

```
import cv2

import numpy as np

def detect_color(image_path):

    # Read the image

    image = cv2.imread(image_path)

    # Convert image from BGR to RGB (OpenCV reads images in BGR format by default)

    image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)

    # Define color boundaries in RGB format

    boundaries = [

        ([17, 15, 100], [50, 56, 200]), # Red

        ([86, 31, 4], [220, 88, 50]), # Blue

        ([25, 146, 190], [62, 174, 250]), # Yellow

    ]

    # Loop over the boundaries

    for (lower, upper) in boundaries:

        # Convert the boundaries to NumPy arrays

        lower = np.array(lower, dtype="uint8")

        upper = np.array(upper, dtype="uint8")

        # Find the colors within the specified boundaries and apply the mask

        mask = cv2.inRange(image, lower, upper)

        output = cv2.bitwise_and(image, image, mask=mask)

    # Show the images

    cv2.imshow("images", np.hstack([image, output]))

    cv2.waitKey(0)
```

```
# Path to the image
```

```
image_path = "example_image.jpg"
```

```
# Call the color detection function
```

```
detect_color(image_path)
```