## GATE 23 EE Q38

## EE23BTECH11204 - Ashley Ann Benoy\*

**Question:** Consider a lead compensator of the form

$$K(s) = \frac{1 + \frac{s}{a}}{1 + \frac{s}{\beta a}}, \quad \beta > 1, \quad a > 0$$

The frequency at which this compensator produces maximum phase lead is 4 rad/s. At this frequency, the gain amplification provided by the controller, assuming an asymptotic Bode-magnitude plot of K(s), is 6 dB. The values of a and  $\beta$ , respectively, are

## **Solution:**

Parameter	Value
Transfer Function	$K(s) = \frac{1 + \frac{s}{a}}{1 + \frac{s}{\beta a}}$
Maximum Phase Lead Frequency	$\omega_m = 4  \text{rad/s}$
Gain Amplification at $\omega_m$	$20\log_{10} K(j\omega_m)  = 6\mathrm{dB}$
Conditions	$\beta > 1,  a > 0$

TABLE I Given Parameters

$$K(s) = \frac{1 + \frac{s}{a}}{1 + \frac{s}{a\beta}}$$

$$K(s) = \frac{s+a}{a} \cdot \frac{a\beta}{s+a\beta}$$

$$= \beta \frac{s+a}{s+a\beta}$$
(2)

- 1. The max phase lead is:  $\omega_m = \sqrt{a \cdot a \cdot \beta}$
- 2. If  $G(s) = \frac{k(s+a)}{s(s+a\beta)}$  has to act as a lead compensator, then  $a\beta$  must be greater than a, i.e.,  $a\beta > a$ .

Using the above properties we have:

$$\omega_m = \sqrt{a \cdot a\beta} = 4 \tag{3}$$

$$\beta > 1$$
 (4)

$$K(j\omega) = \frac{1 + \frac{j\omega}{a}}{1 + \frac{j\omega}{a\beta}} = \beta \frac{j\omega + a}{j\omega + a\beta}$$
 (5)

$$|K(j\omega)| = \frac{\beta \sqrt{\omega^2 + a^2}}{\sqrt{\omega^2 + (a\beta)^2}}$$
 (6)

Using Gain Amplification:

$$20\log_{10}|K(j\omega_m)| = 6\tag{7}$$

$$|K(j\omega_m)| \approx 2$$
 (8)

$$|K(j\omega_m)| = \frac{\beta\sqrt{(\omega_m)^2 + a^2}}{\sqrt{(\omega_m)^2 + (a\beta)^2}} = 2$$
 (9)

$$\frac{\beta\sqrt{16+a^2}}{\sqrt{16+(a\beta)^2}} = 2\tag{10}$$

Solving the above equation, we get  $a \approx 2$  and  $\beta = 4$ . Therefore, the correct answer is **(B) 2, 4**. The Bode plots for the same are as follows:

