

# PSE Molekulardynamik Sheet 3: XML, Linked-cell algorithm and "falling drop - Wall"



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#### **XML** input



- Creation of XML schema file, organized elements in the following way
  - General parameters (output name, output frequency)
  - Simulation parameters (direct sum, linked cells)
  - Particles and objects of particles to simulate (single particles, cuboids, discs)
- Schema validation before reading
  - Check if files adhere to the specified XML schema before parsing them
  - Done for every file with the following declaration

xsi:noNamespaceSchemaLocation="../../src/fileHandling/reader/XMLHandling/ConfigurationFile.xsd"

- Use of Tree-Mapping
  - Ease of use, serialization back to DOM or XML, writing XML file back to disc





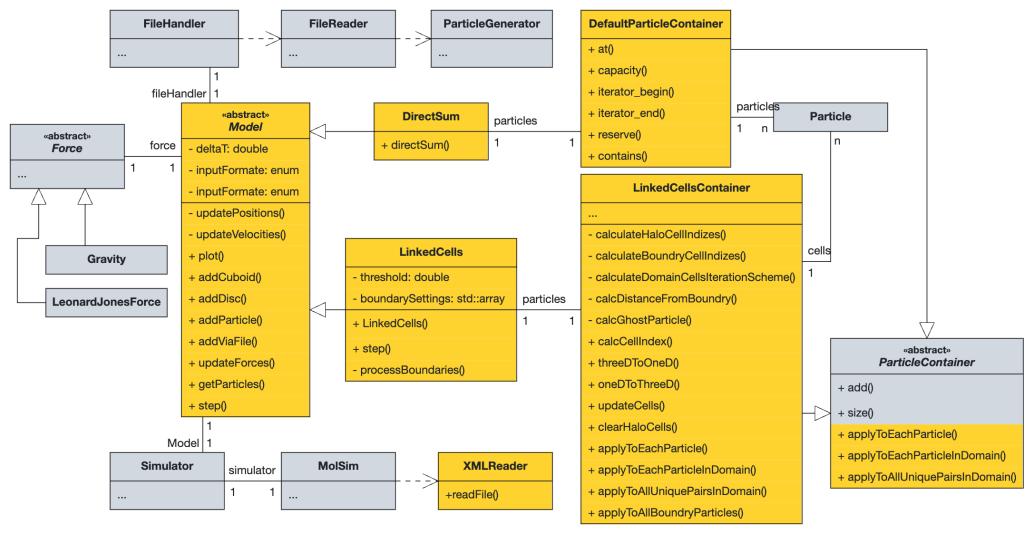
Division of the domain into cells

$$cell\_size = \frac{domain\_size}{number\ of\ cells} \qquad number\_of\_cells = \lfloor \frac{domain\_size}{cut-off\_value} \rfloor$$

- Data Structure: flattened 2D or 3D cell structure into one dimensional vector
- 2D Mode: save memory in 2D simulations by omitting halo cells from third dimension
- Iteration routes: pre calculate iterations routs in constructor
- Grouping of halo and boundary cells: front, back, left, right, top, bottom

### Linked-cell algorithm - Refactoring



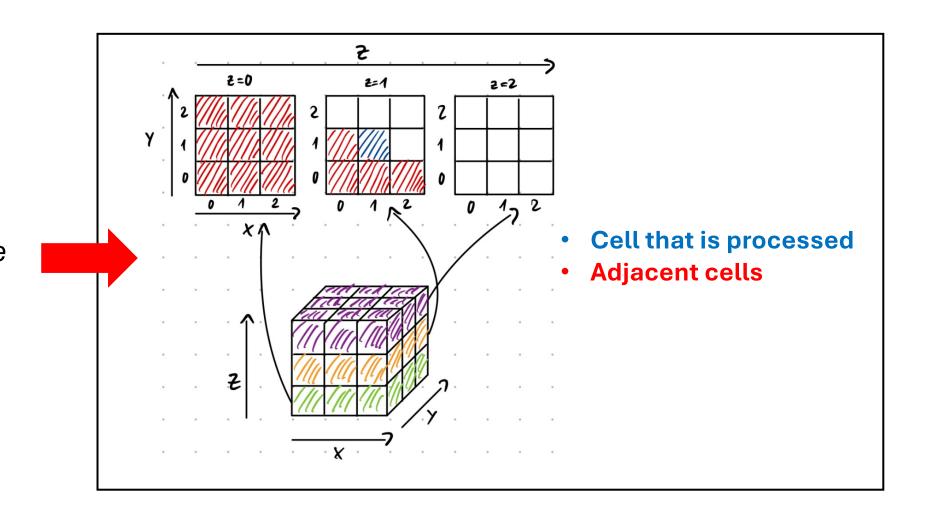






#### Challenge:

"Iterate over unique pairs of particles"





#### Linked-cell algorithm – Implementation

```
void LinkedCellsContainer::applyToAllUniquePairsInDomain(const std::functionvoid(Particle &, Particle &)> &function)
    for (auto& cellGroup: domainCellIterationScheme) {
        //First, consider all pairs within the cell that distance is smaller or equal then the cutoff radius
        for (auto p_i = cells[cellGroup[0]].begin(); p_i != cells[cellGroup[0]].end(); std::advance(p_i, 1)) {
            for (auto p_j = std::next(p_i); p_j != cells[cellGroup[0]].end(); std::advance(p_j, 1)) {
                if (ArrayUtils::L2Norm(p_i->getX() - p_j->getX()) <= rCutOff) {</pre>
                    function(*p_i, *p_j);
        //Then, consider all relevant neighbour cells
        for (auto neighbour = cellGroup.begin() + 1; neighbour != cellGroup.end(); std::advance(neighbour, 1)) {
            for (auto &p_i: cells[cellGroup[0]]) {
                for (auto &p_j: cells[*neighbour]) {
                    if (ArrayUtils::L2Norm(p_i.getX() - p_j.getX()) <= rCutOff) {</pre>
                        function(p_i, p_j);
```

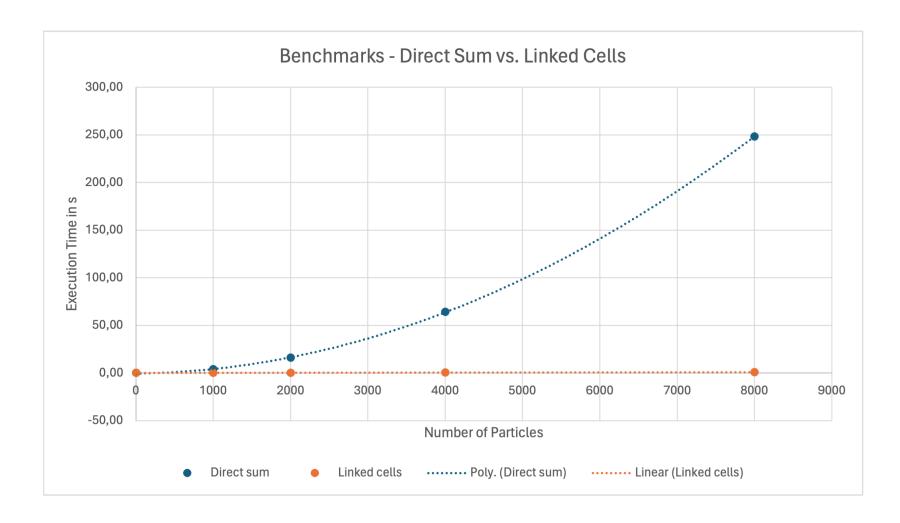




Operating system
Ubuntu 22.04.4 LTS

Processor Intel Core i5-6500 CPU @3.20Hz

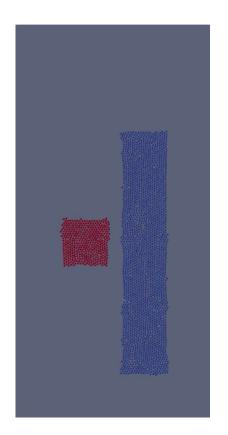
Memory 16 GiB

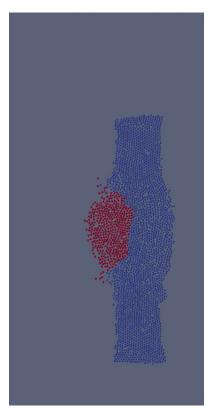


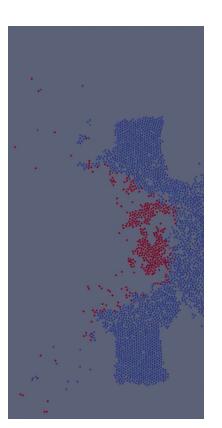


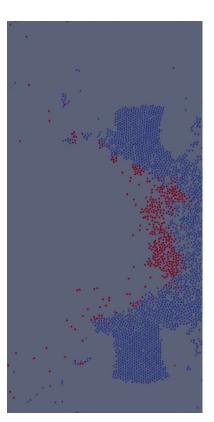


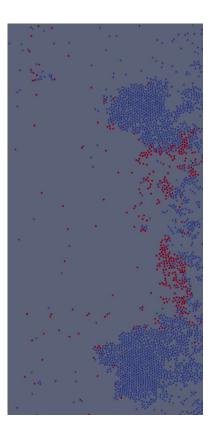
**Note:** Boundary conditions can also be set for each side independently (top, bottom, etc.)













## Simulation of a falling drop – Wall

