view_frames Result

Recorded at time: 1756888057.3902764

```
world
```

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
base_link
```

```
ground_plane
```

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
base_link_inertia
```

```
base
```

Broadcaster: default_authority
Average rate: 60.279
Buffer length: 5.01
Most recent transform: 109.655
Oldest transform: 104.645

```
shoulder_link
```

Broadcaster: default_authority
Average rate: 60.279
Buffer length: 5.01
Most recent transform: 109.655
Oldest transform: 104.645

```
upper_arm_link
```

Broadcaster: default_authority
Average rate: 60.279
Buffer length: 5.01
Most recent transform: 109.655
Oldest transform: 104.645

```
forearm_link
```

Broadcaster: default_authority
Average rate: 60.279
Buffer length: 5.01
Most recent transform: 109.655
Oldest transform: 104.645

```
wrist_1_link
```

Broadcaster: default_authority
Average rate: 60.279
Buffer length: 5.01
Most recent transform: 109.655
Oldest transform: 104.645

```
wrist_2_link
```

Broadcaster: default_authority
Average rate: 60.279
Buffer length: 5.01
Most recent transform: 109.655
Oldest transform: 104.645

```
wrist_3_link
```

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
flange
```

```
ft_frame
```

```
ft_sensor
```

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
tool0
```

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
robotiq_base_link
```

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
robotiq_140_base_link
```

Broadcaster: default_authority
Average rate: 60.279
Buffer length: 5.01
Most recent transform: 109.655
Oldest transform: 104.645

Broadcaster: default_authority
Average rate: 60.279
Buffer length: 5.01
Most recent transform: 109.655
Oldest transform: 104.645

Broadcaster: default_authority
Average rate: 60.279
Buffer length: 5.01
Most recent transform: 109.655
Oldest transform: 104.645

Broadcaster: default_authority
Average rate: 60.279
Buffer length: 5.01
Most recent transform: 109.655
Oldest transform: 104.645

```
left_outer_knuckle
```

```
left_inner_knuckle
```

```
right_outer_knuckle
```

```
right_inner_knuckle
```

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
left_outer_finger
```

```
right_outer_finger
```

Broadcaster: default_authority
Average rate: 60.279
Buffer length: 5.01
Most recent transform: 109.655
Oldest transform: 104.645

Broadcaster: default_authority
Average rate: 60.279
Buffer length: 5.01
Most recent transform: 109.655
Oldest transform: 104.645

```
left_inner_finger
```

```
right_inner_finger
```

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

```
left_inner_finger_pad
```

```
right_inner_finger_pad
```