Digital-to-Analog Conversion

ECE 362 https://engineering.purdue.edu/ece362/

Reading Assignment

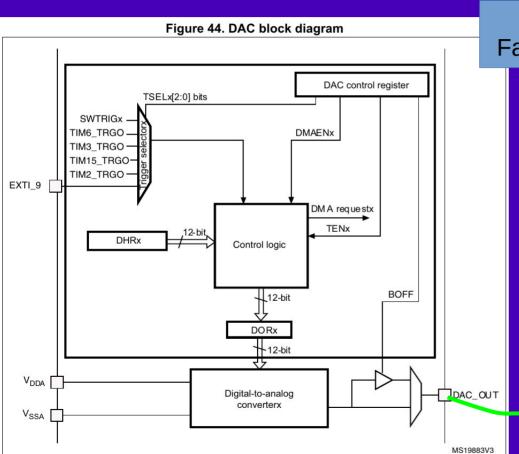
- Textbook, Chapter 21, Digital-to-Analog Conversion, pp. 507 526.
 - Read this first.
- FRM, Chapter 14, Digital-to-analog converter (DAC), pp. 269 281.
 - Scan. Learn basics like I/O registers, enabling, use.
- Textbook, Chapter 20, Analog-to-Digital Conversion, pp. 481 506.
 - Read this later.
- FRM, Chapter 13, Analog-to-Digital converter (ADC), pp. 229 268.
 - Scan this later. Learn basics like I/O registers, enabling, use.

Serial Wire VOLT.REG V_{DD} = 2 to 3.6 V Debug 3.3 V to 1.8 up to 256 KF CORTEX-M0 CPL fury = 48 MHz SRAM 32 KB RESET & CLOCK Vost = 1.65 to 3.6 V XTAL32 kHz OSC32 OUT 2 TAMBED DT/ Backur (ALARM OUT) RTC interface 4 channels 3 compl. channels BRK, ETR input as AF 4 ch., ETR as AF EXT. IT WKUF 256 B 1 compl. BRK as AF 1 channel 1 compl, BRK as AF ➤ IR OUT as AF Window WDG A BY TY CTS BTS SPI1/I2S MISO/MCK SCK/CK CK as AF DRGMCU RX, TX,CTS, RTS CK as AF MISO/MCE SYSCFG IF GP comparator GP comparator 2 12-bit ADC 12-bit DAC - DAC OUT

The STM32F091

- Digital-to-Analog Converter
 - 2 external channels (DAC_OUT1, DAC_OUT2)
 - What pins are those?
 - You can look those up. You know how.
 - Or pay close attention to the lecture.
 - 0 3.6V conversion range
 - Our voltage reference is about 3.0V
 - 12-bit resolution, by default
 - 8-bit resolution too
 - right-aligned (default) or left-aligned

DAC Block Diagram

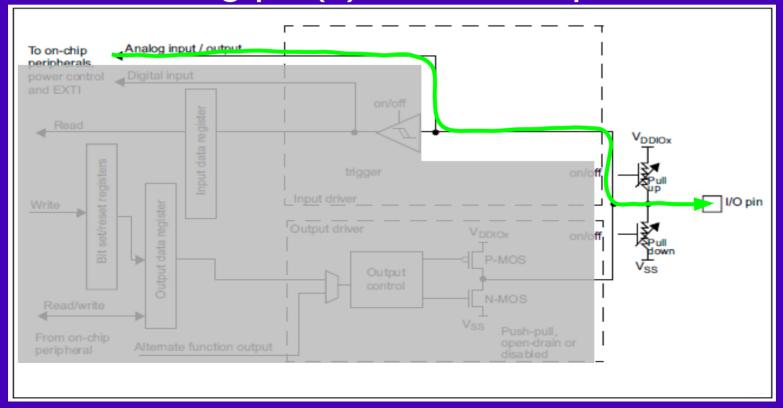


Page 270 of the Family Reference Manual

- A Data Output Register (DORx)
 holds a value that is converted to an
 analog voltage between 0 and 3V.
- CPU can't write directly to DORx.
- Must write to DHRx.
 - "Data Holding Register"
 - A trigger will move DHRx to DORx.

DAC Output Connection

Some analog pin(s) can be output.



Port MODER

- 16 2-bit values determine, input, output, or special operation.
 - 00: Port pin is used for input
 - 01: Port pin is used for output
 - 10: Port pin has an alternate function
 - 11: Port pin is an analog pin

0x00	GPIOx_MODER (where x = BF)	MODER15[1:0]		MODER14[1:0]		MODER13[1:0]		MODER12[1:0]	- 1	MODER11[1:0]	i	MODER10[1:0]		MODER9[1:0]		MODER8[1:0]		MODER7[1:0]		MODER6[1:0]		MODER5[1:0]		MODER4[1:0]		MODED3[1:0]	ייטטטרויטן יי	MODE P2[1:0]	ייסטבועל	MODER 1[1-0]		MODER0[1:0]	
	Reset value	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

How does a DAC work?

 And what does this left-aligned or right-aligned mean?

Let's talk about number systems

- A group of bits can be used to represent arbitrary things
- A character, a number, an image, ...
- "Integers" have a well-known format

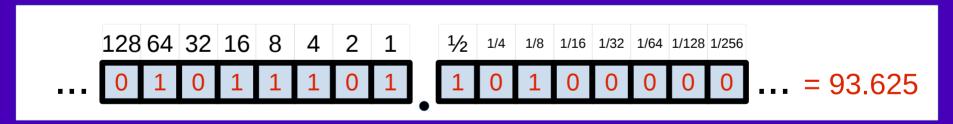
```
128 64 32 16 8 4 2 1

0 1 0 1 1 0 1 = 93
```

- Ellipsis goes off to the left.
- What if we added another bit to the right?

Binary fractions

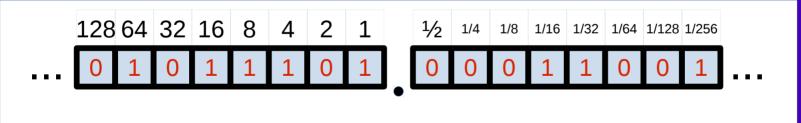
- We can let a 16-bit value represent anything we want, so let's let the upper 8 bits represent an integer, and let the lower 8 bits represent fractional powers of 2
- The dot is called a "binary point"
- Representation, below, is called "fixed point", Q8.8, or just Q8.



- Standard binary addition and subtraction still works.
- Multiplication needs a correcting shift afterward.

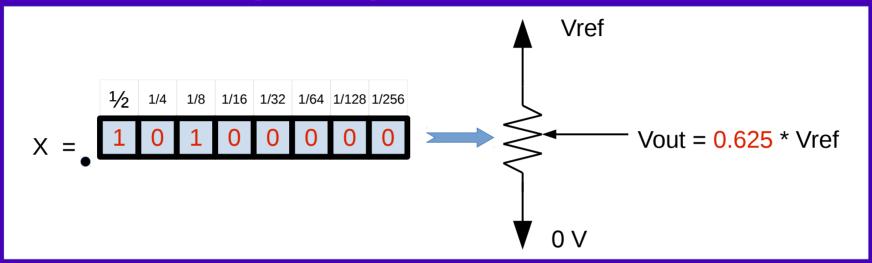
Fixed point is inexact

- Sums of fractional powers of 2, OK.
 - e.g. We can express 3.75 as 00000011.1100....
- Anything else has rounding errors. e.g. 93.1.
- 93 + 1/8 is 93.125 (too big)
- 93 + 1/16 + 1/32 = 93.9375 (too small)
- 93 + 1/16 + 1/32 + 1/256 + 1/512 = 93.099609375 (too small, but closer)



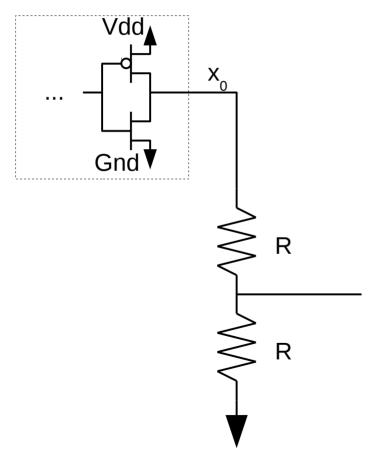
• The precise binary value would repeat forever: 01011101.000110011001100...

Digital potentiometer



- We want hardware that can convert a binary fraction to a voltage.
 - The most significant bit of the fraction is "worth" half the reference voltage.
 - A "left-aligned" conversion value is, effectively, a binary fraction.
- How can we build such a thing?

One-bit DAC



Typical logic gate outputs either "push" high or "pull" low.

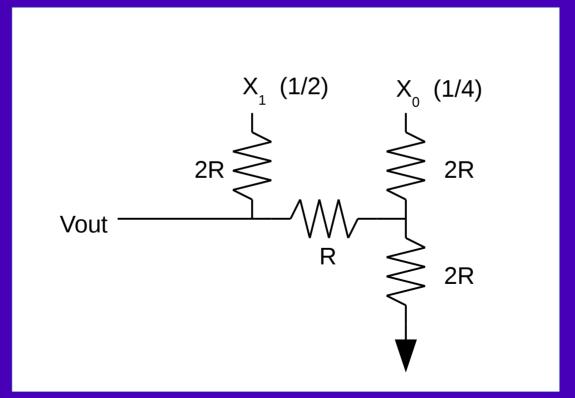
Let Vref = Vdd.

With only one bit, the value x can represent either $\frac{1}{2}$ or 0.

Vout =
$$x_0$$
 * Vref / 2

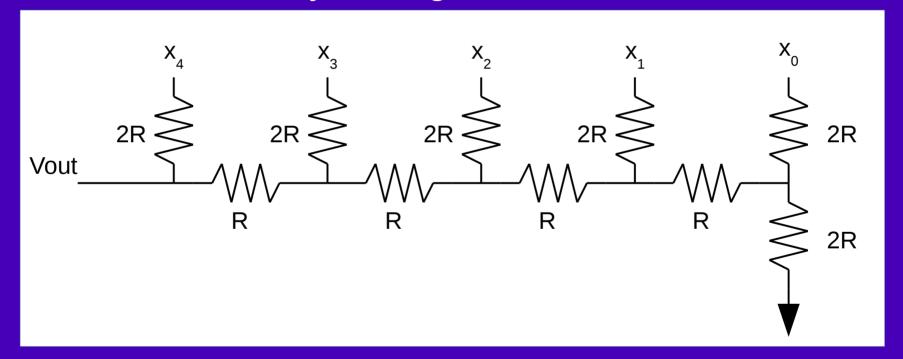
Two-bit DAC

• X can have the values 0, 1/4, 1/2, or 3/4.



Many-bit DAC

Add N more bits by adding N more R-2R resistors...

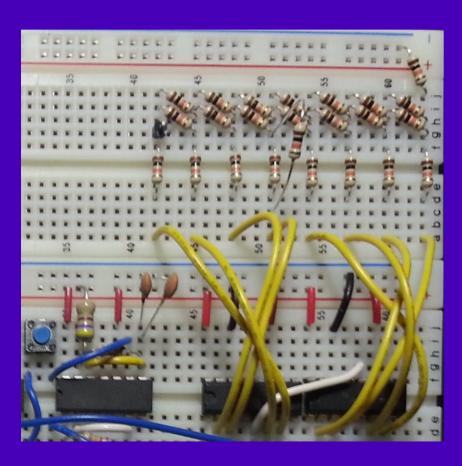


- This is called an R-2R resistor ladder.

DAC: How fast is the conversion?

- Speed of light.
 - Some settling time required due to capacitance (and inductance) in circuit.
 - Small glitches may be present due to differences in delays for turning on and off inputs into the resistor network.
- No iteration or convergence needed.

Build and test...



 Build something like this, connect it to a counter, and you get a sawtooth wave.



Limits of DAC resolution

- Resistor tolerance is a limitation.
- Linearity of the output is only as good as the correctness of the resistor ratios.
- A single errant resistor can be problem.
- Small deviation will cause small error.
- Large deviation causes a non-monotonic output for the sawtooth wave.
- To ensure a monotonic sawtooth, each resistor should be less than +/- $1/(2^N)$ its listed value. Why?
 - Consider transition from 01111 to 10000.
 - If most significant resistor was off by -1/(2⁵) the two values would be the same.
 - For an 8-bit DAC, resistor error must be < 0.4%
 - For a 12-bit DAC, resistor error must be < 0.024%
- Helps if all resistors are on same silicon substrate!
 - Which is what you have on your microcontroller.

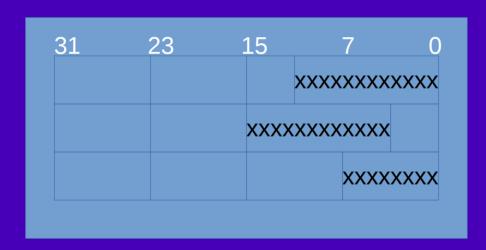


Using the STM32 DAC

- There are two DACs on the STM32F091RCT6.
 - That can be used with two channels / pins.
- Cannot write directly to a DAC output register.
 - Instead, write a digital value to one of three "data holding registers."
 - Some kind of trigger will copy it to the output register.

DAC Holding Registers

- 8-bit or 12-bit
- left-aligned or right-aligned



DAC_DHR12R1: 12-bit, right-aligned, ch1

DAC_DHR12L1: 12-bit, left-aligned, ch1

DAC_DHR8R1: 8-bit, right-aligned, ch1

DAC Triggers

- Seven different trigger possibilities
 - 5 timers
 - EXTI line9
 - Software trigger
- Set with the DAC->CR TSEL1/2 fields.
 - 111 is the software trigger. Use this for now.

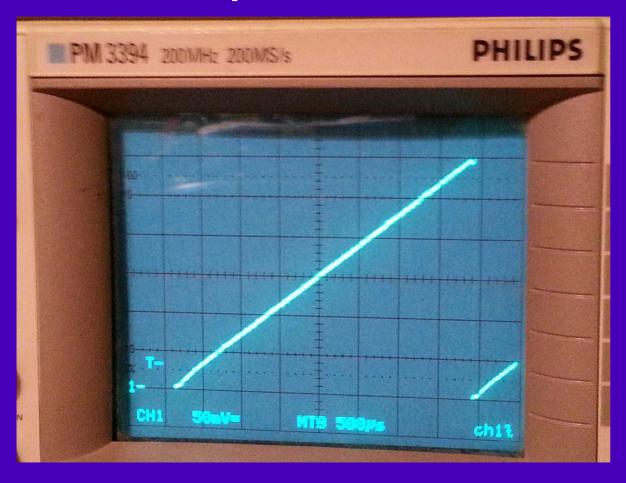
To trigger the DAC with a software trigger

- Wait while the channel trigger is set. Once it is clear:
 - Write a new value to a holding register.
 - Set the trigger bit.

Example code to generate a sawtooth wave

```
void dac soft trigger(void)
   RCC->AHBENR |= RCC AHBENR GPIOAEN; // Enable clock to Port A.
   GPIOA->MODER |= 3<<(2*4): // Set PA4 to analog.
   RCC->APBIENR |= RCC APBIENR DACEN; // Enable clock to DAC.
   DAC->CR &= ~DAC_CR_EN1; // Disable DAC channel 1.
   DAC->CR &= ~DAC_CR_BOFF1; // Do not turn buffer off.
   DAC->CR |= DAC CR TEN1; // Enable trigger.
   DAC->CR |= DAC CR TSEL1; // All ones. Select software trigger.
   DAC->CR |= DAC CR EN1; // Enable DAC channel 1.
   int x = 0:
   for(::) {
       // Wait for DAC to clear the SWTRIG1 bit.
       while((DAC->SWTRIGR & DAC SWTRIGR SWTRIG1) == DAC SWTRIGR SWTRIG1);
       // Put new value into 12-bit, right-aligned holding register.
       DAC -> DHR12R1 = x;
       // Trigger the conversion.
       DAC->SWTRIGR |= DAC SWTRIGR SWTRIG1;
       x = (x + 1) \& 0xfff;
```

Scope view of unloaded pin



- 10x probes.
- 0.5V/div
- 500µs/div
- slight curve on lower end

Conversion Examples

- Assume that V_{RFF} is 3.0 V.
- If the DAC's right-aligned 12-bit data holding register was given the following values, what would the analog output voltage be?
- 0?
- 4095 ?
- 2047 ?
- 1023 ?

Output linearly related to DAC value

Generally, the DAC output will be:

$$V_{OUT} = V_{REF} * \underline{N}$$

$$4096$$

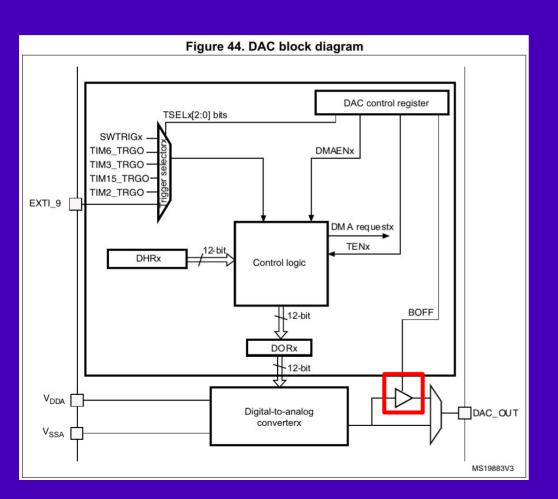
Some differences

- Lecture explanation of a DAC differs from that of the textbook and the FRM.
 - Lecture: Each increment of the DAC value represents 1/4096th of V_{REF}
 - Minimum: 0 * V_{REF}
 - Maximum: 4095/4096 * V_{REF}
 - FRM: Each increment of the DAC value represents 1/4095th of V_{REF}
 - Minimum: 0 * V_{REF}
 - Maximum: 4095/4095 * V_{REF}

Does this difference matter?

- The difference between the lecture and textbook version of a DAC is 1/4096th V_{RFF} or about 0.024%. But nothing is exact...
 - There are deviations from linearity for the DAC.
 - There is often a noise problem with the analog subsystems of the STM32F0.
 - It's about 0.02%. (More about this when we talk about ADC)
- Difference between this lecture and text doesn't matter.
 - You won't notice a range of [0 2.9928] instead of [0 3.0]

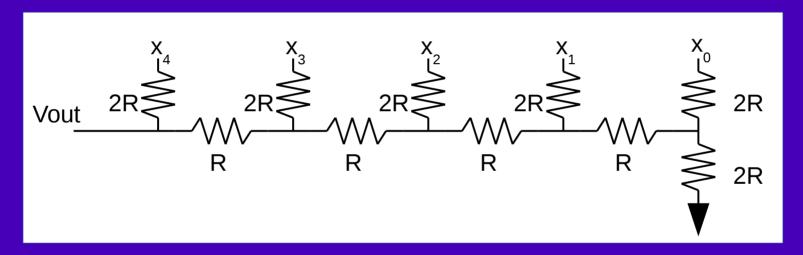
What is BOFF1?



- An output buffer can be turned off.
- You probably want to leave it turned on:
- DAC->CR &= ~
 DAC_CR_BOFF1;

Why do we need a buffer?

Recall the hand-built DAC circuit:



• What's the impedance of Vout if $R = 10K\Omega$?

Why would we turn buffer off?

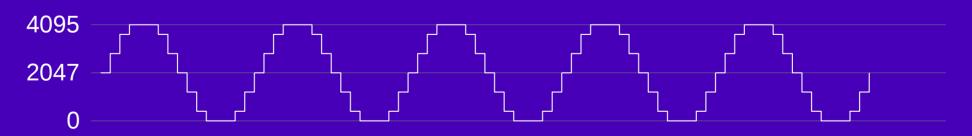
- Maybe you want to use your own high-precision amplifier?
 - Remember that small curve on the low end of the scope view.

DAC uses

- We can use the DAC for slow things:
 - process control, object location manipulation by voltage, etc.
- The DAC can be updated very quickly.
 - More than 100k/sec.
 - This is useful for producing audio.
 - One example is a sine wave table.

What is a sine table?

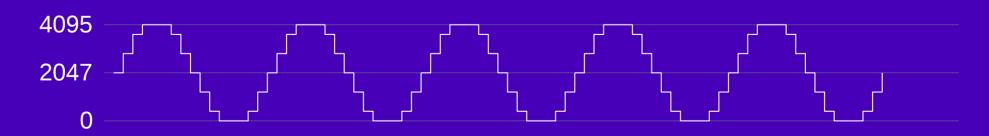
- We saw that writing monotonically-increasing values to the DAC produced a sawtooth wave.
- Imagine a set of 16 samples that look like this, that are sent repeatedly:



• BTW: For a large wave table, we make it "const". Why?32

What is the frequency of the wave?

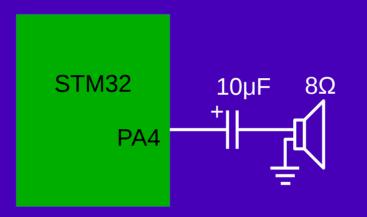
- We can see that this looks like a fuzzy sinusoid.
 - How do we calculate the frequency?
 - Sample/sec / Number of samples in a cycle
 - For 64k samples/sec, 16 samples/cycle...



4 kHz

Demonstration 1: Raw output

First circuit:



- First, try square waves with GPIO.
- Next, try DAC sawtooth, square wave.

What's the large capacitor for?

Ensuring that a constant voltage on pin does not result in a constant current flowing through the speaker coil.

DAC output: Very weak.

6.3.17 DAC electrical specifications

Table 60.	DAC characteristics
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			DAC CHaracteristics									
Symbol	Parameter	Min	Тур	Max	Unit	Comments						
V _{DDA}	Analog supply voltage for DAC ON	2.4	-	3.6	٧	-						
R _{LOAD} ⁽¹⁾	Resistive load with buffer	5	-	-	kΩ	Load connected to V _{SSA}						
LOAD	ON	25	-	-	kΩ	Load connected to V _{DDA}						
R _O ⁽¹⁾	Impedance output with buffer OFF	-	-	15	kΩ	When the buffer is OFF, the Minimum resistive load betwee DAC_OUT and V_{SS} to have a 1% accuracy is 1.5 M Ω						
C _{LOAD} ⁽¹⁾	Capacitive load	-	-	50	pF	Maximum capacitive load at DAC_OUT pin (when the buff is ON).						
DAC_OUT min ⁽¹⁾	Lower DAC_OUT voltage with buffer ON	0.2	-	-	V	It gives the maximum output excursion of the DAC. It corresponds to 12-bit input						
DAC_OUT max ⁽¹⁾	Higher DAC_OUT voltage with buffer ON	-	-	V _{DDA} – 0.2	V	code (0x0E0) to (0xF1C) at V _{DDA} = 3.6 V and (0x155) an (0xEAB) at V _{DDA} = 2.4 V						
DAC_OUT min ⁽¹⁾	Lower DAC_OUT voltage with buffer OFF	-	0.5		mV	It gives the maximum output						
DAC_OUT max ⁽¹⁾	Higher DAC_OUT voltage with buffer OFF	-	-	V _{DDA} – 1LSB	٧	excursion of the DAC.						
I _{DDA} ⁽¹⁾	DAC DC current consumption in quiescent	-	-	600	μA	With no load, middle code (0x800) on the input						
IDDA` ′	mode ⁽²⁾	-	-	700	μA	With no load, worst code (0xF1C) on the input						

- DAC output is just a resistor network.
- Need a lot of resistance on the output.
- Even with the buffer on, it's still wimpy.

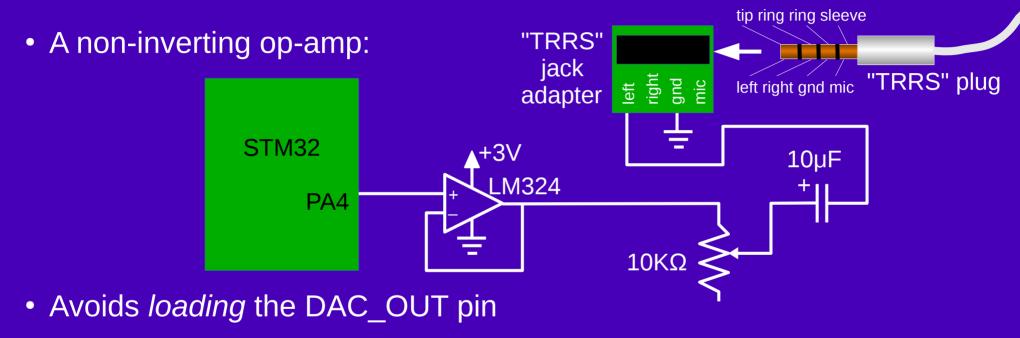
Table 60, Page 89 of STM32F091RxBC datasheet.

Demonstration 2: Amplified output

• Next circuit: $\begin{array}{c} & & & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\$

- DAC sawtooth again, square waves.
- Sine table.

Recommended Circuit



Protects the analog circuitry of the microcontroller

Protect the analog circuitry of the microcontroller!

- CAUTION: When you configure a pin on the STM32 for analog operation, you connect that pin to sensitive electronics inside the chip.
- If that pin is connected to voltage higher than 4V for just an instant, it <u>will</u> permanently, irreversibly damage either the pin or the entire microcontroller.