Total number of rungs in routine: 24

MultiStation\_test:FaultTask:Station1\_ProgramFaults

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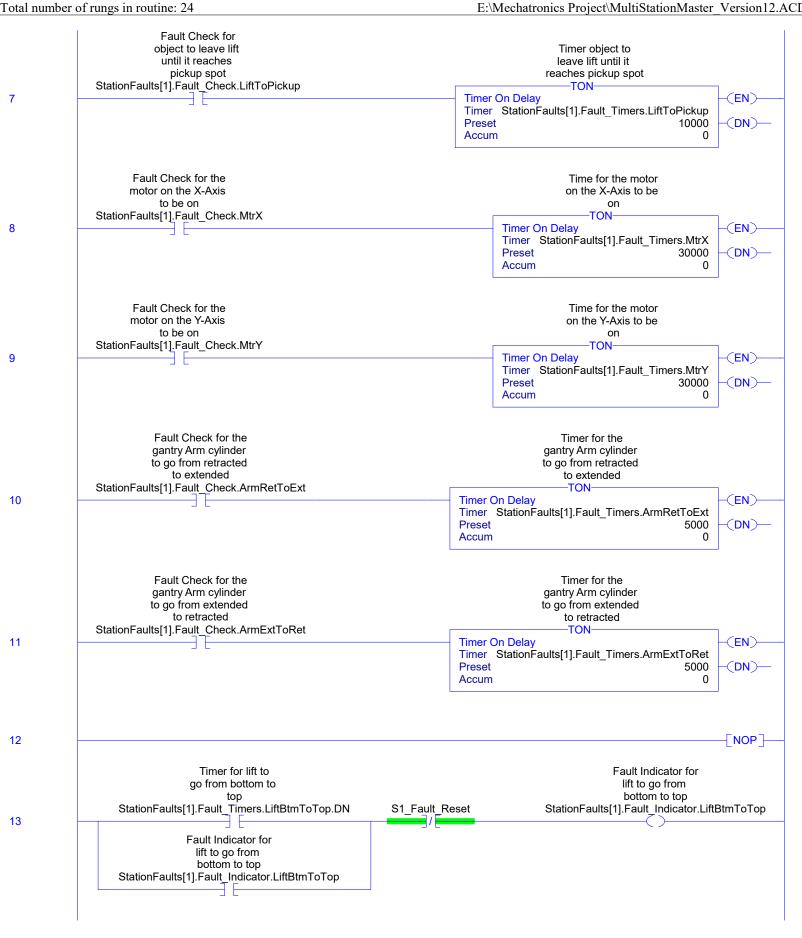
COP-0 Copy File Source StationFaults[0] StationFaults[1] Dest Length S1 Fault Reset COP Copy File 1 Source StationFaults[0] StationFaults[1] Dest Length Fault Check for Timer for lift to lift to go from go from bottom to bottom to top top StationFaults[1].Fault Check.LiftBtmToTop Timer On Delay (EN) Timer StationFaults[1].Fault Timers.LiftBtmToTop (DN) Preset 5000 Accum Fault Check for cylinder to go from Timer for cylinder retracted to to go from retracted extended to extended StationFaults[1].Fault\_Check.LiftCylRetToExt TON-Timer On Delay (EN) Timer StationFaults[1].Fault\_Timers.LiftCylRetToExt **Preset** (DN)Accum 0 Fault Check for cylinder to go from Timer for cylinder extended to to go from extended to retracted retracted StationFaults[1].Fault\_Check.LiftCylExtToRet -TON-Timer On Delay (EN) Timer StationFaults[1].Fault Timers.LiftCylExtToRet Preset 3000 (DN)Accum 0 Fault Check for Timer for lift to lift to go from top go from top to to bottom bottom StationFaults[1].Fault\_Check.LiftTopToBtm TON Timer On Delay  $\langle EN \rangle$ 5 Timer StationFaults[1].Fault\_Timers.LiftTopToBtm Preset 5000 (DN) Accum 0 Fault Check for Timer for conveyor conveyor motor ON motor ON StationFaults[1].Fault\_Check.ConveyorMtr TON-Timer On Delay (EN) 6 Timer StationFaults[1].Fault Timers.ConveyorMtr 10000  $\langle DN \rangle$ Preset Accum

MultiStation\_test:FaultTask:Station1\_ProgramFaults

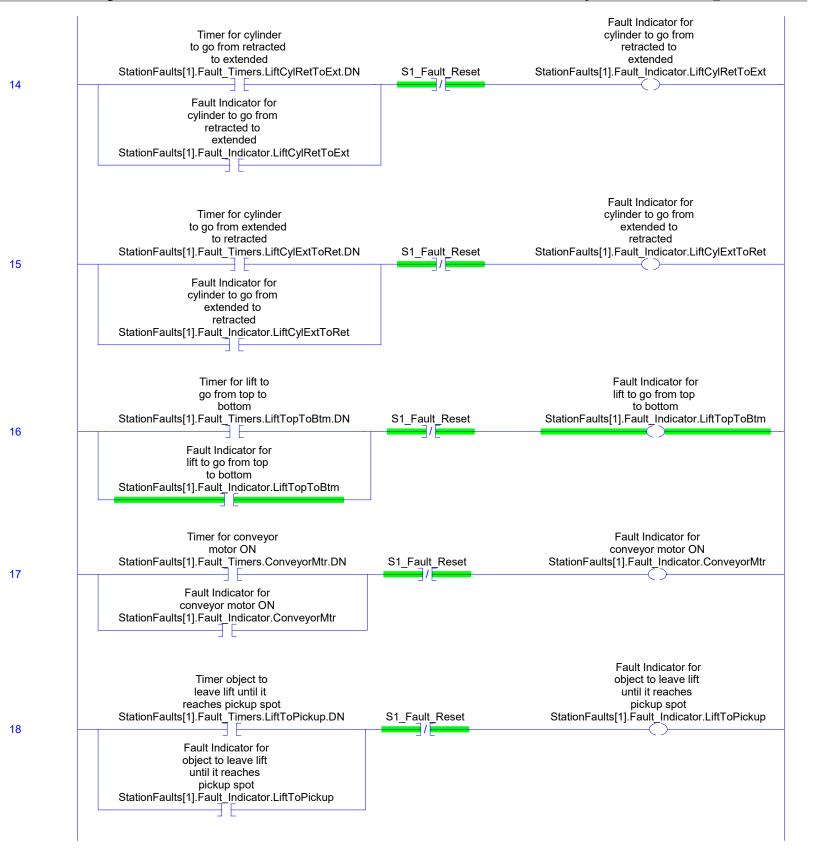
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MultiStation\_test:FaultTask:Station1\_ProgramFaults Total number of rungs in routine: 24



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MultiStation\_test:FaultTask:Station1\_ProgramFaults
Total number of rungs in routine: 24

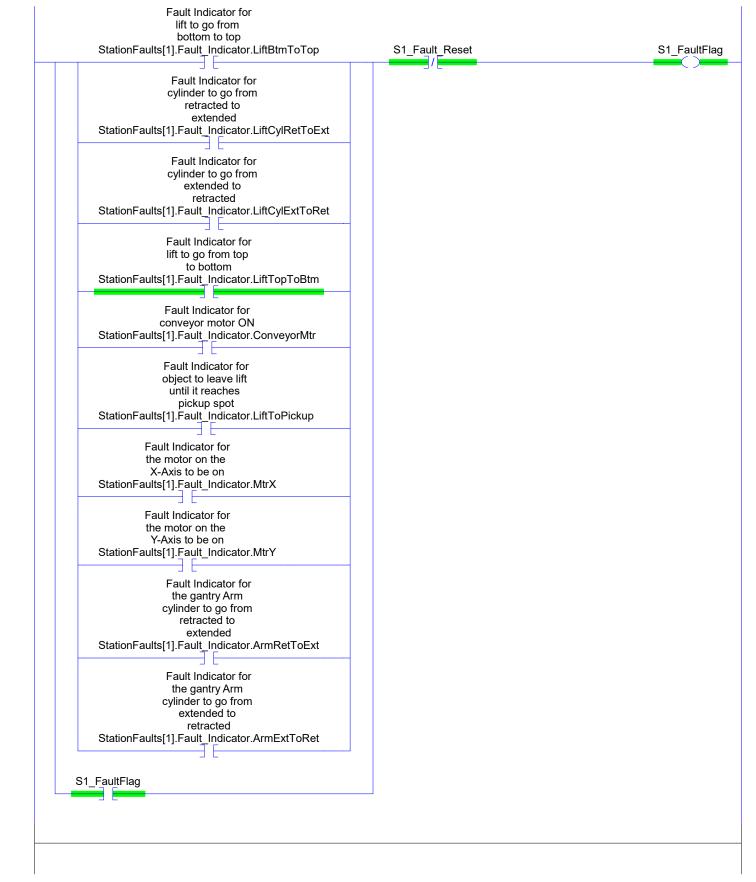
Time for the motor Fault Indicator for on the X-Axis to be the motor on the X-Axis to be on StationFaults[1].Fault\_Timers.MtrX.DN S1\_Fault\_Reset StationFaults[1].Fault\_Indicator.MtrX 19 Fault Indicator for the motor on the X-Axis to be on StationFaults[1].Fault Indicator.MtrX Time for the motor Fault Indicator for on the Y-Axis to be the motor on the Y-Axis to be on StationFaults[1].Fault\_Timers.MtrY.DN StationFaults[1].Fault\_Indicator.MtrY S1 Fault Reset 20 Fault Indicator for the motor on the Y-Axis to be on StationFaults[1].Fault\_Indicator.MtrY Fault Indicator for Timer for the the gantry Arm gantry Arm cylinder cylinder to go from to go from retracted retracted to to extended extended  $StationFaults \hbox{\tt [1].} Fault \underline{\hspace{0.1cm}} Indicator. ArmRetTo Ext$  $StationFaults \hbox{\tt [1].Fault\_Timers.} Arm RetToExt.DN$ S1\_Fault\_Reset 21 Fault Indicator for the gantry Arm cylinder to go from retracted to extended StationFaults[1].Fault Indicator.ArmRetToExt Fault Indicator for the gantry Arm Timer for the gantry Arm cylinder cylinder to go from extended to to go from extended to retracted retracted  $StationFaults \hbox{\tt [1]}. Fault \hbox{\tt \_Indicator}. Arm \hbox{\tt ExtToRet}$ StationFaults[1].Fault\_Timers.ArmExtToRet.DN S1 Fault Reset 22 Fault Indicator for the gantry Arm cylinder to go from extended to retracted StationFaults[1].Fault Indicator.ArmExtToRet

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(End)

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Total number of rungs in routine: 24 E:\Mechatronics Project\MultiStationMaster Version12.ACD



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