LAB-6

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6.1 b:

Given, $\mathbf{x(t)} = e^{jt}$ On calculating its FT, we get $\mathbf{X(jw)} = \frac{4 \sin{(2w)}}{2w}$

- As the input signal is rectangular pulse of unit amplitude, therefore its continuous time FT results in sinc function.
- The sinc is completely **real**.
- Hence, its **imaginary** part is **0**.
- The **phase** plot continuously shifts from $\pi/2$ to $-\pi/2$ due to shift in X(jw) values from positive to negative values in **oscillatory** fashion.

6.1 c:

Observations:

- On changing T from 2 to 1, the signal is compressed in time by factor of 2 while its Fourier transform is expanded by the same factor.
- Also there is **change in amplitude**.
- On changing T from 2 to 4, the signal is expanded in time by factor of 2 while its Fourier transform is compressed by the same factor.
- Also there is **change in amplitude.**

FT Property:

Frequency Scaling Property: If a function is expanded in time by a quantity a, the Fourier Transform is compressed in frequency by same amount and vice-versa.

Hence, if
$$x(t)$$
-----> $X(jw)$
Then $x(at)$ -----> $\frac{1}{|a|}X(\frac{jw}{|a|})$

6.1 d:

(a).Given,
$$\mathbf{x(t)} = e^{jt}$$

On calculating its FT, we get $\mathbf{X(jw)} = \frac{2 \sin{(\pi(1-w))}}{1-w}$

Observations:

- The shape is sinc function
- Img(X(jw)) is 0 because X(jw) is purely real as calculated.

(b).Given,
$$\mathbf{x(t)} = \cos \mathbf{t}$$

 $= (e^{jt} + e^{-jt})/2$
On calculating its FT, we get
 $\mathbf{X(jw)} = \frac{2w \sin{(\pi w)}}{1 - w^2}$

Observations:

- The shape is symmetric sinc function.
- From the symmetry, we observe that **X(jw)** is even which is evident from the expression.
- Img(X(jw)) is 0 because X(jw) is purely real as calculated.

6.1 e:

On calculating its FT, we get

$$X(jw) = \left(\frac{\sin{(\frac{w}{2})}}{\frac{w}{2}}\right)^2$$

Observations:

- The shape is sinc function
- Img(X(jw)) is 0 because X(jw) is purely real as calculated.

6.2: A signal and its samples

The signal has been plotted.

6.3 : Fast Fourier Transform(Radix-2)

When N=2, X(k)=
$$\sum_{n=0}^{1} x(n)e^{\frac{-j\pi kn}{2}}$$

where x(n) is the signal obtained on decomposing the input signal into odd and even components until its length is 2.

6.4: Filtering of periodic signals with LTI systems

6.4 a:

• The relationship between input and output signal can be given as:

$$b_k=a_k(H(jw))$$

• From the relation, we observe that there is **no change in periodicity** of output signal.

6.4 b:

(b).Ideal Low Pass Filter(LPF)

Given,
$$\mathbf{x(t)} = \cos \mathbf{t}$$

= $(e^{jt} + e^{-jt})/2$

F{cos(t)}=
$$\pi(\delta(w+1)+\delta(w-1))$$

On comparing with the standard equation:

$$x(t) = \sum_{k=-N}^{N} a_k e^{jkt}$$

$$a_{-1}=a_1=\frac{1}{2}$$

 $a_0=0$

0 otherwise

$$\rightarrow A = [\frac{1}{2}, 0, \frac{1}{2}]$$

Given, $w_0 = 1$

- The filter will only allow frequencies range such that $kw_0 < |w_c|$
- Also k ranges between -1 to 1
- Hence, allowed frequencies= $w_c < -1$ or $w_c > 1$

Case I: $w_c=2$

• Hence $b_k=a_k$ for k=-1,0,1

Case II: $w_c=0.5$

• Hence $b_k=0$ for k=-1,0,1

(c).Ideal High Pass Filter(HPF)

Given,
$$x(t) = \cos t$$

= $(e^{jt} + e^{-jt})/2$

As calculated above,

$$\rightarrow$$
A= $\left[\frac{1}{2}$,0, $\frac{1}{2}\right]$

Given, $w_0=1$

- The filter will only allow frequencies range such that $kw_0 > |w_c|$
- Also k ranges between -1 to 1
- Hence, allowed frequencies= $-1 < w_c < 1$

Case I: w_c=2

• Hence $b_k=0$ for k=-1,0,1

Case II: $w_c=0.5$

• Hence $b_k=a_k$ for k=-1,0,1

(d).Non-Ideal Filter(LPF)

Given, frequency response, $H(w) = \frac{G}{a+w}$ where a>o,G>0

Observations:

- The output signal has a phase shift
- The amplitude of output signal is decreased.

Complex valued nature of LTI system

- Complex valued nature of LTI system corresponds to phase shift in frequency domain.
- On taking inverse FT, this corresponds to time scale shift in time domain.

6.5: Reconstruction methods

Comparison between the quality of three interpolations

- The quality of interpolated signal is **not uniform** throughout.
- The signal is **better** interpolated in **middle** than at ends.
- If we ignore ends,
 Quality of interpolation: sinc>Linear>Zero Order
- End error occurs due to unavailability of sufficient samples at the end.

Maximum Absolute Error(MAE) between original and reconstructed signal in interval [0.25,1.75]

Zero order hold: 3Linear hold: 0.3827

• **Sinc:** 0.6350

This is evident from above explanation.

6.6: Sampling of non-band limited signal

t_samples vector: -1 : T_s : 1 where T_s is sampling interval.

Observations:

- On decreasing sampling interval, sampling frequency increases.
- Hence, the number of samples increases and signal is better reconstructed.

6.7: Audio signals

, 00010, 40111011011111 CompressionM... 'Uncompressed' NumChannels 2 SampleRate 8000 TotalSamples 268237 33.5296 Duration Title 'Impact Moderato' Comment [] 'Kevin MacLeod' Artist BitsPerSample 16

Rest explanation is given in code.

6.8: Aliasing

Given, $x(t)=cos(5\pi t)$

Nyquist rate: $2*5\pi=10\pi$ rad/sec

 $w_s=2\pi/T_s$

Observations:

• On increasing sampling interval, the error or deviation between original and reconstructed signal increases,

Reason:

- When $T_s <= 0.2 \text{ s}$ or $w_s >= 10\pi \ rad/sec$, the sampling frequency is above the Nyquist rate. Hence the signal is properly reconstructed.
- As the **sampling frequency decreases**, the signal is **imperfectly reconstructed** which is evident from the plot.