Video Compression Assignment 3

In this assignment, we will use the block-based encoding approach, where the size of a block is 8x8. Only the Luma component is considered for the following questions.

Prerequisites

- Programming langauge: Python 3.10+ (IPython)
- Framework: Jupyter

Install dependencies from PyPI:

```
In [18]: %pip install \
    --disable-pip-version-check \
    --quiet \
    numpy \
    Pillow
```

Note: you may need to restart the kernel to use updated packages.

Task 1

Fourier Transform

Please apply the Fourier Transform to the luma component of foreman_qcif_0_rgb.bmp and demonstrate its magnitudes in a 2-D image, as shown in the example below. Note that you need to shift the origin to the center of the image for the magnitude plot.



Solution of Task 1

In []:

Task 2

DCT

Please apply DCT to all the 8x8 luma blocks of foremon_qcif_0_rgb.bmp and use the quantization matrix below for quantization. After DCT and quantization, please apply inverse quantization and IDCT to decode all the blocks and show the decoded frame.

T 16	11	10	16	24	40	51	61	
					58		55	
14	13	16	24	40	57	69	56	
14	17	22	29	51	87	80	62	
18	22	37	56	68	87 109	103	77	
24	35	55	64	81	104	113	92	
49	64	78	87	103	121	120	101	
72	92	95	98	112	100	103	99	

Solution of Task 2

2-D Discrete Cosine Transform

Forward Transform (for NxN block)

The formula adapted from the course slides:

$$F(u,v) = \frac{2}{N}C(u)C(v)\sum_{x=0}^{N-1}\sum_{y=0}^{N-1}f(x,y)\cos\left(\frac{(2x+1)u\pi}{2N}\right)\cos\left(\frac{(2y+1)v\pi}{2N}\right)$$
 where
$$C(t) = \begin{cases} \frac{2}{\sqrt{N}} & \text{if } t=0\\ 2\sqrt{\frac{2}{N}} & \text{otherwise} \end{cases}$$

can be simplified as:

$$F(u,v) = \frac{8}{N^2}C(u)C(v)\sum_{x=0}^{N-1}\sum_{y=0}^{N-1}f(x,y)\cos\left(\frac{(2x+1)u\pi}{2N}\right)\cos\left(\frac{(2y+1)v\pi}{2N}\right)$$
 where
$$C(t) = \begin{cases} 1 & \text{if } t=0\\ \sqrt{2} & \text{otherwise} \end{cases}$$

Inverse Transform (for NxN block)

The formula adapted from the course slides:

$$f(x,y) = \frac{2}{N} \sum_{u=0}^{N-1} \sum_{v=0}^{N-1} C(u)C(v)F(u,v) \cos\left(\frac{(2x+1)u\pi}{2N}\right) \cos\left(\frac{(2y+1)v\pi}{2N}\right)$$
where $C(t) = \begin{cases} \frac{2}{\sqrt{N}} & \text{if } t=0\\ 2\sqrt{\frac{2}{N}} & \text{otherwise} \end{cases}$

can be simplified as:

$$f(x,y) = \frac{8}{N^2} \sum_{u=0}^{N-1} \sum_{v=0}^{N-1} C(u)C(v)F(u,v) \cos\left(\frac{(2x+1)u\pi}{2N}\right) \cos\left(\frac{(2y+1)v\pi}{2N}\right)$$
where $C(t) = \begin{cases} 1 & \text{if } t=0\\ \sqrt{2} & \text{otherwise} \end{cases}$

Implement the DCT and IDCT functions:

```
In [19]: from numpy.typing import NDArray
          from numpy import float64, uint8
          def dct_forward(source: NDArray[uint8], block_size: int) -> NDArray[float64]:
              from numpy import atleast_2d, float64
              from math import sqrt, cos, pi
               source = atleast_2d(source).astype(float64)
              block_size = int(block_size)
              N = block_size
              C = 8 / N / N
              PI_2N = pi / 2 / N
              SR_2 = sqrt(2)
              target = source.copy()
               for i in range(0, target.shape[0] - N + 1, N):
                   for j in range(0, target.shape[1] - N + 1, N):
                       for u in range(N):
                            for v in range(N):
                                a = 0.0
                                for x in range(N):
                                     for y in range(N):
                                              source[i + x, j + y]
* cos((2 * x + 1) * u * PI_2N)
* cos((2 * y + 1) * v * PI_2N)
                                )
target[i + u, j + v] = (
                                    * (1 if u == 0 else SR_2)
* (1 if v == 0 else SR_2)
* a
              return target
          def dct_inverse(source: NDArray[float64], block_size: int) -> NDArray[uint8]:
               from numpy import atleast_2d, float64, uint8
               from math import cos, pi, sqrt
```

```
source = atleast_2d(source).astype(float64)
block_size = int(block_size)
N = block_size
C = 8 / N / N
PI_2N = pi / 2 / N
SR_2 = sqrt(2)
target = source.copy()
for i in range(0, target.shape[0] - N + 1, N):
    for j in range(0, target.shape[1] - N + 1, N):
         for x in range(N):
             for y in range(N):
                  a = 0.0
                  for u in range(N):
                      for v in range(N):
                          a += (
                               (1 if u == 0 else SR_2)
                               * (1 if v == 0 else SR_2)
                               * source[i + u, j + v]

* cos((2 * x + 1) * u * PI_2N)

* cos((2 * y + 1) * v * PI_2N)
                  target[i + x, j + y] = C * a
target = target.round().astype(uint8)
return target
```

Test the DCT and IDCT functions:

```
In [20]: from numpy.random import randint
         from numpy import set_printoptions
         mat = randint(low=0, high=256, size=(17, 8), dtype=uint8)
         mat_dct = dct_forward(mat, 8)
         mat_idct = dct_inverse(mat_dct, 8)
         set_printoptions(precision=1)
         print(mat_dct)
         assert (mat == mat_idct).all()
        [[1058.9 108.4 -26.7 -78.4 12.4
                                               8.7 -12.6
         [ 159.4
                   -3.2 86.9 73.9 -5.8 -32.6 -17.5
43.1 24.3 -16.5 -108.8 6.2 21.
                                                                65. 7
         [ -17.1
                                                                39.57

    48.9
    78.3
    37.4
    50.1
    156.9
    -45.9

    -86.9
    71.7
    113.2
    14.6
    78.6
    -49.7

                                                        4.2 117.8]
                                  14.6 78.6 -49.7 -50.3 -39.8
         [ 31. -143.2 27.2
                                 -1.2 -44.3 -44.8 -143.3 -55.97
         [ 39.4 191.5 -85.2 -1.6 -20. -32.4 -61.8 105.4]
[ -21.6 -42.3 55.5 -49.2 80.7 42.8 -43.3 15.9]
         [1014.9 -97.1
                          40. 45.1
                                         40.6 -5.
                                                       -42.9 116.3]
                                               -40.1 -75.9 -113.9]
         [ -90.9 -76.3
                          67.2 -121.8
                                        52.6
                          6.1 -147.6 -45.7 -132.8 -70.
         [-135.7 -122.2
            8.2 10.1 -55.4 -31.2 85.2 204.4 68.7 169.9]
         [ 116.1 -81.2 110.5 -49.2 -75.1
                                                        61.3 -69.9]
                                                41.1
         [ -57.7 16.3 78.6 -12.1 -79.7
                                                91.6 20.5 -52.2]
         [ -26.2
                   35.7
                           -0.5 -2.4 -8.
                                                -18.9 -88.8 -83.1]
                   65.1 -131.4 14.9 -101.4
                                                       11.2 58.9]
         Γ -35.2
                                               53.4
                           20. 237. 249.
         [ 228.
                   63.
                                                180.
                                                         4. 143. ]]
```

Quantization

Forward Transform

$$F'(u,v) = \operatorname{round}\left(\frac{F(u,v)}{Q(u,v)}\right)$$
 where Q is the quantization matrix

Inverse Transform

 $F(u,v) = F'(u,v) \cdot Q(u,v)$ where Q is the quantization matrix

```
)
def quantize_forward(
   source: NDArray[float64],
   matrix: Optional[NDArray[uint8]] = None,
) -> NDArray[int64]:
   from numpy import atleast_2d, float64, uint8, int64
   source = atleast_2d(source).astype(float64)
       atleast_2d(matrix).astype(uint8)
       if matrix
       else COMMON_QUANTIZATION_MATRIX
   target = source.copy()
   for j in range(
          0, target.shape[1] - matrix.shape[1] + 1, matrix.shape[1]
          / matrix
          ).round()
   target = target.astype(int64)
   return target
def quantize_inverse(
   source: NDArray[int64],
   matrix: Optional[NDArray[uint8]] = None,
) -> NDArray[float64]:
   from numpy import atleast_2d, float64, uint8
   source = atleast_2d(source).astype(float64)
   matrix = (
      atleast_2d(matrix).astype(uint8)
       if matrix
       else COMMON_QUANTIZATION_MATRIX
   target = source.copy()
   for i in range(0, target.shape[0] - matrix.shape[0] + 1, matrix.shape[0]):
       for j in range(
          0, target.shape[1] - matrix.shape[1] + 1, matrix.shape[1]
          target[i : i + matrix.shape[0], j : j + matrix.shape[1]] = (
             source[i : i + matrix.shape[0], j : j + matrix.shape[1]]
              * matrix
   return target
```

Test the quantization and inverse quantization functions:

```
In [22]: from numpy.random import randn
         from numpy import set_printoptions
         mat = randn(17, 8) * 100
        mat_q = quantize_forward(mat)
        mat_iq = quantize_inverse(mat_q)
        set_printoptions(suppress=True)
        print(abs((mat - mat_iq)).mean())
        print(mat_q)
       15.045141116527034
                            7.
                                 2.
        [[ 10.
              11. 13.
                                      -0.
                                            -2.
                                                   1. ]
                           -6. -6.
        [ -2.
               17.
                      5.
                                      -0.
                           1. 3.
                                                  -2. ]
               -5.
                     0.
                                      -1.
                                            1.
                           -2.
-0.
               -4.
           9.
                     -4.
                                 2.
                                      -1.
                                            -1.
                                                   1. ]
          1.
               -2.
                     -1.
                                 1.
                                      -1.
                                            -1.
                                                   1.
                           -1. 2.
0. -1.
-0. 1.
          -6.
               1.
                      1.
                                      -1. -0.
                                                 1. ]
               1.
1.
           1.
                                       1. -0. 1.
          -0.
                      2.
               26.
                                       2. 0. -2. ]
2. 3. -3. ]
        [ 10.
                           4. 2.
7. -6.
-4. 3.
                     9.
          4.
               11. -13.
                                                 -3.]
               8.
          7.
                     -3.
                                       1. -1.
                                                  2.]
        [-13.
                      2.
                           -3.
                                -1.
                                                  -2.]
          2.
                           -1.
                                                  -2. ]
                                       1.
                0.
                                                  -0.]
           3.
                      4.
                            3.
                                 -0.
                                       1.
                                            -1.
                                            0.
           1.
                -0.
                     -3.
                           -2.
                                 0.
                                       0.
                                                  1. ]
                                            0.
           2.
               -1.
                      1.
                           -1.
                                  0.
                                       2.
                                                 -1. ]
        [132.6 -74.8 -50.9
                           47.4 -16.6 29.9 133.7 134.8]]
```

```
In [29]: from IPython.display import display
         from pathlib import Path
         from PIL import Image
         from numpy import asarray
         source_path = Path("../resources/foreman_qcif_0_rgb.bmp").resolve()
         source_image = Image.open(source_path).convert(mode="L")
         source_data = asarray(source_image)
         encoded_data = dct_forward(source_data, 8)
         quantized_data = quantize_forward(encoded_data)
         dequantized_data = quantize_inverse(quantized_data)
         decoded_data = dct_inverse(dequantized_data, 8)
         target_image = Image.fromarray(decoded_data, mode="L")
         display(source_image)
         display(target_image)
         display(
             dict(
                 source_data=source_data,
                 encoded_data=encoded_data,
                 quantized_data=quantized_data,
                 dequantized_data=dequantized_data,
                 decoded_data=decoded_data,
         )
```



```
{'source_data': array([[ 32, 233, 251, ..., 212, 230, 203],
           [ 39, 212, 206, ..., 220, 226, 203],
[ 37, 207, 187, ..., 191, 228, 200],
           [ 14, 132, 215, ..., 176, 174, 154],
[ 15, 132, 215, ..., 191, 193, 178],
[ 14, 131, 212, ..., 128, 127, 118]], dtype=uint8),
 1.8, ...,
                                                          6.,
                          1.6,
           [ -1.7, 1.6, -2.6, ..., 11.6, 0.8, 1. ],
[ 2.8, -1.9, -0.8, ..., -0.2, -5.4, -1.2]]),
 0., -0., 0.],
 [ -0., 0., 0., ..., 0., 0., 0.],

[ -0., 0., -0., ..., 0., 0., 0.],

[ 0., -0., -0., ..., -0., -0., -0.]]),

'dequantized_data': array([[1536., -330., -280., ...,
                                                                                     0., -0.,
                                                                                                         0.],
           [ 24., 96., 14., ..., 0., -0., 0.],
[ 70., -52., -32., ..., -0., -0., -0.]
                                                                          -0.],
 [ -0., 0., 0., ..., 0., 0., 0.],

[ -0., 0., -0., ..., 0., 0., 0.],

[ 0., -0., -0., ..., -0., -0., -0.]],

'decoded_data': array([[ 22, 242, 2, ..., 222, 215, 207],
           [ 43, 203, 202, ..., 220, 224, 204],
[ 55, 200, 196, ..., 189, 219, 215],
           ...,
[ 14, 133, 213, ..., 179, 169, 141],
           [ 13, 132, 211, ..., 188, 194, 194],
[ 13, 132, 211, ..., 132, 121, 114]], dtype=uint8)}
```