Networking and concurrency

Haskell and Cryptocurrencies

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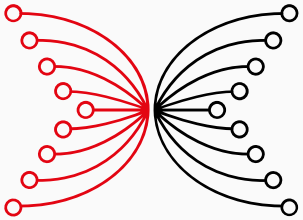
August, 2023



INPUT | OUTPUT

Goals

- Introduce `forkIO`.
- Explain the typical server pattern.
- Software Transactional Memory.

Concurrency vs. Parallelism

Concurrency

Language constructs that support structuring a program as if it had many independent threads of control.

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Language constructs that support structuring a program as if it had many independent threads of control.

- Necessarily involves some amount of side effects.
- Pre-dates and is independent of multicore.
- Can be used to implement parallelism, but is not the only way to do so.

Parallelism

Running (parts of) programs in parallel on multiple cores (or nodes), in order to speed up the program.

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Running (parts of) programs in parallel on multiple cores (or nodes), in order to speed up the program.

- Primary goal is speed, not structure.
- Does not make sense without multiple cores / parallel hardware.
- Does not conceptually require side effects.
- In fact, deterministic results are preferable.

Today

We will only talk about concurrency, primarily in the context of implementing a network server.

Concurrency

Before we start: mini exercise

Implement a simple function that, given an `Int`, returns an `IO`-action which will forever print that number onto the console, once per line:

```haskell
numberForever :: Int -> _  -- return type?
numberForever n = error "TODO: implement me!"
```

```
GHCi> numberForever 42
42
42
42
 ...
```

Forking lightweight threads

```haskell
import Control.Concurrent
data ThreadId  -- abstract
forkIO :: IO () -> IO ThreadId
```

Observations on `forkIO`

- Given computation is started in a separate (Haskell) thread.
- Haskell threads are lightweight and very cheap, *much* cheaper than OS threads.
- Haskell threads can use multiple cores if they are available, but thousands of threads can happily run concurrently on a single core.
- The `ThreadId` is a handle on the thread that can be used to send signals to the thread.

The `-threaded` flag

GHC gives you the choice between two versions of the run-time system:

- By default, you will get a simpler RTS that is restricted to a single OS thread and therefore, a single core.
- If you pass `-threaded` to GHC, you will get a more complex RTS that can use many OS threads and many cores.

Both run-time systems support `forkIO` just fine.

Example

```haskell
main :: IO ()
main = do
  mapM_ (forkIO . numberForever) [1..10]
  thread 0
```

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main = do
  mapM_ (forkIO . numberForever) [1..10]
  thread 0
```

- Numbers are printed in nondeterministic order depending on scheduling decisions of the run-time system.
- All threads are killed if the main thread is killed.
- In GHCi, the main thread is the thread running GHCi itself!

Delaying a thread

```haskell
second :: Int
second = 1000000  -- delays measured in microseconds

thread :: Int -> IO ()
thread n = forever $ do
  print n
  threadDelay (second `div` 10)

main :: IO ()
main = do
  mapM_ (forkIO . thread) [1..10]
  threadDelay (5 * second)
```

Waiting does not keep the CPU busy.

Networking

A “shouting” server

```
main :: IO ()
main = listen (Host "127.0.0.1") "8765" $ \(socket, addr) -> do
  putStrLn $ "listening on: " ++ show addr
  forever $
    void $ acceptFork socket $ \(socket', addr') -> do
      putStrLn $ "accepted client: " ++ show addr'
      h <- socketToHandle socket' ReadWriteMode
      handleClient h
```

```
handleClient :: Handle -> IO ()
handleClient h = do
  hSetBuffering h LineBuffering
  forever $ do
    line <- hGetLine h
    hPutStrLn h $ toUpper <$> line
```

Can be tested using `telnet` or `nc`.

The server pattern

```haskell
main :: IO ()
main = listen… $ \(socket, addr) -> do
  putStrLn $ "listening on: " ++ show addr
  forever $
    void $ acceptFork socket $
      \(socket', addr') -> do
        handleClient …
```

- Endless `accept` loop.
- Fork a new thread for every client.

Threads and exceptions

```haskell
handleClient :: Handle -> IO ()
handleClient h = do
  hSetBuffering h LineBuffering
  forever $ do
    line <- hGetLine h
    hPutStrLn h (map toUpper line)
```

Once the client closes the connection, `hGetLine` will fail with an exception:

- default exception handler will print the exception,
- but only that thread will be terminated.

A corresponding client

```haskell
main :: IO ()
main = connect "127.0.0.1" "8765" $ \(socket, _) -> do
  h <- socketToHandle socket ReadWriteMode
  void $ forkIO $ copyByLine h stdout
  copyByLine stdin h
```

```haskell
copyByLine :: Handle -> Handle -> IO ()
copyByLine from to = forever $ do
  line <- hGetLine from
  hPutStrLn to line
```

Communication between threads

Communication methods

Shared memory

- All threads can access the same memory and communicate by modifying and inspecting mutable variables.
- Very convenient (if large amounts of data are shared).
- Potentially risky (race conditions, ...).

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Message passing

- Communication via messages sent between threads.
- More overhead if large amounts of data are shared.
- Less risky.

Haskell in principle supports both models.

Today, we'll look at shared memory.

Excursion: mutable variables

```haskell
import Data.IORef

data IORef a  -- abstract

newIORef    :: a -> IO (IORef a)
readIORef   :: IORef a -> IO a
writeIORef  :: IORef a -> a -> IO ()
```

Note: `IORef`s can store delayed computations.

Modifying an `IORef`

```
modifyIORef :: IORef a -> (a -> a) -> IO ()
modifyIORef ref f = do
  old <- readIORef ref
  writeIORef ref (f old)
```

(This function is also in the library.)

Example

```
GHCi> r <- newIORef 3
GHCi> readIORef r
3
GHCi> modifyIORef r (+ 1)
GHCi> readIORef r
4
GHCi> writeIORef r 7
GHCi> readIORef r
7
```

Laziness example

```
GHCi> r <- newIORef 3
GHCi> modifyIORef r (`div` 0)
GHCi> readIORef r
*** Exception: divide by zero
```

Modifying an `IORef` strictly

```haskell
modifyIORef' :: IORef a -> (a -> a) -> IO ()
modifyIORef' ref f = do
  old <- readIORef ref
  writeIORef ref $! f old
```

```haskell
($!) :: (a -> b) -> a -> b
f $! (!x) = f x

infixr 0 $!
```

Laziness example revisited

```
GHCi> r <- newIORef 3
GHCi> modifyIORef' r (`div` 0)
*** Exception: divide by zero
```

Communicating via `IORef`s is dangerous

```haskell
thread :: IORef Int -> Int -> IO ()
thread var n = forever $ do
  writeIORef var n
  x <- readIORef var
  when (x /= n) $ print (x, n)

main :: IO ()
main = do
  var <- newIORef 0
  mapM_ (forkIO . thread var) [1..10]
  threadDelay (5 * second)
```

At least with `-threaded -N2`, this will produce output.

Atomic modification

```
atomicModifyIORef' ::
  IORef a -> (a -> (a, b)) -> IO b
```

- Function is applied to current value.
- First component of result will become new value.
- Second component of result is returned.
- Whole operation is performed atomically, without other threads interfering.
- Function forces the value in the `IORef` and the value returned to WHNF.

`IORef`s and concurrency

- The presence of `atomicModifyIORef'` allows modifications of a single `IORef` in a predictable way.
- But operations involving several `IORef`s at once will always be unpredictable.

Classic example: transfer money (mini exercise)

Implement a function `transfer` that "transfers" the given amount from the first given account to the second given account:

```
type Account = IORef Integer
```

```
transfer :: Account -> Account -> Integer -> IO ()
transfer from to amount =
  error "TODO: implement me!"
```

```
GHCi> [a1, a2] <- mapM newIORef [1000, 2000]
GHCi> transfer a1 a2 100
GHCi> mapM readIORef [a1, a2]
[900, 2100]
```

Stress-testing the example

```haskell
main :: IO ()
main = do
  accs <- mapM newIORef [1000, 2500]
  total <- getTotal accs
  print total
  forkIO $ monitor total accs
  replicateM_ 100000
    (forkIO (randomTransfer accs))
  threadDelay (5 * second)  -- horrible!!
```

Stress-testing the example (contd.)

```haskell
getTotal :: [IORef Integer] -> IO Integer
getTotal accs = sum <$> mapM readIORef accs
```

```haskell
randomTransfer :: [IORef Integer] -> IO ()
randomTransfer xs = do
  let maxIndex = length xs - 1
  from   <- randomRIO (0, maxIndex)
  to     <- randomRIO (0, maxIndex)
  amount <- randomRIO (- 100, 100)
  transfer (xs !! from) (xs !! to) amount
```

Stress-testing the example (contd.)

```
monitor :: Integer -> [IORef Integer] -> IO ()
monitor expected accs = forever $ do
  actual <- getTotal accs
  when (actual /= expected) $
    print $ "INVALID STATE: expected "
       ++ show expected
       ++ ", but have "
       ++ show actual
```

`MVar`s

- The traditional solution to the problem we have just seen is *locks*.
- You can use this approach in Haskell, too, by using `MVar`'s from module `Control.Concurrent.MVar`.
- We will (probably) look at `MVar`s in much more detail later. For the time being, however, we will look at *Software Transactional Memory* instead.

Software Transactional Memory

A lock-free approach to concurrency

Haskell's `stm` package offers an appealing approach to concurrency:

- transactions are guaranteed to be run atomically;
- the type system guarantees that transactions can be safely restarted;
- there are no locks, hence no danger of deadlocks;
- transactional computations are easy to compose, unlike classic lock-based approaches.

`Control.Concurrent.STM` interface

```
data STM a  -- abstract
instance Monad STM
data TVar a  -- abstract

  -- transactional variables
newTVar     :: a -> STM (TVar a)
newTVarIO   :: a -> IO (TVar a)
readTVar    :: TVar a -> STM a
writeTVar   :: TVar a -> a -> STM ()

  -- running a transaction
atomically :: STM a -> IO a
```

Note that `STM` is a restricted form of `IO`.

Classic example: transfer money

Library helper function:

```
modifyTVar :: TVar a -> (a -> a) -> STM ()
modifyTVar var f = do
  x <- readTVar var
  writeTVar var (f x)
```

Transfer function:

```
transfer :: Num a => TVar a -> TVar a -> a -> STM ()
transfer from to amount = do
  modifyTVar from (\ x -> x - amount)
  modifyTVar to   (\ x -> x + amount)
```

Stress-testing the example

```haskell
main :: IO ()
main = do
  accs <- mapM newTVarIO [1000, 2500]
  total <- atomically $ getTotal accs
  print total
  forkIO $ monitor total accs
  replicateM_ 100000
    (forkIO (randomTransfer accs))
  threadDelay (5 * second)  -- horrible!!
```

Stress-testing the example (contd.)

```haskell
getTotal :: [TVar Integer] -> STM Integer
getTotal accs = sum <$> mapM readTVar accs
```

```haskell
randomTransfer :: [TVar Integer] -> IO ()
randomTransfer xs = do
  let maxIndex = length xs - 1
  from   <- randomRIO (0, maxIndex)
  to     <- randomRIO (0, maxIndex)
  amount <- randomRIO (- 100, 100)
  atomically $
    transfer (xs !! from) (xs !! to) amount
```

Stress-testing the example (contd.)

```
monitor :: Integer -> [TVar Integer] -> IO ()
monitor expected accs = forever $ do
  actual <- atomically $ getTotal accs
  when (actual /= expected) $
    print $ "INVALID STATE: expected "
       ++ show expected
       ++ ", but have "
       ++ show actual
```

Associating `IO` with transactions

We cannot do IO within a transaction, but we can perform IO after a transaction:

- Compute the data necessary to perform the IO within the transaction and return that from the transaction.

Associating `IO` with transactions

We cannot do IO within a transaction, but we can perform IO after a transaction:

- Compute the data necessary to perform the IO within the transaction and return that from the transaction.
- Because `IO` is first-class data in Haskell, we can even compute the action itself.

Example

```
transfer ::
  TVar Integer -> TVar Integer
   -> Integer -> STM (IO ())
transfer from to amount = do
  current <- readTVar from
  if current < amount
    then return $ putStrLn "not ok"
    else do
      modifyTVar from (\ x -> x - amount)
      modifyTVar to   (\ x -> x + amount)
      return $ putStrLn $ "ok: " ++ show amount
```

Note that `return` is used on something of type `IO ()` here.

Example (contd.)

```haskell
randomTransfer :: [TVar Integer] -> IO ()
randomTransfer xs = do
  let maxIndex = length xs - 1
  from   <- randomRIO (0, maxIndex)
  to     <- randomRIO (0, maxIndex)
  amount <- randomRIO (- 100, 100)
  log    <- atomically $
              transfer (xs !! from) (xs !! to) amount
  log  -- execute the logging action after the transaction
```

Another useful monad combinator

From `Control.Monad`:

```
join :: Monad m => m (m a) -> m a
join mma = do
  ma <- mma
  ma
```

Rewriting the example using `join`

```haskell
randomTransfer :: [TVar Integer] -> IO ()
randomTransfer xs = do
  let maxIndex = length xs - 1
  from   <- randomRIO (0, maxIndex)
  to     <- randomRIO (0, maxIndex)
  amount <- randomRIO (- 100, 100)
  join $ atomically $
    transfer (xs !! from) (xs !! to) amount
```

Retrying or combining transactions

```haskell
retry  :: STM a
orElse :: STM a -> STM a -> STM a
```

Retrying or combining transactions

```
retry  :: STM a
orElse :: STM a -> STM a -> STM a
```

A `retry` does not actually rerun the transaction unless some of the inputs have changed.

An `orElse` tries the second computation only if the first retries.

Example

```haskell
transfer ::
  TVar Integer -> TVar Integer ->
  Integer -> STM (IO ())
transfer from to amount = do
  current <- readTVar from
  when (current < amount) retry
  modifyTVar from (\ x -> x - amount)
  modifyTVar to   (\ x -> x + amount)
  return $ putStrLn $ "ok: " ++ show amount
```

A `retry` example

```haskell
main :: IO ()
main = do
  accs@[a1, a2, a3] <-
    mapM newTVarIO [1000, 2500, 5000]
  join $ atomically $ transfer a1 a3 2000
  mapM_ ((>>= print) . readTVarIO) accs
```

This will block indefinitely!

A `retry` example (contd.)

```
transfer' ::
      TVar Integer
   -> TVar Integer
   -> TVar Integer
   -> Integer
   -> STM (IO ())
transfer' from from' to amount =
  transfer from to amount `orElse`
  transfer from' to amount
```

A `retry` example (contd.)

```
main :: IO ()
main = do
  accs@[a1, a2, a3] <-
    mapM newTVarIO [1000, 2500, 5000]
  join $ atomically $ transfer' a1 a2 a3 2000
  mapM_ ((>>= print) . readTVarIO) accs
```

This will work just fine!

Asynchronous computations

Revisiting the horrible hack

```
main :: IO ()
main = do
  accs <- mapM newTVarIO [1000, 2500]
  total <- atomically $ getTotal accs
  print total
  forkIO $ monitor total accs
  replicateM_ 100000
    (forkIO (randomTransfer accs))
  threadDelay (5 * second)  -- horrible!!
```

We cannot easily wait for all threads to finish.

Why not?

Haskell threads are kept a lightweight as possible.

All additional functionality can and should be built on top when needed.

Transactions again?

We could solve this via more `TVar`s:

- Use a `TVar Bool` to indicate whether a thread is finished.
- Initialize all such `TVar`s to `False`.
- Let the thread set it to `True` when done.
- Have a transaction check all `TVar`s to be `True` and otherwise call `retry`.

Introducing `async`

Fortunately, all this is already done in the `async` package:

```
import Control.Concurrent.Async

async :: IO a -> IO (Async a)  -- an improved forkIO
wait  :: Async a -> IO a
```

Using `async` and `wait`

```haskell
main :: IO ()
main = do
  accs <- mapM newTVarIO [1000, 2500]
  total <- atomically $ getTotal accs
  print total
  forkIO $ monitor total accs
  asyncs <- replicateM 100000
    (async (randomTransfer accs))
  mapM_ wait asyncs
```

Useful helper functions in the library

```
replicateConcurrently  :: Int -> IO a -> IO [a]
replicateConcurrently_ :: Int -> IO a -> IO ()
```

Both of these block until all computations are done.

Using `replicateConcurrently_`

```
main :: IO ()
main = do
  accs <- mapM newTVarIO [1000, 2500]
  total <- atomically $ getTotal accs
  print total
  forkIO $ monitor total accs
  replicateConcurrently_ 100000
    (randomTransfer accs)
```

Asynchronous exceptions and exceptions

Recall:

- If an exception in a thread is triggered but not caught, the thread will be stopped, but the parent will not know.

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- If an exception in a thread is triggered but not caught, the thread will be stopped, but the parent will not know.

With `Async`:

- If an exception in a thread is triggered but not caught, the thread will be stopped and the exception will propagate to the parent once it calls `wait`.

More flexibility

- If the thread itself wants to handle exceptions, it can just catch them.
- The parent can choose to handle propagated exceptions in any way it likes.

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- If the thread itself wants to handle exceptions, it can just catch them.
- The parent can choose to handle propagated exceptions in any way it likes.

The parent can also kill asynchronous computations explicitly:

```
cancel :: Async a -> IO ()
```

This will only return once the computation has actually stopped.