```
In [ ]: !wget https://github.com/Infatoshi/fcc-intro-to-llms/blob/main/wizard_of_oz.txt
      --2023-09-24 13:41:57-- https://github.com/Infatoshi/fcc-intro-to-llms/blob/main/wizard_of_oz.txt
      Resolving github.com (github.com)... 192.30.255.113
      Connecting to github.com (github.com) | 192.30.255.113 | :443... connected.
      HTTP request sent, awaiting response... 200 OK
      Length: 277514 (271K) [text/plain]
      Saving to: 'wizard_of_oz.txt.1'
      wizard_of_oz.txt.1 100%[============] 271.01K --.-KB/s in 0.03s
      2023-09-24 13:41:57 (9.25 MB/s) - 'wizard_of_oz.txt.1' saved [277514/277514]
In [ ]: import torch
       import torch.nn as nn
       from torch.nn import functional as F
       import mmap
       import random
       import pickle
       import argparse
       # parser = argparse.ArgumentParser(description='This is a demonstration program')
       # Here we add an argument to the parser, specifying the expected type, a help message, etc.
       # parser.add_argument('-batch_size', type=str, required=True, help='Please provide a batch_size')
       # args = parser.parse_args()
       # Now we can use the argument value in our program.
       # print(f'batch size: {args.batch_size}')
       device = 'cuda' if torch.cuda.is_available() else 'cpu'
       # batch_size = args.batch_size # to use the batch_size cmd arg -> python file_name.py -batch_size 32
       batch_size = 32
       block_size = 128
       max_iters = 3000
       learning_rate = 3e-4
       eval_iters = 50
       n_embd = 384
       n_head = 4
       n_{ayer} = 4
       dropout = 0.2
       print (device)
      cuda
In [ ]: with open('wizard_of_oz.txt', 'r', encoding='utf-8') as f:
          text = f.read()
       chars = sorted(set(text))
       print (chars)
       vocab_size = len(chars)
      'd', 'e', 'f', 'g', 'h', 'i', 'j', 'k', 'l', 'm', 'n', 'o', 'p', 'q', 'r', 's', 't', 'u', 'v', 'w', 'x', 'y', 'z', '{', '}', '\ufeff']
In [ ]: string_to_int = { ch:i for i,ch in enumerate(chars) }
       int_to_string = { i:ch for i,ch in enumerate(chars) }
       encode = lambda s: [string_to_int[c] for c in s]
       decode = lambda l: ''.join([int_to_string[i] for i in l])
In [ ]: data = torch.tensor(encode(text), dtype=torch.long)
       n = int(0.8*len(data))
       train_data = data[:n]
       val_data = data[n:]
       def get_batch(split):
           data = train_data if split == 'train' else val_data
           ix = torch.randint(len(data) - block_size, (batch_size,))
           x = torch.stack([data[i:i+block_size] for i in ix])
           y = torch.stack([data[i+1:i+block_size+1] for i in ix])
           x, y = x.to(device), y.to(device)
           return x, y
In [ ]: @torch.no_grad()
        def estimate_loss():
           out = {}
           model.eval()
           for split in ['train', 'val']:
              losses = torch.zeros(eval_iters)
               for k in range(eval_iters):
                  X, Y = get_batch(split)
                  logits, loss = model(X, Y)
                  losses[k] = loss.item()
              out[split] = losses.mean()
           model.train()
           return out
In [ ]: class Head(nn.Module):
          """ one head of self-attention """
           def __init__(self, head_size):
               super().__init__()
               self.key = nn.Linear(n_embd, head_size, bias=False)
               self.query = nn.Linear(n_embd, head_size, bias=False)
               self.value = nn.Linear(n_embd, head_size, bias=False)
               self.register_buffer('tril', torch.tril(torch.ones(block_size, block_size)))
               self.dropout = nn.Dropout(dropout)
           def forward(self, x):
               # input of size (batch, time-step, channels)
               # output of size (batch, time-step, head size)
              B,T,C = x.shape
              k = self.key(x) # (B, T, hs)
              q = self.query(x) # (B, T, hs)
               # compute attention scores ("affinities")
               wei = q @ k.transpose(-2,-1) * k.shape[-1]**-0.5 # (B, T, hs) @ (B, hs, T) \rightarrow (B, T, T)
               wei = wei.masked_fill(self.tril[:T, :T] == 0, float('-inf')) # (B, T, T)
               wei = F.softmax(wei, dim=-1) # (B, T, T)
               wei = self.dropout(wei)
               # perform the weighted aggregation of the values
               v = self.value(x) # (B, T, hs)
               out = wei @ v # (B, T, T) @ (B, T, hs) -> (B, T, hs)
               return out
       # [1, 0, 0]
       # [1, 0.6, 0]
       # [1, 0.6, 0.4]
       class MultiHeadAttention(nn.Module):
          """ multiple heads of self-attention in parallel """
           def __init__(self, num_heads, head_size):
               super().__init__()
               self.heads = nn.ModuleList([Head(head_size) for _ in range(num_heads)])
               self.proj = nn.Linear(head_size * num_heads, n_embd)
               self.dropout = nn.Dropout(dropout)
           def forward(self, x):
              out = torch.cat([h(x) for h in self.heads], dim=-1) # (B, T, F) -> (B, T, [h1, h1, h1, h1, h2, h2, h2, h2, h3, h3, h3])
               out = self.dropout(self.proj(out))
               return out
       class FeedFoward(nn.Module):
           """ a simple linear layer followed by a non-linearity """
           def __init__(self, n_embd):
               super().__init__()
               self.net = nn.Sequential(
                  nn.Linear(n_embd, 4 * n_embd),
                  nn.ReLU(),
                  nn.Linear(4 \star n_embd, n_embd),
                  nn.Dropout(dropout),
           def forward(self, x):
               return self.net(x)
        class Block (nn.Module):
           """ Transformer block: communication followed by computation """
           def __init__(self, n_embd, n_head):
               # n_embd: embedding dimension, n_head: the number of heads we'd like
               super().__init__()
               head_size = n_embd // n_head
               self.sa = MultiHeadAttention(n_head, head_size)
               self.ffwd = FeedFoward(n_embd)
               self.ln1 = nn.LayerNorm(n_embd)
               self.ln2 = nn.LayerNorm(n_embd)
           def forward(self, x):
              y = self.sa(x)
               x = self.ln1(x + y)
              y = self.ffwd(x)
               x = self.ln2(x + y)
               return x
       class GPTLanguageModel(nn.Module):
           def __init__(self, vocab_size):
               super().__init__()
               self.token_embedding_table = nn.Embedding(vocab_size, n_embd)
               self.position_embedding_table = nn.Embedding(block_size, n_embd)
               self.blocks = nn.Sequential(*[Block(n_embd, n_head=n_head) for _ in range(n_layer)])
               self.ln_f = nn.LayerNorm(n_embd) # final layer norm
               self.lm_head = nn.Linear(n_embd, vocab_size)
               self.apply(self._init_weights)
           def _init_weights(self, module):
               if isinstance(module, nn.Linear):
                  torch.nn.init.normal_(module.weight, mean=0.0, std=0.02)
                  if module.bias is not None:
                       torch.nn.init.zeros_(module.bias)
               elif isinstance(module, nn.Embedding):
                  torch.nn.init.normal_(module.weight, mean=0.0, std=0.02)
           def forward(self, index, targets=None):
              B, T = index.shape
               # idx and targets are both (B,T) tensor of integers
               tok_emb = self.token_embedding_table(index) # (B, T, C)
               pos_emb = self.position_embedding_table(torch.arange(T, device=device)) # (T,C)
               x = tok\_emb + pos\_emb # (B, T, C)
               x = self.blocks(x) # (B, T, C)
               x = self.ln_f(x) # (B, T, C)
               logits = self.lm_head(x) # (B, T, vocab_size)
               if targets is None:
                   loss = None
               else:
                  B, T, C = logits.shape
                  logits = logits.view(B*T, C)
                  targets = targets.view(B*T)
                   loss = F.cross_entropy(logits, targets)
               return logits, loss
           def generate(self, index, max_new_tokens):
               # index is (B, T) array of indices in the current context
               for _ in range(max_new_tokens):
                  # crop idx to the last block_size tokens
                  index_cond = index[:, -block_size:]
                  # get the predictions
                  logits, loss = self.forward(index_cond)
                  # focus only on the last time step
                  logits = logits[:, -1, :] # becomes (B, C)
                  # apply softmax to get probabilities
                  probs = F.softmax(logits, dim=-1) # (B, C)
                  # sample from the distribution
                  index_next = torch.multinomial(probs, num_samples=1) # (B, 1)
                  # append sampled index to the running sequence
                  index = torch.cat((index, index_next), dim=1) # (B, T+1)
               return index
       model = GPTLanguageModel(vocab_size)
       # print('loading model parameters...')
       # with open('model-01.pkl', 'rb') as f:
       # model = pickle.load(f)
       # print('loaded successfully!')
       m = model.to(device)
In [ ]: # create a PyTorch optimizer
       optimizer = torch.optim.AdamW(model.parameters(), lr=learning_rate)
       for iter in range(max_iters):
           print(iter)
           if iter % eval_iters == 0:
```

losses = estimate\_loss()

logits, loss = model.forward(xb, yb)
optimizer.zero\_grad(set\_to\_none=True)

# sample a batch of data
xb, yb = get\_batch('train')

# evaluate the loss

loss.backward()
 optimizer.step()
print(loss.item())

print(f"step: {iter}, train loss: {losses['train']:.3f}, val loss: {losses['val']:.3f}")

In []: prompt = 'Hello! Can you see me?'
 context = torch.tensor(encode(prompt), dtype=torch.long, device=device)
 generated\_chars = decode(m.generate(context.unsqueeze(0), max\_new\_tokens=100)[0].tolist())
 print(generated\_chars)

Hello! Can you see me?\"\r","\r","\"So he hasken the mountain top of the Mangaboos.\"\r","\r","\"Wolld you sup sin what yo