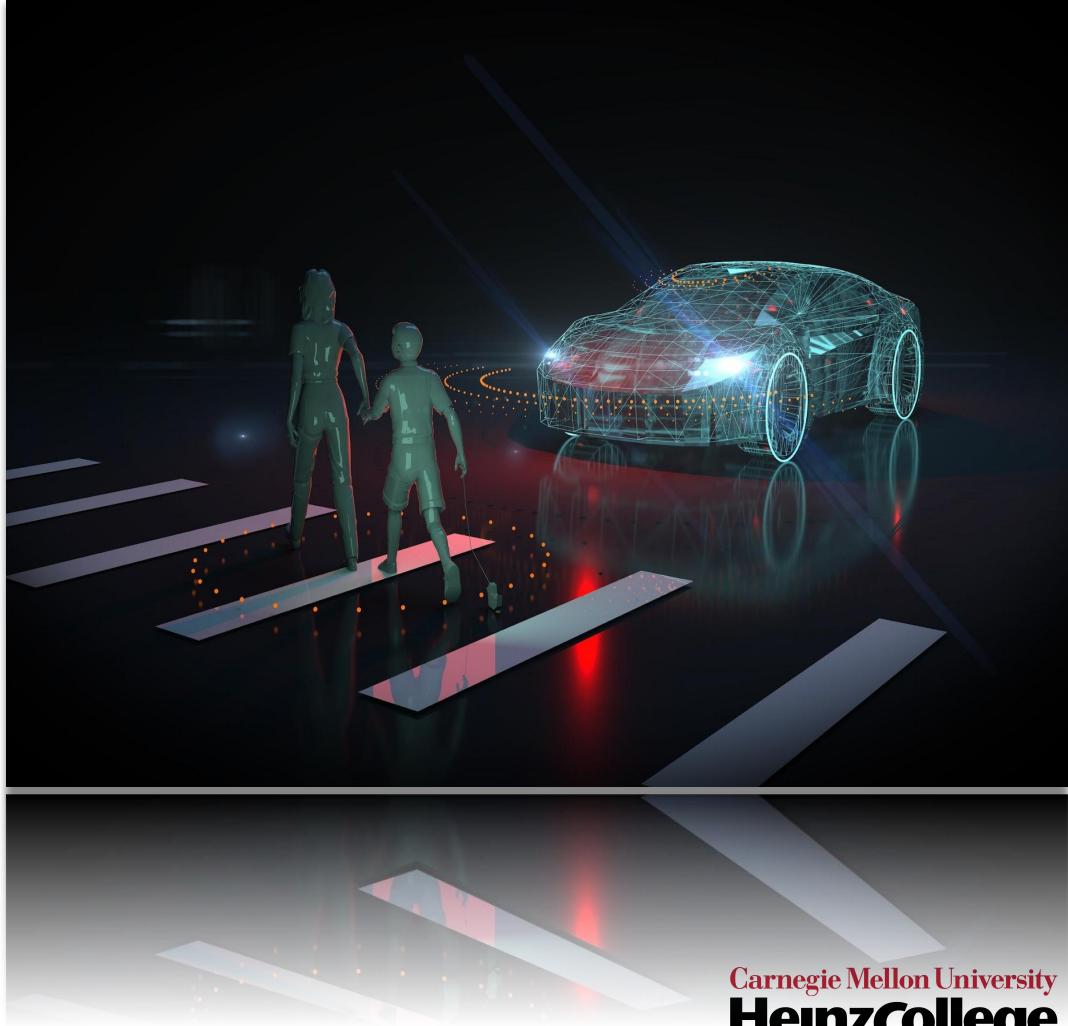


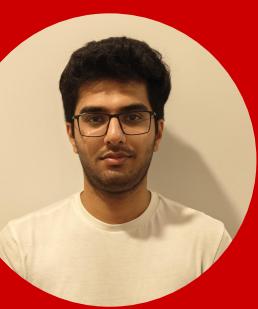


Tier IV

Final Presentation



Meet The Team



**Vimbai
Muyengwa**

**Financial Manager
& Frontend Developer**

IT Systems Professional
and AI enthusiast with
5+ years IT and
Business experience

**Ashay
Koradia**

**Software & Backend
Developer**

Software Engineer,
3 years of work exp.
Project Olympus
Incubation cell member

**Rohan
Ghosh**

**System Admin.
& Backend Developer**

Software Engineer, 5
years experience in
PLM domain

**Youyou
Huang**

**Process Organizer
& Backend Developer**

Data and IT system
professional,
4 years in Information
Management &
Economic Research

**Aakash Ajay
Singh**

**Software & Frontend
Developer**

Software Engineer and AI
enthusiast with
cross-functional skills in
backend systems and
business integration

**Yash
Hulsurkar**

**Project Manager
& Backend Developer**

IT Systems Professional
and Software Engineer, 4
years experience in IAM
and Cybersecurity



Client and Internal Partners



Tier IV Mentor
Michio Hayashi

Carnegie Mellon University
HeinzCollege
INFORMATION SYSTEMS • PUBLIC POLICY • MANAGEMENT

Faculty Advisor
Mark DeSantis

Carnegie Mellon University
HeinzCollege
INFORMATION SYSTEMS • PUBLIC POLICY • MANAGEMENT

Senior Academic Coordinator
Brittany Foster

Carnegie Mellon University
HeinzCollege
INFORMATION SYSTEMS • PUBLIC POLICY • MANAGEMENT

MISM Program Director
Sean Beggs



Agenda

- About Tier IV
- Problem Statement: Understanding the AD Landscape
- The Challenge & Opportunity
- Initial Assumptions and Where We Are Now
- Finding & Implications + Our Solution
- Demo
- Scope of Work
- Looking Ahead: High Level Recommendations
- References



About Tier IV

TIER IV is a deep-tech startup based in Tokyo and is one of the leading developers of Autoware

Company Mission

"CO-CREATE, VALUE, DISRUPTIVELY"

Company Vision

"THE ART OF OPEN SOURCE, REIMAGINE INTELLIGENT VEHICLES."

TIER IV, with the world's first open-source software for **Autonomous Driving (AD)**, has a vision of evolving the autonomous driving market through:

- Open access to AD technology
- Drives implementation of AD technology in tandem with customers
- Primary deployment areas are the Japan and U.S. geographic regions



Understanding the AD Landscape

Traditional Autonomous Vehicle (AV) companies have defined the **Operational Domain Design (ODD)** as the target deployment region itself leading to constraints

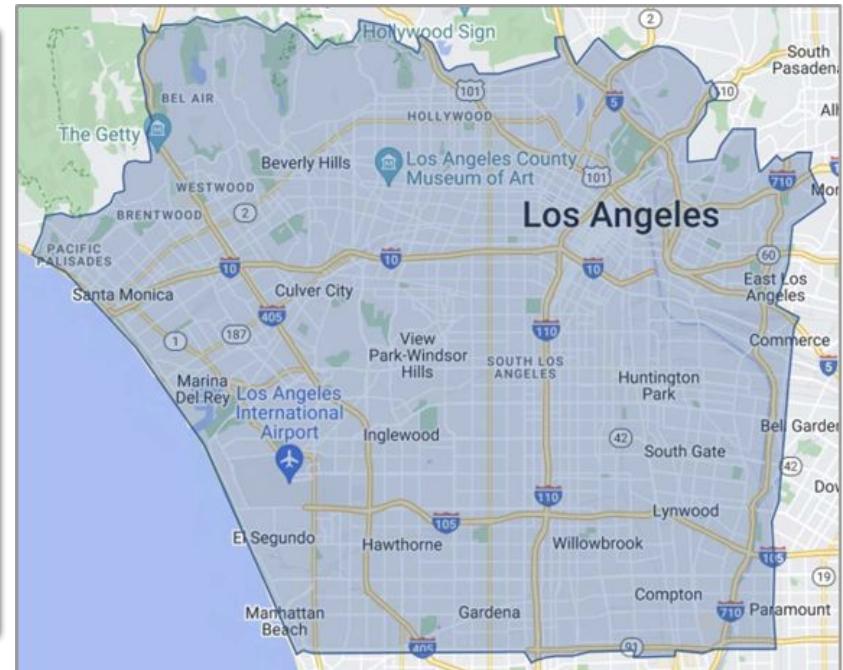
An ODD "defines the operating conditions under which an ADS is designed to operate safely" (ISO 34503)

For example

If they define Los Angeles as the ODD region, they must develop, test, and validate within Los Angeles.

Constraints

- **Regional Constraints:**
Difficulty of scaling into new regions
- **Capital constraints:**
Significant capital investment to collect data



ODD Specification of Waymo, via cpuc.ca.gov



The Time for Autonomous Driving is Now

AVs are coming out of the trough of disillusionment Level 5 AVs will be available by 2030 and the AV market will surpass **\$75 billion**

Society of Automotive Engineers (SAE)	
Levels	Description
Level 0	Vehicles equipped with no automated features, requiring the driver to be in complete control of the vehicle.
Level 1	Vehicles equipped with one or more primary automated features such as cruise control, but requiring the driver to perform all other tasks.
Level 2	Vehicles equipped with two or more primary features, such as adaptive cruise control and lane-keeping, that work together to relieve the driver from controlling those functions.
Level 3	Vehicles equipped with features that allow the driver to relinquish control of the vehicle's safety-critical functions depending on traffic and environmental conditions. The driver is expected to take over control of the vehicle given the constraints of the automated features after an appropriately timed transition period.
Level 4	Vehicles equipped with features that allow the driver to relinquish control of the vehicle's safety-critical functions. The vehicle can perform all aspects of driving even if the driver does not respond to a request to intervene.
Level 5	Fully autonomous vehicles that monitor roadway conditions and perform safety-critical tasks throughout the duration of the trip with or without a driver present. This level of autonomy is appropriate for occupied and unoccupied trips.

Level 5

Fully autonomous vehicles
that monitor roadway
conditions and perform
safety-critical tasks

1



The Challenge/Opportunity

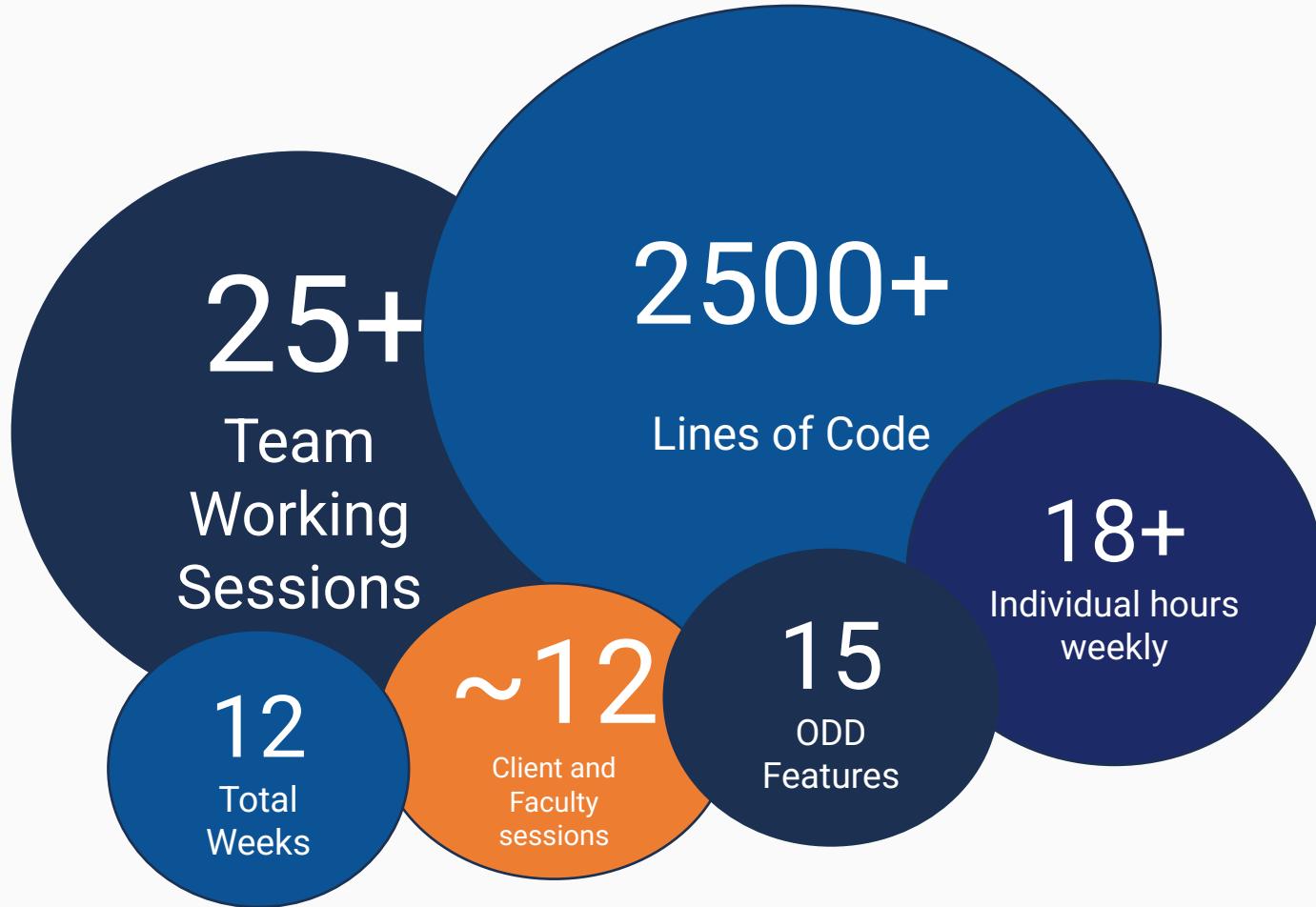
Tier IV can improve ODD **safety standards** for autonomous vehicles preventing premature state level policies push

42,795 people died in vehicle crashes in 2022. **94%** of crashes are due to human error. AVs have the potential to remove/reduce human error and decrease deaths

AVs have the potential to reduce crashes by **90%**, potentially saving approximately **\$190B** per year



Our Project at a Glance





Initial Assumptions

Our work began with understanding the previous team's efforts which provided a grounding for goal setting, refined scope, and new insights

Data Availability Was the Primary Risk: Obtaining access to high-quality, relevant data would be a challenge

Long Routes Were Most Valuable: We initially prioritized finding the longest continuous routes under the belief that longer routes = stronger connectivity

Tool Governance: The tool's end users would be engineers

Backend integration should be accessible and flexible with everyone's Features

Database caching: initial model was using the OSMnx library to get all features from the internet

Timeline feasibility: Possibility of implementing all 3 main ODD elements of environmental, scenery, and dynamic elements



Where We Are Now

Our work began with understanding the previous team's efforts which provided a grounding for goal setting, refined scope, and new insights

Working Visualization Tool: Identified phased approach to implementing visualization tool beginning with High priority Scenery mapping out the road networks within the defined ODD. ODD elements can have parameterizations, so the visualization tool should be able to take input from users and dynamically update the corresponding road network

Data Access Is Readily Available: We've confirmed that data can be fetched efficiently and can be manipulated actionable insights

Value in Route Complexity Over Length: Through stakeholder engagement, we now recognize that routes with more nodes or strategic connectivity (not just length) may offer greater value

Caching & Backend Infrastructure Established: We've implemented MongoDB for Data Storage and Flask Caching

Findings & Implications

Findings & Implications

The following **Focus Areas** have been identified to build a visualization tool to map out the road networks within defined ODD

FOCUS AREA	FINDINGS & IMPLICATIONS
 Location Specific ODD	Geo-specific ODD → Limits scaling
 ISO Standards	Data gaps → Weakens standard design
 Automandering	State-level policy push → Lowers safety in test zones
 Road Networks	ODD compliance gaps → Breaks network coverage

Our Solution



Visualization Tool Current State and Future Work

User interaction with visualization tool sifts through **9.1 billion nodes** via osmnx to retrieve relevant Phase One ODD elements

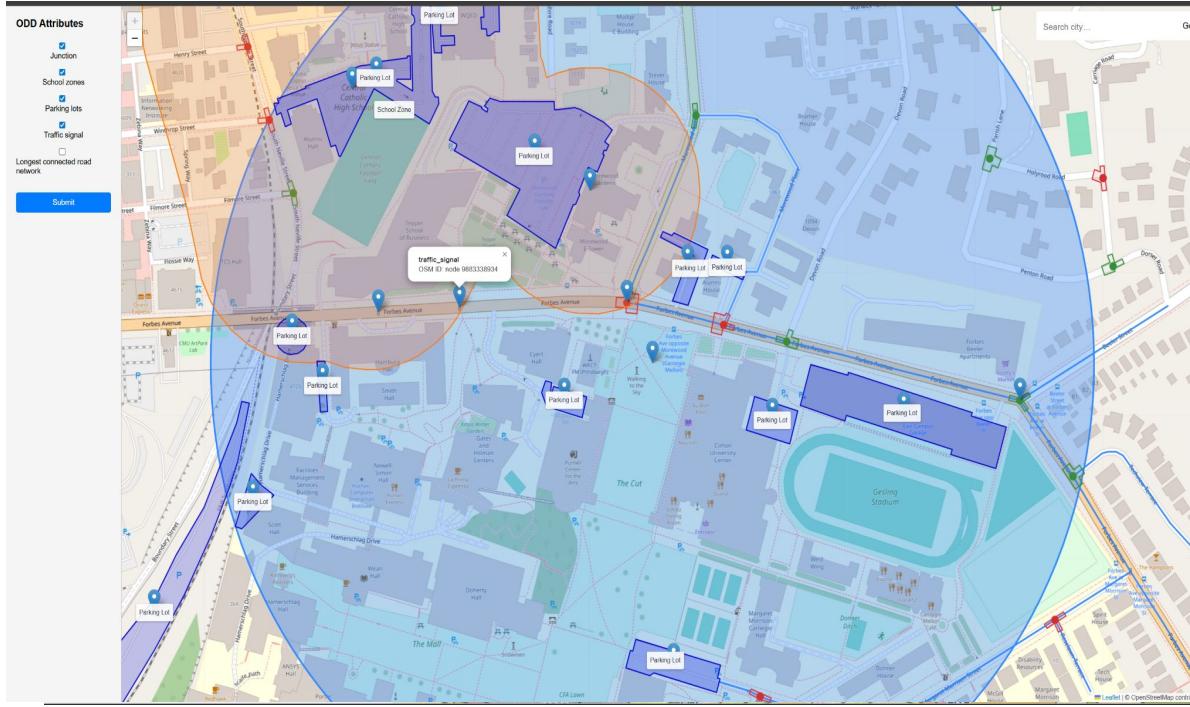
	Current State	Future Work	
ODD Elements	Phase One (High Priority)	Phase Two	Phase Two or Three
Main Category	Scenery	Environment	Dynamic
Sub Category 1	Zones, Driveable Areas, Junctions	Weather, particulates, illumination, connectivity	Traffic agents, subject vehicle
Sub Category 2	Parking lots, traffic management zone, driveable area signs, driveable area type, roundabout, intersection etc.	Wind, rainfall, natural illumination	Agent type, presence of special vehicles, specification
Sub Category 3	Highway types, Speed limits, Lane dimension	Daytime, nighttime, low ambient	Motor vehicles, ambulances, police vehicle, work vehicle



Holistic Visualization Tool (Phase One)

The **Heinz Team** is solving the **mapping problem** from the ODD definition to real-world geographic regions

Tier IV ODD Safety Checker - Pittsburgh



We are developing a **cross functional tool** that can be used by both **Business** and **Autonomous Driving** personas



Business Exec



AV Engineer



Visualization Tool Features

Safety Checker Tool will incorporate **Operational flexibility** from anywhere to prevent scaling issues



Location Agnostic ODD



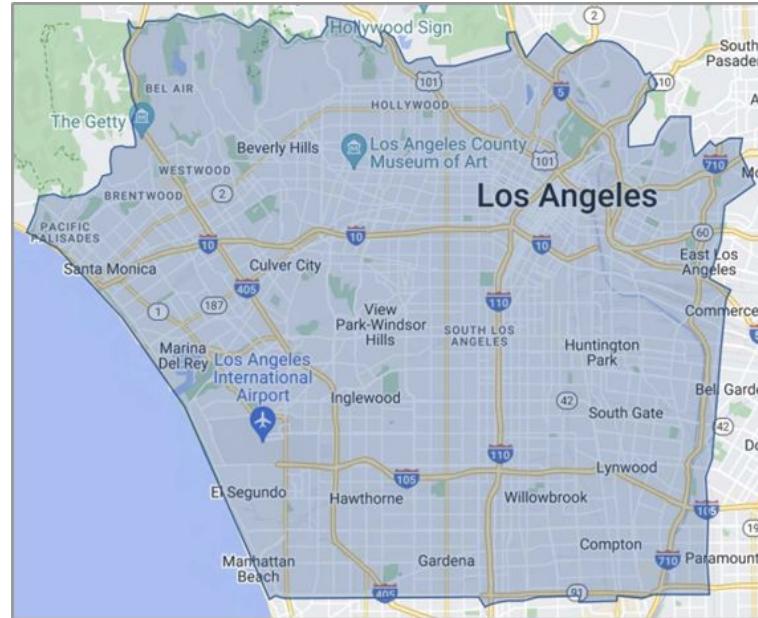
ISO Standards



Automandering Mitigation



Road Networks



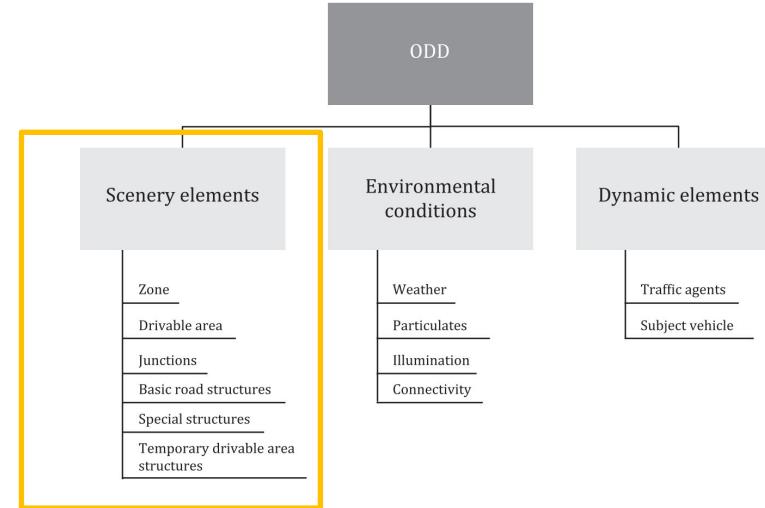
ODD Specification of Waymo, via cpuc.ca.gov



Visualization Tool Features

Combines public and proprietary data will be used to ensure **ISO-34503 ODD Elements compliance**

-  Location Agnostic ODD
-  ISO Standards
-  Automandering Mitigation
-  Road Networks



Overview of ODD, via ISO 34503



Visualization Tool Features

Improves accuracy to **State-level** policies through safety standards incorporating ODD elements



Location Agnostic ODD



ISO Standards



Automandering Mitigation



Road Networks

Promote Fair Regulation





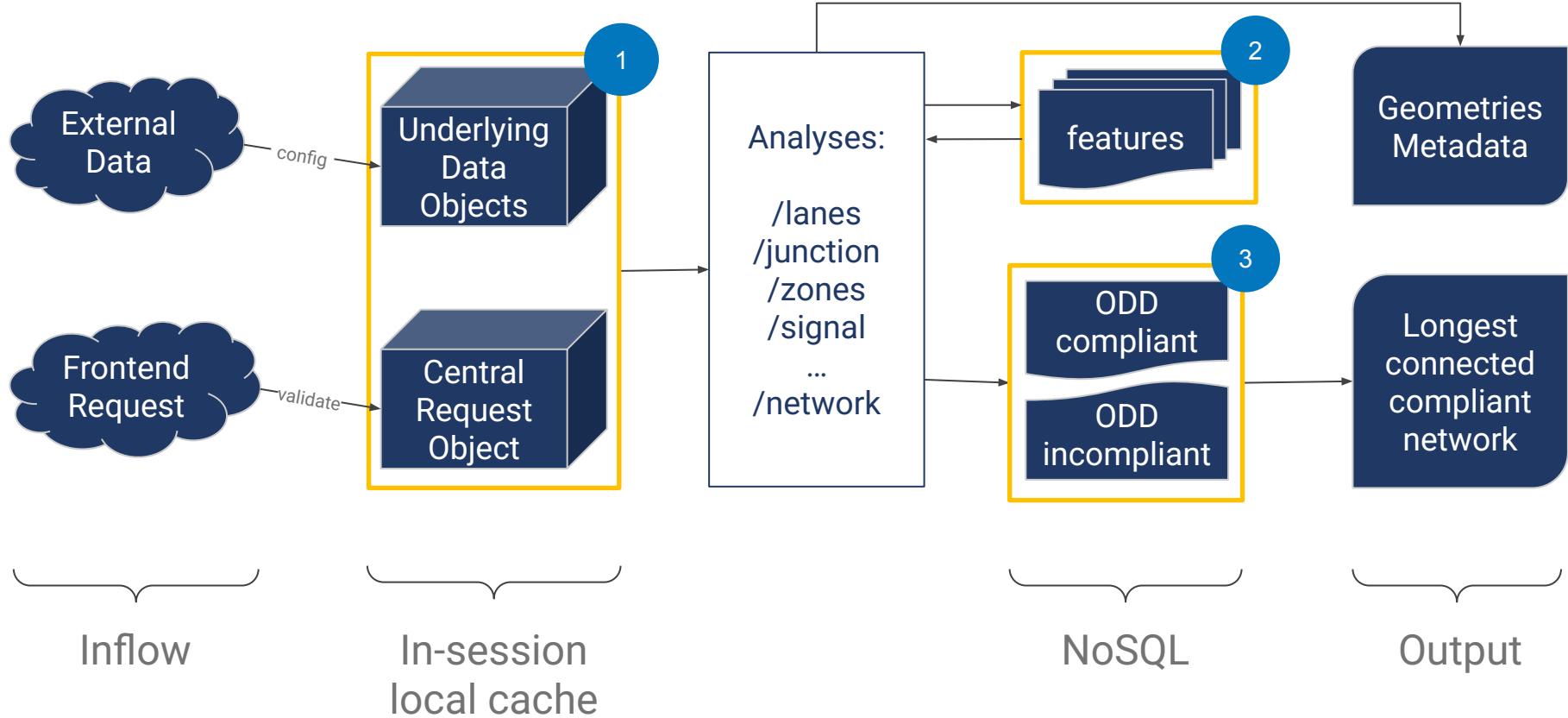
Visualization Tool Features

ODD compliance impacts **network connectivity** for unmapped geographic regions

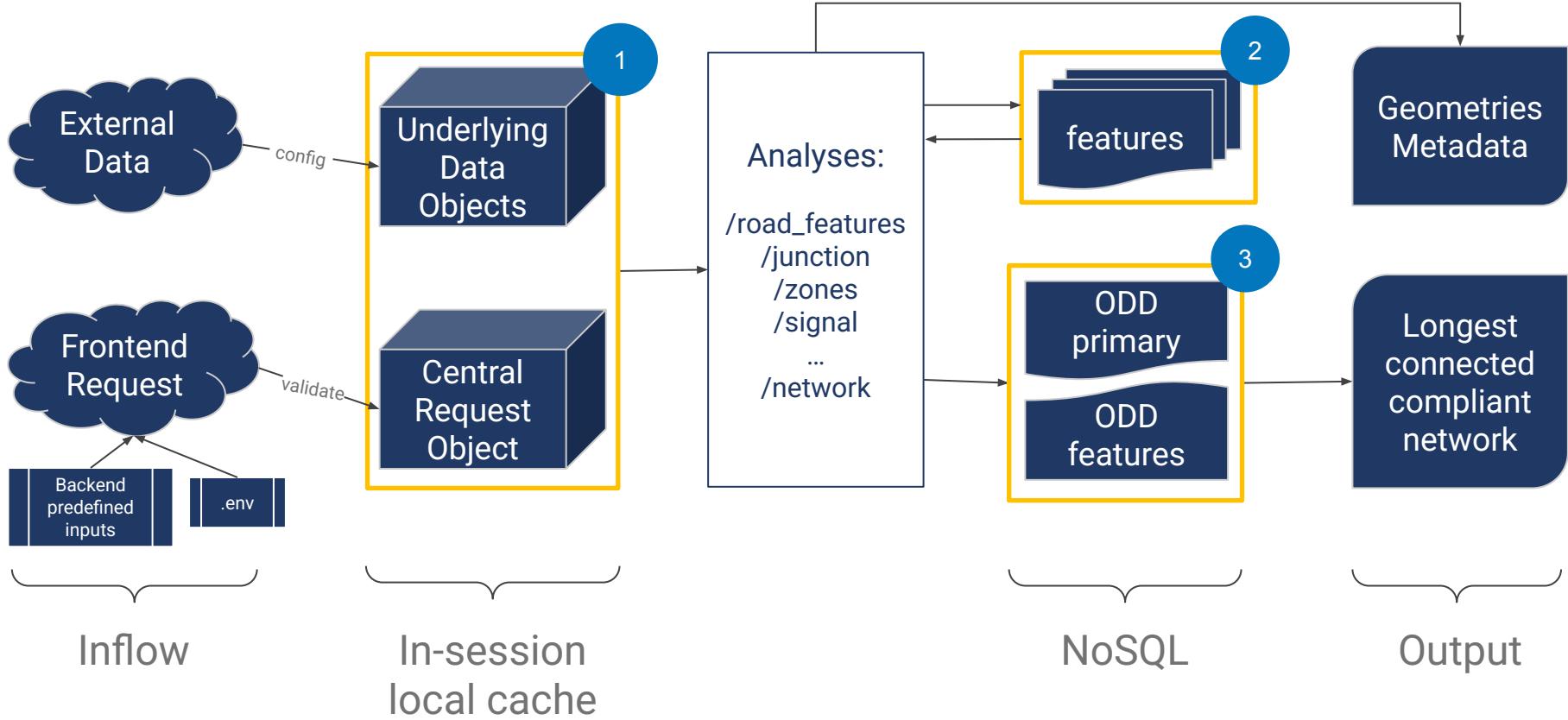
-  Location Agnostic ODD
-  ISO Standards
-  Automandering Mitigation
-  Road Networks

**5 Minute
Demo**

App Workflow



App Workflow



Scope of Work



Scope of Work

Business Objectives

- Visualize Market Reach
- Ensure Safe Scaling
- Increase Transparency
- Aid Fundraising





Economies of Scale Advantage

From Ambiguous Expansion to **Strategic Deployment**

BEFORE [*Expensive, trial-and-error*]

1. Blind investment decisions
2. Unpredictable ROI
3. No expansion strategy

AFTER [*Strategic, data-driven*]

1. Deploy in order of ODD complexity/ROI
2. Predictable returns - Data-driven expansion
3. Systematic expansion strategy to optimize cost



Economies of Scale Advantage

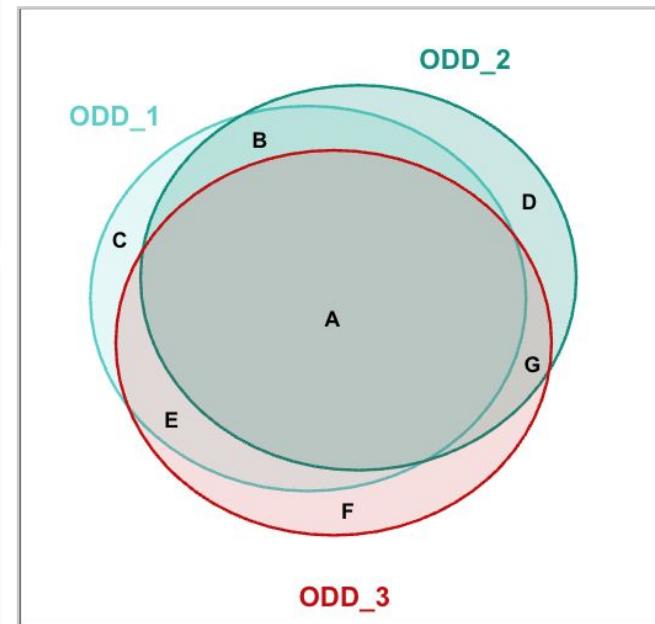
Business Impact: The ODD tool creates economies of scale in deployment validation

Assumptions:

- Engineering validation time (cost) of a given OD is proportional to the ODD area
- Deployment order $1 > 2 > 3$

Settings:

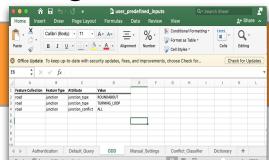
- Engineering time of ODD_1 ($A+B+C+E$): t
- Engineering time for ODD_2 is reduced by a factor of $(D+G)/(A+B+D+G)$
- Engineering time for ODD_3 is reduced by a factor of $(F)/(A+E+F+G)$





Artifact Preview

A glimpse into selected artifacts and their purposes, offering insight into their functional significance

Artifact	Description
Executive Summary	A high-level overview of the project's goals, achievements, and key takeaways (what we built, why it matters, and where it's headed)
Excel (Two Documents)	Features default query settings, analysis parameter setting, prioritized odd Elements
GitHub Documentation	Code, commits, and collaboration.
Future Roadmap	Next steps, high level roadmap across Governance, Technology Management, and User Enablement
Artifacts	   



Project Management



Timeline

26 May

01 June

9 Jun

16 Jun

23 Jun

7 Jul

21 Jul

30 July

Environment Discovery

- In-Development Tool (Front/BackEnd)
- ODD Review/ASAM Opendrive
- ODD Open Street Maps Data Collection



Visualization Tool

- Workshop for ODD Prioritization
- Develop BackEnd
- Develop Front End
- Back/Front end Tasking in Jira



Abstract Representation

- Generalized ODD Schematic
- OpenStreetMaps API Integration
- Data Gathering Parameters



Documentation Development

- Midterm Presentation
- Final Presentation
- Final Prototype, System Components
- Updated Github Artifact
- Executive Summary



Other Feature Developments

- Risk Feature Development
- Boundary Set and Provide coordinates (Region Diameter)



Risks, Issues and Timeline



Project Risks and Issues

Potential impediments and limitations

- Time constraints
- Prioritized ODD elements
- Static map & limited data, lacking dynamic conditions
- Tool performance reliant on third-party APIs



Phase One Roadmap: Looking Ahead





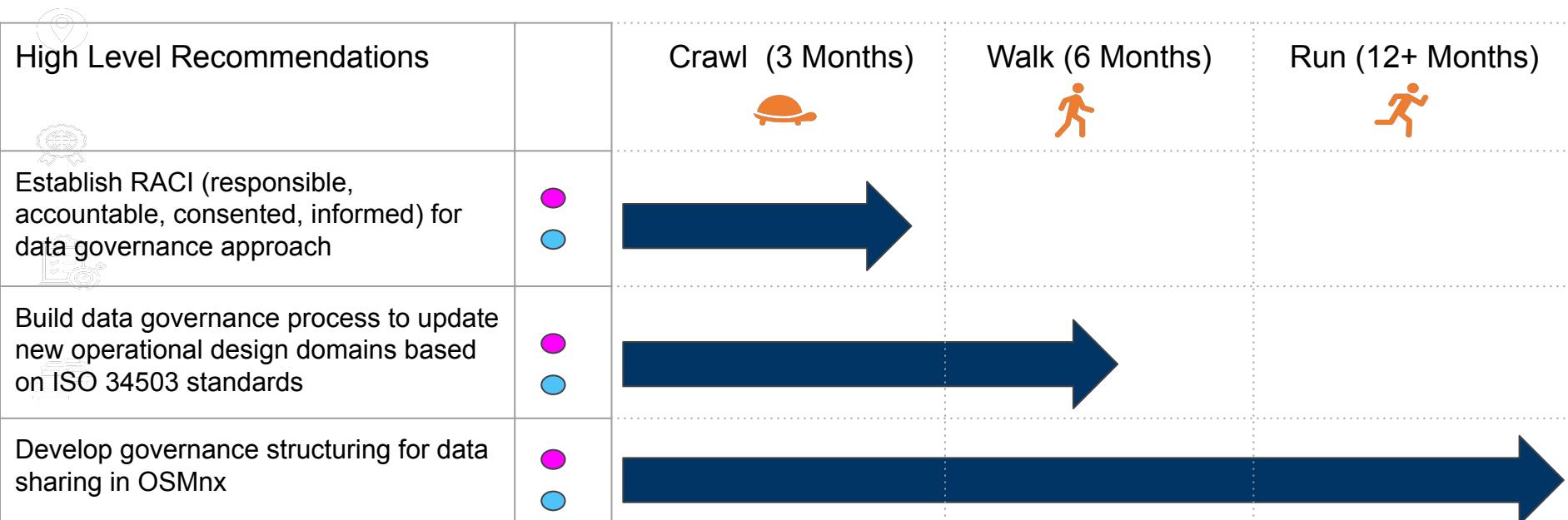
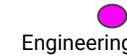
Our work with Tier IV has surfaced high level roadmap recommendations in consideration of continuous and strategic implementation of the visualization tool in phase one



Area of Recommendation	Description	Short Term	Medium Term	Long Term
Governance 	<ul style="list-style-type: none"> ● Governance refers to the framework of policies, roles, responsibilities, and decision-making structures 			
Technology Enablement 	<ul style="list-style-type: none"> ● Technology Enablement is the provisioning and configuration of the right tools, platforms, and technical infrastructure 			
Process Optimization 	<ul style="list-style-type: none"> ● Process Optimization involves analyzing and improving business or operational processes to increase efficiency, reduce cost, and support system adoption 			
User Enablement	<ul style="list-style-type: none"> ● User Enablement focuses on preparing end-users to adopt and effectively use the new system or technology through training, support, and change management. 			



Ensuring proper governance of tool while orchestrating people, process and tools





Technology Enablement is the provisioning and configuration of the right tools, platforms, and technical infrastructure

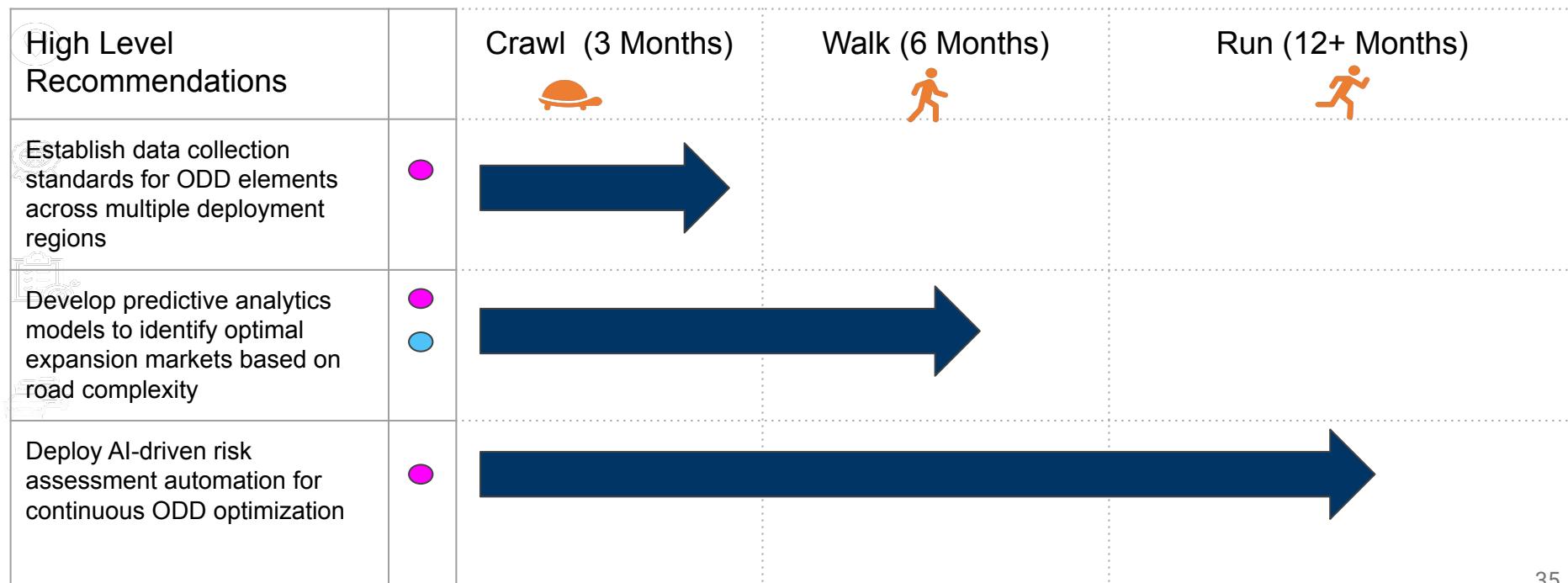
Engineering Business

High Level Recommendations	Crawl (3 Months)	Walk (6 Months)	Run (12+ Months)
Extensions: All-around open-source engagement			
Transparency: Knowledge bridging and skill sets for tech stack python, flask, react, typescript, mongodb, docker			
Exploration: Docker-based containerization to reduce processing times and support system reusability			



Streamlining ODD deployment processes to accelerate market entry and reduce operational complexity

Engineering Business





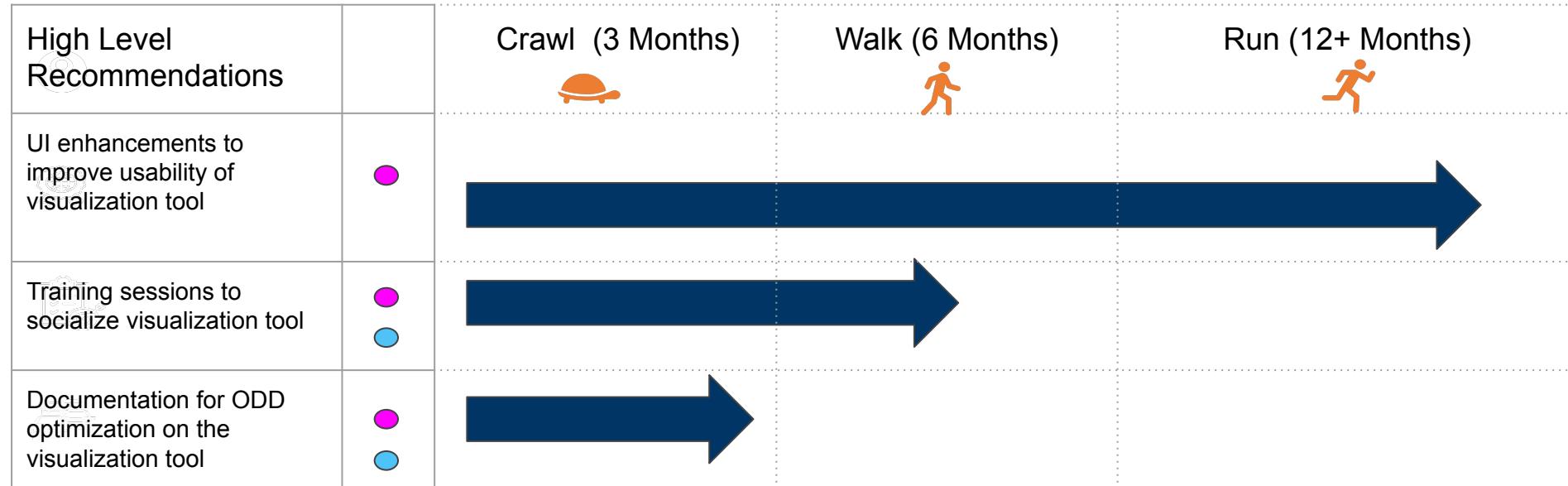
User Enablement focuses on preparing end-users to adopt and effectively use the new system or technology through training, support, and change management



Engineering



Business



Product Strategy

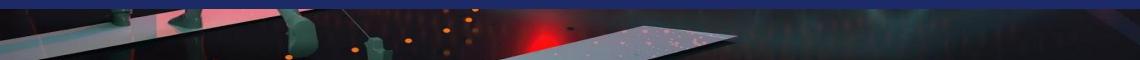


TECHNOLOGY OPPORTUNITY OVERVIEW

Use Real-Time Road Network Analysis Combined With Tier IV's Proprietary Data To Identify The Safest And Most Connected Routes For Autonomous Vehicle Deployment



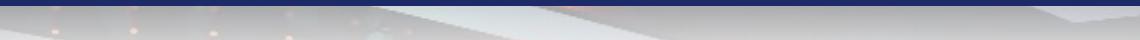
Apply Location-Independent Safety Criteria And Customized Risk Parameters To Reduce New Market Entry Costs And Accelerate Expansion Timelines



Incorporate Global Safety Standards With Proprietary Testing Data To Deliver Consistent Operational Recommendations Across Any Geographic Region



Strategic Decision Automation Transform complex ODD analysis from months of manual work to real-time insights that reduce validation costs and enable data-driven deployment decisions for both technical and business teams





Geography			
Capacities			
Feature extraction	Geometric analysis	ODD compliance check	Most connected network
Risk Assessment			
Legal Risk	Model Risk	Reputation Risk	Operation Risk
H	M	H	H

Product Strategy



TIER IV

Product Strategy Overview			
	DATA GATHERING	MODEL BUILD	INTEGRATION
Activity	Collect OSMnx DATA	Build the ODD compliance logic to check every road segment against the defined safety criteria.	Built for future integration with Tier IV's Autoware ecosystem and deployment tools, enabling plug-and-play ODD analysis in real-world AV workflows.
Outcome	Car behavior dataset with contextual information for ODD elements for safety zones, traffic functions, safety preferences	The longest, continuous, and safest drivable route for strategic deployment planning.	Positions the tool as a core decision-making engine within Tier IV's product suite, enabling data-driven AV deployment, reducing validation costs, and accelerating safe, scalable market expansion.

Thank You



Any Questions?

References and Use of AI

Center for Sustainable Systems, University of Michigan. 2024.
“Autonomous Vehicles Factsheet.” Pub. No. CSS16-18

We used ChatGPT to generate some content for the slides including some textual content to improve wording or make the overall text more concise