# Final Project: Aviation Safety Data Modeling

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# 1 Introduction

As the world become more globalized, different regions are becoming more and more interconnected by thousands of flights every day. Since the amount of air travel has been steadily increases, it is interesting to explore the safety of this mode of transportation through statistical analysis. Personally, Minervans are travelling the globe mostly with airplane so some insights on the safety features of airlines and aircraft types are also of interest. This project aims to use statistical methods to investigate two things: the general trend of air accident over the year and the mortality risks involved with air accident, using data from the Aviation Safety Network.

	day	month	year	type	operator	fat.	cat	Aircraft Type	Aircraft Cat	date
0	1	04	1931	Ford 5-AT-C Tri-Motor	Panagra	0	A1	Military_research	Military	1931-04-01
1	1	04	1937	Ford 5-AT-C Tri-Motor	Star Air Service	0	A1	Military_research	Military	1937-04-01
2	1	04	1956	Martin 4-0-4	TWA	22	A1	Commercial_civil	Commercial	1956-04-01
5	1	08	1942	Junkers Ju-52/3mg4e	German AF	0	A1	Commercial_civil	Commercial	1942-08-01
6	1	12	1984	Boeing 720-027	NASA	0	01	Commercial_civil	Commercial	1984-12-01

Figure 1: Examples Of Cleaned Data

The Aviation Safety Network (ASN) provides a comprehensive record of air accidents for both commercial and military aircrafts carrying at least two people, including cargo and research flights. Unfortunately the data is not accessible in a convenient format, so we transcribed the data from the ASN website to a spreadsheet, with raw information about the date of the accident, the airline operated the flight (e.g., American Airlines, Nippon AIr, etc.), the type of aircraft involved (e.g., Boeing 747, Airbus A300, etc.), the number of fatality and the category of accident (e.g., mechanical issues, hijacking, etc.) The raw data is then cleaned in the following order:

- Three accidents without dates are omitted from analysis
- Aircraft type was matched with a list of commercial and military aircraft on Wikipedia, then classified as such. Accidents with unknown aircraft types were also omitted
- A commercial airline list from Wikipedia were also matched with the airline in the raw data to double-check the initial classification by the aircraft type. Mismatches between the two methods were visually inspected, and aircraft types that were used by both military and commercial purposes were classified as commercial if a known commercial airline employed those types

The code for cleaning data is included in appendix A1 and some examples of the cleaned data is shown in Figure 1. Variable cat represents the category of accident (which will be explained in details in section 3), and the number following the category is whether the aircraft was repairable or was a hull loss (1 for hull loss, 2 for repairable). Further data processing is described in section 2 and 3.

# 2 Accident Trends

First, the cleaned data is categorized into two subsets: commercial and military. This is justified for modeling trends because both subsets are governed by very different events in the real world (for example, military accident peaks when there is a war). Counting the number of accidents in a year, we have roughly 100 datapoints for each subset from 1919 to 2018. The first 70 years will be used in the modeling step and the rest of the data will act as a validation set to confirm our models. A visualization of both subsets is shown in Figure 2.

Two modeling techniques will be considered: Bayesian linear model and statistical sampling using Stan. Both techniques can quantify uncertainty in their predictions but they rely on different assumptions.

### 2.1 Global trend: Linear Model

We assume two things for both model: 1) the global trend is linear with some fluctuations modeled as random noise and 2) even though the observed quantity is integer, we model the trend as a continuous variable with rounding. A linear model has three unobserved variables: the coefficient for the slop, the intercept and the noise due to unaccounted fluctuation of the data. The Bayesian regression framework that Scikit-learn implements (figure 3a) assumes the number of accident is generated by a normal distribution with the trend modeled as a linear combination between product of the slope and the year and the intercept, plus some random noise (which, in turn, has a Cauchy prior with scale=1 and  $x_0 = 1$ ). Both the slope and the intercept are generated by a multivariate normal distribution with a vector mean  $\mu$  and a covariance matrix  $\lambda \mathbb{I}$ .  $\mu$ 

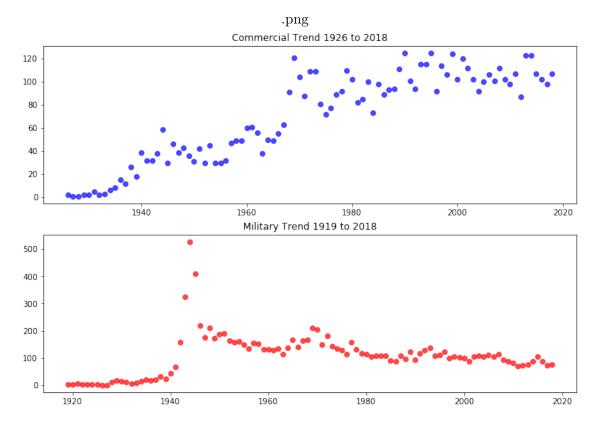


Figure 2: Number Of Accident Per Year, 1919 To 2018

and  $\lambda$  are generated by two Gamma distributions with hyperparameters. The hyperparameters and parameters for this model is jointly estimated by expectation maximization (maximizing the marginal log likelihood).

```
model_trend = """
2
  data {
  //Data and its length
       int<lower=1> length;
       real < lower = 0 > data_[length];
   //Number of generated values
       int<lower=0> n_gen;
8
9
10
  parameters {
11
       //Linear trend model, with 2 coefficients
12
       real coef_1;
13
       real coef_2;
14
       real<lower=0> noise;
15
16
17
18 model {
```

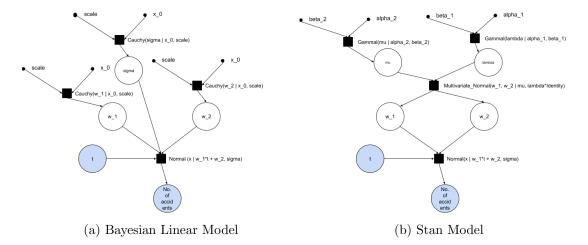


Figure 3: Factor Graph Of Linear Models

```
#Each coefficient is drawn from a broad Cauchy
19
       coef_1 ~ cauchy(0,1);
20
       coef_2 cauchy (0,1);
noise cauchy (0,1);
21
22
       for (i in 1:length) {
23
            data_[i] ~ normal(coef_1*i + coef_2, noise);
24
25
26
27
   generated quantities {
28
       real data_gen[n_gen];
29
       for(i in 1:n_gen) {
30
           data_gen[i] = normal_rng(coef_1*(i+length) + coef_2, noise);
31
32
33
34
stan_model_trend = pystan.StanModel(model_code=model_trend)
```

The Stan model (figure 3b), specified by code above, has a different priors. The slope, intercept and noise are generated by three different broad Cauchy since we assume we don't know the ranges of these parameters beforehand, and these Cauchy-s have specified hyperparameters. The estimations of the parameters are obtained using MCMC sampling of the posterior.

In figure 4a, we can see that model fitted the linear trend reasonably well, with the confidence interval widening where we do not observed the data. Predictions for the unseen data indicates that because we assumes a linear trend, the model fails to anticipate the plateau right after the training data. A similar failure happens to the generated samples of the Stan model in figure 4b. This situation is to be expected since the assumption of linear trend is a strong one that does not hold in this case due to many factors, such as improvements of technical aspects of the aircrafts or the advent of inter-

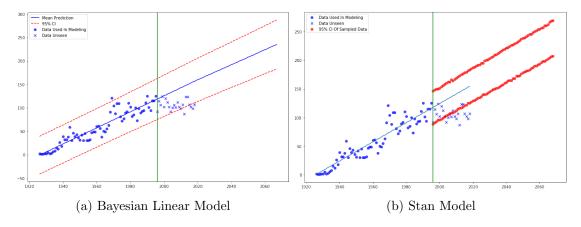


Figure 4: Predictions Of Linear Models - Commercial

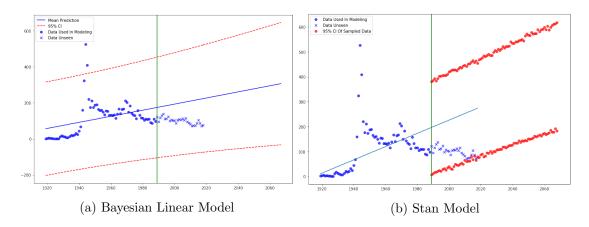


Figure 5: Predictions Of Linear Models - Military

national safety standards in aviation. Interestingly, due to the effect of WWII, the linear trend assumption worked even poorer for the military accidents (figure 5), as shown by the wide confidence intervals of both the Bayesian and the Stan model. Another point worth mentioning is that the estimations of the coefficients by both models with different constructions and different methods of estimations (variational versus MCMC) are the same. This might because in a simple linear model with only two parameters, especially when one of them is the intercept which depends only on the chosen coordinate system, the parameters are independent of each other so estimations using a multivariate normal (Bayesian model) do not differ much from estimations using independent Cauchy-s (Stan model).

# 2.2 Global trend: Quadratic Model

1 model\_trend = """

```
з data {
  //Data and its length
       int<lower=1> length;
       real < lower = 0 > data_[length];
  //Number of generated values
       int < lower = 0 > n_gen;
8
9
10
  parameters {
11
       //Quadratic trend model, with 3 coefficients
12
13
       real coef_2;
14
15
       real coef_3;
       real<lower=0> noise;
16
17
18
  model {
19
       #Each coefficient is drawn from a broad Cauchy
20
       coef_1 cauchy (0,1);
21
       coef_2 ~ cauchy (0,1);
22
       coef_3 ~ cauchy(0,1);
23
       for(i in 1:length) {
24
                      normal(coef_1*i*i + coef_2*i + coef_3, noise);
25
26
27
28
  generated quantities {
29
       real data_gen[n_gen];
30
       for(i in 1:n\_gen) {
31
           data_gen[i] = normal_rng(coef_1*(i+length)*(i+length) + coef_2*(i+
32
      length) + coef_3 , noise);
33
34
35
  stan_model_trend = pystan.StanModel(model_code=model_trend)
```

The only different between the quadratic model and the linear model is that we have three coefficients instead of two: the additional one accounts for the quadratic effect of  $t^2$ . The factor graphs do not differ much from the linear model, but the predictions do. In figure 6, because up to the point where the training data is fed to the model, the trend seems relatively linear so the coefficient of the squared term is small. However, this small term contributes to the rapid widening of the confidence interval since the model assumes a quadratic trend ought to happen at some point in the future, diverging the predictions. Similar observations can be made with the Stan model, where the generated values are also diverging quickly, albeit not as much as the Bayesian model. This is because the interaction between t and  $t^2$  expressed by the estimated covariance matrix of the Bayesian model (since it uses a multivariate normal and the coefficients are generated jointly from them) magnifies the non-linear trend. The performance of the quadratic model is even worse in the military subset in figure 7. As we can see, the model mistakenly assumes a downward trend (since the main assumption is that the

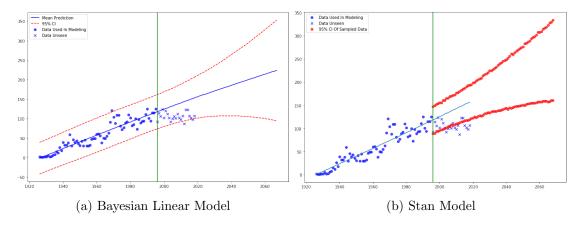


Figure 6: Predictions Of Quadratic Models - Commercial

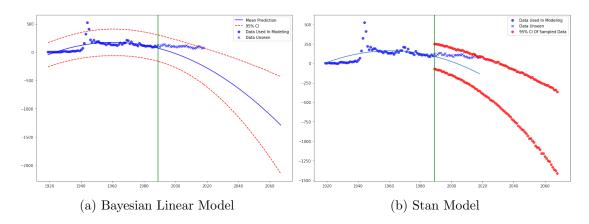


Figure 7: Predictions Of Quadratic Models - Military

trend is quadratic) from WWII on, making the prediction seriously off. Furthermore, since we make no explicit specification for the sign of the observed data (which should be positive) the model predicts negative values.

Clearly, modeling the global trend in this case is not good since no obvious trend can be observed by inspection of the data, and if we keep adding polynomial terms we risk overfitting the model. It's natural to consider modeling the local trend instead, since we might suspect the number of accident per year is affected most by the most recent years, and the further away the less effect any event might have. For example, it's unlikely that WWII has much effect in the difference between the number of accident in 1980 and 1981, but it's highly likely that the number of accidents in WWII is a good predictor for the next few years.

#### 2.3 Local trend: Radial Basis Function Model

A radial basis function has the form

$$f(x, x_0) = e^{-\frac{(x-x_0)^2}{\sigma}}$$

which measures the similarity (by Euclidean distance) between the current point x and a pivot point  $x_0$ . This measure of similarity and be used as a feature to indicate the relative position between the data, and since the effect of the pivot point diminish exponentially with the distance between the points, datapoints separated by a long distance won't have much similar trend, which is exactly what we need to model local trend. Using 100 evenly spaced pivot points between 1919 and 2119 then calculate these similarity measures, we can fit both a Bayesian model and an MCMC model.

```
scaler = MinMaxScaler()
_{2} N = 70
4 #Using sklearn rbf kernel
5 from sklearn.metrics.pairwise import rbf_kernel
7 #100 pivot points
s \text{ kernel} = np. linspace (0,2,100). reshape (-1,1)
9 #Rescaling the year to the range 0 to 1, a standard procedure before
      fitting
10 year_count_com['index'] = scaler.fit_transform(np.array(year_count_com['
      index']).reshape(-1,1))
11
12 X_train = rbf_kernel(np.array(year_count_com['index'][:N]).reshape(-1,1),
      kernel, gamma=10)
13
14 #Using Bayesian model and plotting the results
15 reg = BayesianRidge()
16 reg. fit (X_train, year_count_com['year'].iloc[:N])
plt. figure (figsize = (12,8))
18 x = year_count_com['abs_year']
plt.scatter(x[:N], year_count_com['year'][:N], color='b', alpha=0.7, label=
      'Data Used In Modeling')
20 plt.scatter(x[N:], year_count_com['year'][N:], color='b', marker='x', alpha
      =0.7, label='Data Unseen')
21
22 X_test = rbf_kernel(np.array(year_count_com['index']).reshape(-1,1),\
                       kernel, gamma=10)
24 y-m, y-std = reg.predict(X-test, return_std=True)
25 plt.plot(x, np.round(y_m), color='b', label='Mean Prediction')
26 plt.plot(x, np.round(y_m+2.96*y_std), color='r', linestyle='--', label='95%
       CI'
plt.plot(x, np.round(y_m-2.96*y_std), color='r', linestyle='--')
f_x = np. linspace(1, 1.5, 50). reshape(-1, 1)
K_f_x = rbf_kernel(f_x, kernel, gamma=10)
```

```
31 f_y_m, f_y_std = reg.predict(K_f_x, return_std=True)
f_x = range(2018, 2018+50)
33 plt.plot(f_x, np.round(f_y_m), color='b')
plt.plot(f_x, np.round(f_y_m+2.96*f_y_std), color='r', linestyle='--')
 {\rm 35~plt.plot}\,(\,f_-x\;,\; {\rm np.round}\,(\,f_-y_-m\,-2.96*\,f_-y_-std\,)\;,\; {\rm color}='r\;'\;,\; {\rm linestyle}='--') 
37 plt.axvline(x[N], color='g')
38 plt.legend()
39 plt.show()
40
41 #Using Stan model
42 model_trend_main = """
43
44 data {
   //Data and its length
45
       int<lower=1> length;
46
       real<lower=0> data_[length];
47
   //Number of radial basis points or number of coefficients
48
       int<lower=1> c;
49
   //Kernelized value of the training data
50
       vector[c] rbf_train[length];
51
  //Number of generated values
52
       int < lower = 0 > n_gen;
53
  //Kernelized value of the generated data
       vector[c] rbf_gen[n_gen];
55
56
57
58 parameters {
  //RBF model, with c basis points
59
       row_vector[c] coef_;
60
   //Intercept
61
       real intercept;
62
    /Gaussian noise
63
       real<lower=0> noise;
64
65
66
67 model {
   //Each coefficient is drawn from a broad Cauchy
       for (j \text{ in } 1:c) {
coef_{-}[j] ~ cauchy (0,1);
69
70
71
       for(i in 1:length) {
72
            data_[i] ~ normal((coef_*rbf_train[i]) + intercept, noise);
73
74
75
76
77
  generated quantities {
       real data_gen[n_gen];
78
       for (i in 1: n_gen) {
79
            data_gen[i] = normal_rng((coef_*rbf_gen[i]) + intercept, noise);
80
81
82
83
84 trend_model = pystan.StanModel(model_code=model_trend_main)
```

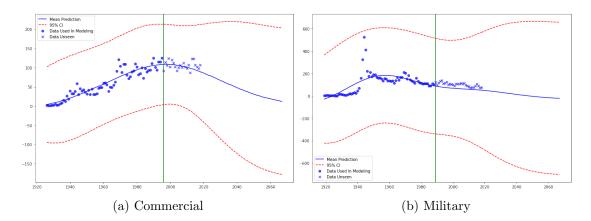


Figure 8: Predictions Of RBF Bayesian Models

```
kernel = np. linspace(0,2,100). reshape(-1,1)
   X_{\text{train}} = \text{rbf\_kernel(np.array(year\_count\_com['index'][:N]).reshape(-1,1)},
       kernel, gamma=10)
   X_gen = rbf_kernel(np.array(year_count_com['index'].iloc[N:]).reshape(-1,1)
       , kernel, gamma=10)
   f_{-}X = np.linspace(1, 1.5, 50).reshape(-1, 1)
   K_fX = rbf_kernel(f_X, kernel, gamma=10)
   X_{gen} = np.concatenate((X_{gen}, K_{f_{-}}X), axis=0)
91
92
   stan_data = {
93
        length ': year_count_com['year'][:N].shape[0],
94
        data_': np.array(year_count_com['year'][:N]),
95
        'c': 100,
96
        'rbf_train': X_train,
97
        'n_{gen}': year_{count\_com}['year'][N:].shape[0] + 50,
        'rbf_gen': X_gen
99
100
   results = trend_model.sampling(data=stan_data)
101
samples = results.extract()
```

In Figure 8 we can see the Bayesian models of commercial and military accidents. By modeling the local the prediction for unseen data is reasonably accurate for both case, and as we expect the confidence interval widened for regions we do no observe data. For this type of model it's important to select the number of pivot points appropriately since if we have too many pivot points we will just model random fluctuations in the data which means we are overfitting. Too few pivot points mean we essentially abandon the local trend for the global trend. Another point woth mentioning is that in figure 9 a failure mode of MCMC sampling is observed: because the pivot points are closed, the coefficients are closely dependent and therefore the posterior has multiple separated peaks, which is the type of distribution Stan hates the most. Thus, R-hat shows that the chains did not mix well and we observe the haywire prediction (full results in the code).

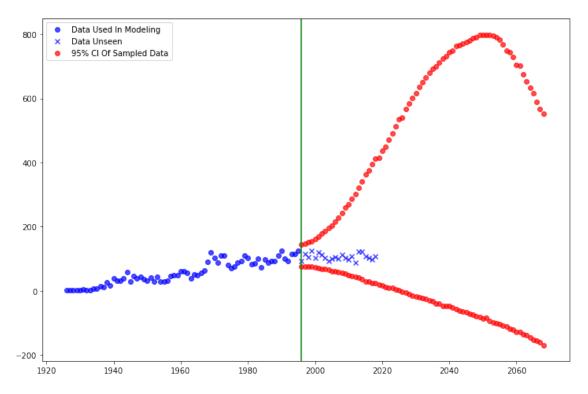


Figure 9: Stan RBF Model

# 3 Mortality Risks & Hull Loss Risks

In the unfortunate event of an accident, we are interested in the risk of fatality given the type of accident we are in, the type of aircraft and the airline operator. Given that the commercial subset is of particular interest in this scenario, we will focus the analysis on this subset, but the model can also be used for the military subset. First, due to the large amount of data available, and as established from the previous section: more recent accident data is more informative to predict future events, we select only a part of the commercial subset for analysis. Given that most commercial aircraft still available today is of either Boeing or Airbus, we select only these aircraft types. We also select only the top 25 airline with the most recorded accident because sampling for the full list of available airline (around 1300) will take too much time. After further cleaning, we have about 620 datapoints for analysis.

```
stan_model_risk = """

data {
//Number of airline
```

```
int<lower=1> L;
   //Number of aircraft
        int<lower=1> C;
   //Number of accident type
        int < lower = 1 > T;
   //Number of datapoint
10
        int < lower = 1 > N;
11
12
   //\mathrm{A} vector of 0/1 in each entry expressing which airline, aircraft and
13
       accident type the datapoint is
        vector < lower = 0 > [L] airline [N];
14
        \begin{array}{ll} vector < lower = 0 > [C] & aircraft [N]; \\ vector < lower = 0 > [T] & accident [N]; \end{array}
15
16
17
   //A vector expressing the number of passenger on that aircraft
18
        int < lower = 0 > passenger [N];
19
20
   //Number of fatality
21
        int < lower = 0 > fat[N];
22
23
24
25
   parameters {
26
27
28
   //Scaling factor for the airline
29
        row_vector<lower=0, upper=1>[L] m_al;
30
   //Scaling factor for the aircraft
        {\scriptstyle \texttt{row\_vector} < \texttt{lower} = 0, \texttt{ upper} = 1 > [C] \texttt{ m\_ac};}
31
   //Scaling factor for the accident type
32
        row_vector < lower = 0, upper = 1 > [T] m_a;
33
34
   //Mortality rate
35
        real<lower=0, upper=1> p;
36
37
38
   model {
39
40
        for (1 in 1:L){
41
             m_al[l] \sim lognormal(0,0.25);
42
43
44
        for (c in 1:C) {
45
             m_{ac}[c] \sim lognormal(0,0.25);
46
47
        for (t in 1:T){
49
             m_a[t] \sim lognormal(0,0.25);
50
51
52
        for(i in 1:N) {
53
             #Sample the mortality rate from a beta distribution, with scaling
54
        factor from the airline, aircraft and accident
             p ~ beta(((m_al*airline[i])+(m_ac*aircraft[i])+(m_a*accident[i])),
55
```

```
fat[i] ~ binomial(passenger[i], p);

fat[i] ~ binomial(passenger[i], p);

model_risk = pystan.StanModel(model_code=stan_model_risk)
```

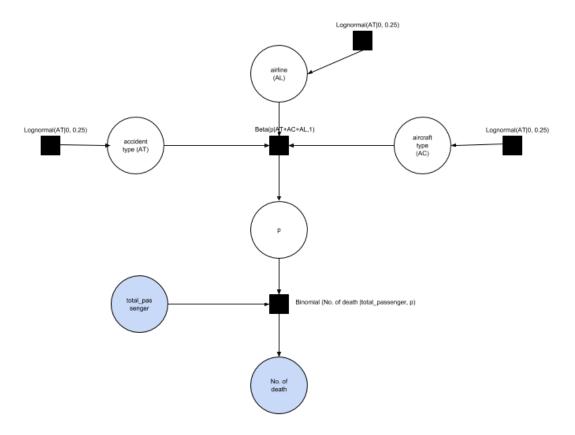


Figure 10: Mortality Risk Model Factor Graph

The model is specified in Stan code above and described in figure 10 factor graph. The unobserved variable of the model includes p, the mortality rate; airline scale factor, which is used as a component of the alpha parameter for the beta distribution; aircraft type scale factor and accident type scale factor. The mortality rate is generated from a beta distribution that skewed to the left if the scale factor sum is large, so larger value of the scale factor means higher chance of death. Finally the number of death is generated from a binomial with the total number of passenger on the plane (depends on the aircraft) and the mortality rate. The results are presented in figure 11 and 12.

In figure 11a we can see that relatively the airlines have quite similar "risk factor". The highest risk belongs to VASP, and the lowest seems to be American Airlines. Com-

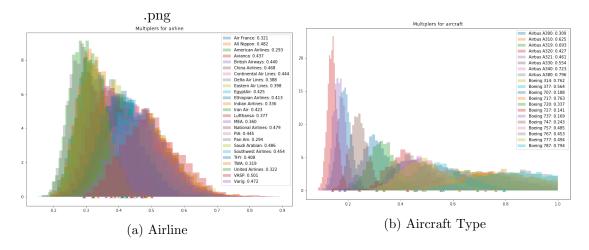


Figure 11: Posteriors Of Scaling Factor - Mortatily Risk

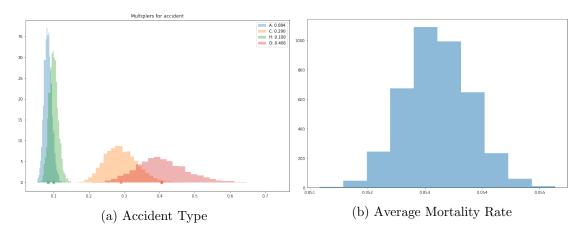


Figure 12: Posteriors Of Scaling Factor - Mortality Risk

pared to the airline, the aircraft type plays a bigger role in the risk of fatality. Bigger airplane (in terms of carrying capacity) seems generally safer, but the biggest airplane in the group, Airbus A380, has the higher scaling factor, which suggests when an accident happen to a big plane it's very usually catastrophic. In figure 12 we can see the most risky type of accident is O type, which is ground fire or sabotage. The mortality rate seems low (0.05 on average, suggesting that usually only 5% of passengers die in an accident), which makes sense intuitively considering how safe aviation travel is.

The same analysis can be made for classification of whether it's a hull loss or not by replacing the binomial distribution as the likelihood by a bernoulli. The results, summarized in figure 13 and 14, suggests that generally the risk for hull-loss is very high (76%) should an accident occur, and all scaling factor concentrates near 1, indicating a high risk of hull-loss in any event of accident (although some type of aircraft or accident seems

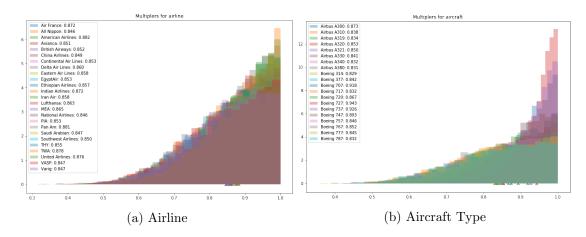


Figure 13: Posteriors Of Scaling Factor - Hull-Loss Risk

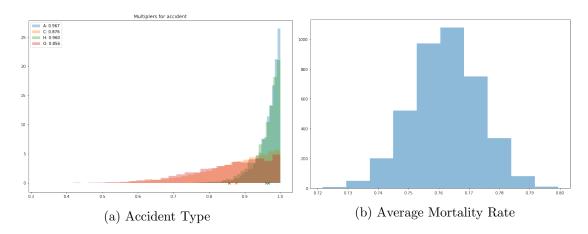


Figure 14: Posteriors Of Scaling Factor - Hull-Loss Risk

to have more variability in terms of being responsible for hull-loss, like C-type accident, which is criminal occurrence, seems to have a high variance, which makes sense since extreme cases like 9/11 is rare).

## **APPENDIX**

#### Data

```
Original Data: https://aviation-safety.net/database/
```

Cleaned Data: https://docs.google.com/spreadsheets/d/1KIOE4XdHbQHs5tCCoYuYpMjXw\_s-0ME32gQ2Fs0zWbc/edit?usp=sharing

```
List of aircraft by type: https://en.wikipedia.org/wiki/List_of_aircraft_by_date_and_usage_category
```

List of commercial airline: https://en.wikipedia.org/wiki/List\_of\_fighter\_aircraft

# Full code

```
1 import pandas as pd
2 import matplotlib.pyplot as plt
з import numpy as np
4 import pystan
5 from sklearn.linear_model import LinearRegression, BayesianRidge
6 from sklearn.preprocessing import MinMaxScaler
8 data = pd.read_csv('/Users/ash/Downloads/clean.csv')
10 def clean_day_year(obj):
      return int(obj)
11
12
13 def clean_month(obj):
       month = str(obj).lower()
14
      if month == 'jan':
month = '01'
15
16
       elif month == 'feb':
17
           month = '02'
18
       elif month == 'mar':
19
           month = '03'
20
       elif month == 'apr':
^{21}
          month = '04'
22
       elif month == 'may':
23
          month = '05'
24
       elif month == 'jun':
25
           month = '06'
26
       elif month == 'jul':
27
           month = ,07,
28
       elif month == 'aug':
29
           month = 0.08,
       elif month == 'sep':
31
           month = '09'
32
       elif month == 'oct':
33
          month = '10'
34
```

```
elif month == 'nov':
35
                      month = '11'
36
               elif month == 'dec':
37
                      month = '12'
              return month
39
40
     def clean_fat(obj):
41
              fat = str(obj)
42
              if fat. find ('+') = -1:
43
                       return int(fat)
44
               elif fat.find('+') != "+":
45
                       total = int(fat[0:fat.find('+')]) + int(fat[fat.find('+')+2:])
46
47
                       return int(total)
49
     data = data.dropna()
     data['day'] = data['day'].apply(clean_day_year)
     data['year'] = data['year'].apply(clean_day_year)
    data['month'] = data['month'].apply(clean_month)
     data['fat.'] = data['fat.'].apply(clean_fat)
54
55 data ['date'] = pd.to_datetime(data [['day', 'month', 'year']])
56 data.head()
57
58 com = data.loc[data['Aircraft Cat'] == 'Commercial']
59 mil = data.loc[data['Aircraft Cat'] == 'Military']
60 print ('Commercial Size:', com.shape)
61 print ('Miliatary Size:', mil.shape)
62
63 #general trend by
64 year_count_com = (com['year'].value_counts()).reset_index()
65 year_count_com = year_count_com.sort_values(by=['index'], kind='mergesort')
66 year_count_com = year_count_com.reset_index(drop=True)
68 year_count_mil = mil['year'].value_counts().reset_index()
     year_count_mil = year_count_mil.sort_values(by=['index'], kind='mergesort')
    year_count_mil = year_count_mil.reset_index(drop=True)
70
72 plt. figure (figsize = (12,8))
73 plt.subplot (2,1,1)
     plt.scatter(range(year_count_com['index'].iloc[0], year_count_com['index'].
             iloc[-1]+1),
                                year_count_com['year'], color='b', alpha=0.7)
75
     plt.title('Commercial Trend {} to {}'.format(year_count_com['index'].iloc
             [0], year_count_com ['index']. iloc [-1])
    plt.subplot(2,1,2)
     plt.scatter(range(year_count_mil['index'].iloc[0], year_count_mil['index'].
             iloc[-1]+1),
                                year_count_mil['year'], color='r', alpha=0.7)
79
     plt.title ('Military Trend \{\} 'to ' \{\}' .format (year\_count\_mil['index'].iloc[0]', format (year\_count\_mil['index'].iloc[0]', format (year\_count\_mil['index'].iloc[0]'), format (year\_count\_mil['index']), format (year\_count\_mil['index']), format (year\_count\_mil['index'])), format (year\_count\_mil['index']), format (year\_count\_mil['index'])), format (year\_count\_mil['index']))), format (year\_count\_mil['index']))), format (year\_count\_mil['index'])))))))))))))))))))))))))))
             year\_count\_mil['index'].iloc[-1]))
     plt.show()
81
82
83 year_count_com['abs_year'] = year_count_com['index']
84 year_count_mil['abs_year'] = year_count_mil['index']
```

```
def visualize_posterior (samples, names):
85
       for _ in names:
86
           plt. figure (figsize = (12,4))
87
           plt.hist(samples[_])
           plt.title('Posterior samples of '+-)
89
       plt.show()
90
91
92 scaler = MinMaxScaler()
93 N = 70
94
   year_count_com ['index'] = scaler.fit_transform(np.array(year_count_com['
      index']).reshape(-1,1))
96 reg = BayesianRidge()
  reg.fit(np.array(year_count_com[['index']].iloc[:N,:]), year_count_com['
       year '].iloc[:N])
  plt. figure (figsize = (12,8))
99 x = year_count_com['abs_year']
plt.scatter(x[:N], year_count_com['year'][:N], color='b', alpha=0.7, label=
       'Data Used In Modeling')
  plt.scatter(x[N:], year_count_com['year'][N:], color='b', marker='x', alpha
      =0.7, label='Data Unseen')
102 y_m, y_std = reg.predict(np.array(year_count_com[['index']]), return_std=
      True)
plt.plot(x, np.round(y_m), color='b', label='Mean Prediction')
  plt.plot(x, np.round(y_m+2.96*y_std), color='r', linestyle='--', label='95%
       CI'
plt.plot(x, np.round(y_m-2.96*y_std), color='r', linestyle='--')
106
f_x = np. linspace (1, 1.5, 50)
108 f_{-y-m}, f_{-y-std} = reg.predict(f_x.reshape(-1,1), return_std=True)
f_x = range(2018, 2018+50)
plt.plot(f_x, np.round(f_y_m), color='b')
plt.plot(f_x, np.round(f_y_m+2.96*f_y_std), color='r', linestyle='--')
plt.plot(f_x, np.round(f_y_m-2.96*f_y_std), color='r', linestyle='--')
plt.axvline(x[N], color='g')
plt.legend()
116 plt.show()
117
model_trend = """
119
120 data {
   //Data and its length
121
       int<lower=1> length;
122
       real<lower=0> data_[length];
   //Number of generated values
       int < lower=0> n_gen;
125
126
127
   parameters {
128
       //Linear trend model, with 2 coefficients
129
       real coef_1;
130
131
       real coef_2;
       real<lower=0> noise;
132
```

```
133
134
   model {
       #Each coefficient is drawn from a broad Cauchy
137
       coef_1 cauchy (0,1);
       coef_2 ~ cauchy(0,1);
138
       noise \tilde{} cauchy (0,1);
139
       for (i in 1:length) {
140
            data_[i] ~ normal(coef_1*i + coef_2, noise);
141
142
143
144
145
   generated quantities {
146
       real data_gen[n_gen];
       for (i in 1: n_gen) {
147
            data_gen[i] = normal_rng(coef_1*(i+length) + coef_2, noise);
148
149
150
151
   stan_model_trend = pystan.StanModel(model_code=model_trend)
152
153
  stan_data = {
154
        'length': year_count_com['year'][:N].shape[0],
155
        'data_': np.array(year_count_com['year'][:N]),
        'n_gen': year_count_com['year'][N:].shape[0] + 50
157
158 }
159
  results = stan_model_trend.sampling(data=stan_data)
  samples = results.extract()
160
161
   paras =['coef_1', 'coef_2', 'noise']
162
   print(results.stansummary(pars=paras))
163
164
  #From CS146 - 14.1 Pre-class, Professor Carl Scheffler
165
   def plot_acf(x):
166
       from scipy import signal
       plt.acorr(
168
            x, maxlags=20, detrend=lambda x: signal.detrend(x, type='constant')
169
170
171
   for param in paras:
172
       plt. figure (figsize = (12, 4))
173
       plot_acf(samples[param])
174
       plt.title(f'Autocorrelation of {param} samples')
175
177
   plt.show()
178
   visualize_posterior (samples, paras)
179
180
181 future = samples['data_gen']
_{182} f_interval = np.percentile(future, axis=0, q=[2.5, 97.5])
183 plt . figure (figsize = (12,8))
184 x = year_count_com['abs_year']
185 plt.scatter(x[:N], year_count_com['year'][:N], color='b', alpha=0.7, label=
```

```
'Data Used In Modeling')
     plt.scatter(x[N:], year_count_com['year'][N:], color='b', marker='x', alpha
             =0.7, label='Data Unseen')
     x_{-} = range(1, year\_count\_com['index']. shape[0]+1)
     y = np.round([x_{-}[i]*np.mean(samples['coef_1'])+np.mean(samples['coef_2'])
             for i in range(len(x))])
plt.plot(year_count_com['abs_year'], y)
      plt.scatter(x[N]+range(stan_data['n_gen']), np.round(f_interval[0,:]),
              color = 'r', alpha = 0.7,
                               label='95% CI Of Sampled Data')
191
      plt.scatter(x[N]+range(stan_data['n_gen']), np.round(f_interval[1,:]),
192
              color = 'r', alpha = 0.7)
plt.axvline(x[N], color='g')
194 plt.legend()
195
     plt.show()
196
197 scaler = MinMaxScaler()
198 N = 70
199
     year_count_mil['index'] = scaler.fit_transform(np.array(year_count_mil['
200
             index']).reshape(-1,1))
201 reg = BayesianRidge()
     reg.fit(np.array(year_count_mil[['index']].iloc[:N,:]), year_count_mil['
             year ']. iloc [:N])
203 plt. figure (figsize = (12,8))
204 x = year_count_mil['abs_year']
{\tt plt.scatter} \ (x \, [:N] \ , \ year\_count\_mil \, [\ 'year'] \, [:N] \ , \ color='b' \ , \ alpha=0.7, \ label=0.7, \ lab
              'Data Used In Modeling')
{\tt plt.scatter} \ (x \, [N:] \ , \ year\_count\_mil \, [\ 'year'] \, [N:] \ , \ color='b' \ , \ marker='x' \ , \ alpha
             =0.7, label='Data Unseen')
207 y_m, y_std = reg.predict(np.array(year_count_mil[['index']]), return_std=
              True)
     plt.plot(x, np.round(y_m), color='b', label='Mean Prediction')
      plt.plot(x, np.round(y_m+2.96*y_std), color='r', linestyle='--', label='95%
                CI ')
plt.plot(x, np.round(y_m-2.96*y_std), color='r', linestyle='--')
211
f_x = np. linspace (1, 1.5, 50)
 \text{213} \ f_{-}y_{-}m \ , \ f_{-}y_{-}std \ = \ reg \ . \ predict \left( \ f_{-}x \ . \ reshape \left( \ -1 \ , 1 \right) \ , \ return_{-}std = True \right) 
f_x = range(2018, 2018+50)
plt.plot(f_x, np.round(f_y_m), color='b')
216 plt.plot(f_x, np.round(f_y_m+2.96*f_y_std), color='r', linestyle='--')
plt.plot(f_x, np.round(f_y_m-2.96*f_y_std), color='r', linestyle='--')
plt.axvline(x[N], color='g')
plt.legend()
221 plt.show()
222
stan_{-}data = \{
               'length': year_count_mil['year'][:N].shape[0],
224
               'data_': np.array(year_count_mil['year'][:N]),
225
               'n_gen': year_count_mil['year'][N:].shape[0] + 50
226
227 }
228 results = stan_model_trend.sampling(data=stan_data)
```

```
229 samples = results.extract()
231 paras =['coef_1', 'coef_2', 'noise']
     print ( results . stansummary ( pars=paras ) )
233
      for param in paras:
234
              plt.figure(figsize=(12, 4))
235
              plot_acf(samples[param])
236
              plt.title(f'Autocorrelation of {param} samples')
237
238
      plt.show()
239
240
241
      visualize_posterior (samples, paras)
243 future = samples [ 'data_gen']
f_interval = np.percentile(future, axis=0, q=[2.5, 97.5])
245 plt. figure (figsize = (12,8))
246 x = year_count_mil['abs_year']
 plt.scatter\left(x\left[:N\right],\ year\_count\_mil\left[\ 'year\ '\right]\left[:N\right],\ color=\ 'b',\ alpha=0.7,\ label=0.7,\ l
              'Data Used In Modeling')
     plt.scatter(x[N:], year_count_mil['year'][N:], color='b', marker='x', alpha
             =0.7, label='Data Unseen')
x_{-} = range(1, year_count_mil['index'].shape[0]+1)
     y = np.round([x_[i]*np.mean(samples['coef_1'])+np.mean(samples['coef_2'])
              for i in range(len(x))])
plt.plot(year_count_mil['abs_year'], y)
     plt.scatter(x[N]+range(stan_data['n_gen']), np.round(f_interval[0,:]),
             color='r', alpha=0.7,
                               label='95% CI Of Sampled Data')
253
     plt.scatter(x[N]+range(stan_data['n_gen']), np.round(f_interval[1,:]),
254
              color='r', alpha=0.7)
plt.axvline(x[N], color='g')
     plt.legend()
257
     plt.show()
scaler = MinMaxScaler()
260 N = 70
261
     year_count_com['index'] = scaler.fit_transform(np.array(year_count_com['
262
             index']).reshape(-1,1))
year_count_com['index^2'] = year_count_com['index']**2
264 reg = BayesianRidge()
265 reg. fit (np.array (year_count_com [['index', 'index^2']].iloc[:N,:]),
             year_count_com['year'].iloc[:N])
266 plt. figure (figsize = (12,8))
267 x = year_count_com['abs_year']
268 plt.scatter(x[:N], year_count_com['year'][:N], color='b', alpha=0.7, label=
              'Data Used In Modeling')
     plt.scatter(x[N:], year_count_com['year'][N:], color='b', marker='x', alpha
             =0.7, label='Data Unseen')
270 y_m, y_std = reg.predict(np.array(year_count_com[['index', 'index^2']]),
              return_std=True)
plt.plot(x, np.round(y_m), label='Mean Prediction', color='b')
272 plt.plot(x, np.round(y_m+2.96*y_std), color='r', linestyle='--', label='95%
```

```
CI ')
plt.plot(x, np.round(y\_m-2.96*y_std), color='r', linestyle='--')
f_x = \text{np.expand\_dims}(\text{np.linspace}(1,1.5,50), \text{axis}=1)
f_x = np.concatenate((f_x, f_x**2), axis=1)
f_y_m, f_y_std = reg.predict(f_x, return_std=True)
f_x = range(2018, 2018+50)
plt.plot(f_x, np.round(f_y_m), color='b')
plt.plot(f_x, np.round(f_y_m+2.96*f_y_std), color='r', linestyle='--')
plt.plot(f_x, np.round(f_y_m-2.96*f_y_std), color='r', linestyle='--')
282
plt.axvline(x[N], color='g')
284 plt.legend()
   plt.show()
286
model_trend = """
288
289 data {
   //Data and its length
290
       int<lower=1> length;
291
        real<lower=0> data_[length];
292
   //Number of generated values
293
       int < lower = 0 > n_gen;
294
295
296
297
   parameters {
       //Quadratic trend model, with 3 coefficients
298
299
        real coef_1;
        real coef_2;
300
        real coef_3;
301
        real<lower=0> noise;
302
303
304
   model {
305
       #Each coefficient is drawn from a broad Cauchy
306
       coef_1 coef_1 cauchy (0,1); coef_2 cauchy (0,1);
307
308
        coef_3 ~ cauchy (0,1);
309
        for(i in 1:length) {
310
            data_{-}[i] ~ normal(coef_{-}1*i*i + coef_{-}2*i + coef_{-}3, noise);
311
312
313
314
   generated quantities {
315
        real data_gen[n_gen];
317
        for(i in 1:n_gen) {
            data_gen[i] = normal_rng(coef_1*(i+length)*(i+length) + coef_2*(i+
       length) + coef_3, noise);
319
320
321
stan_model_trend = pystan.StanModel(model_code=model_trend)
323
stan_data = \{
```

```
'length': year_count_com['year'][:N].shape[0],
325
                        'data_': np.array(year_count_com['year'][:N]),
326
                        'n_gen': year_count_com['year'][N:].shape[0]+50
327
329 results = stan_model_trend.sampling(data=stan_data)
330 samples = results.extract()
331
         paras =['coef_1', 'coef_2', 'coef_3', 'noise']
332
         print(results.stansummary(pars=paras))
333
          for param in paras:
334
                        plt.figure(figsize=(12, 4))
335
336
                       plot_acf(samples[param])
337
                       plt.title(f'Autocorrelation of {param} samples')
339
          plt.show()
340
         visualize_posterior (samples, paras)
341
342
343 future = samples [ 'data_gen']
f_{interval} = p.percentile(future, axis=0, q=[2.5, 97.5])
345 plt. figure (figsize = (12,8))
346 x = year_count_com['abs_year']
plt.scatter(x[:N], year_count_com['year'][:N], color='b', alpha=0.7, label=
                       'Data Used In Modeling')
         plt.scatter(x[N:], year_count_com['year'][N:], color='b', marker='x', alpha
                     =0.7, label='Data Unseen')
x_{-} = range(1, year_{-}count_{-}com['index']. shape[0]+1)
350 y = np.round([x_[i]**2*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.m
                      coef_2 ']) + np.mean(samples['coef_3']) \
                                                        for i in range(len(x))])
351
        \begin{array}{l} plt.\ plot\left(year\_count\_com\left[\begin{array}{c} 'abs\_year \end{array}\right],\ y\right)\\ plt.\ scatter\left(x\left[N\right]+range\left(stan\_data\left[\begin{array}{c} 'n\_gen \end{array}\right]\right),\ np.\ round\left(f\_interval\left[0\right.,:\right]\right), \end{array}
352
                      color='r', alpha=0.7,
                                                  label='95% CI Of Sampled Data')
354
         plt.scatter(x[N]+range(stan_data['n_gen']), np.round(f_interval[1,:]),
                      color='r', alpha=0.7)
356 plt.axvline(x[N], color='g')
        plt.legend()
357
        plt.show()
358
359
360 scaler = MinMaxScaler()
361 \text{ N} = 70
362
         year_count_mil['index'] = scaler.fit_transform(np.array(year_count_mil['
                     index']).reshape(-1,1))
year_count_mil['index^2'] = year_count_mil['index']**2
365 reg = BayesianRidge()
        reg.fit(np.array(year_count_mil[['index', 'index^2']].iloc[:N,:]),
                     year_count_mil['year'].iloc[:N])
367 plt . figure ( figsize = (12,8))
368 x = year_count_mil['abs_year']
         plt.scatter\left(x\left[:N\right],\ year\_count\_mil\left[\ 'year\ '\right]\left[:N\right],\ color='b',\ alpha=0.7,\ label=0.7,\ labe
                       'Data Used In Modeling')
370 plt.scatter(x[N:], year_count_mil['year'][N:], color='b', marker='x', alpha
```

```
=0.7, label='Data Unseen')
371 y_m, y_std = reg.predict(np.array(year_count_mil[['index', 'index^2']]),
              return_std=True)
plt.plot(x, np.round(y_m), label='Mean Prediction', color='b')
plt.plot(x, np.round(y_m+2.96*y_std), color='r', linestyle='--', label='95\%
               CI'
     plt.plot(x, np.round(y_m-2.96*y_std), color='r', linestyle='--')
374
375
f_x = p.expand_dims(p.linspace(1,1.5,50), axis=1)
f_x = np.concatenate((f_x, f_x**2), axis=1)
378 f_y_m, f_y_std = reg.predict(f_x, return_std=True)
f_x = range(2018, 2018+50)
plt.plot(f_x, np.round(f_y_m), color='b')
plt.plot(f_x, np.round(f_y_m+2.96*f_y_std), color='r', linestyle='--')
{\it 382 plt.plot(f_x, np.round(f_y_m-2.96*f_y_std), color='r', linestyle='--')}
384 plt.axvline(x[N], color='g')
385 plt.legend()
386 plt.show()
387
      stan_data = \{
388
                'length': year_count_mil['year'][:N].shape[0],
389
                'data_': np.array(year_count_mil['year'][:N]),
390
                'n_gen': year_count_mil['year'][N:].shape[0]+50
391
393 results = stan_model_trend.sampling(data=stan_data)
394 samples = results.extract()
395
396 paras =['coef_1', 'coef_2', 'coef_3', 'noise']
      print(results.stansummary(pars=paras))
397
398
399 #From CS146 - 14.1 Pre-class, Professor Carl Scheffler
      def plot_acf(x):
400
               from scipy import signal
401
               plt.acorr(
                       x, maxlags=20, detrend=lambda x: signal.detrend(x, type='constant')
403
404
405
      for param in paras:
406
               plt. figure (figsize = (12, 4))
407
               plot_acf(samples[param])
408
               plt.title(f'Autocorrelation of {param} samples')
409
410
     plt.show()
412
     visualize_posterior (samples, paras)
413
414
415 future = samples [ 'data_gen']
f_{interval} = np. percentile (future, axis=0, q=[2.5, 97.5])
and plt. figure (figsize = (12,8))
418 x = year_count_mil['abs_year']
{\tt plt.scatter} \ (x \, [:N] \ , \ year\_count\_mil \, [\ 'year'] \, [:N] \ , \ color='b' \ , \ alpha=0.7, \ label=0.7, \ lab
       'Data Used In Modeling')
```

```
plt.scatter(x[N:], year_count_mil['year'][N:], color='b', marker='x', alpha
                       =0.7, label='Data Unseen')
x_{-} = range(1, year_count_mil['index']. shape[0]+1)
422 y = np.round([x_[i]**2*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.mean(samples['coef_1'])+x_[i]*np.m
                       coef_2'])+np.mean(samples['coef_3'])
                                                          for i in range(len(x))])
423
plt.plot(year_count_mil['abs_year'], y)
425 plt.scatter(x[N]+range(stan_data['n_gen']), np.round(f_interval[0,:]),
                       color='r', alpha=0.7,
                                                    label='95% CI Of Sampled Data')
426
          plt.scatter(x[N]+range(stan_data['n_gen']), np.round(f_interval[1,:]),
                       color = 'r', alpha = 0.7)
plt.axvline(x[N], color='g')
         plt.legend()
         plt.show()
431
432 scaler = MinMaxScaler()
433 N = 70
435 #Using sklearn rbf kernel
436 from sklearn.metrics.pairwise import rbf_kernel
438 #100 pivot points
439 kernel = np. linspace (0, 2, 100). reshape (-1, 1)
440 #Rescaling the year to the range 0 to 1, a standard procedure before
                       fitting
         year_count_com['index'] = scaler.fit_transform(np.array(year_count_com['
                       index']).reshape(-1,1))
442
443 X_{train} = rbf_{kernel}(np.array(year_{count_{com}}['index'][:N]).reshape(-1,1),
                       kernel, gamma=10)
444
445 #Using Bayesian model and plotting the results
446 reg = BayesianRidge()
447 reg. fit (X_train, year_count_com['year'].iloc[:N])
plt. figure (figsize = (12,8))
449 x = year_count_com['abs_year']
 \texttt{plt.scatter} \, (\texttt{x}\, [:N] \, , \, \, \texttt{year\_count\_com} \, [\, \texttt{'year'} \, ] \, [:N] \, , \, \, \texttt{color='b'} \, , \, \, \texttt{alpha=0.7} \, , \, \, \texttt{label=0.7} \, , \, \, \texttt
                        'Data Used In Modeling')
          plt.scatter(x[N:], year_count_com['year'][N:], color='b', marker='x', alpha
                       =0.7, label='Data Unseen')
452
         X_{test} = rbf_{kernel}(np.array(year_count_com['index']).reshape(-1,1),
453
                                                                                kernel, gamma=10)
455 y_m, y_std = reg.predict(X_test, return_std=True)
456 plt.plot(x, np.round(y_m), color='b', label='Mean Prediction')
457 plt.plot(x, np.round(y_m+2.96*y_std), color='r', linestyle='--', label='95\%
                         CI')
plt.plot(x, np.round(y_m-2.96*y_std), color='r', linestyle='--')
f_x = np. linspace(1, 1.5, 50). reshape(-1, 1)
K_f_x = rbf_kernel(f_x, kernel, gamma=10)
462 f_y_m, f_y_std = reg.predict(K_f_x, return_std=True)
f_x = range(2018, 2018+50)
```

```
plt.plot(f_x, np.round(f_y_m), color='b')
plt.plot(f_x, np.round(f_y_m+2.96*f_y_std), color='r', linestyle='--')
 \text{91t.plot}(f_{-x}, \text{np.round}(f_{-y_{-m}}-2.96*f_{-y_{-s}}\text{td}), \text{color='r'}, \text{linestyle='--'}) 
468 plt.axvline(x[N], color='g')
469 plt.legend()
470 plt.show()
471
472 scaler = MinMaxScaler()
473 \text{ N} = 70
474
475
   from sklearn.metrics.pairwise import rbf_kernel
   kernel = np. linspace(0,2,100). reshape(-1,1)
   year_count_mil['index'] = scaler.fit_transform(np.array(year_count_mil['
       index']).reshape(-1,1))
479
   X\_train = rbf\_kernel (np.array (year\_count\_mil ['index'][:N]) . reshape (-1,1) \,,
480
       kernel, gamma=10)
481
482 reg = BayesianRidge()
483 reg. fit (X_train, year_count_mil['year'].iloc[:N])
484 plt . figure (figsize = (12,8))
485 x = year_count_mil['abs_year']
486 plt.scatter(x[:N], year_count_mil['year'][:N], color='b', alpha=0.7, label=
       'Data Used In Modeling')
   plt.scatter\left(x\left[N:\right],\ year\_count\_mil\left[\ 'year\ '\right]\left[N:\right],\ color='b'\ ,\ marker='x'\ ,\ alpha
       =0.7, label='Data Unseen')
488
489 X_{test} = rbf_{kernel(np.array(year_count_mil['index']).reshape(-1,1), \
                         kernel, gamma=10)
490
491 y_m, y_std = reg.predict(X_test, return_std=True)
   plt.plot(x, np.round(y_m), color='b', label='Mean Prediction')
   plt.plot(x, np.round(y_m+2.96*y_std), color='r', linestyle='--', label='95%
   plt.plot(x, np.round(y_m-2.96*y_std), color='r', linestyle='--')
494
f_x = np. linspace(1, 1.5, 50). reshape(-1, 1)
K_f_x = rbf_kernel(f_x, kernel, gamma=10)
498 f_y_m , f_y_std = reg.predict(K_f_x , return_std=True)
f_x = range(2018, 2018+50)
plt.plot(f_x, np.round(f_y_m), color='b')
501 plt.plot(f_x, np.round(f_y_m+2.96*f_y_std), color='r', linestyle='--')
plt.plot(f_x, np.round(f_y_m-2.96*f_y_std), color='r', linestyle='--')
plt.axvline(x[N], color='g')
505 plt.legend()
506 plt.show()
507
model_trend_main = """
509
510 data {
511 //Data and its length
int < lower=1> length;
```

```
real<lower=0> data_[length];
513
   //Number of radial basis points or number of coefficients
514
       int < lower = 1 > c;
     Kernelized value of the training data
        vector[c] rbf_train[length];
517
     Number of generated values
518
       int < lower = 0 > n_gen;
519
     Kernelized value of the generated data
520
       vector[c] rbf_gen[n_gen];
521
522
523
524
   parameters {
525
   //RBF model, with c basis points
       row_vector[c] coef_;
527
     Intercept
       real intercept;
528
     Gaussian noise
529
       real<lower=0> noise;
530
531
532
   model {
533
   //Each coefficient is drawn from a broad Cauchy
534
       for(j in 1:c) {
535
            coef_[j] ~
                       cauchy (0,1);
536
537
        for(i in 1:length) {
538
            data_[i] ~ normal((coef_*rbf_train[i]) + intercept, noise);
539
540
541
542
   generated quantities {
543
       real data_gen[n_gen];
544
545
       for (i in 1:n_gen) {
            data_gen[i] = normal_rng((coef_*rbf_gen[i]) + intercept, noise);
546
547
548
549
   trend_model = pystan.StanModel(model_code=model_trend_main)
550
kernel = np.linspace(0,2,100).reshape(-1,1)
   X_{train} = rbf_{kernel}(np.array(year_{count_{com}['index'][:N]}).reshape(-1,1),
553
       kernel, gamma=10)
  X_gen = rbf_kernel(np.array(year_count_com['index'].iloc[N:]).reshape(-1,1)
554
       , kernel, gamma=10)
  f_X = np. linspace (1, 1.5, 50). reshape (-1, 1)
K_f_X = rbf_kernel(f_X, kernel, gamma=10)
  X_{gen} = np.concatenate((X_{gen}, K_{f_-}X), axis=0)
558
   stan_data = \{
559
        'length': year_count_com['year'][:N].shape[0],
560
        'data_': np.array(year_count_com['year'][:N]),
561
        'c': 100,
562
        'rbf_train': X_train,
563
        'n_gen': year_count_com['year'][N:].shape[0] + 50,
564
```

```
'rbf_gen': X_gen
565
566
   }
567 results = trend_model.sampling(data=stan_data)
   samples = results.extract()
   paras = ['coef_', 'intercept', 'noise']
570
   print(results.stansummary(pars=paras))
571
573 future = samples['data_gen']
f_{interval} = np.percentile(future, axis=0, q=[2.5, 97.5])
575 plt. figure (figsize = (12,8))
s76 x = year_count_com['abs_year']
   plt.scatter(x[:N], year_count_com['year'][:N], color='b', alpha=0.7, label=
        'Data Used In Modeling')
   plt.scatter(x[N:], year_count_com['year'][N:], color='b', marker='x', alpha
       =0.7, label='Data Unseen')
   x_{-} = range(1, year_count_com['index'].shape[0]+1)
   \# y = np.round([x_{i}]**2*np.mean(samples['coef_{1}'])+x_{i}[i]*np.mean(samples['
       coef_2']) + np.mean(samples['coef_3'])\
                     for i in range(len(x))])
581
582 # plt.plot(year_count_com['abs_year'], y)
\texttt{plt.scatter}\left(x\left[N\right] + \texttt{range}\left(\left.\text{stan\_data}\left[\right.\text{'}\text{n\_gen'}\right]\right), \text{ np.round}\left(\left.\text{f\_interval}\left[0\right.,:\right]\right),
       color = 'r', alpha = 0.7,
                 label='95% CI Of Sampled Data')
584
   plt.scatter(x[N]+range(stan_data['n_gen']), np.round(f_interval[1,:]),
       color='r', alpha=0.7)
586
   plt.axvline(x[N], color='g')
587
   plt.legend()
588
   plt.show()
589
   risk_com = com[['year', 'type', 'operator', 'fat.', 'cat']].reset_index(
590
       drop=True)
591
   def clean_cat_1 (obj):
592
        obj = str(obj)
593
        return obj[0]
594
595
   def clean_cat_2(obj):
596
        obj = str(obj)
597
        return obj[1]
598
599
risk_com['Accident Type'] = risk_com['cat']
for risk_com['Loss Type'] = risk_com['cat']
risk_com = risk_com.drop(['cat'], axis=1)
603 risk_com['Accident Type'] = risk_com['Accident Type'].apply(clean_cat_1)
604 risk_com ['Loss Type'] = risk_com ['Loss Type'].apply(clean_cat_2)
   risk_com = risk_com.sort_values(by=['year'], kind='mergesort').reset_index(
       drop=True)
606
   def Boeing_Airbus(data):
607
        df = pd.DataFrame()
608
        for _ in range(data.shape[0]):
609
            if ('Boeing' in data['type'].iloc[_]):
610
                 data.iloc[_-, 1] = data.iloc[_-, 1][:10]
611
```

```
if data.iloc[_, 1] == 'Boeing':
612
613
                    pass
                else:
614
                    df = pd.concat((df, data.iloc[_-,:]), axis=1, sort=False)
            elif ('Airbus' in data['type'].iloc[_]):
616
617
                data.iloc[_-, 1] = data.iloc[_-, 1][:11]
                if data.iloc[_, 1] = 'Airbus':
618
                    pass
619
                else:
620
                    df = pd.concat((df, data.iloc[_-,:]), axis=1, sort=False)
621
       return df.transpose().reset_index(drop=True)
622
623
624
       Top_Airline(data, top_airlines):
       df = pd.DataFrame()
626
             in range (data.shape [0]):
            if data['operator'].iloc[_] in top_airlines:
627
                df = pd.concat((df, data.iloc[_,:]), axis=1, sort=False)
628
       return df.transpose().reset_index(drop=True)
629
630
   def how_many_passenger(data):
631
       data['total'] = np.nan
632
       for _ in range(data.shape[0]):
633
            if data['type'].iloc[_] == 'Boeing 727':
634
                data['total'].iloc[_] = 189
            elif data['type'].iloc[_] == 'Boeing 737':
                data['total'].iloc[_] = 143
637
            elif data['type'].iloc[_] == 'Boeing 707':
638
                data['total'].iloc[_] = 189
639
            elif data['type'].iloc[_] == 'Boeing 747':
640
                data['total'].iloc[_] = 660
641
            elif data['type'].iloc[_] == 'Boeing 720':
data['total'].iloc[_] = 219
642
643
            elif data['type'].iloc[_] == 'Boeing 757':
644
                data['total'].iloc[_] = 295
645
            elif data['type'].iloc[_] == 'Boeing 767':
                data['total'].iloc[_] = 351
647
            elif data['type'].iloc[_] == 'Boeing 777':
648
                data['total'].iloc[_-] = 451
649
            elif data['type'].iloc[_] == 'Boeing 377':
650
                data['total'].iloc[_] = 114
651
            elif data['type'].iloc[_] == 'Boeing 717':
652
                data['total'].iloc[_] = 134
653
            elif data['type'].iloc[_] == 'Boeing 787':
654
                data['total'].iloc[_] = 335
655
            elif data['type'].iloc[_] = 'Boeing 314':
                data['total'].iloc[_] = 77
657
            elif data['type'].iloc[_] = 'Airbus A300':
658
                data['total'].iloc[_] = 300
659
            elif data['type'].iloc[_] = 'Airbus A320':
660
                data['total'].iloc[_] = 186
661
            elif data['type'].iloc[_] = 'Airbus A321':
662
                data['total'].iloc[_] = 240
663
            elif data['type'].iloc[_] = 'Airbus A330':
664
                data['total'].iloc[_] = 335
665
```

```
elif data['type'].iloc[_] = 'Airbus A310':
666
                data['total'].iloc[_] = 220
667
            elif data['type'].iloc[_] == 'Airbus A319':
668
                data['total'].iloc[_] = 160
            elif data['type'].iloc[_] = 'Airbus A340':
670
                data['total'].iloc[_] = 475
671
            elif data['type'].iloc[_] = 'Airbus A380':
672
                data['total'].iloc[_] = 853
673
        return data
674
675
676 risk_com_BA = Boeing_Airbus(risk_com)
   top_25_airlines = risk_com_BA['operator'].value_counts()[:25].index
   risk_data = Top_Airline(risk_com_BA, top_25_airlines)
   risk_data = how_many_passenger(risk_data)
   risk_data = risk_data.drop([505, 504], axis=0).reset_index(drop=True)
681
682
   stan_model_risk = """
683
684
   data {
685
   //Number of airline
686
        int<lower=1> L;
687
     Number of aircraft
688
        int<lower=1> C;
    /Number of accident type
690
        int < lower = 1 > T;
691
692
    Number of datapoint
       int < lower = 1 > N;
693
694
   //A vector of 0/1 in each entry expressing which airline, aircraft and
695
       accident type the datapoint is
        vector < lower = 0 > [L] airline [N]
696
        vector<lower=0>[C] aircraft[N];
697
        vector<lower=0>[T] accident[N];
698
    /A vector expressing the number of passenger on that aircraft
700
        int<lower=0> passenger[N];
701
702
    /Number of fatality
703
        int<lower=0> fat [N];
704
705
706
707
   parameters {
708
   //Scaling factor for the airline
710
        row_vector<lower=0, upper=1>[L] m_al;
711
    /Scaling factor for the aircraft
712
       row_vector<lower=0, upper=1>[C] m_ac;
713
   //Scaling factor for the accident type
714
       {\tt row\_vector}{<}{\tt lower}{=}0, \ {\tt upper}{=}1{>}[T] \ m\_a\,;
715
716
717 // Mortality rate
real < lower = 0, upper = 1 > p;
```

```
719
720
   model {
721
722
        for (1 in 1:L){
723
            m_al[1] \sim lognormal(0,0.25);
724
725
726
        for (c in 1:C){
727
            m_{ac}[c] ~ lognormal(0,0.25);
728
729
730
731
        for (t in 1:T){
            m_a[t] \sim lognormal(0,0.25);
732
733
734
        for (i in 1:N) {
735
            #Sample the mortality rate from a beta distribution, with scaling
736
       factor from the airline, aircraft and accident
            p ~\tilde{}~ beta (((m_al*airline[i]) + (m_ac*aircraft[i]) + (m_a*accident[i])),\\
737
       1);
            fat[i] ~ binomial(passenger[i], p);
738
739
740
741
742
   model_risk = pystan.StanModel(model_code=stan_model_risk)
743
744
   def produce_stan_data(raw):
745
        airline = pd.get_dummies(raw['operator'])
746
        name_airline = airline.columns
747
        airline = np.array(airline, dtype=int)
748
749
        aircraft = pd.get_dummies(raw['type'])
750
        name\_aircraft = aircraft.columns
        aircraft = np.array(aircraft, dtype=int)
752
753
        accident = pd.get_dummies(raw['Accident Type'])
754
       name\_accident = accident.columns
755
        accident = np.array(accident, dtype=int)
756
757
        passenger = np.array(raw['total'], dtype=int)
758
759
        fat = np.array(raw['fat.'], dtype=int)
760
761
       hull = pd.get_dummies(raw['Loss Type'])
762
       hull = np.array(hull.iloc[:,0], dtype=int)
763
764
        data\_dict = {
765
            'L': airline.shape[1],
766
            'C': aircraft.shape[1],
767
            'T': accident.shape[1],
768
            'N': airline.shape[0],
769
770
```

```
'airline': airline,
771
                                  'aircraft': aircraft,
772
                                  'accident': accident,
773
                                  'passenger': passenger,
775
776
                                  'fat': fat,
777
                                  'hull': hull
778
779
                     }
780
781
                     name\_dict = {
782
783
                                 'airline': name_airline,
                                 'aircraft': name_aircraft,
                                  'accident': name_accident
785
786
                     return data_dict, name_dict
787
788
         def plot_posterior(results, name, what):
789
                     if what == 'airline':
790
                                 what_{-} = 'm_{-}al'
791
                      elif what == 'aircraft':
792
                                 what_{-} = 'm_{-}ac'
793
                     else:
794
                                what_{-} = 'm_{-}a'
                     mul = results [what]
796
797
                     plt. figure (figsize = (12,8))
                     for _ in range(mul.shape[1]):
798
                                 {\tt plt.hist} \, ({\tt mul}\, [:\,,\,\_] \,, \; \; {\tt alpha}\, = 0.35 \,, \; \; {\tt bins}\, = 30 \,, \; \; {\tt density} = {\tt True} \,, \; \; {\tt label} = {\tt str} \, ({\tt str}\, ({\tt s
799
                   name [what] [ \_])+': \{0:.3f\}'. format (mul[:, \_]. mean()))
                                 plt.scatter(mul[:,_].mean(),0, marker='\mathbf{x}', s=40)
800
                     plt.legend()
801
                     plt.title('Multiplers for {}'.format(what))
802
                     \text{mul} = \text{mul.reshape}(-1,1)
803
                     plt. figure (figsize = (12,8))
804
                     plt.hist(mul, alpha=0.35, bins=30, density=True, label='var: {0:.3f}'.
805
                    format(mul.var()))
                     plt.scatter(mul.mean(), 0, marker='x', s=40, label='mean: {0:.3 f}'.
806
                    format(mul.mean()))
                     plt.title('All multipliers')
807
                     plt.legend()
808
                     plt.show()
809
                     print ('95% CI for all {} multipliers is:'.format(what), (np.percentile(
810
                   mul, 2.5), np. percentile (mul, 97.5)))
stan_data, name = produce_stan_data(risk_data)
sis results = model_risk.sampling(data=stan_data, n_jobs=1)
814 results
815
s16 plot_posterior(results, name, 'airline')
plot_posterior(results, name, 'aircraft')
818
        plot_posterior(results, name, 'accident')
820 plt . figure (figsize = (12,8))
```

```
plt.hist(results['p'], alpha=0.5)
822 plt.show()
823
   stan_model_risk_hull = """
824
825
826 data {
   //Number of airline
827
       int<lower=1> L;
828
    //Number of aircraft
829
       int<lower=1> C;
830
    /Number of accident type
831
832
        int < lower = 1 > T;
833
    /Number of datapoint
       int<lower=1> N;
835
   //A vector of 0/1 in each entry expressing which airline, aircraft and
836
       accident type the datapoint is
        vector < lower = 0 > [L] airline [N];
837
        vector < lower = 0 > [C] aircraft [N];
838
        vector < lower = 0 > [T] accident [N];
839
840
       Binary indicator of whether it's a hull loss or not
841
       int < lower=0> hull [N];
842
843
844
845
846
   parameters {
847
   //Scaling factor for the airline
848
        row_vector < lower = 0, upper = 1 > [L] m_al;
849
    //Scaling factor for the aircraft
850
        row_vector<lower=0, upper=1>[C] m_ac;
851
    /Scaling factor for the accident type
852
        row_vector<lower=0, upper=1>[T] m_a;
853
    //Mortality rate
855
        real<lower=0, upper=1> p;
856
857
858
   model {
859
860
        for (l in 1:L){
861
            m_al[1] \sim lognormal(0,0.25);
862
863
864
        for (c in 1:C) {
865
            m_{ac}[c] \sim lognormal(0,0.25);
866
867
868
        for (t in 1:T){
869
            m_a[t] \sim lognormal(0,0.25);
870
871
872
        for (i in 1:N) {
873
```

```
p ~\tilde{}~ beta (((m_al*airline[i]) + (m_ac*aircraft[i]) + (m_a*accident[i])), \\
874
        1);
              hull[i] ~ bernoulli(p);
875
877
878
879
model_risk_hull = pystan.StanModel(model_code=stan_model_risk_hull)
881
stan_data, name = produce_stan_data(risk_data)
ses results = model_risk_hull.sampling(data=stan_data, n_jobs=1)
884 results
plot_posterior(results, name, 'airline')
plot_posterior(results, name, 'aircraft')
plot_posterior(results, name, 'accident')
888 plt . figure ( figsize = (12,8))
889 plt.hist(results['p'], alpha=0.5)
890 plt.show()
```