## Viterbi algorithm

Input: observations of length T, state-graph of length N Output: best-path

for each state s from 1 to N do

$$q[1,s] \leftarrow p(s|s_0) \cdot p(o_1|s)$$
 backpointers $[1,s] \leftarrow 0$ 

for each time step t from 2 to T do for each state s from 1 to N do

$$q[t,s] \leftarrow \max_{s'=1}^{N} q[t-1,s'] \cdot p(s|s') \cdot p(o_t|s)$$

backpointers  $[t,s] \leftarrow \operatorname{argmax}_{s'=1}^N q[t-1,s'] \cdot p(s|s')$ 

$$s \leftarrow \operatorname{argmax}_{s'=1}^N q[T, s']$$
 return the backtrace path from backpointers  $[T, s]$