L2 Tensors – Multidimensional Arrays

Tensors

- PyTorch is a library for Python programs that facilitates building deep learning projects
- PyTorch is an open-source machine learning library based on the Torch library, developed by Facebook's AI Research lab
- Tensors, the basic data structure in PyTorch
- The PyTorch library primarily supports NVIDIA CUDA-based GPUs

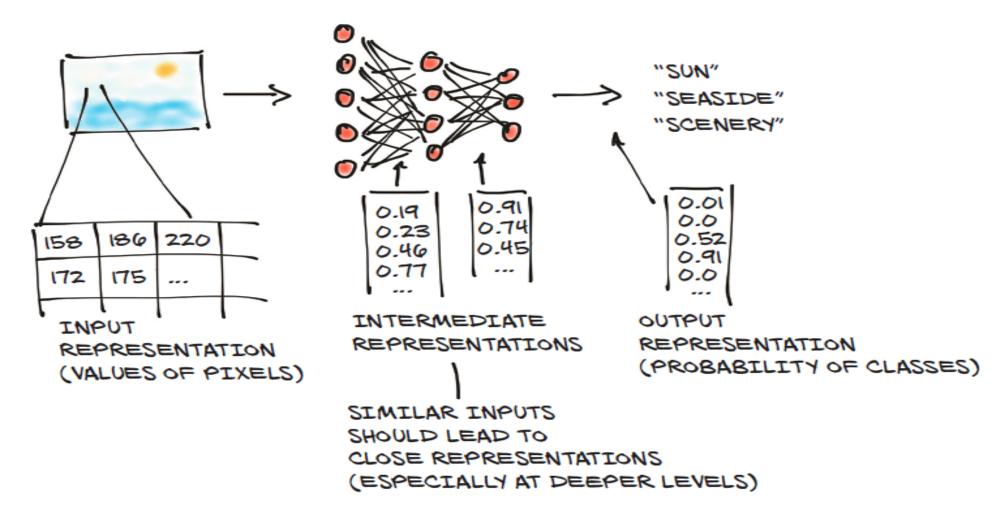
Transforming an input representation to an output representation

- Deep learning consists of building a system that can transform data from one representation to another.
- This transformation is driven by extracting commonalities from a series of examples that demonstrate the desired mapping
- Floating-point numbers are the way a network deals with information
- we need a way to encode real-world data and then decode the output back and use for our purpose
- Hence, we need to deal with all the floating-point numbers in PyTorch by using tensors

Transforming an input representation to an output representation

- A deep neural network typically learns the transformation from one form of data to another in stages
- This means the partially transformed data between each stage can be thought of as a sequence of intermediate representations (2nd step in figure).
- Intermediate representations are the results of combining the input with the weights of the previous layer of neurons.
- Each intermediate representation is unique to the inputs that preceded it
- For image recognition, early representations can be things such as edge detection or certain textures like fur.
- Deeper representations can capture more complex structures like ears, noses, or eyes.
- In general, such intermediate representations are collections of floating-point numbers that characterize the input
- Such characterization is specific to the task at hand and is learned from relevant examples.
- These collections of floating-point numbers and their manipulation are at the heart of modern Al

Transforming an input representation to an output representation

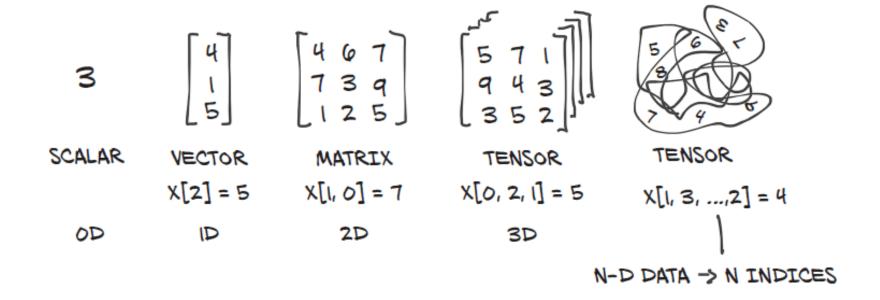


Converting image pixel into floating-point numbers

Tensors

- Before we can begin the process of converting our data to floating-point input
 - We must need to deal with how PyTorch handles and stores data—
 - as input, as intermediate representations, and as output
- PyTorch introduces a fundamental data structure: the tensor
- In the context of deep learning, tensors refer to the generalization of vectors and matrices to an arbitrary number of dimensions
- Another name for the same concept is multidimensional array.
- The dimensionality of a tensor coincides with the number of indexes used to refer to scalar values within the tensor
- NumPy is also popular for multidimensional array library
- Compared to NumPy arrays, PyTorch tensors have a few superpowers
 - ability to perform very fast operations on graphical processing units (GPUs),
 - distribute operations on multiple devices or machines, and
 - keep track of the graph of computations that created them
- PyTorch features seamless interoperability with NumPy, SciPy, Scikit-learn and Pandas

Tensors are the building blocks for representing data in PyTorch



Tensors vs Numpy and Tensors vs multidimensional Arrays of C, C++, Java

- Tensors vs Numpy
- Tensors are multidimensional arrays like n-dimensional NumPy array.
- However, tensors can be used in GPUs as well, which is not in the case of NumPy array
- Tensors vs multidimensional array used in C, C++, and Java
- tensors should have the same size of columns in all dimensions
- Also, the tensors can contain only numeric data types

How to manipulate tensors using the PyTorch tensor library

Creating Tensor in PyTorch

- A tensor can contain elements of a single data type.
- We can create a tensor using a python list or NumPy array.
- The torch has 10 variants of tensors for both GPU and CPU.
- Different ways of defining a tensor.
- torch.tensor(): It copies the data to create a tensor; however, it infers the data type automatically.
- torch.Tensor(): It copies the data and creates its tensor. It is an alias for torch.FloatTensor.
- torch.as_tensor(): The data is shared and not copied in this case while creating the data and accepts any type of array for tensor creation.
- torch.from_numpy(): It is similar to tensor.as_tensor() however it accepts only numpy array.

Creating Tensor in PyTorch

```
import torch
import numpy as np
data1 = [1, 2, 3, 4, 5, 6]
data2 = np.array([1.5, 3.4, 6.8, 9.3, 7.0, 2.8])
# creating tensors and printing
t1 = torch.tensor(data1)
t2 = torch.Tensor(data1)
t3 = torch.as tensor(data2)
t4 = torch.from_numpy(data2)
print("Tensor: ",t1, "Data type: ", t1.dtype,"\n")
print("Tensor: ",t2, "Data type: ", t2.dtype,"\n")
print("Tensor: ",t3, "Data type: ", t3.dtype,"\n")
print("Tensor: ",t4, "Data type: ", t4.dtype,"\n")
print("numpy array", data2, "Data type:", data2. dtype)
```

```
Tensor: tensor([1, 2, 3, 4, 5, 6]) Data type:
torch.int64
Tensor: tensor([1., 2., 3., 4., 5., 6.]) Data type:
torch.float32
Tensor: tensor([1.5000, 3.4000, 6.8000, 9.3000,
7.0000, 2.8000], dtype=torch.float64) Data type:
torch.float64
Tensor: tensor([1.5000, 3.4000, 6.8000, 9.3000,
7.0000, 2.8000], dtype=torch.float64) Data type:
torch.float64
numpy array [1.5 3.4 6.8 9.3 7. 2.8] Data type:
```

Verify that the numpy array and torch tensor have similar data types which is float64 as shown above

float64

Methods for NumPy to PyTorch and PyTorch to NumPy

• The two main methods for NumPy to PyTorch (and back again) are:

- torch.from_numpy(ndarray) NumPy array -> PyTorch tensor.
- torch.Tensor.numpy() PyTorch tensor -> NumPy array

Convert tensor to numpy array - .numpy()

Convert a PyTorch tensor to a Numpy array using the .numpy method of a tensor.

print("npz=",npz)

Tensor Attributes

The two fundamental attributes of a tensor are:

Shape: refers to the dimensionality of array or matrix

- Rank: refers to the number of dimensions present in tensor
 - TENSOR.ndim: Check number of dimensions for TENSOR or
 - len(TENSOR.shape)
- dtype what datatype are the elements within the tensor stored in?
- device what device is the tensor stored on? (usually GPU or CPU)

Create a random tensor and find details

```
tensor([[0.8549, 0.5509, 0.2868, 0.2063],
# Create a tensor
                                                                 [0.4451, 0.3593, 0.7204, 0.0731],
                                                                 [0.9699, 0.1078, 0.8829, 0.4132]])
some_tensor = torch.rand(3, 4)
                                                              Shape of tensor: torch.Size([3, 4])
                                                              Datatype of tensor: torch.float32
                                                              Device tensor is stored on: cpu
# Find out details about it
print(some tensor)
print(f"Shape of tensor: {some tensor.shape}")
print(f"Datatype of tensor: {some_tensor.dtype}")
print(f"Device tensor is stored on: {some tensor.device}")
```

Tensor Attribute - .shape

```
t1 = torch.tensor(4.)
t2 = torch.tensor([1., 2, 3, 4])
t3 = torch.tensor([[5., 6],
           [7, 8],
            [9, 10]])
t4 = torch.tensor([
  [[11, 12, 13],
   [13, 14, 15]],
  [[15, 16, 17],
   [17, 18, 19.]]])
```

```
print(t1)
print(t1.shape)
print(t2)
print(t2.shape)
print(t3)
print(t3.shape)
print(t4)
print(t4.shape)
```

```
tensor(4.)
torch.Size([])
tensor([1., 2., 3., 4.])
torch.Size([4])
tensor([[ 5., 6.],
     [7., 8.],
     [9., 10.]])
torch.Size([3, 2])
tensor([[[11., 12., 13.],
      [13., 14., 15.]],
     [[15., 16., 17.],
      [17., 18., 19.]]]
torch.Size([2, 2, 3])
```

Tensor Attribute - .shape

```
import torch
# creating a tensors
t1=torch.tensor([1, 2, 3, 4])
t2=torch.tensor([[1, 2, 3, 4],
          [5, 6, 7, 8],
          [9, 10, 11, 12]])
# printing the tensors:
print("Tensor t1: \n", t1)
print("\nTensor t2: \n", t2)
# shape of tensors
print("\nShape of t1: ", t1.shape)
print("Shape of t2: ", t2.shape)
# rank of tensors
print("\nRank of t1: ", len(t1.shape))
print("Rank of t2: ", len(t2.shape))
```

Rank of t2: 2

Restructuring Tensors in Pytorch

- We can modify the shape and size of a tensor as desired in PyTorch.
- We can also create a transpose of an n-d tensor.
- Three common ways to change the structure of tensor :
- .reshape(a, b): returns a new tensor with size a,b
- .resize(a, b): returns the same tensor with the size a,b
- .transpose(a, b): returns a tensor transposed in a and b dimension
- transposes in PyTorch use either:
 - torch.transpose(input, dim0, dim1) where input is the desired tensor to transpose and dim0 and dim1 are the dimensions to be swapped.
 - tensor.T where tensor is the desired tensor to transpose.

Restructuring Tensors in Pytorch

Transpose Parameters

- input (Tensor) the input tensor.
- dim0 (int) the first dimension to be transposed
- dim1 (int) the second dimension to be transposed
- transpose(0, 1) (or transpose(): defaults to swapping the first two dimensions)
- for a 2D tensor, transpose(0, 1) and transpose(1, 0) have the same effect—they transpose the matrix. The difference is with tensors of higher dimensions

```
x = torch.randn(2, 3)
print(x)
torch.transpose(x, 0, 1)

tensor([[ 0.0094,  0.3476,  0.5798],
      [ 0.5781,  0.6393, -1.6365]])
tensor([[ 0.0094,  0.5781],
      [ 0.3476,  0.6393],
      [ 0.5798, -1.6365]])
```

Restructuring Tensors in Pytorch

```
import torch
                                                          Reshaping
                                                          tensor([[ 1, 2],
# defining tensor
                                                               [3, 4],
t = torch.tensor([[1, 2, 3, 4],
                                                              [5, 6],
           [5, 6, 7, 8],
                                                              [7, 8],
           [9, 10, 11, 12]])
                                                              [ 9, 10],
                                                               [11, 12]])
# reshaping the tensor
print("Reshaping")
                                                          Resizing
print(t.reshape(6, 2))
                                                          tensor([[ 1, 2, 3, 4, 5, 6],
                                                               [7, 8, 9, 10, 11, 12]])
# resizing the tensor
print("\nResizing")
                                                          Transposing
print(t.resize_(2, 6))
                                                          tensor([[ 1, 7],
                                                               [2, 8],
# transposing the tensor
                                                              [ 3, 9],
print("\nTransposing")
                                                               [ 4, 10],
print(t.transpose(1, 0))
                                                               [5, 11],
                                                               [ 6, 12]])
```

Restructuring Tensors in Pytorch - reshape vs resize

```
import torch
                                                                             Original Tensor:
original_tensor = torch.tensor([[1, 2, 3], [4, 5, 6]])
                                                                             tensor([[1, 2, 3],
# Reshape example
                                                                                   [4, 5, 6]])
new shape = (3, 2)
                                                                             Reshaped Tensor:
reshaped tensor = original tensor.reshape(new shape)
                                                                             tensor([[1, 2],
print("Original Tensor:")
                                                                                    [3, 4],
print(original tensor)
                                                                                    [5, 6]])
print("Reshaped Tensor:")
print(reshaped tensor)
                                                                             Resized Tensor (inplace):
print()
                                                                             tensor([[1, 2],
# Resize example (inplace)
                                                                                    [3, 4],
new size = (3, 2)
                                                                                    [5, 6]])
original tensor.resize (new size)
print("Resized Tensor (inplace):")
                                                                             Original Tensor:
print(original tensor)
                                                                             tensor([[1, 2],
print()
                                                                                    [3, 4],
# Transpose example
                                                                                    [5, 6]])
transposed_tensor = original_tensor.transpose(0, 1)
                                                                             Transposed Tensor:
print("Original Tensor:")
                                                                             tensor([[1, 3, 5],
print(original_tensor)
                                                                                    [2, 4, 6]])
print("Transposed Tensor:")
print(transposed tensor)
```

Reshape vs resize

reshape

- The reshape operation is used to change the shape of the tensor. In this example, the original tensor is reshaped from a 2x3 matrix to a 3x2 matrix.
- The reshape operation is used to change the shape of a tensor while keeping the same underlying data. It creates a new view of the original tensor with the specified shape.
- resize (Inplace):
- The resize_ operation is an inplace operation used to change the size of the tensor. Here, the original tensor is resized to a new size of 3x2.
- The resize_ method is the inplace version that modifies the original tensor. It's recommended to use inplace operations to avoid deprecated warnings
- transpose
- The transpose operation is used to swap dimensions of the tensor. There is no inplace version of transpose. It always returns a new tensor

Mathematical Operations on Tensors in PyTorch

We can perform various mathematical operations on tensors using Pytorch similar to NumPy arrays

```
Also works with operators - +, - *, /
    import torch
   # defining two tensors
   t1 = torch.tensor([1, 2, 3, 4])
                                                                tensor2 + tensor1
   t2 = torch.tensor([5, 6, 7, 8])
                                                                tensor([ 6, 8, 10, 12])
    # adding two tensors
    print("tensor2 + tensor1")
                                                                tensor2 - tensor1
                                                                tensor([4, 4, 4, 4])
    print(torch.add(t2, t1))
   # subtracting two tensor
                                                                tensor2 * tensor1
    print("\ntensor2 - tensor1")
                                                                tensor([ 5, 12, 21, 32])
    print(torch.sub(t2, t1))
                                                                tensor2 / tensor1
    # multiplying two tensors
                                                                tensor([5.0000, 3.0000, 2.3333, 2.0000])
    print("\ntensor2 * tensor1")
    print(torch.mul(t2, t1))
    # diving two tensors
    print("\ntensor2 / tensor1")
    print(torch.div(t2, t1))
```

From Python lists to PyTorch tensors

- List indexing vs
- List of three numbers in Python

```
[4]: a = [1.0, 2.0, 1.0]
  print(a[0])
  a[2] = 3.0
  a

1.0
[4]: [1.0, 2.0, 3.0]
```

Tensor indexing Import the torch module

Creates a one-dimensional tensor of size 3 filled with 1s

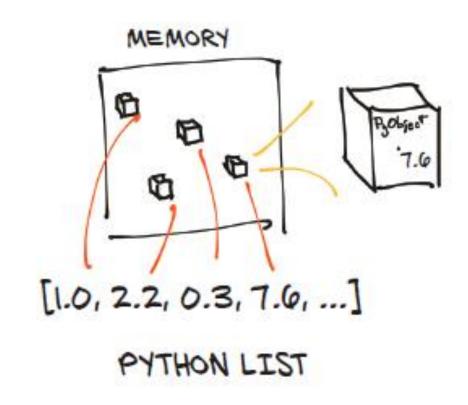
```
import torch
a = torch.ones(3)
print(a)
print(a[1])
print(float(a[1]))
a[2] = 2.0
print(a)
tensor([1., 1., 1.])
tensor(1.)
1.0
tensor([1., 1., 2.])
```

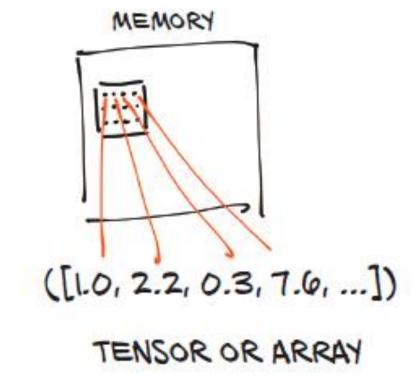
How tensors are different from a list? The essence of tensors

The essence of tensors

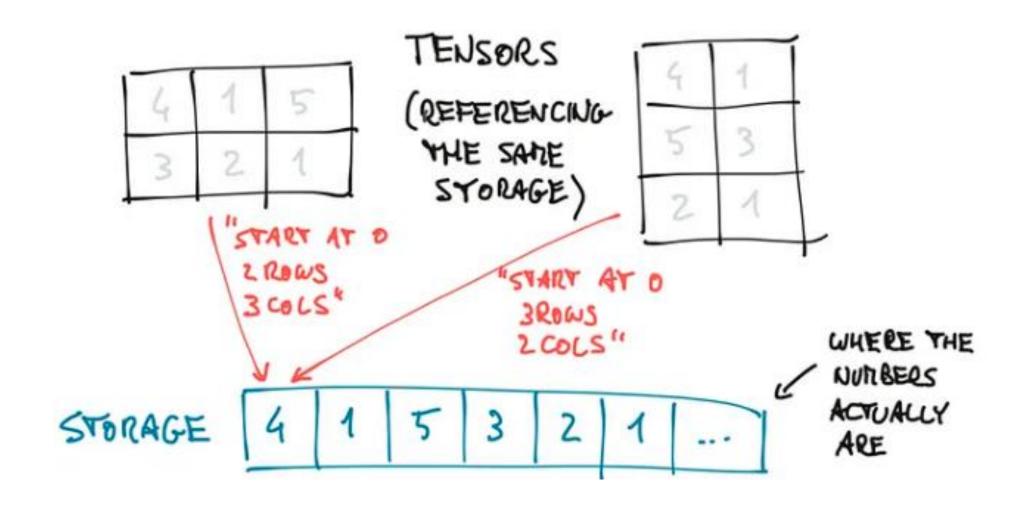
- Python lists or tuples of numbers are collections of Python objects that are individually allocated in memory (left side figure)
- PyTorch tensors or NumPy arrays, on the other hand, are views over (typically) contiguous memory blocks containing unboxed C numeric types rather than Python objects.
- Each element is a 32-bit (4-byte) float in this case (right side of figure)
- This means storing a 1D tensor of 1,000,000 float numbers will require exactly 4,000,000 contiguous bytes, plus a small overhead for the metadata (such as dimensions and numeric type).

The essence of tensors





Tensors are views over a Storage instance



Matrix Multiplication using PyTorch

- The methods in PyTorch expect the inputs to be a Tensor
- matrix multiplication methods:
- 1. torch.mm()
- 2. torch.matmul()
- 3. torch.bmm()
- 4. @ operator

torch.mm is a shortcut for matmul

Matrix multiplication using transpose

```
# Perform matmul on tensor_A and tensor_B
tensor A = torch.rand(size=(2,3)).to(device)
tensor_B = torch.rand(size=(2,3)).to(device)
print("tensor A=", tensor A)
print("tensor_B=", tensor_B)
# tensor C = torch.matmul(tensor_A, tensor_B) # won't work because of
shape error
print("tensor_B.T=", tensor_B.T)
tensor C = torch.matmul(tensor A, tensor B.T)
print("tensor C=", tensor C, tensor C.shape)
```

Matrix multiplication using transpose

```
tensor A= tensor([[0.0108, 0.9455, 0.7661],
    [0.2634, 0.1880, 0.5174])
tensor B= tensor([[0.7849, 0.1412, 0.3112],
    [0.7091, 0.1775, 0.4443]])
tensor B.T= tensor([[0.7849, 0.7091],
    [0.1412, 0.1775],
    [0.3112, 0.4443]]
tensor C = tensor([[0.3803, 0.5159],
    [0.3943, 0.4501]]) torch.Size([2, 2])
```

Matrix Multiplication using PyTorch - torch.mm()

- Computes matrix multiplication by taking an m×n Tensor and an n×p Tensor.
- It can deal with only two-dimensional matrices and not with single-dimensional ones.
- This function does not support broadcasting.
- Broadcasting is the way the Tensors are treated when their shapes are different.
- The smaller Tensor is broadcasted to suit the shape of the wider or larger Tensor for operations.
- torch.mm(Tensor_1, Tensor_2, out=None)
- The parameters are two Tensors and the third one is an optional argument. Another Tensor to hold the output values can be given there.

Matrix Multiplication using PyTorch - torch.mm()

Ex1: Same dimensions

```
import torch
mat 1 = torch.tensor([[1, 2, 3],
            [4, 3, 8],
             [1, 7, 2]]
mat_2 = torch.tensor([[2, 4, 1],
             [1, 3, 6],
             [2, 6, 5]]
torch.mm(mat 1, mat 2, out=None)
Ex2: tensor 1 is of 2\times2 dimension, tensor 2 is of 2\times3 dimension.
So the output will be of 2×3
import torch
mat 1 = torch.tensor([[1, 2], [4, 3]])
mat_2 = torch.tensor([[2, 4, 1], [1, 3, 6]])
torch.mm(mat_1, mat_2, out=None)
```

Matrix Multiplication using PyTorch - torch.mm()

```
Ex1: Same dimensions
                                                                             tensor([[10, 28, 28],
import torch
                                                                                 [27, 73, 62],
                                                                                 [13, 37, 53]])
mat_1 = torch.tensor([[1, 2, 3],
            [4, 3, 8],
            [1, 7, 2]]
mat_2 = torch.tensor([[2, 4, 1],
            [1, 3, 6],
            [2, 6, 5]]
torch.mm(mat 1, mat 2, out=None)
                                                                             tensor([[ 4, 10, 13],
Ex2: tensor_1 is of 2×2 dimension, tensor_2 is of 2×3 dimension.
                                                                                 [11, 25, 22]]
So the output will be of 2×3
import torch
mat_1 = torch.tensor([[1, 2], [4, 3]])
mat_2 = torch.tensor([[2, 4, 1], [1, 3, 6]])
torch.mm(mat 1, mat 2, out=None)
```

Matrix Multiplication using PyTorch - torch.matmul()

- Allows the computation of multiplication of single-dimensional matrices, 2D matrices and mixed ones also.
- This method also supports broadcasting and batch operations.
- Depending upon the input matrices dimensions, the operation to be done is decided.
- The general syntax is given below.
- torch.matmul(Tensor_1, Tensor_2, out=None)

Matrix Multiplication using PyTorch - torch.matmul()

Various possible dimensions of the arguments and the operations

argument_1	argument_2	Action taken
1-dimensional	1-dimensional	The dot product (scalar) is calculated
2-dimensional	2-dimensional	General matrix multiplication is done
1-dimensional	2-dimensional	The tensor-1 is prepended with a '1' to match dimension of tensor-2 a 1 for the purpose of the matrix multiply. After the matrix multiply, the prepended dimension is removed.
2-dimensional	1-dimensional	Matrix-vector product is calculated
1/N-dimensional (N>2)	1/N-dimensional (N>2)	Batched matrix multiplication is done

```
Ex1: Arguments of the same dimension
import torch
vec_1 = torch.tensor([3, 6, 2])
vec_2 = torch.tensor([4, 1, 9])
print("Single dimensional tensors :", torch.matmul(vec_1, vec_2))
# both arguments 2D
mat_1 = torch.tensor([[1, 2, 3],
            [4, 3, 8],
            [1, 7, 2]]
 mat_2 = torch.tensor([[2, 4, 1],
            [1, 3, 6],
            [2, 6, 5]]
out = torch.matmul(mat_1, mat_2)
print("\n3x3 dimensional tensors :\n", out)
```

```
Ex1: Arguments of the same dimension
import torch
vec_1 = torch.tensor([3, 6, 2])
vec 2 = torch.tensor([4, 1, 9])
print("Single dimensional tensors :", torch.matmul(vec_1, vec_2))
# both arguments 2D
mat_1 = torch.tensor([[1, 2, 3],
            [4, 3, 8],
            [1, 7, 2]]
 mat_2 = torch.tensor([[2, 4, 1],
            [1, 3, 6],
            [2, 6, 5]]
out = torch.matmul(mat_1, mat_2)
print("\n3x3 dimensional tensors :\n", out)
```

```
Ex1: Arguments of different dimensions
import torch
# first argument 1D and second argument 2D
mat1 1 = torch.tensor([3, 6, 2])
mat1 2 = torch.tensor([[1, 2, 3],
             [4, 3, 8],
             [1, 7, 2]]
out 1 = torch.matmul(mat1 1, mat1 2)
print("\n1D-2D multiplication :\n", out 1)
# first argument 2D and second argument 1D
mat2 1 = torch.tensor([[2, 4, 1],
             [1, 3, 6],
             [2, 6, 5]]
mat2_2 = torch.tensor([4, 1, 9])
# assigning to output tensor
out_2 = torch.matmul(mat2_1, mat2_2)
print("\n2D-1D multiplication :\n", out_2)
```

```
Ex1: Arguments of different dimensions
import torch
# first argument 1D and second argument 2D
mat1 1 = torch.tensor([3, 6, 2])
mat1 2 = torch.tensor([[1, 2, 3],
             [4, 3, 8],
             [1, 7, 2]]
out_1 = torch.matmul(mat1_1, mat1_2)
print("\n1D-2D multiplication :\n", out 1)
# first argument 2D and second argument 1D
mat2 1 = torch.tensor([[2, 4, 1],
             [1, 3, 6],
             [2, 6, 5]]
mat2_2 = torch.tensor([4, 1, 9])
# assigning to output tensor
out 2 = torch.matmul(mat2 1, mat2 2)
print("\n2D-1D multiplication :\n", out 2)
```

1D-2D multiplication: tensor([29, 38, 61])

2D-1D multiplication: tensor([21, 61, 59])

```
Ex3: N-dimensional argument (N>2)
import torch
# creating Tensors using randn()
mat 1 = torch.randn(2, 3, 3)
mat 2 = torch.randn(3)
# printing the matrices
print("matrix A :\n", mat 1)
print("\nmatrix B :\n", mat 2)
# output
print("\nOutput :\n", torch.matmul(mat 1, mat 2))
```

```
Ex3: N-dimensional argument (N>2)
import torch
# creating Tensors using randn()
mat 1 = torch.randn(2, 3, 3)
mat 2 = torch.randn(3)
# printing the matrices
print("matrix A :\n", mat 1)
print("\nmatrix B :\n", mat 2)
# output
print("\nOutput :\n", torch.matmul(mat 1, mat 2))
```

```
matrix A:
tensor([[[ 0.3437, -0.1045, 0.2069],
     [-0.7087, 3.0298, 1.8346],
     [1.0761, -0.2179, -0.0404]],
    [[ 0.9028, 0.6267, -0.6288],
     [-0.3468, -0.3376, 1.8786],
     [-0.9405, -0.8161, 0.2485]]])
matrix B:
tensor([-0.6310, -0.3815, -0.3336])
Output:
tensor([[-0.2460, -1.3208, -0.5824],
    [-0.5990, -0.2790, 0.8220]])
```

- provides batched matrix multiplication for the cases where both the matrices to be multiplied are of only 3-Dimensions (x×y×z) and the first dimension (x) of both the matrices must be same.
- This does not support broadcasting. The syntax is as given below.
- torch.bmm(Tensor_1, Tensor_2, deterministic=false, out=None)
- The "deterministic" parameter takes up boolean value. A 'false' does a faster calculation which is non-deterministic.
- A 'true' does a slower calculation however, it is deterministic.

Ex: the matrix_1 is of dimension $2\times3\times3$. The second matrix is of dimension $2\times3\times4$.

```
import torch
# 3D matrices
mat_1 = torch.randn(2, 3, 3)
mat_2 = torch.randn(2, 3, 4)

print("matrix A :\n",mat_1)
print("\nmatrix B :\n",mat_2)

print("\nOutput :\n",torch.bmm(mat_1,mat_2))
```

```
matrix A:
                                                           Output:
tensor([[[ 0.8639, 1.6221, 0.1931],
     [2.3902, 0.3274, -1.7375],
    [0.6995, -0.2053, -0.5686]],
    [[-0.9331, -0.3916, -0.8546],
    [-0.5468, -1.8374, -0.3086],
    [-2.2238, -1.2308, -1.0526]]])
matrix B:
tensor([[[-7.7382e-02, 5.3086e-01, -1.6793e+00, -
2.2021e+00],
     [1.1075e+00, -6.5119e-01, 8.2038e-04, 1.1264e-01],
     [-4.5405e-01, 6.0790e-01, -4.1423e-01, -3.0507e-01]],
    [[ 1.1997e+00, -1.0194e+00, 4.8544e-02, 6.8989e-01],
     [3.3041e-01, -9.4842e-01, -1.0319e+00, -5.3241e-01],
    [-5.0360e-01, 4.0240e-01, -8.7856e-02, 1.1704e-01]]])
```

Matrix Multiplication using PyTorch - @ operator

- @ operator:
- The @ Simon H operator, when applied on matrices performs multiplication element-wise on 1D matrices and
- normal matrix multiplication on 2D matrices.
- If both the matrices have the same dimension, then the matrix multiplication is carried out normally without any broadcasting/prepending.
- If any one of the matrices is of a different dimension, then appropriate broadcasting is carried out first and then the multiplication is carried out.
- This operator applies to N-Dimensional matrices also

Matrix Multiplication using PyTorch - @ operator

```
# single dimensional matrices
oneD 1 = torch.tensor([3, 6, 2])
oneD 2 = torch.tensor([4, 1, 9])
# two dimensional matrices
twoD 1 = torch.tensor([[1, 2, 3],
             [4, 3, 8],
             [1, 7, 2]]
twoD_2 = torch.tensor([[2, 4, 1],
             [1, 3, 6],
             [2, 6, 5]]
 # N-dimensional matrices (N>2)
 # 2x3x3 dimensional matrix
ND 1 = torch.tensor([[-0.0135, -0.9197, -0.3395],
            [-1.0369, -1.3242, 1.4799],
            [-0.0182, -1.2917, 0.6575]],
           [[-0.3585, -0.0478, 0.4674],
            [-0.6688, -0.9217, -1.2612],
            [1.6323, -0.0640, 0.4357]]])
```

```
# 2x3x4 dimensional matrix
ND 2 = \text{torch.tensor}([[[0.2431, -0.1044, -0.1437, -1.4982],
            [-1.4318, -0.2510, 1.6247, 0.5623],
            [1.5265, -0.8568, -2.1125, -0.9463]],
            [[0.0182, 0.5207, 1.2890, -1.3232],
            [-0.2275, -0.8006, -0.6909, -1.0108],
            [1.3881, -0.0327, -1.4890, -0.5550]]])
print("1D matrices output :\n", oneD 1 @ oneD 2)
print("\n2D matrices output :\n", twoD 1 @ twoD 2)
print("\nN-D matrices output :\n", ND 1 @ ND 2)
print("\n Mixed matrices output :\n", oneD_1 @ twoD_1 @
twoD 2)
```

Matrix Multiplication using PyTorch - @ operator

```
1D matrices output:
tensor(36)
2D matrices output:
tensor([[10, 28, 28],
    [27, 73, 62],
    [13, 37, 53]])
N-D matrices output:
tensor([[[ 0.7953, 0.5231, -0.7751, -0.1757],
     [3.9030, -0.8274, -5.1287, -0.5915],
     [2.8487, -0.2372, -3.4850, -1.3212]],
    [[0.6531, -0.1637, -1.1250, 0.2633],
    [-1.5532, 0.4309, 1.6526, 2.5166],
    [0.6491, 0.8869, 1.4995, -2.3370]]])
Mixed matrices output:
tensor([218, 596, 562])
```