Types of Functions

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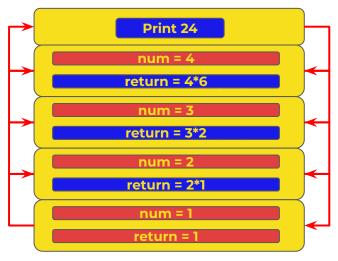
Outlines

- Recursive functions
- Inline functions
- Callback functions
- Reentrant and Non-Reentrant functions
- Synchronous and Asynchronous functions

Recursive functions

A function is said to be recursive if it calls itself directly or indirectly.

```
#include <stdio.h>
int factorial(int num)
{
    if(num == 1)
    {
        return num;
    }
    else
    {
        return (num * factorial(num-1));
    }
}
int main()
{
    printf("%d", factorial(4));
    return 0;
}
```



Inline functions

- Inline functions are functions that have small definitions and can be substituted at the place where the function call is made.
- There is no guarantee that the function will actually be inlined.
- Compiler does inlining for performing optimizations.

```
void inline swap(int* x, int* y);
void func_test() __attribute__((always_inline));
```

- Advantages over Macros:
 - Since they are functions so type of arguments is checked by the compiler whether they are correct or not.
 - They can include multiple lines of code without trailing backslashes.
 - Inline functions have their own scope for variables and they can return a value.
 - Debugging code is easy in case of Inline functions as compared to macros.

Callback functions

- The callback function is the function called using a pointer to that function,
 i.e it isn't called directly by its name.
- It tells the lower layers modules what to invoke from upper layers when a specific event happens.

Callback functions

```
// App.c
#include "led.h"
#include "timer.h"
. . . .
int main()
     setOvfCallback(LED off);
     LED on();
     TIMER start(1000);
     while (1)
```

```
// Timer.c
int count = 0;
void static (*ovfCallback) (void);
void setOvfCallback(void (*Callback)(void))
    ovfCallback = Callback;
ISR (TIMER OVERFLOW)
    if (count == 1000)
          ovfCallback();
```

Reentrant and Non-Reentrant functions

- The function is called reentrant if it can be interrupted in the middle of its execution and be called safely again without any data corruption.
- Conditions that make the function Reentrant:
 - It shouldn't use shared resource (global variable).
 - It shouldn't modify its own code. (state changing in other contexts).
 - It shouldn't call a non-reentrant function.

```
/* Reentrant */
void swap(int* x, int* y)
{
    int temp;
    temp = *x;
    *x = *y;
    *y = *temp;
}
```

```
int temp;
/* Non-reentrant */
void swap(int* x, int* y)
{
        temp = *x;
        *x = *y;
        *y = temp;
}
```

Synchronous and Asynchronous functions

- A functions/tasks are told to be synchronous if performed one at a time and the following is waiting the previous functions to finish.
- A functions/tasks are told to be asynchronous, when you can move to another task before the previous one finishes.

Synchronous and Asynchronous functions

```
/*This shows an example of Synchronous function calls*/
#include <windows.h>
#include cess.h>
#include <stdio.h>
void Func1(void*);
void Func2(void*);
CRITICAL SECTION Section; //This will act as Mutex
int main()
       InitializeCriticalSection(&Section);
       //Synchronous calling
       printf("Synchronous Calling\n");
       Func1(0);
       Func2(0);
       //This is done after all threads have finished processing
       DeleteCriticalSection(&Section);
       printf("Main exit");
       return 0;
```

```
void Func1(void *P)
{
  int Count;

  for (Count = 1; Count < 11; Count++)
  {
        EnterCriticalSection(&Section);
        printf("Func1 loop %d\n", Count);
        LeaveCriticalSection(&Section);
        Sleep(1000);
  }
  return;
}</pre>
```

```
void Func2(void *P)
{
  int Count;

for (Count = 10; Count > 0; Count--)
  {
     EnterCriticalSection(&Section);
     printf("Func2 loop %d\n", Count);
     LeaveCriticalSection(&Section);
     sleep(1000);
  }
  return;
}
```

Synchronous and Asynchronous functions

```
/*This shows an example of Asynchronous function calls*/
#include <windows.h>
#include  process.h>
#include <stdio.h>
void Func1(void*);
void Func2(void*);
CRITICAL SECTION Section: //This will act as Mutex
int main()
        InitializeCriticalSection(&Section);
        //Asynchronous calling
        printf("Asynchronous calling\n");
        HANDLE hThreads[2];
        //Create two threads and start them
        hThreads[0] = (HANDLE) beginthread(Func1, 0, NULL);
        hThreads[1] = (HANDLE) beginthread(Func2, 0, NULL);
        //Makes sure that both the threads have finished before going further
        WaitForMultipleObjects(2, hThreads, TRUE, INFINITE);
        //This is done after all threads have finished processing
        DeleteCriticalSection(&Section);
        printf("Main exit");
        return 0:
```

```
void Func1(void *P)
{
  int Count;

  for (Count = 1; Count < 11; Count++)
  {
        EnterCriticalSection(&Section);
        printf("Func1 loop %d\n", Count);
        LeaveCriticalSection(&Section);
        Sleep(1000);
  }
  return;
}</pre>
```

```
void Func2(void *P)
{
  int Count;

  for (Count = 10; Count > 0; Count--)
  {
      EnterCriticalSection(&Section);
      printf("Func2 loop %d\n", Count);
      LeaveCriticalSection(&Section);
      Sleep(1000);
  }
  return;
}
```

Summary

- You have learned what types of functions you may interact with in embedded systems
- Recursive functions are complex and consumes stack
- Take care of non-reentrant functions
- Callbacks are strong tool used in embedded systems