

MatGeo Presentation - Problem 6.3.4

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Question

Find the shortest distance between the lines

$$\mathbf{r} = (\mathbf{i} + 2\mathbf{j} + \mathbf{k}) + \kappa_1(\mathbf{i} - \mathbf{j} + \mathbf{k}) \quad (0.1)$$

$$\mathbf{r} = (2\mathbf{i} - \mathbf{j} - \mathbf{k}) + \kappa_2(2\mathbf{i} + \mathbf{j} + 2\mathbf{k}) \quad (0.2)$$

Solution

→ The lines can be represented in vector form as

$$L_1 \equiv \mathbf{x} = \mathbf{A} + \kappa_1 \mathbf{m}_1 = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} + \kappa_1 \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} \quad (0.3)$$

$$L_2 \equiv \mathbf{x} = \mathbf{B} + \kappa_2 \mathbf{m}_2 = \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix} + \kappa_2 \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} \quad (0.4)$$

→ To check whether the given lines are skewed

$$\mathbf{M} = (\mathbf{m}_1 \quad \mathbf{m}_2) = \begin{pmatrix} 1 & 2 \\ -1 & 1 \\ 1 & 2 \end{pmatrix}, \mathbf{B} - \mathbf{A} = \begin{pmatrix} 1 \\ -3 \\ -2 \end{pmatrix} \quad (0.5)$$

$$\begin{pmatrix} 1 & 2 & 1 \\ -1 & 1 & -3 \\ 1 & 2 & -2 \end{pmatrix} \xrightarrow[R_3 \leftrightarrow R_3 - R_1]{R_2 \leftrightarrow R_2 + R_1} \begin{pmatrix} 1 & 2 & 1 \\ 0 & 3 & -2 \\ 0 & 0 & -3 \end{pmatrix} \quad (0.6)$$

$$\text{rank}(\mathbf{M} \quad \mathbf{B} - \mathbf{A}) = 3 \implies \text{The given lines are skew} \quad (0.7)$$

Solution

→ Let $x_1(\mu_1)$ and $x_2(\mu_2)$ be the points closest to each other from the lines L_1 and L_2 , respectively

$$\mathbf{x}_1 = \mathbf{A} + \mu_1 \mathbf{m}_1 \qquad \mathbf{x}_2 = \mathbf{B} + \mu_2 \mathbf{m}_2 \qquad (0.8)$$

→ Now, we have

$$(\mathbf{x}_1 - \mathbf{x}_2)^T \mathbf{m}_1 = (\mathbf{x}_1 - \mathbf{x}_2)^T \mathbf{m}_2 = 0 \qquad (0.9)$$

$$(\mathbf{x}_1 - \mathbf{x}_2)^T (\mathbf{m}_1 \quad \mathbf{m}_2) = 0 \qquad (0.10)$$

$$\mathbf{M}^T (\mathbf{x}_1 - \mathbf{x}_2) = 0 \qquad (0.11)$$

→ Using the *least squares method*

$$\mathbf{x}_1 - \mathbf{x}_2 = \mathbf{A} - \mathbf{B} + (\mathbf{m}_1 \quad \mathbf{m}_2) \begin{pmatrix} \mu_1 \\ -\mu_2 \end{pmatrix} \qquad (0.12)$$

$$0 = \mathbf{M}^T (\mathbf{A} - \mathbf{B}) + \mathbf{M}^T \mathbf{M} \begin{pmatrix} \mu_1 \\ -\mu_2 \end{pmatrix} \qquad (0.13)$$

$$\mathbf{M}^T \mathbf{M} \mu = \mathbf{M}^T (\mathbf{B} - \mathbf{A}), \quad \mu = \begin{pmatrix} \mu_1 \\ -\mu_2 \end{pmatrix} \qquad (0.14)$$

Solution

→ To perform *singular value decomposition*, we do the following eigen-decompositions

$$\mathbf{M}^T \mathbf{M} = \begin{pmatrix} 3 & 3 \\ 3 & 9 \end{pmatrix} = \mathbf{V} \mathbf{D}_2 \mathbf{V}^T \quad (0.15)$$

$$\mathbf{M} \mathbf{M}^T = \begin{pmatrix} 5 & 1 & 5 \\ 1 & 2 & 1 \\ 5 & 1 & 5 \end{pmatrix} = \mathbf{U} \mathbf{D}_1 \mathbf{U}^T \quad (0.16)$$

→ For $\mathbf{M}^T \mathbf{M}$, the characteristic polynomial is

$$\text{char}(\mathbf{M}^T \mathbf{M}) = \begin{vmatrix} 3 - \lambda & 3 \\ 3 & 9 - \lambda \end{vmatrix} = \lambda^2 - 12\lambda + 18 \quad (0.17)$$

$$\implies \lambda_1 = 6 + 3\sqrt{2}, \lambda_2 = 6 - 3\sqrt{2} \quad (0.18)$$

→ For λ_1 , the augmented matrix formed using the eigenvalue-eigenvector equation gives

$$\begin{pmatrix} -3 - 3\sqrt{2} & 3 \\ 3 & 3 - 3\sqrt{2} \end{pmatrix} \xleftrightarrow{\text{which simplifies to}} \begin{pmatrix} 1 & 1 - \sqrt{2} \\ 0 & 0 \end{pmatrix} \quad (0.19)$$

Solution

$$\Rightarrow \mathbf{v}_1 = \frac{1}{\sqrt{4-2\sqrt{2}}} \begin{pmatrix} -1+\sqrt{2} \\ 1 \end{pmatrix} \quad (0.20)$$

→ For λ_2 , the augmented matrix formed using the eigenvalue-eigenvector equation gives

$$\begin{pmatrix} -3+3\sqrt{2} & 3 \\ 3 & 3+3\sqrt{2} \end{pmatrix} \xleftrightarrow{\text{which simplifies to}} \begin{pmatrix} 1 & 1+\sqrt{2} \\ 0 & 0 \end{pmatrix} \quad (0.21)$$

$$\Rightarrow \mathbf{v}_2 = \frac{1}{\sqrt{4+2\sqrt{2}}} \begin{pmatrix} -1-\sqrt{2} \\ 1 \end{pmatrix} \quad (0.22)$$

→ Using (15), we get

$$\mathbf{V} = (\mathbf{v}_1 \quad \mathbf{v}_2) = \begin{pmatrix} \frac{-1+\sqrt{2}}{\sqrt{4-2\sqrt{2}}} & \frac{-1-\sqrt{2}}{\sqrt{4+2\sqrt{2}}} \\ \frac{1}{\sqrt{4-2\sqrt{2}}} & \frac{1}{\sqrt{4+2\sqrt{2}}} \end{pmatrix} \quad (0.23)$$

$$\mathbf{D}_2 = \begin{pmatrix} 6+3\sqrt{2} & 0 \\ 0 & 6-3\sqrt{2} \end{pmatrix} \quad (0.24)$$

Solution

→ For \mathbf{MM}^T , the characteristic polynomial is

$$\text{char}(\mathbf{MM}^T) = \begin{vmatrix} 5 - \lambda & 1 & 5 \\ 1 & 2 - \lambda & 1 \\ 5 & 1 & 5 - \lambda \end{vmatrix} = \lambda(\lambda^2 - 12\lambda + 18) \quad (0.25)$$

$$\implies \lambda_1 = 6 + 3\sqrt{2}, \lambda_2 = 6 - 3\sqrt{2}, \lambda_3 = 0 \quad (0.26)$$

→ For λ_1 , the augmented matrix formed using the eigenvalue-eigenvector equation gives

$$\begin{pmatrix} -1 - 3\sqrt{2} & 1 & 5 \\ 1 & -4 - 3\sqrt{2} & 1 \\ 5 & 1 & -1 - 3\sqrt{2} \end{pmatrix} \xleftrightarrow{\text{simplifies to}} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 4 - 3\sqrt{2} \\ 0 & 0 & 0 \end{pmatrix} \quad (0.27)$$

$$\implies \mathbf{u}_1 = \frac{1}{\sqrt{36 - 24\sqrt{2}}} \begin{pmatrix} 1 \\ -4 + 3\sqrt{2} \\ 1 \end{pmatrix} = \frac{1}{\sqrt{12}} \begin{pmatrix} 1 + \sqrt{2} \\ 2 - \sqrt{2} \\ 1 + \sqrt{2} \end{pmatrix} \quad (0.28)$$

Solution

→ For λ_2 , the augmented matrix formed using the eigenvalue-eigenvector equation gives

$$\begin{pmatrix} -1 + 3\sqrt{2} & 1 & 5 \\ 1 & -4 + 3\sqrt{2} & 1 \\ 5 & 1 & -1 + 3\sqrt{2} \end{pmatrix} \xleftrightarrow{\text{simplifies to}} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 4 + 3\sqrt{2} \\ 0 & 0 & 0 \end{pmatrix} \quad (0.29)$$

$$\Rightarrow \mathbf{u}_2 = \frac{-1}{\sqrt{36 + 24\sqrt{2}}} \begin{pmatrix} 1 \\ -4 - 3\sqrt{2} \\ 1 \end{pmatrix} = \frac{1}{\sqrt{12}} \begin{pmatrix} 1 - \sqrt{2} \\ 2 + \sqrt{2} \\ 1 - \sqrt{2} \end{pmatrix} \quad (0.30)$$

→ For λ_3 , the augmented matrix formed using the eigenvalue-eigenvector equation gives

$$\begin{pmatrix} 5 & 1 & 5 \\ 1 & 2 & 1 \\ 5 & 1 & 5 \end{pmatrix} \xleftrightarrow{\text{simplifies to}} \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad (0.31)$$

Solution

$$\Rightarrow \mathbf{u}_3 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \quad (0.32)$$

→ Using (16), we get the following

$$\mathbf{U} = (\mathbf{u}_1 \quad \mathbf{u}_2 \quad \mathbf{u}_3) = \begin{pmatrix} \frac{1+\sqrt{2}}{\sqrt{12}} & \frac{1-\sqrt{2}}{\sqrt{12}} & -\frac{1}{\sqrt{2}} \\ \frac{2-\sqrt{2}}{\sqrt{12}} & \frac{2+\sqrt{2}}{\sqrt{12}} & 0 \\ \frac{1+\sqrt{2}}{\sqrt{12}} & \frac{1-\sqrt{2}}{\sqrt{12}} & \frac{1}{\sqrt{2}} \end{pmatrix} \quad (0.33)$$

$$\Rightarrow \mathbf{U}_R = \begin{pmatrix} \frac{1+\sqrt{2}}{\sqrt{12}} & \frac{1-\sqrt{2}}{\sqrt{12}} \\ \frac{2-\sqrt{2}}{\sqrt{12}} & \frac{2+\sqrt{2}}{\sqrt{12}} \\ \frac{1+\sqrt{2}}{\sqrt{12}} & \frac{1-\sqrt{2}}{\sqrt{12}} \end{pmatrix} \quad (0.34)$$

$$\mathbf{D}_1 = \begin{pmatrix} 6+3\sqrt{2} & 0 & 0 \\ 0 & 6-3\sqrt{2} & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad (0.35)$$

Solution

→ Then, for using *singular value decomposition*, we define

$$\mathbf{\Sigma} \triangleq \begin{pmatrix} \sqrt{6+3\sqrt{2}} & 0 \\ 0 & \sqrt{6-3\sqrt{2}} \\ 0 & 0 \end{pmatrix} \Rightarrow \mathbf{\Sigma}_R \triangleq \begin{pmatrix} \sqrt{6+3\sqrt{2}} & 0 \\ 0 & \sqrt{6-3\sqrt{2}} \end{pmatrix} \quad (0.36)$$

→ Using *singular value decomposition* and substituting in (14)

$$\mathbf{M} = \mathbf{U}_R \mathbf{\Sigma}_R \mathbf{V}^T \quad (0.37)$$

$$\mathbf{V} \mathbf{\Sigma}_R^T \mathbf{U}_R^T \mathbf{U}_R \mathbf{\Sigma}_R \mathbf{V}^T \mu = \mathbf{V} \mathbf{\Sigma}_R^T \mathbf{U}_R^T (\mathbf{B} - \mathbf{A}) \quad (0.38)$$

$$\mathbf{V} \mathbf{\Sigma}_R^2 \mathbf{V}^T \mu = \mathbf{V} \mathbf{\Sigma}_R \mathbf{U}_R^T (\mathbf{B} - \mathbf{A}) \quad (0.39)$$

$$\mu = (\mathbf{V} \mathbf{\Sigma}_R^2 \mathbf{V}^T)^{-1} \mathbf{V} \mathbf{\Sigma}_R \mathbf{U}_R^T (\mathbf{B} - \mathbf{A}) \quad (0.40)$$

$$\mu = \mathbf{V} \mathbf{\Sigma}_R^{-2} \mathbf{V}^T \mathbf{V} \mathbf{\Sigma}_R \mathbf{U}_R^T (\mathbf{B} - \mathbf{A}) \quad (0.41)$$

$$\mu = \mathbf{V} \mathbf{\Sigma}_R^{-1} \mathbf{U}_R^T (\mathbf{B} - \mathbf{A}) \quad (0.42)$$

Solution

→ Putting the required values in (42)

$$\mu = \begin{pmatrix} \frac{-1+\sqrt{2}}{\sqrt{4-2\sqrt{2}}} & \frac{-1-\sqrt{2}}{\sqrt{4+2\sqrt{2}}} \\ \frac{1}{\sqrt{4-2\sqrt{2}}} & \frac{1}{\sqrt{4+2\sqrt{2}}} \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{6+3\sqrt{2}}} & 0 \\ 0 & \frac{1}{\sqrt{6-3\sqrt{2}}} \end{pmatrix} \begin{pmatrix} \frac{1+\sqrt{2}}{\sqrt{12}} & \frac{2-\sqrt{2}}{\sqrt{12}} & \frac{1+\sqrt{2}}{\sqrt{12}} \\ \frac{1-\sqrt{2}}{\sqrt{12}} & \frac{2+\sqrt{2}}{\sqrt{12}} & \frac{1-\sqrt{2}}{\sqrt{12}} \end{pmatrix} \begin{pmatrix} 1 \\ -3 \\ -2 \end{pmatrix} \quad (0.43)$$

$$\begin{pmatrix} \mu_1 \\ -\mu_2 \end{pmatrix} = \begin{pmatrix} \frac{-1+\sqrt{2}}{\sqrt{12}} & \frac{-1-\sqrt{2}}{\sqrt{12}} \\ \frac{1}{\sqrt{12}} & \frac{1}{\sqrt{12}} \end{pmatrix} \begin{pmatrix} \frac{-7+2\sqrt{2}}{\sqrt{12}} \\ \frac{-7-2\sqrt{2}}{\sqrt{12}} \end{pmatrix} = \begin{pmatrix} 11/6 \\ -7/6 \end{pmatrix} \quad (0.44)$$

$$\Rightarrow \begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix} = \begin{pmatrix} 11/6 \\ 7/6 \end{pmatrix} \quad (0.45)$$

Solution

→ This gives us the vector coordinates of x_1 and x_2 , as

$$\mathbf{x}_1 = \begin{pmatrix} 1 \\ 2 \\ 1 \end{pmatrix} + \left(\frac{11}{6}\right) \begin{pmatrix} 1 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 17/6 \\ 1/6 \\ 17/6 \end{pmatrix} \quad (0.46)$$

$$\mathbf{x}_2 = \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix} + \left(\frac{7}{6}\right) \begin{pmatrix} 2 \\ 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 26/6 \\ 1/6 \\ 8/6 \end{pmatrix} \quad (0.47)$$

→ And the least distance as

$$\|\mathbf{x}_1 - \mathbf{x}_2\| = \left\| \begin{pmatrix} -3/2 \\ 0 \\ 3/2 \end{pmatrix} \right\| \quad (0.48)$$

$$= \frac{3\sqrt{2}}{2} \quad (0.49)$$

Solution

3D Plot of Two Lines and Points of Closest Approach

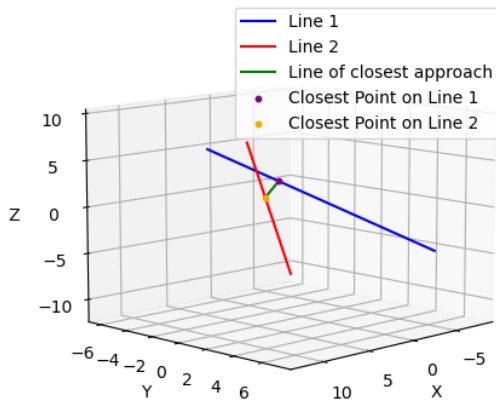


Figure: Plot of given lines and shortest distance between them

File: points.c

```
#include <stdio.h>

int main() {
    FILE *fp;

    // -----
    // Question 6.3.4
    // -----

    fp = fopen("points.dat", "w");
    fprintf(fp, "%d,%d,%d\n", 1, 2, 1); // A
    fprintf(fp, "%d,%d,%d\n", 2, -1, -1); // B
    fprintf(fp, "%d,%d,%d\n", 1, -1, 1); // m1
    fprintf(fp, "%d,%d,%d\n", 2, 1, 2); // m2
    fprintf(fp, "%f,%f,%f\n", 17/6, 1/6, 17/6); // c1
    fprintf(fp, "%f,%f,%f\n", 26/6, 1/6, 8/6); // c2
    fclose(fp);
    return 0;
}
```

File: call_c.py

```
import subprocess

# Compile the C program
subprocess.run(["gcc", "points.c", "-o", "points"])

# Run the compiled C program
result = subprocess.run(["./points"], capture_output=True, text=True)

# Print the output from the C program
print(result.stdout)
```

File: plot.py

```
import numpy as np
import matplotlib.pyplot as plt
from mpl_toolkits.mplot3d import Axes3D

# Define the lines with their parametric equations
# Define the parametric values for kappa_1 and kappa_2
kappa_1_vals = np.linspace(-5, 5, 50)
kappa_2_vals = np.linspace(-5, 5, 50)
# Parametric equations of the lines
r1 = np.array([1, 2, 1]) + kappa_1_vals[:, None] * np.array([1, -1, 1])
r2 = np.array([2, -1, -1]) + kappa_2_vals[:, None] * np.array([2, 1, 2])

# Plot the lines
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
# Plot line 1
ax.plot(r1[:, 0], r1[:, 1], r1[:, 2], label='Line_1', color='blue')
# Plot line 2
ax.plot(r2[:, 0], r2[:, 1], r2[:, 2], label='Line_2', color='red')

# Points of closest approach on both lines
closest_point_1 = np.array([17/6, 1/6, 17/6])
closest_point_2 = np.array([26/6, 1/6, 8/6])
```


File: plot.py

```
# Mark the vector along points of closest approach
closest_line_vals = np.linspace(0, 1, 10)
closest_line = np.array([17/6, 1/6, 17/6]) + closest_line_vals[:, None] * np.array([3/2, 0, -3/2])
ax.plot(closest_line[:, 0], closest_line[:, 1], closest_line[:, 2], label='Line of closest approach', color='green')

# Mark the points of closest approach
ax.scatter(closest_point_1[0], closest_point_1[1], closest_point_1[2], color='purple', s=10, label='Closest Point on Line 1')
ax.scatter(closest_point_2[0], closest_point_2[1], closest_point_2[2], color='orange', s=10, label='Closest Point on Line 2')

# Labels and title
ax.set_xlabel('X')
ax.set_ylabel('Y')
ax.set_zlabel('Z')
ax.set_title('3D Plot of Two Lines and Points of Closest Approach')

# Set the camera angle
ax.view_init(elev=10, azim=45)

# Show the plot
ax.legend()
plt.show()
```