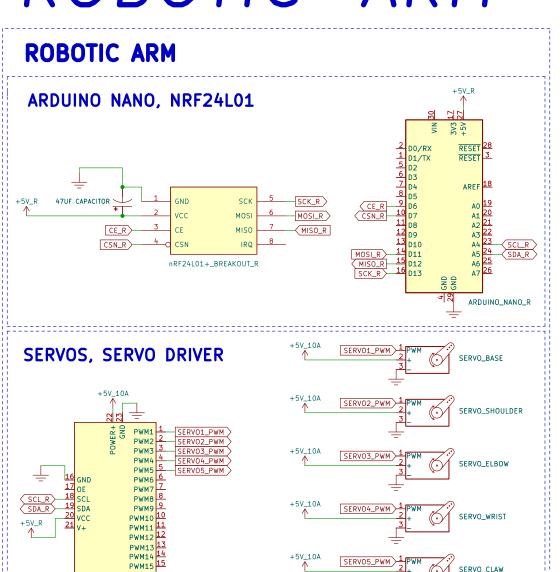
ROBOTIC-ARM

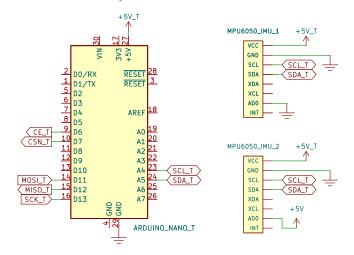


Notes

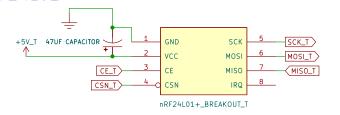
- The "5V_10A" line is connected to a 5V 10 Amp power adapter, and is not the same as a the 5V line coming from the Arduino
- Connections ending in "R" are for reciever parts (robotic arm)
 Connections ending in "T" are for transmitter parts (gesture controller)

GESTURE CONTROLLER

ARDUINO NANO, MPU6050s



NRF24L01



Ashish Agrahari

Sheet: /
File: RoboticArmSchematic.kicad_sch

Title: Robotic—Arm

Size: A4 Date: 2023-02-28 Rev: 1

KiCad E.D.A. eeschema (6.0.10) Id: 1/1