# Artificial Intelligence

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# Knowledge in learning

So far we learnt a function input  $\rightarrow$  output.

We only assumed to know the form of the function (such as a decision tree) defined by the hypothesis space.

Can we take advantage of **prior knowledge** about the world?

In most cases the prior knowledge is represented as general first-order logical theories.

### Some methods:

- current-best-hypothesis search
- version space learning
- inductive logic programming

# Logical formulation of learning

Some

Hypotheses, example descriptions, and classification will be represented using **logical sentences**.

### **Examples**

attributes become unary predicates

Alternate( $X_1$ )  $\land \neg Bar(X_1) \land \neg Fri/Sat(X_1) \land Hungry(X_1) \land ...$ 

classification is given by literal using the goal predicate

WillWait( $X_1$ ) or  $\neg$  WillWait( $X_1$ )

### Hypothesis will have the form

 $\forall x \text{ Goal}(x) \Leftrightarrow C_i(x)$ 

C<sub>i</sub> is called the extension of the predicate

 $\forall$ r WillWait(r)  $\Leftrightarrow$  Patrons(r,Some)

V (Patrons(r,Full) ∧ Hungry(r) ∧ Type(r,French))

 $\vee$  (Patrons(r,Full)  $\wedge$  Hungry(r)  $\wedge$  Type(r,Thai)  $\wedge$  Fri/Sat(r))

V (Patrons(r,Full) ∧ Hungry(r) ∧ Type(r,Burger))

# Hypothesis space

Fri/Sat?

## **Hypothesis space** is the set of all hypothesis.

The learning algorithm believes that one hypothesis is correct, that is, it believes the sentence:

Hypotheses that are not consistent with the examples can be rules out.

There are two possible ways to be **inconsistent** with an example (the notions originated in medicine to describe erroneous results from lab tests)

- false negative hypothesis says the example should be negative but in fact it is positive
- false positive hypothesis says the example should be positive but in fact it is negative

# The idea is to maintain a single hypothesis, and to adjust it as new examples arrive in order to maintain consistency

if the example is consistent with the hypothesis

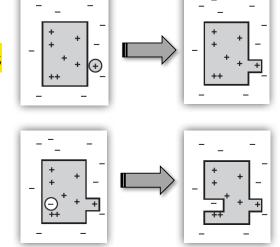
then do not change it

i<mark>f false negative</mark>

then generalize the hypothesis

if false positive

then **specialize** the hypothesis



# The current-best-hypothesis learning algorithm

```
function CURRENT-BEST-LEARNING(examples, h) returns a hypothesis or fail
  if examples is empty then
    return h
    e ← FIRST(examples)
  if e is consistent with h then
    return CURRENT-BEST-LEARNING(REST(examples), h)
  else if e is a false positive for h then
    for each h' in specializations of h consistent with examples seen so far do
        h" ← CURRENT-BEST-LEARNING(REST(examples), h')
        if h" ≠ fail then return h"
    else if e is a false negative for h then
        for each h' in generalizations of h consistent with examples seen so far do
        h" ← CURRENT-BEST-LEARNING(REST(examples), h')
        if h" ≠ fail then return h"
        return fail
```

# Specialization and generalization

# **How to implement specialization and generalization** of the hypothesis?

- If hypothesis  $h_1$  is a **generalization** of hypothesis  $h_2$ , then we must have  $\forall x C_2(x) \Rightarrow C_1(x)$
- C<sub>i</sub> is typically a conjunction of predicates
  - generalization can be realized by dropping conditions or by adding disjuncts
  - specialization can be realized by adding extra conditions or by removing disjuncts

Example	Attributes										Target
	Alt	Bar	Fri	Hun	Pat	Price	Rain	Res	Type	Est	Wait
$X_1$	Т	F	F	Т	Some	\$\$\$	F	Т	French	0-10	Т
$X_2$	Т	F	F	Т	Full	\$	F	F	Thai	30–60	F
$X_3$	F	Т	F	F	Some	\$	F	F	Burger	0-10	Т
$X_4$	Т	F	Т	Т	Full	\$	F	F	Thai	10-30	Т
$X_5$	Т	F	Т	F	Full	\$\$\$	F	Т	French	>60	F
$X_6$	F	Т	F	Т	Some	\$\$	T	Т	Italian	0-10	Т
$X_7$	F	Т	F	F	None	\$	Т	F	Burger	0-10	F
$X_8$	F	F	F	Т	Some	\$\$	Т	Т	Thai	0-10	Т
$X_9$	F	T	T	F	Full	\$	Т	F	Burger	>60	F
$X_{10}$	Т	Т	Т	Т	Full	\$\$\$	F	Т	Italian	10-30	F
$X_{11}$	F	F	F	F	None	\$	F	F	Thai	0-10	F
$X_{12}$	Т	Т	Т	Т	Full	\$	F	F	Burger	30-60	Т

#### A restaurant example:

- the first example is positive, attribute Alternate(X<sub>1</sub>) is true, so let the initial hypothesis be
   h<sub>1</sub>: ∀x WillWait(x) ⇔ Alternate(x)
- the second example is negative, hypothesis predicts it to be positive, so it is a false positive; we need to specialize by adding extra condition
  - $h_2$ :  $\forall x \ WillWait(x) \Leftrightarrow Alternate(x) \land Patrons(x,Some)$
- the thirst example is positive, the hypothesis predicts it to be negative, so it is a false negative; we need to generalize by dropping the condition Alternate
  - $h_3$ :  $\forall x \ WillWait(x) \Leftrightarrow Patrons(x,Some)$
- The fourth example is positive, the hypothesis predicts it to be negative, so it is a false positive; we need to generalize by adding a disjunct (we cannot drop the Patrons condition)
  - $h_3$ :  $\forall x \ WillWait(x) \Leftrightarrow Patrons(x,Some) \lor (Patrons(x,Full) \land Fri/Sat(x))$

# Current-best-hypothesis: properties

# After each modification of the hypothesis we need to check all the previous examples.

There are several possible generalizations and specializations and we may need to **backtrack** where no simple modification of the hypothesis is consistent with all the data.

# The source of problems – strong commitment

 The algorithm has to choose a particular hypothesis as its best guess even though it does not have enough data yet to be sure of the choice.

A solution could be least-commitment search.

The hypothesis space can be viewed as a disjunctive sentence  $h_1 \vee h_2 \vee h_3 \vee ... \vee h_n$ 

Hypothesis inconsistent with a new example is removed from the disjunction. Assuming the original hypothesis space does in fact contain the right answer, the reduced disjunction must still contain the right answer.

The set of hypothesis remaining is called the **version space**.

The version space learning algorithm (also the **candidate elimination** algorithm).

```
function VERSION-SPACE-LEARNING(examples) returns a version space local variables: V, the version space: the set of all hypotheses V \leftarrow the set of all hypotheses for each example e in examples do
    if V is not empty then V \leftarrow VERSION-SPACE-UPDATE(V, e)
return V

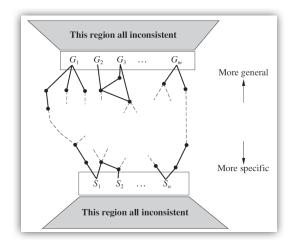
function VERSION-SPACE-UPDATE(V, e) returns an updated version space V \leftarrow \{h \in V : h \text{ is consistent with } e\}
```

This approach is incremental: one never has to go back and reexamine the old examples

# Representation of version space

Hypothesis space is enormous, so how can we possibly write down this enormous disjunction?

We have an ordering of hypothesis space (generalization/specialization) so we can specify boundaries, where each boundary will be a set of hypothesis (a boundary set).



### G = a most general boundary

- consistent with all observations so far
- there are no consistent hypotheses that are more general
- initially True

### S = a most specific boundary

- · consistent with all observations so far
- there are no consistent hypotheses that are more specific
- initially False

Everything in between G-set and S-set is guaranteed to be consistent with the examples and nothing else is consistent.

### For each new example we update the sets G and S:

- false positive for S<sub>i</sub>
  - \$\throw S\_i out of the S-set
- false negative for S<sub>i</sub>
  - replace S<sub>i</sub> in the S-set by all its immediate generalizations
- false positive for G<sub>i</sub>
  - replace G<sub>i</sub> in the G-set by all its immediate specilaizations
- false negative for G<sub>i</sub>
  - \$\text{throw G}\_i \text{ out of the G-set}

### The algorithm continues until one of three things happens:

- we have exactly one hypothesis left in the version space
- the version space collapses (either S or G becomes empty)
- we run out of examples and have several hypothesis remaining in the version space
  - the version space represents a disjunction of hypotheses
  - if the hypothesis disagree in classification, one possibility is to take the majority vote

# Properties of version space learning

# If the domain contains noise or insufficient attributes for exact classification, the version space will always collapse.

to date, no completely successful solution has been found

# If we allow unlimited disjunction in the hypothesis space,

- the S-set will always contain a single most-specific hypothesis (the disjunction of the descriptions of positive examples)
- the G-set will contain just the negation of the disjunction of the descriptions of the negative examples
- can be addressed by allowing only limited forms of disjunction by including a generalization hierarchy of more general predicates:
  - instead of WaitEstimate(x,30-60) V WaitEstimate(x,>60) we can use LongWait(x)

The pure version space algorithm was first applied in the Meta-DENDRAL system, which was designed to learn rules for predicting how molecules would break into pieces in mass spectrometer.

Inductive logic programming (ILP) combines inductive methods with the power of first-order representations (logic programs).

ILP works well with relationships between objects, which is hard for attribute-only approaches.

In principle the general knowledge-induction problem is to solve the entailment constraint:

Background Λ Hypothesis Λ Descriptions |= Classifications

Two principal approaches to ILP:

- top-down inductive learning methods (system FOIL)
- inductive learning with inverse deduction (system PROGOL)



ILP problem

Background  $\Lambda$  Hypothesis  $\Lambda$  Descriptions |= Classifications

• **Examples** are typically given as Prolog facts

```
Father(Philip,Charles), Father(Philip, Anne), ...
Mother(Mum,Margaret), Mother(Mum, Elizabeth), ...
Married(Diana, Charles), Married(Elizabeth, Philip), ...
Male(Philip), Male(Charles), ...
Female(Beatrice), Female(Margaret),...
```

Similarly known classifications are given by Prolog facts:

```
Grandparent (Mum, Charles), Gradparent (Elizabeth, Beatrice), ...

¬Gradparent (Mum, Harry), ¬Grandparent (Spencer, Peter), ...
```

Possible hypothesis:

```
Grandparent(x,y) \Leftrightarrow [\existsz Mother(x,z) \land Mother(z,y)] \lor [\existsz Mother(x,z) \land Father(z,y)] \lor [\existsz Father(x,z) \land Mother(z,y)] \lor [\existsz Father(x,z) \land Father(z,y)]
```

We can exploit background knowledge:

```
Parent(x,y) \Leftrightarrow Mother(x,y) \lor Father(x,y)
```

Then we can simplify the hypothesis:

```
Grandparent(x,y) \Leftrightarrow [\exists z Parent(x,z) \land Parent(z,y)]
```

Start with a clause with an empty body

Grandfather(x,y)  $\leftarrow$ 

- This clause classifies every example as positive, so it needs to be specialized
  - by adding literals one at a time to the body

```
Grandfather(x,y) ← Father(x,y)
Grandfather(x,y) ← Parent(x,z)
Grandfather(x,y) ← Father(x,z)
```

- We prefer the specialization that classifies correctly more examples
- specialize this clause further

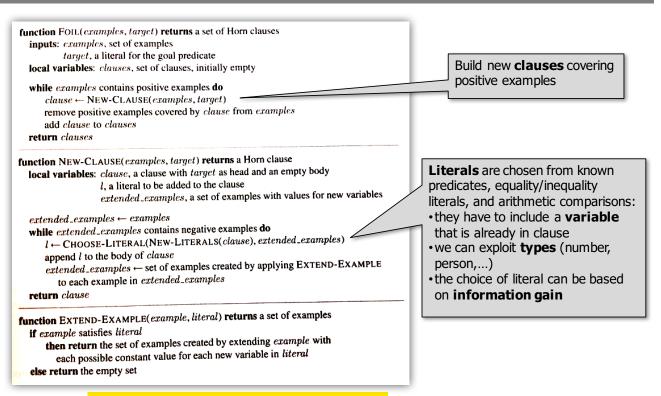
```
Grandfather (x,y) \leftarrow Father(x,z) \land Parent(z,y)
```

 if background knowledge Parent is not available we may need to add more clauses

```
Grandfather(x,y) \leftarrow Father(x,z) \land Father(z,y)
Grandfather(x,y) \leftarrow Father(x,z) \land Mother(z,y)
```

each clause covers some positive examples and no negative example

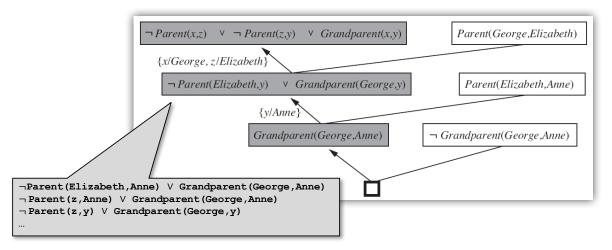
# Top-down learning algorithm



System FOIL solved a long sequence of exercises on list-processing functions (for example append, QuickSort).

### Background $\wedge$ Hypothesis $\wedge$ Descriptions |= Classifications

- Classical resolution deduces Classifications from Background, Hypothesis, Descriptions.
- We can run the proof backward, find Hypothesis such that the proof goes through:
  - for resolvent C produce C<sub>1</sub> and C<sub>2</sub> (if C<sub>2</sub> is given then produce C<sub>1</sub>)





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