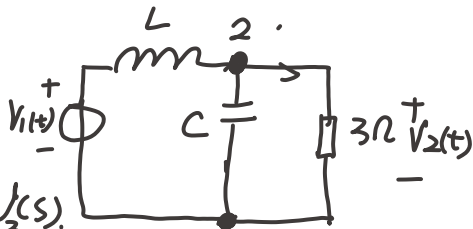


专题1. 10-1-1

$$\begin{cases} U_2(s) = U_C(s) \\ \frac{U_2(s) - U_1(s)}{sL} = C s U(s) + \frac{U_2(s)}{3} \end{cases}$$



我是根据  
节压法得到的

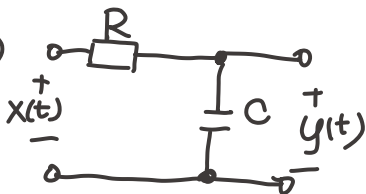
$$U_2(s) \left( \frac{1}{sL} + \left( s + \frac{1}{3} \right) \right) = \frac{U_1(s)}{sL}$$

$$\begin{aligned} \frac{U_2(s)}{U_1(s)} &= \frac{\frac{1}{sL}}{\frac{1}{sL} + \left( s + \frac{1}{3} \right)} = \frac{1}{1 + \left( s^2 L + \frac{1}{3} s L \right)} \\ &= \frac{1}{1 + s + s^2} \end{aligned}$$

$$\begin{cases} \frac{1}{3} L = 1 \\ CL = 1 \end{cases} \Rightarrow \begin{cases} L = 3 \\ C = \frac{1}{3} \end{cases}$$

10-1-3 既考了方程 又考响应和零极点图

$$\begin{aligned} (1) \quad X(s) + i_C(s) R &= Y(s) \\ i_C(s) &= C s U_C(s) \\ &= C s Y(s) \end{aligned}$$



$$\therefore X(s) - R C s Y(s) = Y(s) \Rightarrow \text{写成?}$$

$$(2) \quad H(s) = \frac{Y(s)}{X(s)} = \frac{1}{1 + R C s} = \frac{1}{1 + 2s} = \frac{1}{2} \cdot \frac{1}{\frac{1}{2} + s}$$

$$x(t) u(t) = u(t) + 2 \cos 2t u(t)$$

$$\mathcal{F}(x(t) u(t)) = \frac{1}{s} + 2 \frac{s}{s^2 + 4}$$

$$= \frac{S^2 + 4 + 2S}{S(S^2 + 4)} \quad \frac{1}{\frac{1}{2} + j2} =$$

$H(j\omega) = \frac{1}{2} \cdot \frac{1}{\frac{1}{2} + j\omega}$  对一个复指数周期信号  
(3) 用正弦稳态去做  $= \frac{1}{1 + 2j\omega}$

$$x(t) = 1 + 2 \frac{e^{2jt} + e^{-2jt}}{2} = 1 + e^{2jt} + e^{-2jt}$$

$$|H(j2)| = \frac{1}{2} \cdot \frac{1}{\sqrt{\frac{1}{4} + 4}} = \frac{1}{2} \cdot \frac{1}{\sqrt{\frac{17}{4}}} = \frac{1}{\sqrt{17}}$$

$$\therefore H(j\omega) = \frac{1 - 2j\omega}{1 + 4\omega^2} \quad |H(j0)| = 1.$$

$$\varphi(j2) = \arctan\left(\frac{1 - 4j}{1 + 16}\right) = \arctan(-4) = -75.96^\circ$$

$$y(t) = 1 |H(j0)| + \frac{2}{\sqrt{17}} \cos(2t - \arctan 4)$$

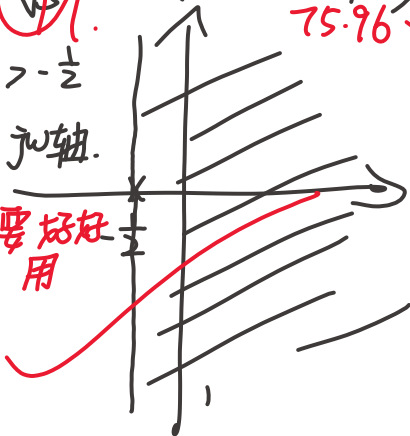
$\downarrow$  不用对t求导

$$= 1 + \frac{2}{\sqrt{17}} \cos(2t - 75.96^\circ)$$

(4). ROC  $\text{Re}\{s\} > -\frac{1}{2}$

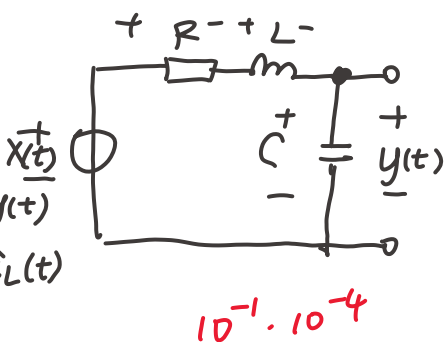
稳定. 因为包含  $j\omega$  轴.

差不多. 正弦稳定要好好用



10-1-4

$$\begin{aligned}
 (1) \quad & y(t) = u_C(t) \\
 & x(t) = u_R(t) + u_L(t) + y(t) \\
 & i_C(t) = C \frac{du_C(t)}{dt} = i_L(t) \\
 & u_L(t) = L \frac{di_L(t)}{dt}
 \end{aligned}$$



$$x(t) = R \cdot C \frac{dy(t)}{dt} + LC \frac{d^2 y(t)}{dt^2} + y(t)$$

变换域:  $X(s) = RCs Y(s) + LCs^2 Y(s) + Y(s)$

$$\therefore H(s) = \frac{Y(s)}{X(s)} = \frac{1}{RCs + LCs^2 + 1}$$

$$(2) \quad H(s) = \frac{1}{R \cdot 0.1m s + 10^{-5} s^2 + 1}$$

别给自己找一堆麻烦.

≠ 实数极点. 则  $\Delta = (R \cdot 0.1m)^2 - 4 \cdot 10m < 0$

$$H(s) = \frac{1}{R \cdot 10^{-4} s + 10^{-5} s^2 + 1}$$

$$= \frac{10^5}{s^2 + 10RS + 10^5}$$

$$H(s) = \frac{10^5}{(s-s_1)(s-s_2)}$$

$$s = \frac{-10R \pm \sqrt{100R^2 - 4 \times 10^5}}{2}$$

$$= R^2 \cdot 0.01m - 40m < 0$$

$$R^2 < 4000$$

算对了只是凑巧

$$\therefore \Delta = 100R^2 - 4 \times 10^5 < 0$$

$$R^2 - 4 \times 10^3 < 0$$

$$\therefore 0 < R < \sqrt{4000}$$

这样证明是不够的

① 对实信号.  $X(t) = X^*(t)$ .

$$X(s) = X^*(s^*)$$

也就是 如  $s_1$  是零点  $X(s_1) = 0$

$$X^*(s_1^*) = 0 = X(s_1^*)$$

因为首先 0 是个实值, 共轭是其本身.  $s_1^*$  也为  
 $s_1$  是极点.  $\therefore X(s_1) = \infty = X^*(s_1^*) = \infty$  零点.

$\infty$  的含义是距离上的无穷远, 所以共轭肯定也在  
 无穷远处.  $\therefore s_1^*$  也是极点.

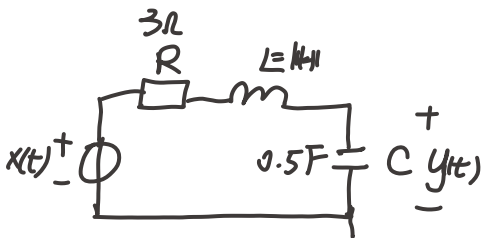
说明了共轭之定理是: 零极点, 总共轭存在 (对实信号)

10-1-6  $R=3$

$$(1). \dot{v}_C(t) = C \frac{dy(t)}{dt}$$

$$u_L = L \frac{di_C(t)}{dt}$$

$$= LC \frac{d^2 y(t)}{dt^2}$$



$$v_C(0^-) = 1.$$

$$v_C'(0^-) = 2.$$

$$\therefore X(t) = \dot{v}_C(t) R + u_L(t) + y(t)$$

变换域.  $X(s) = RCs Y(s) + LCs^2 Y(s) + Y(s).$

$$\therefore H(s) = \frac{Y(s)}{X(s)} = \frac{1}{RCs + LCs^2 + 1}$$

$$\text{代入 } H(s) = \frac{1}{1.5s + 0.5s^2 + 1} = \frac{2}{s^2 + 3s + 2}$$

$$= 2 \cdot \left( \frac{1}{s+1} - \frac{1}{s+2} \right) \quad \text{ROC} \quad \text{Re}(s) > -1$$

$$\cdot h(t) = 2 \cdot (e^{-t} - e^{-2t}) u(t)$$

(2)

$$\text{微分. } 0.5 \frac{d^2 y(t)}{dt^2} + 1.5 \frac{dy(t)}{dt} + y(t) = x(t)$$

$$(3) \quad y(t) = y_{zi}(t) + y_{zs}(t)$$

$$= y_{zi}(t) + x(t) * h(t)$$

$$\therefore x(t) = e^{-3t} u(t), \quad X(s) = \frac{1}{s+3} \quad \text{ROC: } \text{Re}(s) > -3$$

$$\cdot y_{zs}(t) = \mathcal{L}^{-1} \left\{ \frac{1}{s+3} \left( \frac{1}{s+1} - \frac{1}{s+2} \right) \right\}$$

$$= \mathcal{L}^{-1} \left[ \frac{1}{2} \left( \frac{1}{s+1} - \frac{1}{s+3} \right) - \frac{1}{s+2} + \frac{1}{s+3} \right]$$

$$= 2 \cdot \left\{ \frac{1}{2} (e^{-t} - e^{-3t}) - e^{-2t} + e^{-3t} \right\} u(t)$$

$$= (e^{-t} - e^{-3t} - 2e^{-2t} + 2e^{-3t}) u(t)$$

$$= \underline{(e^{-t} - 2e^{-2t} + e^{-3t}) u(t)}$$

$$y_{zi}''(t) + 3y_{zi}'(t) + 2y_{zi}(t) = 0$$

$$\text{对单边 L 变换. } y'(t) \xrightarrow{\mathcal{L}} sY(s) + y(0)$$

$$y'(t) \xrightarrow{\mathcal{L}} sY(s) + \underline{sy(0^-)} + \underline{y'(0^-)}$$

$$\cdot s^2 Y(s) + \underline{-(2+s)} + 1 + 2s + 3(sY(s) + 1) + 2Y(s) = 0 \quad \text{为什么不对}$$

$$\cdot \quad Y(s) (s^2 + 3s + 2) + 1 + 2s + 3 = 0 \quad \begin{matrix} s+5 \\ -s-4 \end{matrix}$$

$$Y(s) = \frac{-2}{(s+2)(s+1)}$$

$$\therefore Y(s) = \frac{-2}{s+1} \quad \therefore y_{zi}(t) = -2e^{-t}u(t)$$

$$\cdot \quad y(t) = -2e^{-t}u(t) + (e^{-t} - 2e^{-2t} + e^{-3t})u(t)$$

$$= (-e^{-t} - 2e^{-2t} + e^{-3t})u(t)$$

$$y_{zi}(t) = Ae^{-2t} + Be^{-t}$$

↓  
这个解  $y_{zi}(t)$  的方法是没有问题的。  
顺便证明为什么会是那样。

$$\int_{0^-}^{+\infty} y'(t) e^{-st} dt =$$

$$= \frac{-3}{s+2} + \frac{+4}{s+1} \Rightarrow y_{zi}(t) = (3e^{-2t} + 4e^{-t})u(t)$$

$$(+3e^{-2t} - 5e^{-2t} + e^{-3t})u(t)$$

$$y'(t) \xleftrightarrow{uL} sY(s) - y(0^-)$$

$$\int_{0^-}^{+\infty} y'(t) e^{-st} dt = \int_{0^-}^{+\infty} y'(t) e^{-st} dt + y(0^-)$$

我们是能求的。

我们实际要的是

$$\int_{0^-}^{+\infty} e^{-st} dy(t) = y(t)e^{-st} \Big|_{0^-}^{+\infty} + s \int_{0^-}^{+\infty} y(t)e^{-st} dt$$

$$= -y(0^-) + s \int_0^-^{+\infty} y(t) e^{-st} dt = y(0^-) + sY(s)$$

$$\text{证} \int_0^-^{+\infty} e^{-st} y''(t) dt = \int_0^-^{+\infty} e^{-st} dy'(t)$$

$$= e^{-st} y'(t) \Big|_0^-^{+\infty} + s \int_0^-^{+\infty} e^{-st} dy(t)$$

$$= -y'(0^-) + s \left( y(t) e^{-st} \Big|_0^-^{+\infty} + s \int_0^-^{+\infty} e^{-st} y(t) dt \right)$$

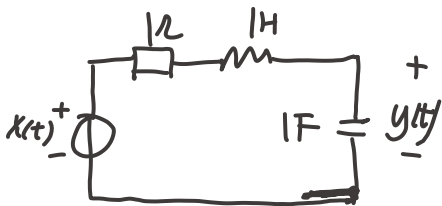
$$= \underline{-y'(0^-) + s[-y(0^-)] + s^2 Y(s)}$$

### 10-1-7 滤波特性

$$1) X(t) = i_C(t) \cdot R + u_L(t)$$

$$u_L(t) = LC \frac{d^2 y(t)}{dt^2} + y(t)$$

$$i_C(t) = C \frac{dy(t)}{dt}$$

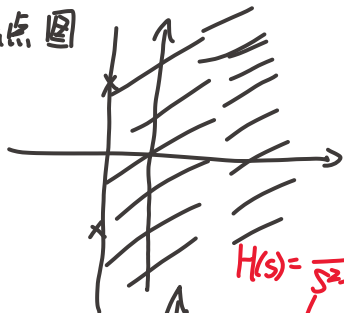


$$\text{变换域} \quad X(s) = CsR Y(s) + LCs^2 Y(s) + Y(s)$$

$$\begin{aligned} \therefore H(s) &= \frac{Y(s)}{X(s)} = \frac{1}{1 + CRS + Lcs^2} \\ &= \frac{1}{1 + s + s^2} \end{aligned}$$

$$s^2 + s + 1 = 0 \quad s = \frac{-1 \pm \sqrt{3}j}{2}$$

极点图



因果系统

ROC:  $\text{Re}\{s\} > \frac{1}{2}$

$$H(j\omega) = \frac{1}{1 + j\omega + (-\omega^2)}$$

$$H(s) = \frac{1}{s^2 + s + 1} = \frac{1}{(s + \frac{1}{2})^2 + \frac{3}{4}}$$

没必要

(2)



当  $\omega = \pm \frac{\sqrt{3}}{2}$  时,  $|H(j\omega)|$  最大  
是带通的. 低通的

(3).  $R = 10^{-2} \Omega$

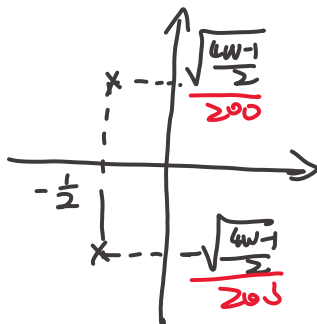
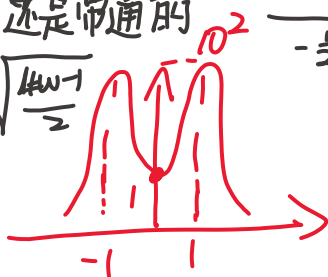
$$H(s) = \frac{1}{1 + 10^{-2}s + s^2}$$

$$= \frac{1}{100s^2 + s + 100}$$

$$s = \frac{-1 \pm \sqrt{1 - 400}}{200}$$

$|H(j\omega)|$  还是带通的

$$\omega = \sqrt{\frac{400-1}{2}}$$



$$\frac{1}{100s^2 + s + 100}$$



决定对 10-1-7 重新梳理

$H(s) = \frac{1}{s^2 + s + 1}$  得到之后, 为了从零极点图得到幅频特性图, 不妨用  $H(s)$  什数寻找极值

$$H(s) = \frac{1}{(s + \frac{1}{2})^2 + \frac{3}{4}} \quad \operatorname{Re}(s) > -\frac{1}{2}$$

再代入  $s = j\omega$ .

$$H(j\omega) = \frac{1}{(j\omega + \frac{1}{2})^2 + \frac{3}{4}}$$

$$= \frac{1}{-\omega^2 + 1 + j\omega}$$

$$|H(j\omega)| = \frac{1}{\sqrt{\omega^2 + (1 - \omega^2)^2}} = \frac{1}{\sqrt{\omega^4 - \omega^2 + 1}} \quad \text{当 } \omega^2 = \frac{1}{2} \text{ 时.}$$

即  $\omega = \pm \frac{\sqrt{2}}{2}$  时  $|H(j\omega)|_{\max}$ .

$|H(j \pm \frac{\sqrt{2}}{2})| = \frac{2}{\sqrt{3}}$  其实  $|H(j\omega)| = \frac{1}{\sqrt{1 - \omega^2 + \omega^4}}$  可以定性知道幅频, 但不可以定量. 定量老老实实搞函数

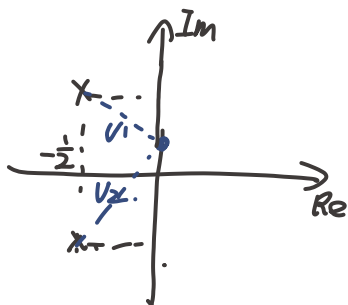
(3).  $H(s) = \frac{1}{-s^2 + 1 + 0.01j\omega}$  可以先定性

发现  $\omega \rightarrow \infty \quad |H(j\omega)| \rightarrow 0$

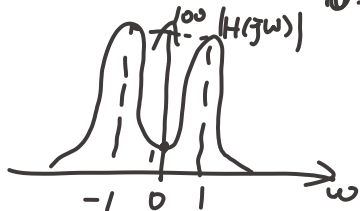
$\omega \rightarrow 0 \quad |H(j\omega)| \rightarrow 1$

$$|H(j\omega)| = \frac{1}{\sqrt{(-\omega^2 + 1)^2 + 10^{-4}\omega^2}} \quad \text{还是令 } \omega^2 = (-2 + 10^{-4})$$

$$\omega = \sqrt{\frac{2 - 10^{-4}}{2}} \approx 1$$



此时  $H(j\omega) \approx \frac{1}{0.01} = 100$



10-1-13. (1)

$$y(t) = L \frac{di_L(t)}{dt}$$

$$i_L(t) = \frac{1}{L} \int y(t) dt$$

$$C \frac{dy(t)}{dt} + i_L(t) + \frac{y(t)}{R_2} = \frac{x(t) - y(t)}{R_1}$$

$$\therefore i_L(s) = \frac{1}{s} \cdot \frac{1}{L} Y(s)$$

$$Cs Y(s) + \frac{1}{sL} Y(s) + \frac{1}{R_2} Y(s) = \frac{X(s) - Y(s)}{R_1}$$

$$\therefore Y(s) \left( 0.5s + \frac{10}{s} + 2 \right) = X(s)$$

$$\frac{Y(s)}{X(s)} = H(s) = \frac{1}{0.5s + \frac{10}{s} + 2} = \frac{2s}{s^2 + 4s + 20}$$

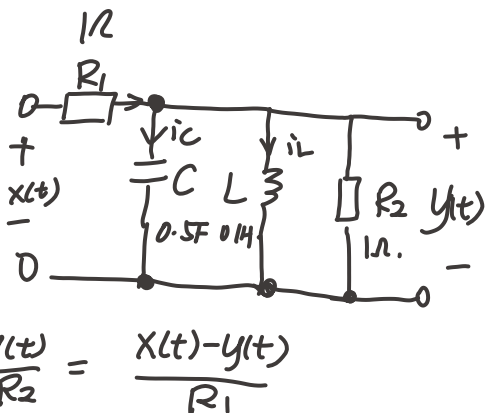
$$= \frac{2s}{(s+2)^2 + 16} = \frac{2s}{(s+2)^2 + 4^2}$$

ROC:

$$\therefore \cos(4t) u(t) \xrightarrow{f} \frac{4}{s^2 + 4^2}$$

$$\sin(4t) u(t) \xrightarrow{f} \frac{s}{s^2 + 4^2}$$

$$\frac{\text{Re}(s) > -2}{\text{不稳定}}$$



$$\checkmark \because e^{-2t} X(t) \xleftrightarrow{q} X(s+2)$$

$$h(t) = \mathcal{L}^{-1} \left[ \frac{2(s+2)}{(s+2)^2 + 4} \right] \quad \text{形式不动}$$

$$= e^{-2t} (2\cos 4t - \sin 4t) u(t)$$

↓  
留S.可自推.

$$(3) \quad H(j\omega) = \frac{2j\omega}{-\omega^2 + 4j\omega + 20}$$

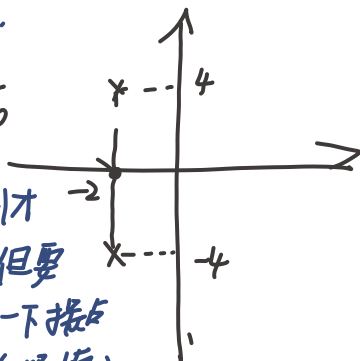
$$= \frac{2j\omega}{(j\omega + 2)^2 + 4}$$

这种相比网才  
其实不好算 但要

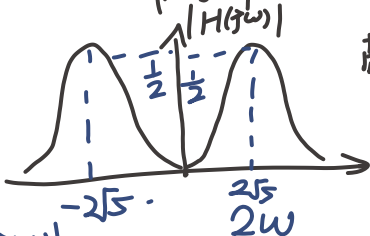
$$\text{当 } \omega \rightarrow 0 \quad |H(j\omega)| \rightarrow 0$$

$$\omega \rightarrow \infty \quad |H(j\omega)| \rightarrow 0$$

算一下拐点  
(极值)



$$0 < \omega < \infty \quad |H(j\omega)| \neq 0$$



带通

4π

$$|H(j\omega)| = \frac{2\omega}{\sqrt{(20-\omega^2)^2 + 16\omega^2}} = \frac{2\omega}{\sqrt{400 - 40\omega^2 + \omega^4 + 16\omega^2}}$$

$$\therefore \frac{400}{\omega^2} + \omega^2 - 24 \geq 16$$

ω = 2√5 时  
±

$$\leq \frac{2}{\sqrt{16}} = \frac{1}{2}$$

$$= \frac{2}{\sqrt{\frac{400}{\omega^2} - 24 + \omega^2}}$$

10-2-2  $R_1 = 30\Omega$   $R_2 = 10\Omega$

