

# Anikait Singh

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## Education

### Stanford University

PhD in Computer Science

Palo Alto, CA

Sept. 2023 - Present

**Advisor:** Professor Chelsea Finn

**Close Collaborators:** Professor Aviral Kumar, Professor Tatsunori Hashimoto

**Research Focus:** Methods for decision making that are able to leverage diverse data sources and enable scaling.

### University of California, Berkeley

Bachelor of Arts in Computer Science

Berkeley, CA

Aug. 2019 - May. 2023

**GPA:** 3.986, **Technical GPA:** 4.0

Highest Distinction in General Scholarship

**Selected Coursework:** Machine Learning, Deep Learning, Deep Reinforcement Learning, AI, Probability/Random Processes, Convex Optimization, Natural Language Processing, Information Theory, Graduate Probability Theory, Speech Recognition

**Organizations:** UPE, UCB Sikh Student Association, Berkeley Legends

## Publications

- [1] **Preference Fine-Tuning of LLMs Should Leverage Suboptimal, On-Policy Data** [Paper] [Website]  
Anikait Singh\*, Fahim Tajwar\*, Archit Sharma, Rafael Rafailov, Jeff Schneider, Tengyang Xie, Stefano Ermon, Chelsea Finn, Aviral Kumar  
International Conference on Machine Learning (ICML), 2024
- [2] **D5RL: Diverse Datasets for Data-Driven Deep Reinforcement Learning**  
Rafael Rafailov\*, Kyle Beltran Hatch\*, Anikait Singh, Aviral Kumar, Laura Smith, Ilya Kostrikov, Philippe Hansen-Estruch, Victor Kolev, Philip J. Ball, Jiajun Wu, Sergey Levine, Chelsea Finn  
Reinforcement Learning Conference (RLC), 2024
- [3] **Robotic Offline RL from Internet Videos via Value-Function Pre-Training** [Paper]  
Chethan Bhateja\*, Derek Guo\*, Dibya Ghosh\*, Anikait Singh, Manan Tomar, Quan Vuong, Yevgen Chebotar, Sergey Levine, Aviral Kumar
- [4] **Open X-Embodiment: Robotic Learning Datasets and RT-X Models** [Paper]  
Open X-Embodiment Collaboration  
IEEE International Conference on Robotics and Automation (ICRA), 2024.
- [5] **RT-2: Vision-Language-Action Models Transfer Web Knowledge to Robotic Control** [Paper]  
Google DeepMind Robotics  
Conference on Robot Learning (CoRL), 2023.
- [6] **Offline RL With Realistic Datasets: Heteroskedasticity and Support Constraints** [Paper]  
Anikait Singh\*, Aviral Kumar\*, Quan Vuong, Yevgen Chebotar, Sergey Levine  
Conference on Neural Information Processing Systems (NeurIPS), 2023
- [7] **Cal-QL: Calibrated Offline RL Pre-Training for Efficient Online Fine-Tuning** [Paper]  
Mitsuhiko Nakamoto\*, Yuexiang Zhai\*, Anikait Singh, Yi Ma, Chelsea Finn, Aviral Kumar, Sergey Levine  
Conference on Neural Information Processing Systems (NeurIPS), 2023
- [8] **Pre-Training for Robots: Offline RL Enables Learning New Tasks from a Handful of Trials** [Paper]  
Aviral Kumar\*, Anikait Singh\*, Frederik Ebert\*, Yanlai Yang, Chelsea Finn, Sergey Levine  
Robotic Science and Systems (RSS), 2023 (*Acceptance rate: 20.6%*)
- [9] **Should I Run Offline Reinforcement Learning or Behavioral Cloning?** [Paper] [Blog]  
Aviral Kumar\*, Joey Hong\*, Anikait Singh, Sergey Levine  
International Conference on Learning Representations (ICLR), 2022.
- [10] **A Workflow for Offline Model-Free Robotic Reinforcement Learning** [Paper] [Talk]  
Aviral Kumar\*, Anikait Singh\*, Stephen Tian, Chelsea Finn, Sergey Levine  
Conference on Robot Learning (CoRL), 2021 (*Oral Presentation*). (*Acceptance rate: 6.5%*)
- [11] **A Mobile Application for Keyword Search in Real-World Scenes** [Paper]  
Shrinivas Pundlik\*, Anikait Singh\*, Gautam Baghel, Vilte Baliutavičiute, Gang Luo  
IEEE Journal of Translational Engineering in Health and Medicine (IEEE), 2019.

## Preprints

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- [1] **Improving Test-Time Search with Backtracking Against In-Context Value Verifiers**  
Anikait Singh, Kushal Arora, Sedrick Keh, Jean Mercat, Tatsu Hashimoto, Chelsea Finn, Aviral Kumar  
In Submission to International Conference on Machine Learning (ICML), 2025
- [2] **Few-Shot Preference Optimization of Synthetic Data in LLMs Elicits Effective Personalization** [Paper] [Website]  
Anikait Singh\*, Sheryl Hsu\*, Kyle Hsu, Eric Mitchell, Stefano Ermon, Tatsu Hashimoto, Archit Sharma\*, Chelsea Finn\*  
In Submission to Association for Computational Linguistics (ACL), 2025
- [3] **Personalized Preference Fine-tuning of Diffusion Models** [Paper]  
Meihua Dang\*, Anikait Singh\*, Linqi Zhou, Stefano Ermon, Jiaming Song  
In Submission to the Conference on Computer Vision and Pattern Recognition (CVPR), 2025
- [4] **Adaptive Inference-Time Compute: LLMs Can Predict if They Can Do Better, Even Mid-Generation**  
Rohin Manvi, Anikait Singh, Stefano Ermon  
In Submission to International Conference on Machine Learning (ICML), 2025
- [5] **Test-Time Alignment via Hypothesis Reweighting**  
Yoonho Lee, Jonathan Williams, Henrik Marklund, Archit Sharma, Eric Mitchell, Anikait Singh, Chelsea Finn  
In Submission to International Conference on Learning Representations (ICLR), 2025

## Experience

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### Toyota Research Institute (TRI)

Los Altos, CA

Mentor: Kushal Arora, Sedrick Keh and Jean Mercat

June 2024 - Sept. 2024

- LLMs and VLMs are vital for tasks like coding, mathematics, and robotic planning, utilizing multi-step reasoning to decompose and solve complex problems accurately.
- Developed a value function verifier to estimate progress in a reasoning problem, enabling accurate credit assignment across substeps and improving policy performance through lower variance estimates.
- Empirically studied this approach in both pure language and multimodal domains

### Google DeepMind Robotics

Mountain View, CA

Mentor: Quan Vuong and Jialin Wu

Apr. 2023 - February 2024

- Worked on learning vision-language-action models that leverage internet scale data to boost generalization and enable emergent semantic reasoning for robotic manipulation.
- Trained models to enable better few-shot (in-context) learning to allow for better generalization to new objects, skills, and embodiments. Utilized Retrieval as an approach to automatically construct shots to prompt new behaviors.
- Empirically studied how PeFT methods can be leveraged to enable efficient adaptation of pre-trained VLMS.

### X, the moonshot factory

Mountain View, CA

Mentor: Lam Nyguen and Grace Brentano

Dec. 2022 - Apr. 2023

- Worked on an early-stage project looking at using Reinforcement Learning for Supply Chain Management.
- Devised methods to represent high-dimensional action spaces to make decision-making in these settings easier and more efficient.
- Collaborated with partners such as Uniqlo/Fast Retailing to understand how their retail company is structured and how methods can be developed for them to have better inventory management.

## Teaching Experience/Mentorship

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### Deep Learning Portal

Program Coordinator, Mentor, 2024

### CS 285: Deep Reinforcement Learning

Teaching Assistant: Fall 2022, Fall 2023

### CS 188: Intro to AI

Teaching Assistant: Spring 2022

### CS 61B: Data Structures and Algorithms

Deep Dive Instructor: Fall 2022

## Awards and Honors

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2023-2028

**NSF Graduate Fellowship:** Stanford University

2022

**CRA Outstanding Undergraduate Researcher Award Finalist:** UC Berkeley

2019 - 2023

**Dean's List:** UC Berkeley

## Technical Skills

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**Programming** Python, Java, C

**Frameworks** PyTorch, JAX, TensorFlow, Docker, NumPy

**Languages** English(Native), Hindi, Punjabi, Spanish

**Misc** Office, L<sup>A</sup>T<sub>E</sub>X