

# GATE 23 EE Q38

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**Question:** Consider a lead compensator of the form

$$K(s) = \frac{1 + \frac{s}{a}}{1 + \frac{s}{\beta a}}, \quad \beta > 1, \quad a > 0$$

The frequency at which this compensator produces maximum phase lead is 4 rad/s. At this frequency, the gain amplification provided by the controller, assuming an asymptotic Bode-magnitude plot of  $K(s)$ , is 6 dB. The values of  $a$  and  $\beta$ , respectively, are

- (A) 1, 16 (B) 2, 4 (C) 3, 5 (D) 2.66, 2.25

**Solution:**

Parameter	Value
Transfer Function	$K(s) = \frac{1 + \frac{s}{a}}{1 + \frac{s}{\beta a}}$
Maximum Phase Lead Frequency	$\omega_m = 4 \text{ rad/s}$
Gain Amplification at $\omega_m$	$20 \log_{10}  K(j\omega_m)  = 6 \text{ dB}$
Conditions	$\beta > 1, a > 0$

TABLE I  
GIVEN PARAMETERS

$$K(s) = \frac{1 + \frac{s}{a}}{1 + \frac{s}{a\beta}}$$

$$K(s) = \frac{s + a}{a} \cdot \frac{a\beta}{s + a\beta} \quad (1)$$

$$= \beta \frac{s + a}{s + a\beta} \quad (2)$$

1. The max phase lead is  $\omega_m = \sqrt{a \cdot a\beta}$

2. If  $G(s) = \frac{k(s+a)}{s(s+a\beta)}$  has to act as a lead compensator, then  $a\beta$  must be greater than  $a$ , i.e.,  $a\beta > a$ .

3.  $a + j\omega_m = j\omega_m$

4.  $\frac{\omega_m}{a\beta} = 0$

Using the above properties we have:

$$\omega_m = \sqrt{a \cdot a\beta} = 4 \quad (3)$$

$$\beta > 1 \quad (4)$$

Using gain amplification:

$$K(j\omega_m) = \frac{1 + \frac{j\omega_m}{a}}{1 + \frac{j\omega_m}{a\beta}} \quad (5)$$

$$= \frac{j\omega_m}{a} \quad (6)$$

Using gain amplification in dB:

$$20 \log_{10} |K(j\omega_m)| = 20 \log_{10} \left( \frac{\omega_m}{a} \right) = 6 \quad (7)$$

Solving for  $a$ :

$$\log_{10} \left( \frac{\omega_m}{a} \right) = 0.3 \quad (8)$$

$$\frac{\omega_m}{a} = 10^{0.3} \quad (9)$$

$$a \approx \frac{\omega_m}{10^{0.3}} \quad (10)$$

$$a \approx \frac{4}{2} \quad (11)$$

$$a \approx 2 \quad (12)$$

Since  $a \approx 2$ , and  $\beta = 4$ ,

Therefore, the correct answer is **(B) 2, 4**.