# 1 Algebra

# Functions and Symmetries

### **Definition 0.1.1 Functions**

A function  $f:X\to Y$  is called

- injective if  $f(x_1) = f(x_2) \implies x_1 = x_2$ . f is said to be one-to-one on X
- surjective if for every  $y \in Y$ ,  $\exists x \in X \text{ s.t. } f(x) = y$ . f is said to take X onto Y
- bijective if it is both injective and surjective

# Definition 1.1.3 Graph Isomorphisms

An **isomorphism** between two graphs is a *bijection* between them that preserves all edges. More precisely, if  $\Gamma_1$  and  $\Gamma_2$  are graphs, with sets of vertices  $V_1$  and  $V_2$  respectively, then an isomorphism from  $\Gamma_1$  and  $\Gamma_2$  is a bijection

$$f: V_1 \to V_2$$

such that  $f(v_1)$  and  $f(v_2)$  are joined by an edge if and only if  $v_1$  and  $v_2$  are also joined by an edge. We say that  $\Gamma_1$  and  $\Gamma_2$  are isomorphic if there exists an isomorphism  $f:\Gamma_1\to\Gamma_2$ 

# Definition 1.1.9 Symmetry

A **symmetry** of a graph is an *isomorphism* from the graph to itself, i.e. if the set of vertices is V, then the symmetry is a bijection  $f: V \to V$  that preserves edges. That is, a symmetry is a bijection  $f: V \to V$  such that  $f(v_1)$  and  $f(v_2)$  are joined by an edge if and only if  $v_1$  and  $v_2$  are joined by an edge.

# Groups

# Definition 1.2.3 Groups

For an operation \*, We say a non-empty set G is a **group** under \* if the following four axioms hold:

- G1 Closure: \* is a binary operation on G, that is  $a*b \in G$  for all  $a,b \in G$ .
- G2 Associativity: (a\*b)\*c = a\*(b\*c) for all  $a,b,c \in G$
- G3 Identity: There exists an *identity* element of G such that e\*g=g\*e=g for all  $g\in G$ .
- **G4 Inverse:** Every element  $g \in G$  has an inverse  $g^{-1}$  such that  $q * q^{-1} = q^{-1} * q = e$

# Definition 1.2.6 Abelian Group

The definition of a group doesn't require that a\*b=b\*a. We say that a group is **abelian** or **commutative** if a\*b=b\*a for every  $a,b\in G$ . We say that a commutes with b, or that a and b commute

## Subgroups

# Definition 2.1.1 Subgroups

Let G be a group. We say that a non-empty subset H of G is a **subgroup** of G if H itself is a group (under the operation from G). We write  $H \leq G$  if H is a subgroup of G. If  $H \neq G$ , we write H < G and say H is a proper subgroup

### Theorem 2.1.3: Subgroup Test

 $H \subseteq G$  is a subgroup of G if and only if:

- S1: H is not empty
- **S2:** If  $h, k \in H$  then  $h * k \in H$
- S3: If  $h \in H$  then  $h^{-1} \in H$

Alternative test for subgroups:

- $\widetilde{S1}$ : H is not empty.
- $\widetilde{S2}$ : If  $h, k \in H$  then  $h * k^{-1} \in H$

# Definition 2.2.4 Order of an Element

Let G be a group and  $g \in G$ . Then the **order** o(g) of g is the *least* natural number n such that

$$g^n = e$$

If no such n exists, we say that g has infinite order

### Definition 2.2.3 Order of a Group

The **order** of a finite group, written |G|, is the number of elements in G. If G is infinite we say that  $|G| = \infty$ , or the order of G is infinite.

# Theorem 2.2.6: Order of a Finite Group

In a finite group, every element has finite order.

If g is an element of a finite group G, then there exists  $k\in\mathbb{N}$  such that  $g^k=g^{-1}$ 

# Definition 2.2.8 Generating Subset

Let G be a group and let  $g \in G$  be an element. We define the subset

$$\langle g \rangle := \{ g^k \mid k \in \mathbb{Z} \} = \{ \dots, g^{-2}, g^{-1}, e, g, g^2, \dots \}$$

Note that if G is finite, then by 2.2.6  $\langle g \rangle$  is finite, and we can think of  $\langle g \rangle$  as

$$\langle g \rangle = \{ e, g, \dots, g^{o(g)-1} \}$$

# Definition 2.2.10 Cyclic Subgroup

A subgroup  $H \leq G$  is **cyclic** if  $H = \langle h \rangle$  for some  $h \in H$ . In this case, we say that H is the *cyclic subgroup generated by h*. If  $G = \langle g \rangle$  for some  $g \in G$ , then we say that the group G is *cyclic*, and that g is a *generator*.

## Remark 2.2.12 - 16: Consequences of Cyclic groups

- **2.2.12** If  $g \in G$ , then  $o(g) = |\langle g \rangle|$
- 2.2.13: If G is cyclic, then G is abelian.
- 2.2.14: Let G be a finite group. Then

G is cyclic  $\iff$  G has an element of order |G|

- 2.2.15: Let G be a cyclic group and let H be a subgroup of G. Then H is cyclic.
- 2.2.16: Let  $m, n \in \mathbb{N}$ , let  $G = \langle g \rangle$  be a cyclic group of order m and  $H = \langle h \rangle$  be a cyclic group of order n. Then

 $G \times H$  cyclic  $\iff m$  and n are coprime  $(\gcd(m,n) = 1)$ 

# Cosets and Lagrange

### Definition 2.3.2 Relation

Let X be a set, and R a subset of  $X \times X$ ; thus R consists of some ordered pairs (s,t) with  $s,t \in X$ . If  $(s,t) \in R$  we write  $s \sim t$  and say "s is related to t". We call  $\sim$  a **relation** on X.

### Definition 2.3.2 Equivalence Relation

- Reflexive:  $x \sim x$  for all  $x \in X$
- Symmetric:  $x \sim y$  implies that  $y \sim x$  for all  $x, y \in X$
- Transitive:  $x \sim y$  and  $y \sim z$  implies that  $x \sim z$  for all  $x,y,z \in X$

A relation  $\sim$  is called an **equivalence relation** on X if it satisfies the following three axioms:

### Definition 2.3.4 Coset

Let  $H \leq G$  and let  $g \in G$ . Then a left coset of H in G is a subset of G of the form gH, for some  $g \in G$ . We denote the set of left cosets of H in G by G/H

# Theorem 2.4.2: Lagrange's Theorem

Suppose that G is a finite group.

- If H < G, then |H| divides |G|
- Let  $g \in G$ . Then o(g) divides |G|
- For all  $q \in G$ , we have that  $q^{|G|} = e$

### Theorem 2.3.8: Coset Rules

Let  $H \leq G$ 

- For all  $h \in H$ , hH = H. In particular eH = H
- For  $g_1, g_2 \in G$ , the following are equivalent
  - $q_1 H = q_2 H$
  - there exists  $h \in H$  such that  $g_2 = g_1 h$
  - $-g_2 \in g_1H$
- For  $g_1, g_2 \in G$ , define  $g_1 \sim g_2$  if and only if  $g_1 H = g_2 H$ . Then  $\sim$  defines an equivalence relation on G.

# Theorem 2.4.4: Index of a Subgroup

The **index** of  $H \leq G$  is defined as the number of distinct left cosets of H in G, which by Lagrange's is  $|G/H| = \frac{|G|}{|H|}$ 

## Remark 2.4.6 - 8: Consequences of Lagrange

- 2.4.6: Suppose that G is a group with |G|=p, where p is prime. Then G is a cyclic group
- 2.4.7: Suppose that G is a group with |G| < 6. Then G is abelian
- 2.4.8: If p is a prime and  $a \in \mathbb{Z}$ , then  $a^p \equiv a \mod p$

# Homomorphisms and Isomorphisms

## Definition 3.1.1 Group Homomorphism

Let  $(G,*),(H,\circ)$  be groups. A map  $\phi:G\to H$  is called a  ${\bf homomorphism}$  if

$$\phi(x*y) = \phi(x) \circ \phi(y)$$
 for all  $x, y \in G$ 

Note that the product on the left is formed using \*, while the product on the right is formed using  $\circ$ 

# Definition 3.1.2 Group Isomorphism

A group homomorphism  $\phi: G \to H$  that is also a bijection is called an **isomorphism** of groups. In this case we say that G and H are *isomorphic* and we write  $G \cong H$ . An isomorphism  $G \to G$  is called an **automorphism** of G.

# Theorem 3.1.L: Cyclic Isomorphisms

All finite cyclic groups of the same order are isomorphic to each other. Therefore, cyclic groups of order n are isomorphic to  $(\mathbb{Z}_n, +)$ 

All infinite cyclic groups are *isomorphic* to each other. Therefore, each cyclic group of infinite order is isomorphic to  $(\mathbb{Z}, +)$ 

# Remark 3.1.5: Consequences of Homomorphisms

Let  $\phi: G \to H$  be a group homomorphism. Then

- $\phi(e_G) = e_H$
- $\phi(g^k) = (\phi(g))^k$  and  $\phi(g^{-1}) = (\phi(g))^{-1}$  for all  $g \in G$
- If  $\phi$  is injective, the order of  $g \in G$  equals the order of  $\phi(g) \in H.$

## Definition 3.1.7 Normal Subgroup

A subgroup  $N \leq G$  is **normal** if the left and right cosets of N are equal, i.e. gN = Ng for all  $g \in G$ . If N is a normal subgroup of G, we write  $N \triangleleft G$ . Kernels of homomorphisms are always normal subgroups

## Definition 3.1.6 Image and Kernel of a Group

Let  $\phi: G \to H$  be a group homomorphism.

• The **image** of  $\phi$  is defined to be

$$\operatorname{im} \phi := \{ h \in H \mid h = \phi(q) \text{ for some } q \in G \}$$

• The **kernel** of  $\phi$  is defined to be

$$\ker \phi := \{ g \in G \,|\, \phi(g) = e_H \}$$

Note:  $\operatorname{im} \phi$  is a subgroup of H and  $\operatorname{ker} \phi$  is a subgroup of G

## Theorem 3.2.1: Product Isomorphisms

Let  $H, K \leq G$  be subgroups with  $H \cup K = \{e\}$ .

- The map  $\phi: H \times K \to HK$  given by  $\phi: (h, k) \to hk$  is bijective
- If every element of H commutes with every element of K when multiplied in G (i.e.  $hk = kh \quad \forall h \in H, k \in K$ ), then HK is a subgroup of G, and it is isomorphic to  $H \times K$  via  $\phi$

### Theorem 3.2.3: Size of Product Group

Let  $H,K \leq G$  be finite subgroups of a group G such that  $H \cup K = \{e\}$  Then  $|HK| = |H| \times |K|$ .

# **Group Actions**

### Definition 4.1.1 Group Action

Let (G, \*) be a group, and let X be a nonempty set. Then a (left) **action** of G on X is a map

$$G \times X \to X$$

written  $(q, x) \mapsto q \cdot x$ , such that

$$q_1 \cdot (q_2 \cdot x) = (q_1 * q_2) \cdot x$$
 and  $e \cdot x = x$ 

for all  $g_1, g_2 \in G$  and all  $x \in X$ .

## Definition 4.1.4 Kernel of an Action, Faithful Action

Suppose that G acts on X. Then the set

$$N := \{ g \in G \mid g \cdot x = x \forall x \in X \}$$

is a subgroup of G, and is called the **kernel** of the action. If  $N=\{e\}$ , then we say the action is **faithful** 

### Definition 4.2.1 Orbit, Stabilizer, and Fix

For every x in X, the **orbit** of x is defined by

$$Orb_G(x) = \{g \cdot x \mid g \in G\}$$

This is a subset of X

For every x in X, the **stabilizer** of x is defined by

$$Stab_G(x) = \{ g \in G : g \cdot x = x \}$$

This is a subgroup of G

For every g in G, the fix of g is defined by

$$Fix(g) = \{ x \in X \mid g \cdot x = x \}$$

Let G act on X, let  $x\in X$  and set  $H:=\operatorname{Stab}_G(x).$  If  $y=g\cdot x$  for some  $g\in G,$  then

$$\operatorname{send}_x(y) = gH$$

# Theorem 4.2.5: Orbit Equivalence

Let G act on X. Then

$$x \sim y \iff y = q \cdot x \text{ for some } q \in G$$

defines an equivalence relation on X. The equivalence classes are the orbits of G. Thus when G acts on X, we obtain a partition of X into orbits

#### Theorem 4.3.1: Orbit-Stabilizer Theorem

Suppose G is a finite group acting on a set X, and let  $x \in X$ . Then  $|\operatorname{Orb}_G(x)| \times |\operatorname{Stab}_G(x)| = |G|$ , or in words:

size of orbit × size of stabilizer = order of group

### Theorem 4.3.4: Orbit Send Theorem

Let G act on X, let  $x \in X$ , and let set  $H := \operatorname{Stab}_G(x)$ . Then the map

 $\operatorname{send}_x : \operatorname{Orb}_G(x) \to G/H \text{ which sends } y \mapsto \operatorname{send}_x(y)$ 

### Theorem 4.4.2: Cauchy's Theorem

Let G be a group, p be prime. If p divides |G|, then G contains an element of order p

# 2 Analysis

## Real Numbers and Bounds

### **Definition 1.1 The Real Numbers**

 $\mathbb{R}$  is defined as the set of real numbers. It has two operations + and \*, and it is a field, i.e. satisfies group axioms for both, in addition the Distributive law:

$$a \cdot (b+c) = a \cdot b + a \cdot c$$

The set of real numbers is also ordered, i.e. there is a relation < which satisfies pretty much what you think it does

Finally, the set of real numbers is complete, i.e. there are no gaps between any numbers.

## Definition 1.3.2 Suprema and Bounds

Let  $E \subset \mathbb{R}$  be nonempty

- The set E is said to be bounded above if there is  $M \in R$  such that  $a \leq M$  for all  $a \in E$
- A real number M is called an upper bound of the set E if a < M for all  $a \in E$
- A real number s is called the **supremum** of the set E if
  - -s is an upper bound of E
  - -s < M for all upper bounds M of the set E

If a number s exists, we shall say that E has a supremum and write  $s = \sup E$ 

If the supremum s exists, then s is the least upper bound of the set E. The supremum is also unique if it exists.

### Definition 1.3.10 Infimum

If the same properties as a supremum apply but in the other direction, a number s is instead called the **infimum** of the set E. Infimum and Supremum are related via the reflection principle:

- Set E has a supremum if and only if the set -E has an infimum. Also  $\inf(-E) = -\sup(E)$
- Set E has an infimum if and only if the set -E has a supremum. Also  $\sup(-E) = -\inf(E)$

# Theorem 1.3.5: Suprema Approximation Property

If the set  $E\subset\mathbb{R}$  has a supremum then for any positive number  $\epsilon>0$  there exists  $a\in E$  such that

$$\sup E - \epsilon < a \le \sup E$$

# Theorem 1.3.7: Archimedean Principle

Given positive real numbers  $a,b\in\mathbb{R}$  there is an integer  $n\in N$  such that b< na

### Definition 1.5.2 Countability

Let E be a set. E is said to be:

- Finite if either  $E = \emptyset$ , or there is an integer  $n \in \mathbb{N}$  and a bijection  $f : \{1, 2, 3, ..., n\} \to E$ . We say that the set E has n elements
- Countable if there is a bijective function  $f: \mathbb{N} \to E$
- At most countable if E is finite or countable
- Uncountable if E is neither finite nor countable

Additionally, a nonempty set E is at most countable if and only if there is a surjective function  $f: \mathbb{N} \to E$ 

# Sequences and Series

## Definition 2.1.1 Convergence of a Sequence

A sequence of real numbers  $(x_n)$  is said to converge to a real number a if for every  $\epsilon >_0$  there is a  $N \in \mathbb{N}$  where for every  $n \geq N$  we have that  $|x_n - a| < \epsilon$ 

### Definition 2.1.9 Bounds of Sequences

Let  $(x_n)$  be a sequence of real numbers.

- $(x_n)_{n\in\mathbb{N}}$  is said to be **bounded above** if  $x_n\leq M$  for some  $M\in\mathbb{R}$  and all  $n\in\mathbb{N}$
- $(x_n)_{n\in\mathbb{N}}$  is said to be **bounded below** if  $x_n\geq m$  for some  $m\in\mathbb{R}$  and all  $n\in\mathbb{N}$
- $(x_n)_{n\in\mathbb{N}}$  is said to be **bounded** if it is both bounded above and below

### Remark 2.2.1 - ?: Limit Theorems

- Let  $E \subset \mathbb{R}$ . If E has a finite supremum then there is a sequence  $(x_n)$  with each  $x_n \in E$  such that  $x_n \to \sup E$  as  $n \to \infty$ . The same goes for a finite infimum
- Comparison Theorem for sequences: Suppose that  $(x_n)$ ,  $(y_n)$  are real sequences. If both  $\lim_{n\to\infty} x_n$ ,  $\lim_{y\to\infty} y_n$  exist and belong to  $\mathbb{R}*$ , and if  $x_n\leq y_n$  for all  $n\geq N$  for some  $N\in\mathbb{N}$ , then  $\lim_{n\to\infty} x_n\leq \lim_{n\to\infty} y_n$

### Definition 2.3.1 Monotone Sequences

Let  $(s_n)$  be a sequence of real numbers.

- $(s_n)$  is said to be increasing if  $s_1 \leq s_2 \leq s_3 \leq \cdots$ , and strictly increasing if  $s_1 < s_2 < s_3 < \cdots$
- $(s_n)$  is said to be decreasing if  $s_1 \geq s_2 \geq s_3 \geq \cdots$ , and strictly decreasing if  $s_1 > s_2 > s_3 > \cdots$
- $(s_n)$  is said to be monotone if it is either increasing or decreasing

### Theorem lots: Top 10 Limit Theorems

- Squeeze Theorem (for sequences): Suppose that  $(x_n)$ ,  $(y_n)$ , and  $(w_n)$  are real sequences
  - If both  $x_n \to a$  and  $y_n \to a$  as  $n \to \infty$ , and if  $x_n \le w_n \le y_n$  for all  $n \ge N_0$ , then  $w_n \to a$  as  $n \to \infty$
  - If  $x_n \to 0$  and  $(y_n)$  is bounded,  $x_n y_n \to 0$  as  $n \to \infty$
- Divergence Test:
  - If  $\sum_{n=1}^{\infty} a_n$  converges, then  $a_n \to 0$ .
  - If  $(a_n)_{n\in\mathbb{N}}$  doesn't converge to 0, then  $\sum_{n=1}^\infty a_n$  diverges. Be careful that the converse isn't true.
- Comparison Test: Let  $(a_n)_{n\in\mathbb{N}}$  and  $(b_n)_{n\in\mathbb{N}}$  be two sequences such that  $0\leq a_n\leq b_n$  for all n.
  - If  $\sum_n b_n$  converges, then  $\sum_n a_n$  converges as well.
  - If  $\sum_n a_n$  diverges, then  $\sum_n b_n$  diverges as well.
- Limit Comparison Test: Let  $(a_n)_{n\in\mathbb{N}}$  and  $(b_n)_{n\in\mathbb{N}}$  be two real sequences with  $a_n\geq 0$  and  $b_n>0$  for all n. Assume that  $a_n/b_n\to L$  for some  $L\in(0,\infty)$ . Then,  $\sum_{n=1}^\infty a_n$  converges iff  $\sum_{n=1}^\infty b_n$  converges.
  - If L=0 and  $\sum_{n=1}^{\infty} b_n$  converges then  $\sum_{n=1}^{\infty} a_n$  converges
  - If  $L = \infty$  and  $\sum_{n=1}^{\infty} a_n$  diverges then  $\sum_{n=1}^{\infty} b_n$  diverges
- Root Test: Let  $\sum_{n=0}^{\infty} a_n$  be a series with non-negative terms such that  $\sqrt[n]{a_n} \to L$  where  $0 \le L \le +\infty$ .
  - If  $0 \le L < 1$  then the series  $\sum_{n=0}^{\infty} a_n$  converges.
  - If L > 1 then the series  $\sum_{n=0}^{\infty} a_n$  diverges.
  - If L=1, the series may or may not converge
- Ratio Test: Let  $\sum_{n=0}^{\infty} a_n$  be a series with positive terms such that  $(a_{n+1})/(a_n) \to L$ , where  $0 \le L \le +\infty$ .
  - If  $0 \le L < 1$  then the series  $\sum_{n=0}^{\infty} a_n$  converges.
  - If L > 1 then the series  $\sum_{n=0}^{\infty} a_n$  diverges.
  - If L=1 then compare to p series
- Cauchy's Condensation Test: Let  $(a_n)_{n\in\mathbb{N}}$  be a decreasing sequence with non-negative terms. Then the following are equivalent:
  - The series  $\sum_{n=1}^{\infty} a_n$  converges
  - The series  $\sum_{n=0}^{\infty} 2^n a_{2^n}$  converges.
- Alternating Series Test: Let (b<sub>n</sub>)<sub>n∈N</sub> be a decreasing sequence of non-negative real numbers that converges to zero.
   Then the series ∑<sub>n=1</sub><sup>∞</sup> (-1)<sup>n-1</sup>b<sub>n</sub> converges.
- Monotone Convergence Theorem: If a sequence of real numbers  $(s_n)$  is increasing and bounded above, or decreasing and bounded below, then  $(s_n)$  is convergent (and converges to the supremum/infinum of the set  $\{x_n \mid n \in \mathbb{N}\}$  respectively).
- Geometric Series Test: Assume  $a, r \in \mathbb{R}, a, r \neq 0$ . Then

$$\sum_{n=1}^{\infty} a \cdot r^n = \begin{cases} \frac{a}{1-r} & \text{if } |r| < 1\\ \text{diverges} & \text{if } |r| \ge 1 \end{cases}$$

Notice that a is always the first term in the series, and r is the  $common\ ratio$ 

# Continuity and Functional Limits

### **Definition 4.1.1 Continuity**

Let f be a real-valued function whose domain is a subset of  $\mathbb{R}$ . The function f is **continuous** at  $x_0$  in dom (f) if, for every sequence  $(x_n)$  in dom (f) converging to  $x_0$ , we have

$$\lim_{n \to \infty} f(x_n) = f(x_0)$$

If f is continuous at each  $a \in S \subseteq \text{dom}(f)$  and then we say that f is continuous on S. If f is continuous on dom(f) then we say that f is continuous

## Theorem 4.1.6: $\epsilon - \delta$ Definition of Continuity

A function  $f:A\to\mathbb{R}$  is continuous if for all  $\epsilon>0$ , there exists some  $\delta>0$  s.t. for all  $x\in A$  for which  $0<|x-c|<\delta$ , we have

$$|f(x) - f(c)| < \epsilon$$

## Theorem 6.1.4: Evil $\epsilon - \delta$ definition of continuity

A function  $f:A\to\mathbb{R}$  is not continuous if there exists  $\epsilon>0$  such that for all  $\delta>0$  there exists some  $x\in A$  satisfying  $0<|x-c|<\delta$  for which  $|f(x)-f(c)|\geq \epsilon$ 

### Definition 4.2.1 Bounds of a Function

Let  $E\subseteq \mathbb{R}$  be nonempty. A function  $f:E\to \mathbb{R}$  is said to be bounded on E if

$$|f(x)| \le M$$
, for all  $x \in E$ 

where M is some (large) real number.

### Theorem 4.2.2: Extreme Value Theorem

Let  $I \subseteq \mathbb{R}$  be a closed and bounded interval. Let  $f: I \to \mathbb{R}$  be continuous on I. Then f is bounded on the interval I, denoted by

$$m = \inf\{f(x) \mid x \in I\}, \qquad M = \sup\{f(x) \mid x \in I\}$$

Then there exist points  $x_m, x_M \in I$  such that

$$f(x_m) = m$$
 and  $f(x_M) = M$ 

## Theorem 4.2.4: $\epsilon - \delta$ Limit jr.

Let  $f:I\to\mathbb{R}$  where I is an open nonempty interval. If f is continuous at a point  $a\in I$  and f(a)>0 then for some  $\delta,\,\epsilon>0$  we have that

$$f(x) > \epsilon$$
, for all  $x \in (a - \delta, a + \delta)$ 

### Theorem 4.2.5: Intermediate Value Theorem

Let I be a non-degenerate interval and let  $f: I \to \mathbb{R}$  be a continuous function. If  $a, b \in I$ , a < b, then on the interval (a, b), f attains all values between f(a) and f(b). i.e. given  $y_0$  between f(a) and f(b), there exists  $x_0 \in (a, b)$  such that  $f(x_0) = y_0$ 

### Theorem 4.2.6: Bolzano's Theorem

Let f(x) be continuous on [a,b] such that f(a)f(b)<0, then there exists  $c\in(a,b)$  such that f(c)=0

## Theorem 4.3.1: $\epsilon - \delta$ definition of a limit

Let  $f: A \to \mathbb{R}$  and let c be a limit point of A. Then we say that

$$\lim_{x \to c} f(x) = L$$

if for all  $\epsilon > 0$  there exists some  $\delta > 0$  such that for every  $x \in A$  for which  $0 < |x - c| < \delta$ , we have

$$|f(x) - L| < \epsilon$$

We also say  $\lim_{x\to c} f(x)$  converges to L in such a situation

### Differentiation

# Definition 5.1.1 First Principle Differentiation

A real function f is said to be differentiable at a point  $a \in \mathbb{R}$  if f is defined at some open interval containing a, and

$$f'(a) = \lim_{x \to a} \frac{f(x) - f(a)}{x - a}$$

exists. f'(a) is called the derivative of f at the point a

## Theorem 5.1.3: Differentiable implies Continuous

Let I be an open interval,  $x_0 \in I$  and  $f: I \to \mathbb{R}$  be differentiable at  $x_0$ . Then f is continuous at  $x_0$ . The converse is not true, an example is f(x) = |x| which isn't differentiable at 0.

### Theorem 5.1.4: Differentiable Intervals

Let  $f: I \to \mathbb{R}$  be a given function, where I is an open interval. We say that f is differentiable in I iff it is differentiable at every point in I. At endpoints, derivatives only have to be one-sided

#### Theorem 5.2.1: Differentiation Rules

Let  $f,g:(a,b)\to\mathbb{R}$  be differentiable on (a,b). Then f+g and  $f\cdot g$  are differentiable on (a,b). If  $g(x)\neq 0$  for all  $x\in (a,b)$ , then f/g is differentiable. Moreover,

• Sum rule: (f+g)' = f' + g'

• Product Rule: (fg)' = f'g + fg'

• Quotient Rule:  $(f/g)' = (f'g - fg')/g^2$ 

### Theorem 5.4.6: Inverse Function Theorem

Let f be injective and continuous on an open interval I. If  $a \in f(I)$  and f' at the point  $f^{-1}(a) \neq 0$  exists and is nonzero, then  $f^{-1}$  is differentiable at a and

$$(f^{-1})'(a) = \frac{1}{f'(f^{-1}(a))}$$

### Theorem 5.2.2: Chain Rule

Let f,g be real functions. If f is differentiable at a and g is differentiable at f(a) then  $g\circ f$  is differentiable at a and

$$(g \circ f)'(a) = g'(f(a))f'(a)$$

### Theorem 5.3.1 - 3: Differentiation Theorem ladder

- Rolle's Theorem: Let  $a, b \in \mathbb{R}$ , a < b. If  $f : [a, b] \to \mathbb{R}$  is continuous in [a, b], differentiable in (a, b) and f(a) = f(b), then there exists a point c in (a, b) such that f'(c) = 0
- Mean Value Theorem: If  $f:[a,b]\to\mathbb{R},\ a< b$  is continuous in [a,b], differentiable in (a,b) then  $\exists c\in(a,b)$  s.t.

$$f'(c) = \frac{f(b) - f(a)}{b - a}$$

• Generalised MVT: If  $f, g: [a, b] \to \mathbb{R}$  is continuous in [a, b] and differentiable in (a, b), then  $\exists c$  in (a, b) such that

$$(f(b) - f(a))g'(c) = (g(b) - g(a))f'(c)$$

If g(b) - g(a),  $g'(c) \neq 0$  then this can be written as

$$\frac{f(b) - f(a)}{g(b) - g(a)} = \frac{f'(c)}{g'(c)}$$

### Theorem 5.4.2: Monotone Functions

Let a < b be real and f be continuous on [a,b] and differentiable on (a,b).

- If  $f'(x) > 0 \ \forall x \in (a, b)$ , then f is strictly increasing on [a, b]
- If  $f'(x) < 0 \ \forall x \in (a,b)$ , then f is strictly decreasing on [a,b]
- If  $f'(x) = 0 \ \forall x \in (a, b)$ , then f is constant on [a, b]

Additionally, if f is injective and continuous on an interval I, Then f and  $f^{-1}$  is strictly monotone on I and f(I) respectively

# Theorem 5.5.1: Taylor Series

Let  $f: I \to \mathbb{R}$  be n+1 times differentiable and  $x_0 \in I$ , for an open interval I. For each  $x \in I$ , there is a c between  $x_0$  and x such that

$$f(x) = \sum_{k=0}^{n} \frac{f^{(k)}(x_0)}{k!} (x - x_0)^k + \frac{f^{(n+1)}(c)}{(n+1)!} (x - x_0)^{n+1}$$

(c depends on x and n)

Now suppose that  $f:(a,b)\to\mathbb{R}$  is infinitely differentiable and let  $x_0\in(a,b)$ . Fix x in (a,b). For every positive integer N we have

$$f(x) = \sum_{k=0}^{N} \frac{f^{(k)}(x_0)}{k!} (x - x_0)^k + R_N(x)$$

If  $R_N(x) \to 0$  as  $n \to \infty$ , we have

$$f(x) = \sum_{k=0}^{\infty} \frac{f^{(k)}(x_0)}{k!} (x - x_0)^k$$

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# 3 Examples Catalogue

# Geometric Examples of a Group

# Example 1.2.4: Dihedral Group $D_n$

The set of symmetries of an n-gon forms a group under composition. We call this group the **Dihedral Group**  $D_n$ 

The Dihedral group of n has precisely  $|D_n| = 2n$  elements, namely

- The identity e
- n-1 anticlockwise rotations of  $\frac{2pi}{n}$ . We denote this operation with g
- n reflections. If n is odd, then there are n reflections from a point to the opposite edge. If n is even, there are  $\frac{n}{2}$  reflections from point to point, and  $\frac{n}{2}$  from edge to edge. We denote a vertical reflection with h, and rotated reflections as compositions of h and g

From this, we see that

$$D_n = \{e, g, g^2, \dots, g^{n-1}, h, gh, g^2h, \dots, g^{n-1}h\}$$

# Example 1.3.2: Symmetric Group

The set of all symmetries of  $\{1, 2, ..., n\}$  is called the **symmetric group**  $S_n$ . It is a group under composition with order  $|S_n| = n!$  The symmetric group can be thought of as every permutation of the set  $\{1, 2, ..., n\}$ , or can also be thought of as an n-gon where every edge is connected to each other.

# Example ?: Example of a Coset

Consider  $\mathbb{Z}_4$  under addition, and let  $H=\{0,2\}$  (e=0.) The cosets of H in G are:

$$eH = e*H = \{e*h \,|\, h \in H\} = \{0+h \,|\, h \in H\} = \{0,2\}$$

$$1H = 1 * H = \{1 * h | h \in H\} = \{1 + h | h \in H\} = \{1, 3\}$$

$$2H = 2 * H = \{2 * h \mid h \in H\} = \{2 + h \mid h \in H\} = \{0, 2\}$$

$$3H = 3 * H = \{3 * h \mid h \in H\} = \{3 + h \mid h \in H\} = \{1, 3\}$$

Hence there are two cosets, namely

$$0 * H = 2 * H = \{0, 2\}$$
 and  $1 * H = 3 * H = \{1, 3\}$ 

The above shows that  $g_1H=g_2H$  is possible, even when  $g_1\neq g_2$  We also have

$$G/H=\{eH=2H,1H=3H\}=\{\{0,2\},\{1,3\}\}$$

## Example 3.3.5: p-series

The series  $\sum_{p=1}^{\infty} \frac{1}{k^p}$  converges if p > 1, and it diverges if  $p \le 1$ . At

p = 1, this series is called the **Harmonic Series**.

To show divergence/convergence of a series, we can compare it to the p-series

## Example 10000: $\epsilon$ -N Convergence

Show that the sequence  $\left(\frac{2n+1}{3n+2}\right)_{n\in\mathbb{N}}$  converges to  $\frac{2}{3}$ 

We start with the rough work. Start with an arbitrary  $\epsilon > 0$  and find an  $N_{\epsilon}$  s.t.  $\left|\frac{2n+1}{3n+2} - \frac{2}{3}\right| < \epsilon$  for all  $n > N_{\epsilon}$ . Let's explore this.

$$\left|\frac{2n+1}{3n+2} - \frac{2}{3}\right| = \frac{11}{3(3n+2)} < \epsilon \quad \implies \quad n > \frac{1}{3} \left(\frac{11}{3\epsilon} - 2\right)$$

**Proof:** Let  $\epsilon > 0$ . Pick a positive integer N such that

$$N > \frac{1}{3} \left( \frac{11}{3\epsilon} - 2 \right)$$

Then.

$$\frac{11}{3(3N+2)} < \epsilon$$

For all n with n > N we have

$$|a_n - L| = \left| \frac{2n+5}{3n+2} - \frac{2}{3} \right| = \frac{11}{3(3n+2)} \le \frac{11}{3(3N+2)} < \epsilon$$

another method of finding a limit is

$$\left|\frac{2n+1}{3n+2} - \frac{2}{3}\right| = \frac{11}{3(3n+2)} = \frac{11}{9n+6} < \frac{11}{9n} < \epsilon$$

Since 9n+6>9n, this means that the right fraction is larger than the left fraction in all cases. This means if we can find a right fraction that is smaller than  $\epsilon$  then the left fraction must also.

**Proof:** let  $\epsilon > 0$ . Pick a positive integer N such that  $N > \frac{11}{9\epsilon}$ . Then  $\frac{11}{9N} < \epsilon$ . For all n with  $n \ge N$ , we have

$$|a_n - L| = \left| \frac{2n+5}{3n+2} - \frac{2}{3} \right| = \frac{11}{9n+6} \le \frac{11}{9n} \le \frac{11}{9N} < \epsilon$$

## Example a: $\epsilon - \delta$ Continuity Template

**Proof:** Let  $\epsilon > 0$  be given. Set  $\delta = \_(\text{If there is a constant}, \text{ then set as "<" e.g. <math>\delta < \min\{1, \epsilon\})$ . Then for all  $x \in \mathbb{R}$  such that  $|x - -| < \delta$  we have

Optional: preliminary step to determine an upper bound Therefore, / Therefore since "x term" < "constant", "Same steps as rough working"

$$|x - y| < |x - y| < \delta = \epsilon$$
 (same rule applies about constants)

### Example ?: $\epsilon - \delta$ Continuity

Using the definition of continuity, prove that the function  $f: \mathbb{R}\setminus\{\frac{9}{5}\}\to\mathbb{R}$  defined by  $f(x)=\frac{x^2}{5x-9}$  is continuous at  $x_0=2$  Since  $x_0=2$ , our delta should end up as  $|x-2|<\delta$ . Start with  $|f(x)-f(a)|<\epsilon$ 

$$|f(x) - f(a)| = \left| \frac{x^2}{5x - 9} - \frac{4}{10 - 9} \right|$$

$$= \left| \frac{x^2}{5x - 9} - 4 \right|$$

$$= \left| \frac{x^2 - 20x + 36}{5x - 9} \right|$$

$$= \left| \frac{(x - 18)(x - 2)}{5x - 9} \right|$$

$$= |x - 2| \left| \frac{x - 18}{5x - 9} \right|$$

We have |x-2|, so we want to turn the RH fraction into a constant. If we let the neighbourhood around  $\delta$  to be no less than  $\frac{1}{10}$  (i.e.  $x \in (1.9, 2.1)$ ) (this number can be anything, but smaller than  $\frac{1}{5}$  since there is an asymptote at  $\frac{9}{5}$ ), using the number with the largest value in that range we can get an upper bound for  $\delta$ .

$$\left| \frac{x - 18}{5x - 9} \right| < \left| \frac{1.9 - 18}{9.5 - 9} \right| = \left| \frac{-16.1}{0.5} \right| = \left| -32.2 \right| \implies \left| \frac{x - 18}{5x - 9} \right| < 32.2$$

Therefore

$$|x-2| \left| \frac{x-18}{5x-9} \right| < |x-2| \cdot 32.2 < \epsilon$$

Therefore, we can take  $\delta = \max\{1/10, \epsilon/32.2\}$ 

**Proof:** Let  $\epsilon > 0$  be given, set  $\delta = \min\{\frac{1}{10}, \frac{\epsilon}{32.2}\}$ . Then for all  $x \in \mathbb{R}$  such that  $|x-2| < \delta$  we have

$$\left| \frac{x - 18}{5x - 9} \right| < \left| \frac{1.9 - 18}{9.5 - 9} \right| = \left| \frac{-16.1}{0.5} \right| = \left| -32.2 \right| \implies \left| \frac{x - 18}{5x - 9} \right| < 32.2$$

Therefore, since  $\left|\frac{x-18}{5x-9}\right| < 32.2$ ,

$$|f(x) - f(a)| = \left| \frac{x^2}{5x - 9} - \frac{4}{10 - 9} \right| = \left| \frac{x^2 - 20x + 36}{5x - 9} \right|$$

$$= \left| \frac{(x-18)(x-2)}{5x-9} \right| = |x-2| \left| \frac{x-18}{5x-9} \right| \le 32.2 \cdot |x-2| < 32.2 \cdot \delta = \epsilon$$

### Example ): $\epsilon - \delta$ Discontinuity

From negation of  $\epsilon - \delta$  continuity - A function  $f: A \to \mathbb{R}$  is not continuous if there exists  $\epsilon > 0$  such that for all  $\delta > 0$  there exists some  $x \in A$  satisfying  $0 < |x - c| < \delta$  for which  $|f(x) - f(c)| \ge \epsilon$ 

$$|f(x) - f(a)| < \epsilon \implies \left| sin\left(\frac{1}{x}\right) - 0 \right| < \epsilon \implies \left| sin\left(\frac{1}{x}\right) \right| < \epsilon$$

So we want to show that we can find an  $\epsilon$  such that for every  $\delta > 0$ , we can find an x where  $|x| < \delta$  and also  $|\sin(\frac{1}{x})| \ge \epsilon$ .

Since sin(x) repeats, if we can find an x such that  $sin(\frac{1}{x})$  is an exact value then we can define  $\epsilon$  as something lower than that. If we want a value where  $sin(\frac{1}{x})=1$ , this will be true if  $x=1/(\frac{\pi}{2}+2N\pi)$ , where N is a positive integer.

Since x has to be bounded by  $\delta$ , go from  $\delta$ 

$$\begin{split} |x| &< \delta \\ \left| \frac{1}{\frac{\pi}{2} + 2N\pi} \right| &< \delta \\ \frac{1}{\frac{\pi}{2} + 2N\pi} &< \delta \quad \text{(will always be positive since N positive int)} \\ \frac{\pi}{2} + 2N\pi &> \frac{1}{\delta} \\ N &> \frac{1}{2\pi} \left( \frac{1}{\delta} - \frac{\pi}{2} \right) \end{split}$$

**Proof:** Let  $\epsilon = \frac{1}{2}$ . Let  $\delta > 0$  be given. Pick a positive integer N such that  $N > \frac{1}{2\pi} \left( \frac{1}{\delta} - \frac{\pi}{2} \right)$  and set  $x = \frac{1}{\frac{\pi}{2} + 2N\pi}$ . Then for all  $x \in \mathbb{R}$  such that  $0 < x < \delta$ , we have

$$|f(x)| = \left| \sin\left(\frac{1}{x}\right) \right| = \left| \sin\left(\frac{\pi}{2} + 2N\pi\right) \right| = 1 \ge \frac{1}{2} = \epsilon$$

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