, we may intuitively say that there should be an edge between the 4th and 5th pixels.



If the intensity difference were smaller between the 4th and the 5th pixels and if the intensity differences between the adjacent neighboring pixels were higher, it would not be as easy to say that there should be an edge in the corresponding region. Moreover, one could argue that this case is one in which there are several edges.



histogram

An image histogram is a type of histogram that acts as a graphical representation of the tonal distribution in a digital image. It plots the number of pixels for each tonal value. By looking at the histogram for a specific image a viewer will be able to judge the entire tonal distribution at a glance

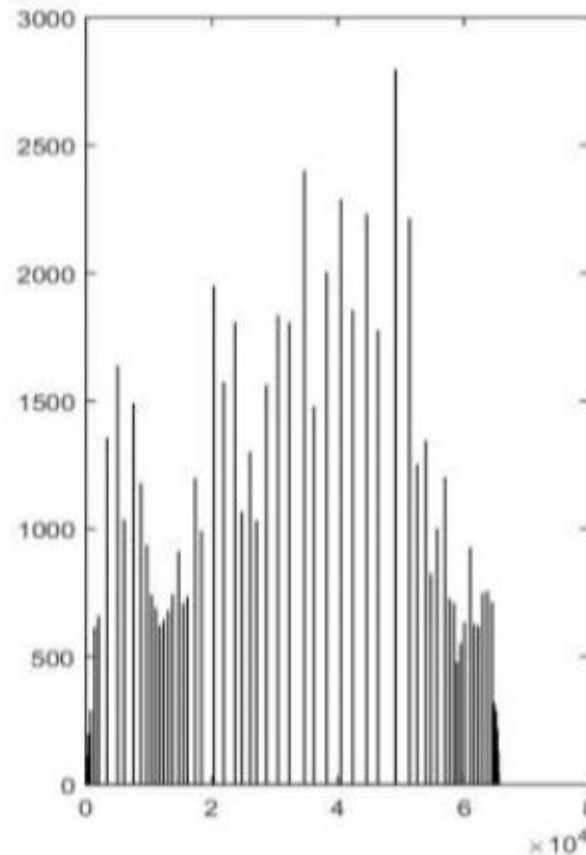


Image thresholding based on Shannon and Tsallis entropies

- ▶ Random event E that occurs with probability $P(E)$
- ▶ information content of E :

$$I(E) = \log\left(\frac{1}{P(E)}\right) = -\log(P(E))$$

- ▶ Let Alphabet $Z = \{z_1, z_2, z_3, \dots, z_k\}$
- ▶ Source symbol probability $P = \{p_1, p_2, p_3, \dots, p_k\}$
- ▶ This set of probabilities must satisfy the condition $\sum_{i=1}^k p_i = 1$

$$S(Z) = \sum_{i=1}^k p_i \log(p_i)$$

- ▶ If we consider that a system can be decomposed in two statistical independent subsystems A and B
- ▶ the Shannon entropy has the extensive property (additivity):
$$S(A + B) = S(A) + S(B)$$

- ▶ However, for non-extensive systems Tsallis has proposed a generalization of the (BGS) Boltzmann-Gibbs-Shannon statistics which is useful for describing the thermo statistical properties of non-extensive systems. It is based on a generalized entropic form

$$S_q = \frac{1}{q-1} \left(1 - \sum_{i=1}^k p_i^q \right)$$

- ▶ where the real number q is a entropic index that characterizes the degree of non-extensivity
- ▶ This expression recovers to BGS entropy in the limit $q \rightarrow 1$
- ▶ Tsallis entropy has a non-extensive property for statistical independent systems, defined by the following rule

$$S_q(A + B) = S_q(A) + S_q(B) + (1 - q) \cdot S_q(A) \cdot S_q(B)$$

- ▶ This generalization can be extended to image processing areas, specifically for the image segmentation, applying Tsallis entropy to threshold images, which have non-additive information content

- ▶ Let $p_i = p_1, p_2, p_3, \dots, p_k$ be the probability distribution for an image with k gray-levels.

- ▶ We derive two probability distributions

- ▶ (A - the object) , (B - the background)

- ▶ Given by: $p_A: \frac{p_1}{p_A}, \frac{p_2}{p_A}, \dots, \frac{p_t}{p_A}$, $\frac{p_{t+1}}{p_B}, \frac{p_{t+2}}{p_B}, \dots, \frac{p_k}{p_B}$ And where

$$p_A = \sum_{i=1}^t p_i \quad , p_b = \sum_{i=t+1}^k p_i$$

- ▶ The Tsallis entropy of order q for each distribution is defined as:

$$S_q^A(t) = \frac{1}{q-1} \left(1 - \sum_{i=1}^t p_A^q \right)$$

$$S_q^B(t) = \frac{1}{q-1} \left(1 - \sum_{i=t+1}^k p_B^q \right)$$

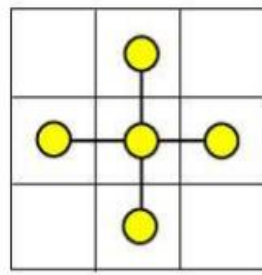
- ▶ When $S_q(t)$ is maximized, the luminance level t that maximizes the function is considered to be the optimum threshold value

$$t^*(q) = \arg_{t \in G} \max [S_q^A(t) + S_q^B(t) + (1-q) \cdot S_q^A(t) \cdot S_q^B(t)]$$

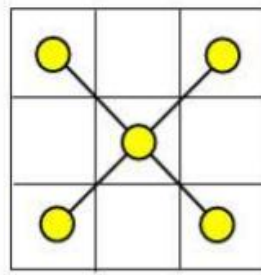
- ▶ When $q \rightarrow 1$ it will be equal to the same value found by shannons method

$$t^*(q) = \arg_{t \in G} \max [S_q^A(t) + S_q^B(t)]$$

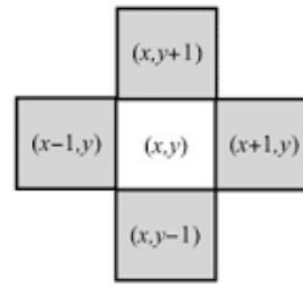
- ▶ we can choose value of q lies between 0 and 1



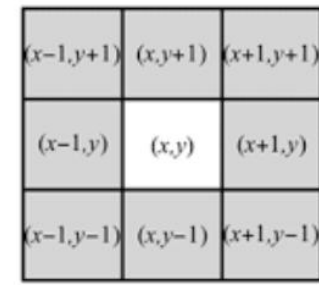
(a)



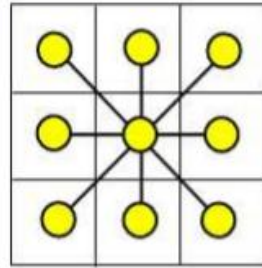
(b)



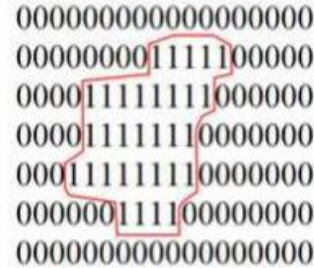
4-neighbourhood



8-neighbourhood



(c)



(d)

S

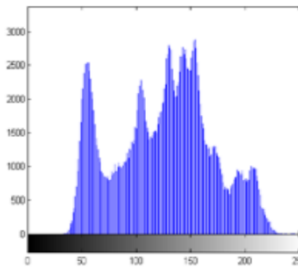
Fig. 1: (a) 4-connected, (b) Diagonal 4-connected, (c) 8-connected, and (d) Connected component.

P	S	P	S
$\frac{1}{9}$	0.10602	$\frac{6}{9}$	0.11739
$\frac{2}{9}$	0.14515	$\frac{7}{9}$	0.08489
$\frac{3}{9}$	0.15904	$\frac{8}{9}$	0.04546
$\frac{4}{9}$	0.15652	$\frac{9}{9}$	0
$\frac{5}{9}$	0.14181		

Algo Flow



Grayscale image $M \times N$



Probability distribution
(Histogram)



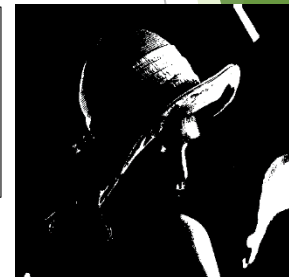
Calculate global
threshold
(shennon)

Calculate local threshold
for the object
(Tsalil)

Calculate local threshold
for the background
(Tsalil)

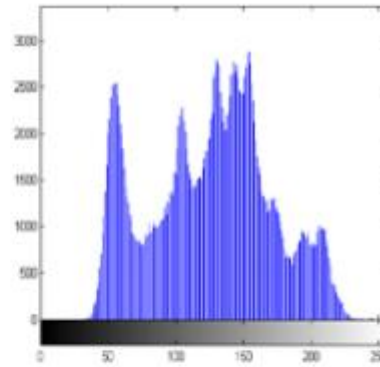
Calculate Binery Matrix

Edge detection





Original image



histogram



Canny method



LOG method



Sobel method



Proposed method

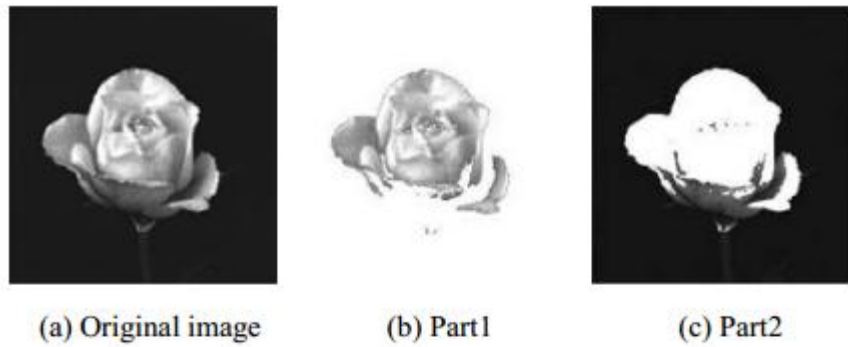


Fig. 2. Original image , and its parts, Part1 and Part2.

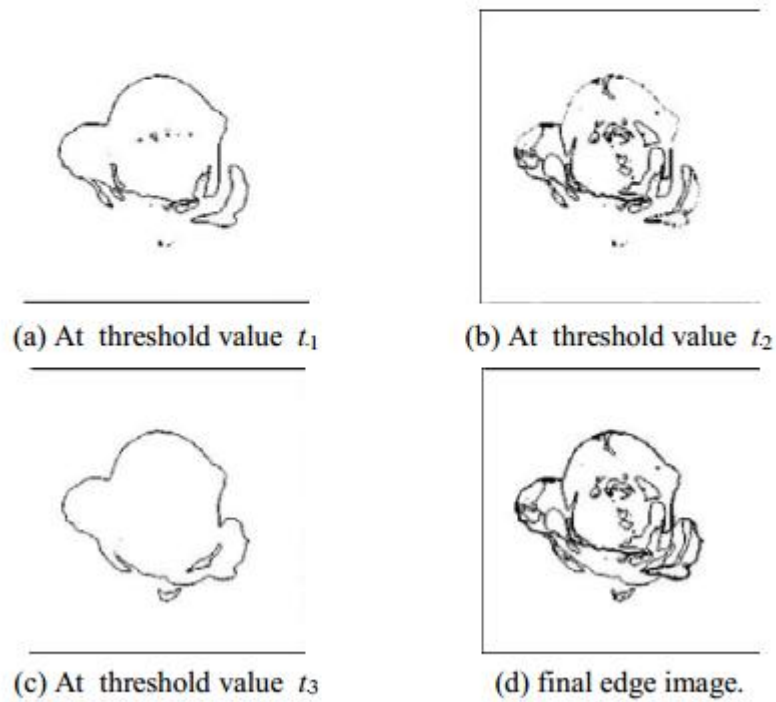
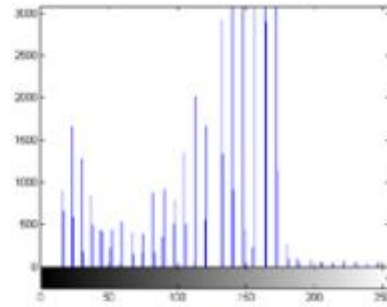


Fig. 3 Edge images of original image , its parts, Part1 and Part2 and final output of edge image



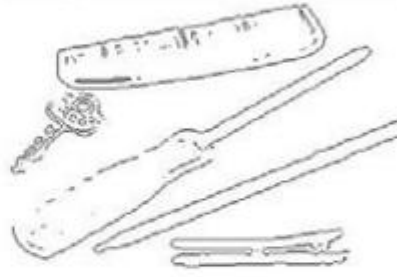
Original image



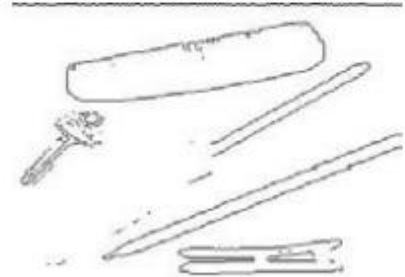
histogram



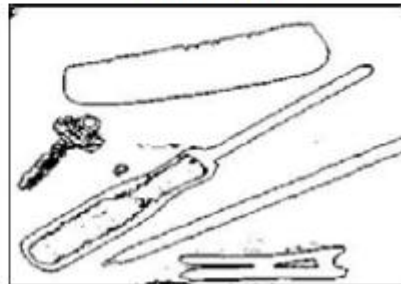
Canny method



LOG method



Sobel method



Proposed method

Fig. 10. Tools image with 322×228 pixel.

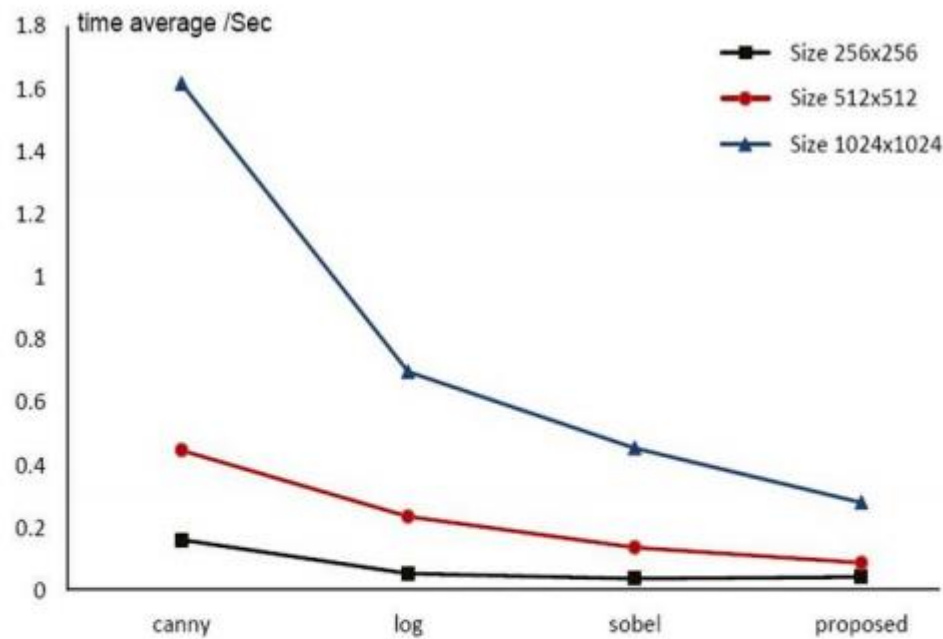


Fig. 4: Run time of Canny, LOG, Sobel, and proposed method with different size test images

Results

- ▶ Experimental results demonstrate that the proposed method achieves better result than some classic methods and the quality of the edge detector of the output images is robust and decrease the computation time

Thank you