## MatGeo Presentation - Problem 4.3.55

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## Question

Find the vector equation of the plane passing through the points  $\mathbf{R}(2,5,-3)$ ,  $\mathbf{S}(-2,-3,5)$  and  $\mathbf{T}(5,3,-3)$ .

Points	Name
$\begin{pmatrix} 2 \\ 5 \\ -3 \end{pmatrix}$	Point <b>R</b>
$\begin{pmatrix} -2 \\ -3 \\ 5 \end{pmatrix}$	Point <b>S</b>
$\begin{pmatrix} 5\\3\\-3 \end{pmatrix}$	Point <b>T</b>

Table: List of Points

 $\rightarrow$  We can write the equation for the required plane as

$$\mathbf{n}^T \mathbf{x} = c \tag{0.1}$$

 $\rightarrow$  Also, **R**, **S** and **T** satisfy this equation. Hence

$$\mathbf{n}^{\mathsf{T}}\mathbf{R} = c \tag{0.2}$$

$$\mathbf{n}^T \mathbf{S} = c$$
$$\mathbf{n}^T \mathbf{T} = c$$

ightarrow From (1), (2), (3) and (4), we get

$$\mathbf{n}^{T} (\mathbf{R} \quad \mathbf{S} \quad \mathbf{T}) = c (1 \quad 1 \quad 1)$$
 (0.5)

 $\rightarrow$  Using transpose on both sides, we get

$$\begin{pmatrix} \mathbf{R} & \mathbf{S} & \mathbf{T} \end{pmatrix}^T \mathbf{n} = c \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \tag{0.6}$$

$$\mathbf{n} = c \left( \begin{pmatrix} \mathbf{R} & \mathbf{S} & \mathbf{T} \end{pmatrix}^T \right)^{-1} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

(0.7)

(0.3)

(0.4)

$$= c \left( \begin{pmatrix} 2 & -2 & 5 \\ 5 & -3 & 3 \\ -3 & 5 & -3 \end{pmatrix}^{T} \right)^{-1} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$= c \begin{pmatrix} 2 & 5 & -3 \\ -2 & -3 & 5 \\ 5 & 3 & -3 \end{pmatrix}^{-1} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$= \frac{c}{56} \begin{pmatrix} -6 & 6 & 16 \\ 19 & 9 & -4 \\ 9 & 19 & 4 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$= \frac{c}{7} \begin{pmatrix} 2 \\ 3 \end{pmatrix}$$

$$(0.8)$$

 $\rightarrow$  From (11), we get the value of

$$\mathbf{n} = \begin{pmatrix} 2 \\ 3 \\ 4 \end{pmatrix} \tag{0.12}$$

 $\rightarrow$  From (2) and (12), we get

$$c = \begin{pmatrix} 2 & 3 & 4 \end{pmatrix} \begin{pmatrix} 2 \\ 5 \\ -3 \end{pmatrix} = 7 \tag{0.13}$$

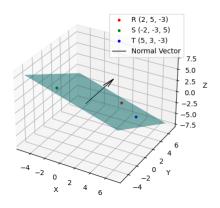


Figure: Plot of plane  $\mathbf{n}^T \mathbf{x} = c$ 

# File: points.c

# File: call\_c.py

```
import subprocess
# Compile the C program
subprocess.run(["gcc", "points.c", "-o", "points"])
# Run the compiled C program
result = subprocess.run(["./points"], capture_output=True, text=True)
# Print the output from the C program
print(result.stdout)
```

## File: plot.py

```
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D
# Define the points
R = np.array([2, 5, -3])
S = np.arrav([-2, -3, 5])
T = np.array([5, 3, -3])
normal = np.array([2, 3, 4])
# Create a grid to plot the plane
x = np.linspace(-5, 7, 10)
y = np.linspace(-5, 7, 10)
X, Y = np.meshgrid(x, y)
# Equation of the plane: Ax + By + Cz = D
A, B, C = normal
D = np.dot(normal, R)
# Solve for Z
Z = (D - A * X - B * Y) / C
# Plotting the plane and the points R, S, T
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
# Plot the points
ax.scatter(*R, color='r', label='R_{ij}(2,...5,...-3)', s=10)
ax.scatter(*S. color='g', label='S_{ij}(-2, -3, -5)', s=10)
ax.scatter(*T, color='b', label='T_{11}(5,13,1-3)', s=10)
```

# File: plot.py

```
# Plot the plane
ax.plot_surface(X, Y, Z, alpha=0.5, rstride=100, cstride=100, color='c')

# Plot the normal vector starting from point R
ax.quiver(0, 0, 0, normal[0], normal[1], normal[2], color='k', length=1, linewidth=1, label='Normal_UVector'
)

# Labels and legend
ax.set_xlabel('X')
ax.set_ylabel('Y')
ax.set_zlabel('Z')
ax.set_zlabel('Z')
ax.legend()

# Display plot
plt.show()
```