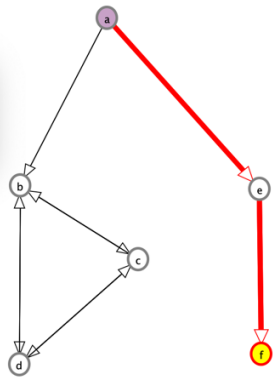
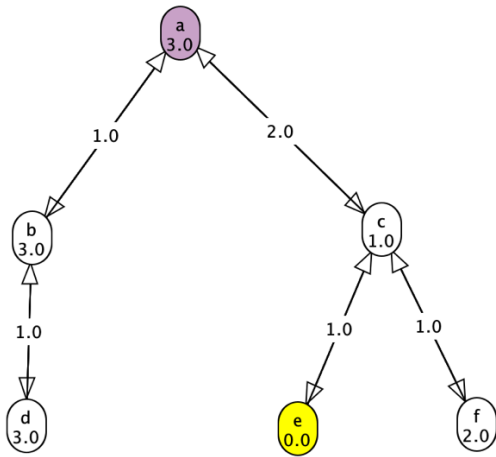
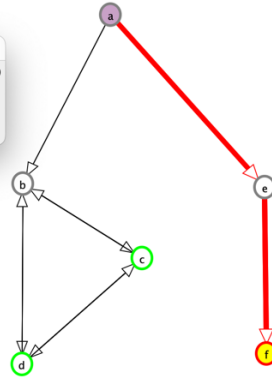


● ● ● Goal Node Reached  
Path found: a --> e --> f (Goal)  
Path cost: 2.0  
Nodes expanded: 8  
OK



● ● ● Goal Node Reached  
Path found: a --> e --> f (Goal)  
Path cost: 2.0  
Nodes expanded: 6  
OK



● ● ● Goal Node Reached  
Path found: a --> c --> e (Goal)  
Path cost: 3.0  
Nodes expanded: 3  
OK

