

User Manual

for S32K3 GPT Driver

Document Number: UM34GPTASRR21-11 Rev0000R3.0.0 Rev. 1.0

| | |
|---|-----------|
| 1 Revision History | 2 |
| 2 Introduction | 3 |
| 2.1 Supported Derivatives | 3 |
| 2.2 Overview | 4 |
| 2.3 About This Manual | 5 |
| 2.4 Acronyms and Definitions | 6 |
| 2.5 Reference List | 6 |
| 3 Driver | 8 |
| 3.1 Requirements | 8 |
| 3.2 Driver Design Summary | 8 |
| 3.3 Hardware Resources | 9 |
| 3.4 Deviations from Requirements | 10 |
| 3.5 Driver Limitations | 11 |
| 3.6 Driver usage and configuration tips | 11 |
| 3.7 Runtime errors | 12 |
| 3.8 Symbolic Names Disclaimer | 12 |
| 4 Tresos Configuration Plug-in | 13 |
| 4.1 Module Gpt | 16 |
| 4.2 Container GptChannelConfigSet | 16 |
| 4.3 Container GptChannelConfiguration | 17 |
| 4.4 Parameter GptChannelId | 17 |
| 4.5 Parameter GptHwIp | 17 |
| 4.6 Parameter GptChannelMode | 18 |
| 4.7 Parameter GptChannelTickFrequency | 18 |
| 4.8 Parameter GptChannelTickValueMax | 19 |
| 4.9 Parameter GptEnableWakeup | 20 |
| 4.10 Parameter GptNotification | 20 |
| 4.11 Reference GptChannelEcucPartitionRef | 20 |
| 4.12 Reference GptModuleRef | 21 |
| 4.13 Reference GptChannelClkSrcRef | 21 |
| 4.14 Container GptWakeupConfiguration | 22 |
| 4.15 Reference GptWakeupSourceRef | 22 |
| 4.16 Container GptPit | 23 |
| 4.17 Parameter GptPitModule | 23 |
| 4.18 Parameter PitFreezeEnable | 24 |
| 4.19 Container GptPitChannels | 24 |
| 4.20 Parameter GptPitChannel | 25 |
| 4.21 Parameter ChainMode | 25 |

| | |
|---|----|
| 4.22 Container GptStm | 25 |
| 4.23 Parameter GptStmModule | 27 |
| 4.24 Parameter GptStmPrescaler | 27 |
| 4.25 Parameter GptStmAlternatePrescaler | 28 |
| 4.26 Parameter StmFreezeEnable | 28 |
| 4.27 Container GptStmChannels | 29 |
| 4.28 Parameter GptStmChannel | 29 |
| 4.29 Parameter StmAbsoluteCounting | 30 |
| 4.30 Container GptRtc | 30 |
| 4.31 Parameter GptRtcModule | 31 |
| 4.32 Parameter RtcFreezeEnable | 31 |
| 4.33 Parameter DivBy512 | 31 |
| 4.34 Parameter DivBy32 | 32 |
| 4.35 Parameter GptRtcChannelClkSrc | 32 |
| 4.36 Container GptEmios | 33 |
| 4.37 Parameter GptEmiosModule | 33 |
| 4.38 Container GptEmiosChannels | 34 |
| 4.39 Parameter GptEmiosChannel | 34 |
| 4.40 Parameter EmiosFreezeEnable | 35 |
| 4.41 Parameter GptEmiosPrescaler | 35 |
| 4.42 Parameter GptEmiosAlternatePrescaler | 36 |
| 4.43 Container GptHwConfiguration | 36 |
| 4.44 Parameter GptIsrHwId | 37 |
| 4.45 Parameter GptIsrEnable | 37 |
| 4.46 Parameter GptChannelsUsed | 38 |
| 4.47 Container GptConfigurationOfOptApiServices | 38 |
| 4.48 Parameter GptDeinitApi | 39 |
| 4.49 Parameter GptEnableDisableNotificationApi | 39 |
| 4.50 Parameter GptTimeElapsedApi | 40 |
| 4.51 Parameter GptTimeRemainingApi | 40 |
| 4.52 Parameter GptVersionInfoApi | 40 |
| 4.53 Parameter GptWakeupFunctionalityApi | 41 |
| 4.54 Parameter GptPredefTimerFunctionalityApi | 41 |
| 4.55 Container GptAutosarExt | 42 |
| 4.56 Parameter GptEnableDualClockMode | 42 |
| 4.57 Parameter GptChangeNextTimeoutValueApi | 43 |
| 4.58 Parameter GptEnableUserModeSupport | 43 |
| 4.59 Parameter ChainModeApi | 43 |
| 4.60 Parameter GptStandbyWakeupSupport | 44 |
| 4.61 Container GptDriverConfiguration | 44 |

| | |
|---|----|
| 4.62 Parameter GptDevErrorDetect | 45 |
| 4.63 Parameter GptPredefTimer100us32bitEnable | 45 |
| 4.64 Parameter GptMulticoreSupport | 46 |
| 4.65 Parameter GptPredefTimer1usEnablingGrade | 46 |
| 4.66 Parameter GptTimeoutMethod | 46 |
| 4.67 Parameter GptTimeoutDuration | 47 |
| 4.68 Parameter GptReportWakeupSource | 48 |
| 4.69 Reference GptEcucPartitionRef | 48 |
| 4.70 Reference GptKernelEcucPartitionRef | 49 |
| 4.71 Container GptClockReferencePoint | 49 |
| 4.72 Reference GptClockReference | 49 |
| 4.73 Container GptPredefTimerConfiguration | 50 |
| 4.74 Container GptPredefTimer_1us_16Bit | 50 |
| 4.75 Parameter GptHwChannel | 51 |
| 4.76 Parameter GptChannelPrescaler | 51 |
| 4.77 Parameter GptFreezeEnable | 52 |
| 4.78 Reference GptChannelClkSrcRef | 52 |
| 4.79 Container GptPredefTimer_1us_24Bit | 53 |
| 4.80 Parameter GptHwChannel | 53 |
| 4.81 Parameter GptChannelPrescaler | 54 |
| 4.82 Parameter GptFreezeEnable | 54 |
| 4.83 Reference GptChannelClkSrcRef | 55 |
| 4.84 Container GptPredefTimer_1us_32Bit | 55 |
| 4.85 Parameter GptHwChannel | 55 |
| 4.86 Parameter GptChannelPrescaler | 56 |
| 4.87 Parameter GptFreezeEnable | 56 |
| 4.88 Reference GptChannelClkSrcRef | 57 |
| 4.89 Container GptPredefTimer_100us_32Bit | 57 |
| 4.90 Parameter GptHwChannel | 58 |
| 4.91 Parameter GptChannelPrescaler | 58 |
| 4.92 Parameter GptFreezeEnable | 59 |
| 4.93 Reference GptChannelClkSrcRef | 59 |
| 4.94 Container CommonPublishedInformation | 60 |
| 4.95 Parameter ArReleaseMajorVersion | 60 |
| 4.96 Parameter ArReleaseMinorVersion | 60 |
| 4.97 Parameter ArReleaseRevisionVersion | 61 |
| 4.98 Parameter ModuleId | 61 |
| 4.99 Parameter SwMajorVersion | 62 |
| 4.100 Parameter SwMinorVersion | 62 |
| 4.101 Parameter SwPatchVersion | 63 |

| | |
|--|-----------|
| 4.102 Parameter VendorApiInfix | 63 |
| 4.103 Parameter VendorId | 64 |
| 5 Module Index | 65 |
| 5.1 Software Specification | 65 |
| 6 Module Documentation | 66 |
| 6.1 Emios IPL | 66 |
| 6.1.1 Detailed Description | 66 |
| 6.1.2 Data Structure Documentation | 66 |
| 6.1.3 Types Reference | 67 |
| 6.1.4 Enum Reference | 68 |
| 6.2 Gpt Driver | 69 |
| 6.2.1 Detailed Description | 69 |
| 6.2.2 Macro Definition Documentation | 70 |
| 6.2.3 Types Reference | 73 |
| 6.2.4 Enum Reference | 74 |
| 6.2.5 Function Reference | 74 |
| 6.3 Pit IPL | 79 |
| 6.3.1 Detailed Description | 79 |
| 6.3.2 Enum Reference | 79 |
| 6.4 Rtc IPL | 81 |
| 6.4.1 Detailed Description | 81 |
| 6.4.2 Enum Reference | 81 |
| 6.5 Stm IPL | 84 |
| 6.5.1 Detailed Description | 84 |
| 6.5.2 Macro Definition Documentation | 84 |
| 6.5.3 Enum Reference | 84 |



Chapter 1

Revision History

| Revision | Date | Author | Description |
|----------|------------|--------------|--|
| 1.0 | 31.03.2023 | NXP RTD Team | S32K3 Real-Time Drivers AUTOSAR 4.4 & R21-11 Version 3.0.0 |

Chapter 2

Introduction

- [Supported Derivatives](#)
- [Overview](#)
- [About This Manual](#)
- [Acronyms and Definitions](#)
- [Reference List](#)

This User Manual describes NXP Semiconductor AUTOSAR GPT for S32K3. AUTOSAR GPT driver configuration parameters and deviations from the specification are described in GPT Driver chapter of this document. AUTOSAR GPT driver requirements and APIs are described in the AUTOSAR GPT driver software specification document.

2.1 Supported Derivatives

The software described in this document is intended to be used with the following microcontroller devices of NXP Semiconductors:

- s32k310_mqfp100
- s32k310_lqfp48
- s32k311_mqfp100 / MWCT2015S_mqfp100
- s32k311_lqfp48
- s32k312_mqfp100 / MWCT2016S_mqfp100
- s32k312_mqfp172 / MWCT2016S_mqfp172
- s32k314_mqfp172
- s32k314_mapbga257
- s32k322_mqfp100 / MWCT2D16S_mqfp100
- s32k322_mqfp172 / MWCT2D16S_mqfp172

- s32k324_mqfp172 / MWCT2D17S_mqfp172
- s32k324_mapbga257
- s32k341_mqfp100
- s32k341_mqfp172
- s32k342_mqfp100
- s32k342_mqfp172
- s32k344_mqfp172
- s32k344_mapbga257
- s32k394_mapbga289
- s32k396_mapbga289
- s32k358_mqfp172
- s32k358_mapbga289
- s32k328_mqfp172
- s32k328_mapbga289
- s32k338_mqfp172
- s32k338_mapbga289
- s32k348_mqfp172
- s32k348_mapbga289
- s32m274_lqfp64
- s32m276_lqfp64

All of the above microcontroller devices are collectively named as S32K3.

Note: MWCT part numbers contain NXP confidential IP for Qi Wireless Power.

2.2 Overview

AUTOSAR (AUTomotive Open System ARchitecture) is an industry partnership working to establish standards for software interfaces and software modules for automobile electronic control systems.

AUTOSAR:

- paves the way for innovative electronic systems that further improve performance, safety and environmental friendliness.
- is a strong global partnership that creates one common standard: "Cooperate on standards, compete on implementation".
- is a key enabling technology to manage the growing electrics/electronics complexity. It aims to be prepared for the upcoming technologies and to improve cost-efficiency without making any compromise with respect to quality.
- facilitates the exchange and update of software and hardware over the service life of the vehicle.

2.3 About This Manual

This Technical Reference employs the following typographical conventions:

- **Boldface** style: Used for important terms, notes and warnings.
- *Italic* style: Used for code snippets in the text. Note that C language modifiers such "const" or "volatile" are sometimes omitted to improve readability of the presented code.

Notes and warnings are shown as below:

Note

This is a note.

Warning

This is a warning

2.4 Acronyms and Definitions

| Term | Definition |
|-------|--|
| API | Application Programming Interface |
| ASM | Assembler |
| BSMI | Basic Software Make file Interface |
| GPT | General Purpose Timer |
| C/CPP | C and C++ Source Code |
| CS | Chip Select |
| CTU | Cross Trigger Unit |
| DEM | Diagnostic Event Manager |
| DET | Development Error Tracer |
| DMA | Direct Memory Access |
| ECU | Electronic Control Unit |
| FIFO | First In First Out |
| LSB | Least Significant Bit |
| MCU | Micro Controller Unit |
| MIDE | Multi Integrated Development Environment |
| MSB | Most Significant Bit |
| N/A | Not Applicable |
| RAM | Random Access Memory |
| SIU | Systems Integration Unit |
| SWS | Software Specification |
| VLE | Variable Length Encoding |
| XML | Extensible Markup Language |

2.5 Reference List

| # | Title | Version |
|----|--|--|
| 1 | Specification of GPT Driver | AUTOSAR Release R21-11 |
| 2 | Specification of Communication Stack Types | AUTOSAR Release R21-11 |
| 3 | Specification of Compiler Abstraction | AUTOSAR Release R21-11 |
| 4 | Specification of Platform Types | AUTOSAR Release R21-11 |
| 5 | Specification of Standard Types | AUTOSAR Release R21-11 |
| 6 | S32K3xx Reference Manual | Rev.6, Draft B, 01/2023 |
| 7 | S32K39 and S32K37 Reference Manual | Rev. 2 Draft A, 11/2022 |
| 8 | S32M27x Reference Manual | Rev.2, Draft A, 02/2023 |
| 9 | S32K3xx Datasheet | Rev. 6, 11/2022 |
| 10 | S32K396 Datasheet | Rev. 1.1 — 08/2022 |
| 11 | S32M2xx Datasheet | Rev. 2 RC — 12/2022 |
| 11 | S32K311 Errata | S32K311_0P98C Mask Set Errata, Rev. 6/March/2023, 3/2023 |
| 12 | S32K312 Errata | Mask Set Errata for Mask 0P09C, Rev. 25/April/2022 |

| # | Title | Version |
|----|----------------|---|
| 13 | S32K342 Errata | Mask Set Errata for Mask 0P97C, Rev. 10, 11/2022 |
| 14 | S32K3x4 Errata | Mask Set Errata for Mask 0P55A/1P55A, Rev. 14/↔ Oct/2022 |
| 15 | S32K358 Errata | S32K358_0P14E Mask Set Errata – Rev. 28, 9/2022 |
| 16 | S32K396 Errata | S32K396_0P40E Mask Set Errata, Rev. DEC2022, 12/2022 |

Chapter 3

Driver

- [Requirements](#)
- [Driver Design Summary](#)
- [Hardware Resources](#)
- [Deviations from Requirements](#)
- [Driver Limitations](#)
- [Driver usage and configuration tips](#)
- [Runtime errors](#)
- [Symbolic Names Disclaimer](#)

3.1 Requirements

- Requirements for this driver are detailed in the RTD GPT AUTOSAR Release R21-11.
- Driver Software Specification document (See S32K3XX Reference Manual, Rev.6, Draft B, 01/2023 ; S32K396 Reference Manual, Rev. 2 Draft A , 11/2022 and S32M27x Reference Manual, Rev.2, Draft A, 02/2023).

3.2 Driver Design Summary

The RTD driver assures reentrancy (single core execution) for the APIs based on the following assumptions:

- The "called-again" API is for a different resource (hardware/logic channel);
- Common variables/registers accessed with "rmw" are guarded by Exclusive Areas which need to be correctly implemented in RTE on user side;

The GPT Driver implements the following channels on S32K3 peripherals.

The table provides information regarding the Timer channels available for the various derivatives across different packages in S32K3XX family. This table lists only the supported packages by GPT driver.

RTC module features :

- 32-bit counter
- RTC interrupt with interrupt enable.
- Selectable counter clock sources
- Counter runs in all modes of operation.

PIT timer module features :

- Four 32-bit counters per module
- Independent timeout periods for each timer
- Independent interrupt source.

STM timer module features :

- One 32-bit up counter with 8-bit prescaler (1 to 256) per module.
- Four 32-bit compare channels
- Independent interrupt source for each channel.

eMios timer module features :

- Up to 24 channels chosen among Unified or Dedicated Channels, not necessarily numbered in a continuous sequence.
- Data registers of either 8-, 16-, 24-, or 32-bit width. (See Configuration information)
- Counter buses B, C, D, and E can be driven by Unified Channels 0, 8, 16, and 24, respectively. (See Configuration information)
- Counter bus A can be driven by Unified Channel 23.
- Counter bus F can be driven by a specified Unified Channel, defined by the system configuration.
- Two global prescalers
- One prescaler per channel (CP)
- Timebases shared through the counter buses
- State of the Unified Channels can be frozen for debug purposes

3.3 Hardware Resources

| # | Hardware IP | Description |
|---|-------------|-------------------------------|
| 1 | STM | System Timer Module |
| 2 | PIT | Periodic Interrupt Timer |
| 3 | RTC | Real Time Clock |
| 4 | eMios | Enhanced Modular IO Subsystem |

3.4 Deviations from Requirements

The driver deviates from the AUTOSAR GPT Driver software specification in some places.

There are also some additional requirements (on top of requirements detailed in AUTOSAR GPT Driver software specification) which need to be satisfied for correct operation.

Deviations Status Column Description

| Term | Definition |
|------|-----------------------|
| N/S | Out of scope |
| N/I | Not implemented |
| N/F | Not fully implemented |

Below table identifies the AUTOSAR requirements that are not fully implemented, implemented differently, or out of scope for the driver.

| Requirement | Status | Description | Notes |
|----------------------|--------|--|---|
| SWS_Gpt_00261 | N/S | Gpt_Irq.c shall include Gpt.h for the prototype declaration of the notification functions. | Rejection reason: Gpt_Irq.c is not needed. Autosar specific interrupt behaviour is implemented using a normal function placed in the Gpt.c file. |
| SWS_Gpt_00278 | N/S | Module - Header File - Imported Type - EcuM_flex - EcuM.h - EcuM_WakeupSourceType - Std_Types - StandardTypes.h - Std_ReturnType - StandardTypes.h - Std_VersionInfoType - | Rejection reason: No production errors needed for current development. |
| SWS_Gpt_00381 | N/S | These requirements are not applicable to this specification. | Not a requirement |
| ECUC_Gpt_00235 | N/S | Container Name - GptWakeupConfiguration - Description - Function pointer to callback function (for wakeup notification). - Configuration Parameters - | Rejection reason: Wrong Description: Function pointer to callback function (for non-wakeup notification).It shall relate to wakeup configuration. |
| SWS_Gpt_CONSTR_00001 | N/S | DRAFT: The ECUC partitions referenced by GptKernelEcucPartitionRef shall be a subset of the ECUC partitions referenced by GptEcucPartitionRef.() | Type IV Autosar multicore not implemented for current module. AAI-445; Agree that each module can reject the Autosar Standard requirement |

| Requirement | Status | Description | Notes |
|----------------|--------|--|--|
| ECUC_Gpt_00338 | N/S | <p>Name - GptKernelEcuc↔ PartitionRef - Parent Container</p> <p>- GptDriverConfiguration - Description - Maps the GPT kernel to zero or one ECUC partitions to assign the driver kernel to a certain core. The ECUC partition referenced is a subset of the ECUC partitions where the GPT driver is mapped to. Note: The kernel reference shall not be set in case the GPT driver is implemented without a kernel (refer to definition of GptEcucPartitionRef).Tags:</p> <p>atp.Status=draft - Multiplicity - 0..1 - Type - Reference to [EcucPartition] - Post-Build Variant Multiplicity - true - Post-Build Variant Value - true - Multiplicity Configuration Class - Pre-compile time - X - All Variants - Link time - - - - Post-build time - - - - Value Configuration Class - Pre-compile time - X - All Variants - Link time - - - - Post-build time - - - - Scope / Dependency - scope: ECU -</p> | Type IV Autosar multicore not implemented for current module. AAI-445; Agree that each module can reject the Autosar S-standard requirement. |

3.5 Driver Limitations

The GPT driver software have some following limitations for RTD S32K3

- Does not support PredefTimerFunctionality for eMios

3.6 Driver usage and configuration tips

In this chapter, the extra features from our drivers that are not described in the AutoSAR standard are detailed.

- On function: Emios_Gpt_Ip_StartTimer(instance, channel, compareValue), compareValue parameter value must be less than the maximum value of counter register, With S32K396 (S32K3XX family) counter register is on 24bits and that for the rest the counter register is on 16bits.
- Rtc clock source configuration: To select a Rtc clock source, the user needs to use clock tool component. Rtc clock source parameter from RTC LLD driver (or GPT HLD Driver) will be automatically configured with the value from clock tool component. Please refer to the picture:



```
./img/ConfigRtcClkSrc.png
```

Figure 3.1 Config inside clock tool component

3.7 Runtime errors

The driver generates the following DEM errors at runtime.

| Function | Error Code | Condition triggering the error |
|-----------------------------|------------|---|
| Gpt_ValidateChannelStatus() | GPT_E_BUSY | API service called when timer channel is still busy (running) |
| Gpt_ValidateMode() | GPT_E_MODE | API service called when driver is in wrong mode |

3.8 Symbolic Names Disclaimer

All containers having symbolicNameValue set to TRUE in the AUTOSAR schema will generate defines like:

```
#define <Mip>Conf_<Container_ShortName>_<Container_ID>
```

For this reason it is forbidden to duplicate the names of such containers across the RTD configurations or to use names that may trigger other compile issues (e.g. match existing `#ifdefs` arguments).

Chapter 4

Tresos Configuration Plug-in

This chapter describes the Tresos configuration plug-in for the driver. All the parameters are described below.

- Module [Gpt](#)
 - Container [GptChannelConfigSet](#)
 - * Container [GptChannelConfiguration](#)
 - Parameter [GptChannelId](#)
 - Parameter [GptHwIp](#)
 - Parameter [GptChannelMode](#)
 - Parameter [GptChannelTickFrequency](#)
 - Parameter [GptChannelTickValueMax](#)
 - Parameter [GptEnableWakeup](#)
 - Parameter [GptNotification](#)
 - Reference [GptChannelEcucPartitionRef](#)
 - Reference [GptModuleRef](#)
 - Reference [GptChannelClkSrcRef](#)
 - Container [GptWakeupConfiguration](#)
 - Reference [GptWakeupSourceRef](#)
 - * Container [GptPit](#)
 - Parameter [GptPitModule](#)
 - Parameter [PitFreezeEnable](#)
 - Container [GptPitChannels](#)
 - Parameter [GptPitChannel](#)
 - Parameter [ChainMode](#)
 - * Container [GptStm](#)
 - Parameter [GptStmModule](#)
 - Parameter [GptStmPrescaler](#)
 - Parameter [GptStmAlternatePrescaler](#)
 - Parameter [StmFreezeEnable](#)
 - Container [GptStmChannels](#)
 - Parameter [GptStmChannel](#)
 - Parameter [StmAbsoluteCounting](#)

- * Container [GptRtc](#)
 - Parameter [GptRtcModule](#)
 - Parameter [RtcFreezeEnable](#)
 - Parameter [DivBy512](#)
 - Parameter [DivBy32](#)
 - Parameter [GptRtcChannelClkSrc](#)
- * Container [GptEmios](#)
 - Parameter [GptEmiosModule](#)
 - Container [GptEmiosChannels](#)
 - Parameter [GptEmiosChannel](#)
 - Parameter [EmiosFreezeEnable](#)
 - Parameter [GptEmiosPrescaler](#)
 - Parameter [GptEmiosAlternatePrescaler](#)
- Container [GptHwConfiguration](#)
 - * Parameter [GptIsrHwId](#)
 - * Parameter [GptIsrEnable](#)
 - * Parameter [GptChannelsUsed](#)
- Container [GptConfigurationOfOptApiServices](#)
 - * Parameter [GptDeinitApi](#)
 - * Parameter [GptEnableDisableNotificationApi](#)
 - * Parameter [GptTimeElapsedApi](#)
 - * Parameter [GptTimeRemainingApi](#)
 - * Parameter [GptVersionInfoApi](#)
 - * Parameter [GptWakeupFunctionalityApi](#)
 - * Parameter [GptPredefTimerFunctionalityApi](#)
- Container [GptAutosarExt](#)
 - * Parameter [GptEnableDualClockMode](#)
 - * Parameter [GptChangeNextTimeoutValueApi](#)
 - * Parameter [GptEnableUserModeSupport](#)
 - * Parameter [ChainModeApi](#)
 - * Parameter [GptStandbyWakeupSupport](#)
- Container [GptDriverConfiguration](#)
 - * Parameter [GptDevErrorDetect](#)
 - * Parameter [GptPredefTimer100us32bitEnable](#)
 - * Parameter [GptMulticoreSupport](#)
 - * Parameter [GptPredefTimer1usEnablingGrade](#)
 - * Parameter [GptTimeoutMethod](#)

- * Parameter [GptTimeoutDuration](#)
- * Parameter [GptReportWakeupSource](#)
- * Reference [GptEcucPartitionRef](#)
- * Reference [GptKernelEcucPartitionRef](#)
- * Container [GptClockReferencePoint](#)
 - Reference [GptClockReference](#)
- Container [GptPredefTimerConfiguration](#)
 - * Container [GptPredefTimer_1us_16Bit](#)
 - Parameter [GptHwChannel](#)
 - Parameter [GptChannelPrescaler](#)
 - Parameter [GptFreezeEnable](#)
 - Reference [GptChannelClkSrcRef](#)
 - * Container [GptPredefTimer_1us_24Bit](#)
 - Parameter [GptHwChannel](#)
 - Parameter [GptChannelPrescaler](#)
 - Parameter [GptFreezeEnable](#)
 - Reference [GptChannelClkSrcRef](#)
 - * Container [GptPredefTimer_1us_32Bit](#)
 - Parameter [GptHwChannel](#)
 - Parameter [GptChannelPrescaler](#)
 - Parameter [GptFreezeEnable](#)
 - Reference [GptChannelClkSrcRef](#)
 - * Container [GptPredefTimer_100us_32Bit](#)
 - Parameter [GptHwChannel](#)
 - Parameter [GptChannelPrescaler](#)
 - Parameter [GptFreezeEnable](#)
 - Reference [GptChannelClkSrcRef](#)
- Container [CommonPublishedInformation](#)
 - * Parameter [ArReleaseMajorVersion](#)
 - * Parameter [ArReleaseMinorVersion](#)
 - * Parameter [ArReleaseRevisionVersion](#)
 - * Parameter [ModuleId](#)
 - * Parameter [SwMajorVersion](#)
 - * Parameter [SwMinorVersion](#)
 - * Parameter [SwPatchVersion](#)
 - * Parameter [VendorApiInfix](#)
 - * Parameter [VendorId](#)

4.1 Module Gpt

Configuration of the Gpt (General Purpose Timer) module.

Included containers:

- [GptChannelConfigSet](#)
- [GptHwConfiguration](#)
- [GptConfigurationOfOptApiServices](#)
- [GptAutosarExt](#)
- [GptDriverConfiguration](#)
- [GptPredefTimerConfiguration](#)
- [CommonPublishedInformation](#)

| Property | Value |
|-------------------------|---|
| type | ECUC-MODULE-DEF |
| lowerMultiplicity | 0 |
| upperMultiplicity | 1 |
| postBuildVariantSupport | true |
| supportedConfigVariants | VARIANT-POST-BUILD, VARIANT-PRE-COMPILE |

4.2 Container GptChannelConfigSet

This container is the base of an Configuration Set which contains the configured GPT channels.

This way, different configuration sets can be defined for post-build process.

Included subcontainers:

- [GptChannelConfiguration](#)
- [GptPit](#)
- [GptStm](#)
- [GptRtc](#)
- [GptEmios](#)

| Property | Value |
|------------------------------|-------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |

4.3 Container GptChannelConfiguration

This container contains the channel-wide configuration (parameters) of the GPT Driver

Included subcontainers:

- [GptWakeupConfiguration](#)

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 1 |
| upperMultiplicity | Infinite |
| postBuildVariantMultiplicity | false |
| multiplicityConfigClasses | VARIANT-POST-BUILD: PRE-COMPILE |
| | VARIANT-PRE-COMPILE: PRE-COMPILE |

4.4 Parameter GptChannelId

Channel Id of the GPT channel. This value will be assigned to the symbolic name derived of the GptChannelConfiguration container short name.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | AUTOSAR_ECUC |
| symbolicNameValue | true |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |
| defaultValue | 0 |
| max | 4294967295 |
| min | 0 |

4.5 Parameter GptHwIp

Vendor specific: Selects the physical GPT Channel.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| default Value | STM |
| literals | ['STM', 'PIT', 'EMIOS', 'RTC'] |

4.6 Parameter GptChannelMode

Specifies the behaviour of the timerchannel after the timeout has expired

| Property | Value |
|------------------------------|---|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | AUTOSAR_ECUC |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| default Value | GPT_CH_MODE_ONESHOT |
| literals | ['GPT_CH_MODE_CONTINUOUS', 'GPT_CH_MODE_ONESHOT'] |

4.7 Parameter GptChannelTickFrequency

EN: Specifies the tick frequency of the timer channel in Hz.

| Property | Value |
|-------------------|----------------------|
| type | ECUC-FLOAT-PARAM-DEF |
| origin | AUTOSAR_ECUC |
| symbolicNameValue | false |

| Property | Value |
|------------------------------|----------------------------------|
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | 1.9996338561054494 |
| max | 9.223372036854776E18 |
| min | 0.0 |

4.8 Parameter GptChannelTickValueMax

Maximum value in ticks, the timer channel is able to count.

With the next tick, the timer rolls over to zero.

It is mandatory to set 4294967295 for the RTC and STM channels

(corresponding to the 32 bits counter resolution), 16777215 for EMIOS

(corresponding to the 24 bits counter resolution)

and 65535 for the EMIOS channels (corresponding to the

16 bits counter resolution)!

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | AUTOSAR_ECUC |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | 65535 |
| max | 4294967295 |
| min | 65535 |

4.9 Parameter GptEnableWakeup

Enables wakeup capability of CPU for a channel.

| Property | Value |
|------------------------------|--|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | AUTOSAR_ECUC |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | false |

4.10 Parameter GptNotification

Function pointer to callback function(for non-wakeup notification).

The field is editable only if the switch GptEnableDisableNotificationApi is true.

| Property | Value |
|------------------------------|--|
| type | ECUC-FUNCTION-NAME-DEF |
| origin | AUTOSAR_ECUC |
| symbolicNameValue | false |
| lowerMultiplicity | 0 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | true |
| multiplicityConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE VARIANT-POST-BUILD: POST-BUILD |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | NULL_PTR |

4.11 Reference GptChannelEcucPartitionRef

Maps a GPT channel to zero or one ECUC partition to limit the access to this channel group. The ECUC partitions referenced are a subset of the ECUC partitions where the GPT driver is mapped to.

| Property | Value |
|------------------------------|---|
| type | ECUC-REFERENCE-DEF |
| origin | AUTOSAR_ECUC |
| lowerMultiplicity | 0 |
| upperMultiplicity | Infinite |
| postBuildVariantMultiplicity | true |
| multiplicityConfigClasses | VARIANT-POST-BUILD: PRE-COMPILE |
| | VARIANT-PRE-COMPILE: PRE-COMPILE |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-POST-BUILD: PRE-COMPILE |
| | VARIANT-PRE-COMPILE: PRE-COMPILE |
| requiresSymbolicNameValue | False |
| destination | /AUTOSAR/EcuDefs/EcuC/EcuPartitionCollection/EcuPartition |

4.12 Reference GptModuleRef

Maps a GPT channel to zero or one ECUC partition to limit the access to this channel group. The ECUC partitions referenced are a subset of the ECUC partitions where the GPT driver is mapped to.

| Property | Value |
|------------------------------|--|
| type | ECUC-CHOICE-REFERENCE-DEF |
| origin | NXP |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| requiresSymbolicNameValue | False |
| destinations | ['/TS_T40D34M30I0R0/Gpt/GptChannelConfigSet/GptPit/GptPitChannels', '/TS_T40D34M30I0R0/Gpt/GptChannelConfigSet/GptStm/GptStmChannels', '/TS_T40D34M30I0R0/Gpt/GptChannelConfigSet/GptEmios/GptEmios← Channels', '/TS_T40D34M30I0R0/Gpt/GptChannelConfigSet/GptRtc'] |

4.13 Reference GptChannelClkSrcRef

Reference to the GptClockReferencePoint from which the channel clock is derived.

| Property | Value |
|----------|--------------------|
| type | ECUC-REFERENCE-DEF |

| Property | Value |
|------------------------------|---|
| origin | AUTOSAR_ECUC |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| requiresSymbolicNameValue | False |
| destination | /AUTOSAR/EcucDefs/Gpt/GptDriverConfiguration/GptClockReferencePoint |

4.14 Container GptWakeupConfiguration

This container defines the wakeup source codes reported to Ecu State Manager.

Included subcontainers:

- None

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 0 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | false |
| multiplicityConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |

4.15 Reference GptWakeupSourceRef

In case the wakeup-capability is true this value is transmitted to the Ecu State Manager.

Implementation Type: reference to EcuM_WakeupSourceType

| Property | Value |
|------------------------------|--------------------|
| type | ECUC-REFERENCE-DEF |
| origin | AUTOSAR_ECUC |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |

| Property | Value |
|---------------------------|---|
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| requiresSymbolicNameValue | true |
| destination | /AUTOSAR/EcuDefs/EcuM/EcuMConfiguration/EcuMCommon← Configuration/EcuMWakeupSource |

4.16 Container GptPit

Configuration of a Pit module available on the platform.

Included subcontainers:

- [GptPitChannels](#)

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 0 |
| upperMultiplicity | Infinite |
| postBuildVariantMultiplicity | false |
| multiplicityConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |

4.17 Parameter GptPitModule

Select the physical Pit Module.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |

| Property | Value |
|--------------|-----------------------------|
| defaultValue | PIT_0 |
| literals | ['PIT_0', 'PIT_1', 'PIT_2'] |

4.18 Parameter PitFreezeEnable

Enables/Disables freeze bit.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | false |

4.19 Container GptPitChannels

Pit hw channels.

Included subcontainers:

- None

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 1 |
| upperMultiplicity | Infinite |
| postBuildVariantMultiplicity | false |
| multiplicityConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |

4.20 Parameter GptPitChannel

Selects one of the Pit channels available on the platform.

| Property | Value |
|------------------------------|--|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | CH_RTI |
| literals | ['CH_RTI', 'CH_0', 'CH_1', 'CH_2', 'CH_3'] |

4.21 Parameter ChainMode

Enables/Disables chain mode

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | false |

4.22 Container GptStm

Configuration of a Stm module available on the platform.

Included subcontainers:

- [GptStmChannels](#)

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 0 |
| upperMultiplicity | Infinite |
| postBuildVariantMultiplicity | false |
| multiplicityConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |

4.23 Parameter GptStmModule

Select the physical Stm Module.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | STM_0 |
| literals | ['STM_0', 'STM_1', 'STM_2'] |

4.24 Parameter GptStmPrescaler

Vendor specific: The GPT module specific clock prescaler value.

Note with STM:

- STM prescaler should be between 1-256.

| Property | Value |
|------------------------------|------------------------|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |

| Property | Value |
|---------------------------|--|
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | 1 |
| max | 256 |
| min | 1 |

4.25 Parameter GptStmAlternatePrescaler

Vendor specific: The GPT module specific clock prescaler value.

Note with STM:

- STM prescaler should be between 1-256.

| Property | Value |
|------------------------------|--|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | 1 |
| max | 256 |
| min | 1 |

4.26 Parameter StmFreezeEnable

Enables/Disables freeze bit.

| Property | Value |
|-------------------|------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |

| Property | Value |
|------------------------------|----------------------------------|
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | false |

4.27 Container GptStmChannels

STM hw channels

Included subcontainers:

- None

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 1 |
| upperMultiplicity | Infinite |
| postBuildVariantMultiplicity | false |
| multiplicityConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |

4.28 Parameter GptStmChannel

Selects one of the Stm channels available on the platform.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |

| Property | Value |
|--------------|----------------------------------|
| defaultValue | CH_0 |
| literals | ['CH_0', 'CH_1', 'CH_2', 'CH_3'] |

4.29 Parameter StmAbsoluteCounting

Enables/Disables absolute compare value.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |
| defaultValue | false |

4.30 Container GptRtc

Configuration of a Pit module available on the platform.

Included subcontainers:

- None

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 0 |
| upperMultiplicity | Infinite |
| postBuildVariantMultiplicity | false |
| multiplicityConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |

4.31 Parameter GptRtcModule

Select the physical Pit Module.

| Property | Value |
|------------------------------|--|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | RTC_0_CH_0 |
| literals | ['RTC_0_CH_0'] |

4.32 Parameter RtcFreezeEnable

Enables/Disables freeze bit

| Property | Value |
|------------------------------|--|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | false |

4.33 Parameter DivBy512

Optional 512 prescaler

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| default Value | false |

4.34 Parameter DivBy32

Optional 32 prescaler

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| default Value | false |

4.35 Parameter GptRtcChannelClkSrc

Selectable counter clock sources (IRCs and OSCs)

? Clock source 0

? Clock source 1

? Clock source 2

? Clock source 3

| Property | Value |
|------------------------------|--|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | RTC_IP_CLOCK_SOURCE_0 |
| literals | ['RTC_IP_CLOCK_SOURCE_0', 'RTC_IP_CLOCK_SOURCE_1', 'RTC_IP_CLOCK_SOURCE_2', 'RTC_IP_CLOCK_SOURCE_3'] |

4.36 Container GptEmios

Configuration of an EMIOS module available on the platform.

Included subcontainers:

- [GptEmiosChannels](#)

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 0 |
| upperMultiplicity | Infinite |
| postBuildVariantMultiplicity | false |
| multiplicityConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |

4.37 Parameter GptEmiosModule

Select the physical Emios Module.

| Property | Value |
|-------------------|----------------------------|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |

| Property | Value |
|------------------------------|--|
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | EMIOS_0 |
| literals | ['EMIOS_0', 'EMIOS_1', 'EMIOS_2'] |

4.38 Container GptEmiosChannels

Vendor specific: The GPT module specific clock prescaler value.

Note with EMIOS:

- EMIOS prescaler should be between 1-4.

Included subcontainers:

- None

| Property | Value |
|------------------------------|---|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 1 |
| upperMultiplicity | Infinite |
| postBuildVariantMultiplicity | false |
| multiplicityConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE VARIANT-POST-BUILD: PRE-COMPILE |

4.39 Parameter GptEmiosChannel

Selects one of the EMIOS channels available on the platform.

| Property | Value |
|-------------------|----------------------------|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |

| Property | Value |
|------------------------------|---|
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | CH_0 |
| literals | ['CH_0', 'CH_1', 'CH_2', 'CH_3', 'CH_4', 'CH_5', 'CH_6', 'CH_7', 'CH_8', 'CH_16', 'CH_22', 'CH_23'] |

4.40 Parameter EmiosFreezeEnable

This container enable/disable freeze for eMios

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | false |

4.41 Parameter GptEmiosPrescaler

Vendor specific: The GPT module specific clock prescaler value.

If an eMIOS channel is being used,

this parameter configures the clock divider value

for the internal prescaler of specific Unified Channel.

Note with EMIOS:

- EMIOS prescaler should be between 1-16.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | 1 |
| max | 16 |
| min | 1 |

4.42 Parameter GptEmiosAlternatePrescaler

Vendor specific: The GPT module specific clock prescaler value.

Note with EMIOS:

- EMIOS prescaler should be between 1-16.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | 1 |
| max | 16 |
| min | 1 |

4.43 Container GptHwConfiguration

List of all HW channel resources for GPT module.

Included subcontainers:

- None

| Property | Value |
|------------------------------|-------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 51 |
| upperMultiplicity | 51 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |

4.44 Parameter GptIsrHwId

ID of HW interrupt resources.

| Property | Value |
|------------------------------|---|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | true |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE VARIANT-POST-BUILD: PRE-COMPILE |
| defaultValue | STM_0_CH_1 |
| literals | ['STM_0_CH_0', 'STM_0_CH_1', 'STM_0_CH_2', 'STM_0_CH_3', 'STM_1_CH_0', 'STM_1_CH_1', 'STM_1_CH_2', 'STM_1_CH_3', 'STM_2_CH_0', 'STM_2_CH_1', 'STM_2_CH_2', 'STM_2_CH_3', 'PIT_0_CH_0', 'PIT_0_CH_1', 'PIT_0_CH_2', 'PIT_0_CH_3', 'PIT_1_CH_0', 'PIT_1_CH_1', 'PIT_1_CH_2', 'PIT_1_CH_3', 'PIT_2_CH_0', 'PIT_2_CH_1', 'PIT_2_CH_2', 'PIT_2_CH_3', 'EMIOS_0_CH_0', 'EMIOS_0_CH_1', 'EMIOS_0_CH_2', 'EMIOS_0_CH_3', 'EMIOS_0_CH_4', 'EMIOS_0_CH_5', 'EMIOS_0_CH_6', 'EMIOS_0_CH_7', 'EMIOS_0_CH_8', 'EMIOS_0_CH_16', 'EMIOS_0_CH_22', 'EMIOS_0_CH_23', 'EMIOS_1_CH_0', 'EMIOS_1_CH_8', 'EMIOS_1_CH_16', 'EMIOS_1_CH_22', 'EMIOS_1_CH_23', 'EMIOS_2_CH_0', 'EMIOS_2_CH_8', 'EMIOS_2_CH_16', 'EMIOS_2_CH_22', 'EMIOS_2_CH_23', 'RTC_0_CH_0', 'STM_0_PREDEF', 'STM_1_PREDEF', 'STM_2_PREDEF'] |

4.45 Parameter GptIsrEnable

Enable/Disable HW channels' Interrupt Sources.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-POST-BUILD: PRE-COMPILE |
| | VARIANT-PRE-COMPILE: PRE-COMPILE |
| default Value | false |

4.46 Parameter GptChannelsUsed

This column configures HW channels which are going to be used.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-POST-BUILD: PRE-COMPILE |
| | VARIANT-PRE-COMPILE: PRE-COMPILE |
| default Value | false |

4.47 Container GptConfigurationOfOptApiServices

This container contains all configuration switches for configuring optional API services of the GPT driver.

Included subcontainers:

- None

| Property | Value |
|----------|-------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |

| Property | Value |
|------------------------------|-------|
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |

4.48 Parameter GptDeinitApi

Adds / removes the service Gpt_DeInit() from the code.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | AUTOSAR_ECUC |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |
| defaultValue | true |

4.49 Parameter GptEnableDisableNotificationApi

Adds / removes the services Gpt_EnableNotification() and Gpt_DisableNotification from the code.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | AUTOSAR_ECUC |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |
| defaultValue | true |

4.50 Parameter GptTimeElapsedApi

Adds / removes the service Gpt_GetTimeElapsed() from the code.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | AUTOSAR_ECUC |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |
| defaultValue | true |

4.51 Parameter GptTimeRemainingApi

Adds / removes the service Gpt_GetTimeRemaining() from the code.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | AUTOSAR_ECUC |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |
| defaultValue | true |

4.52 Parameter GptVersionInfoApi

Adds / removes the service Gpt_GetVersionInfo() from the code.

| Property | Value |
|----------|------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |

| Property | Value |
|------------------------------|---|
| origin | AUTOSAR_ECUC |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE VARIANT-POST-BUILD: PRE-COMPILE |
| defaultValue | false |

4.53 Parameter GptWakeupFunctionalityApi

Adds / removes the services Gpt_SetMode(), Gpt_EnableWakeup() Gpt_DisableWakeup() and Gpt_Cbk_CheckWakeup() from the code.

| Property | Value |
|------------------------------|---|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | AUTOSAR_ECUC |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE VARIANT-POST-BUILD: PRE-COMPILE |
| defaultValue | true |

4.54 Parameter GptPredefTimerFunctionalityApi

Adds / removes the services Gpt_SetMode(), Gpt_EnableWakeup() Gpt_DisableWakeup() and Gpt_Cbk_CheckWakeup() from the code.

| Property | Value |
|-------------------|------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |

| Property | Value |
|------------------------------|----------------------------------|
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |
| default Value | true |

4.55 Container GptAutosarExt

Enabling the settings of this section will configure the driver in a mode not compliant with AUTOSAR requirements.

Included subcontainers:

- None

| Property | Value |
|------------------------------|-------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |

4.56 Parameter GptEnableDualClockMode

Enables prescaler settings at mode transition.true: Enabled.false: Disabled.

Note This feature is not required by Autosar.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |
| default Value | false |

4.57 Parameter GptChangeNextTimeoutValueApi

Vendor specific: Enables settings for changing the channel counter compare value of a running counter.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |
| defaultValue | false |

4.58 Parameter GptEnableUserModeSupport

When this parameter is enabled, the GPT module will adapt to run from User Mode. There is no difference between User mode and Privileged mode in GPT module.

Note: Implementation Specific Parameter.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |
| defaultValue | false |

4.59 Parameter ChainModeApi

Vendor specific: Enable/disable API for Chain Mode support.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |
| default Value | false |

4.60 Parameter GptStandbyWakeupSupport

The driver shall NOT CLEAR the interrupt flag, the interrupt enable bit and also should not disable the counter, during init (Gpt_SRtc_Init()) the flag is already set.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |
| default Value | false |

4.61 Container GptDriverConfiguration

This container contains the module-wide configuration (parameters) of the GPT Driver.

Included subcontainers:

- [GptClockReferencePoint](#)

| Property | Value |
|------------------------------|-------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |

4.62 Parameter GptDevErrorDetect

Enables/Disables development error detection.

| Property | Value |
|------------------------------|---|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | AUTOSAR_ECUC |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE VARIANT-POST-BUILD: PRE-COMPILE |
| defaultValue | false |

4.63 Parameter GptPredefTimer100us32bitEnable

Enables/Disables the feature 100us/ tick

| Property | Value |
|------------------------------|---|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | AUTOSAR_ECUC |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-POST-BUILD: PRE-COMPILE VARIANT-PRE-COMPILE: PRE-COMPILE |
| defaultValue | false |

4.64 Parameter GptMulticoreSupport

Enables/Disables Multicore Support.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |
| defaultValue | false |

4.65 Parameter GptPredefTimer1usEnablingGrade

Specifies the grade of enabling the GPT Predef Timers with 1us tick duration.

| Property | Value |
|------------------------------|--|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | AUTOSAR_ECUC |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-POST-BUILD: PRE-COMPILE |
| | VARIANT-PRE-COMPILE: PRE-COMPILE |
| defaultValue | GPT_PREDEF_TIMER_1US_DISABLED |
| literals | ['GPT_PREDEF_TIMER_1US_16BIT_ENABLED', 'GPT_PREDEF_TIMER_1US_16_24BIT_ENABLED', 'GPT_PREDEF_TIMER_1US_16_24_32BIT_ENABLED', 'GPT_PREDEF_TIMER_1US_DISABLED'] |

4.66 Parameter GptTimeoutMethod

GptTimeoutMethod: Configures the timeout method.

Based on this selection a certain timeout method from OsIf will be used in the driver.

Note: If SystemTimer or CustomTimer are selected make sure the corresponding timer is enabled in OsIf General configuration.

Note: Implementation Specific Parameter.

| Property | Value |
|------------------------------|--|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |
| defaultValue | OSIF_COUNTER_DUMMY |
| literals | ['OSIF_COUNTER_SYSTEM', 'OSIF_COUNTER_CUSTOM', 'OSIF_COUNTER_DUMMY'] |

4.67 Parameter GptTimeoutDuration

The unit of measurement is given in number of microseconds. This is a timeout value which is used to wait till

- PIT_RTI_LDVAL is synchronized into the RTI clock domain

If the Status is not updated then after this timeout a runtime error will be reported.

This parameter is used for PitRti only

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-POST-BUILD: PRE-COMPILE |
| | VARIANT-PRE-COMPILE: PRE-COMPILE |
| defaultValue | 800 |
| max | 65535 |
| min | 1 |

4.68 Parameter GptReportWakeupSource

Enables/Disables wakeup source reporting.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | AUTOSAR_ECUC |
| symbolicNameValue | False |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |
| default Value | true |

4.69 Reference GptEcucPartitionRef

Maps the GPT driver to zero or multiple ECUC partitions to make the driver API available in the according partition. Depending on the addressed timer resource the interfaces operate as follows:

In case of partition local timer resources (n:1 mapping) the API operates as an independent instance in the according ECUC partition.

In case of global timer resources (1:m mapping) the API operates on the global timer resource either by protected access to the resource or by implementing an according kernel.

| Property | Value |
|------------------------------|--|
| type | ECUC-REFERENCE-DEF |
| origin | AUTOSAR_ECUC |
| lowerMultiplicity | 0 |
| upperMultiplicity | Infinite |
| postBuildVariantMultiplicity | true |
| multiplicityConfigClasses | VARIANT-POST-BUILD: PRE-COMPILE |
| | VARIANT-PRE-COMPILE: PRE-COMPILE |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-POST-BUILD: PRE-COMPILE |
| | VARIANT-PRE-COMPILE: PRE-COMPILE |
| requiresSymbolicNameValue | False |
| destination | /AUTOSAR/EcucDefs/EcuC/EcucPartitionCollection/EcucPartition |

4.70 Reference GptKernelEcucPartitionRef

Maps the GPT kernel to zero or one ECUC partitions to assign the driver kernel to a certain core. The ECUC partition referenced is a subset of the ECUC partitions where the GPT driver is mapped to.

| Property | Value |
|------------------------------|--|
| type | ECUC-REFERENCE-DEF |
| origin | AUTOSAR_ECUC |
| lowerMultiplicity | 0 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | true |
| multiplicityConfigClasses | VARIANT-POST-BUILD: PRE-COMPILE |
| | VARIANT-PRE-COMPILE: PRE-COMPILE |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-POST-BUILD: PRE-COMPILE |
| | VARIANT-PRE-COMPILE: PRE-COMPILE |
| requiresSymbolicNameValue | False |
| destination | /AUTOSAR/EcucDefs/EcuC/EcucPartitionCollection/EcucPartition |

4.71 Container GptClockReferencePoint

This container contains a parameter, which represents a reference to a container of the type McuClockReferencePoint (defined in module MCU).

Included subcontainers:

- None

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 1 |
| upperMultiplicity | Infinite |
| postBuildVariantMultiplicity | false |
| multiplicityConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |

4.72 Reference GptClockReference

Reference to a container of the type McuClockReferencePoint, to select an input clock.

| Property | Value |
|------------------------------|---|
| type | ECUC-REFERENCE-DEF |
| origin | AUTOSAR_ECUC |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-POST-BUILD: PRE-COMPILE |
| | VARIANT-PRE-COMPILE: PRE-COMPILE |
| requiresSymbolicNameValue | False |
| destination | /AUTOSAR/EcuDefs/Mcu/McuModuleConfiguration/McuClockSetting↔ Config/McuClockReferencePoint |

4.73 Container GptPredefTimerConfiguration

Container for configuring the Predefined Timer functionality.

Included subcontainers:

- [GptPredefTimer_1us_16Bit](#)
- [GptPredefTimer_1us_24Bit](#)
- [GptPredefTimer_1us_32Bit](#)
- [GptPredefTimer_100us_32Bit](#)

| Property | Value |
|------------------------------|-------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |

4.74 Container GptPredefTimer_1us_16Bit

This container contains the 1U_16BIT predef timer configuration (parameters) of the GPT Driver

Included subcontainers:

- None

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 0 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | false |
| multiplicityConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |

4.75 Parameter GptHwChannel

Vendor specific: Selects the physical GPT Channel. PIT not use for this feature

| Property | Value |
|------------------------------|--|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | STM_0_PREDEF |
| literals | ['STM_0_PREDEF', 'STM_1_PREDEF', 'STM_2_PREDEF'] |

4.76 Parameter GptChannelPrescaler

Vendor specific: The GPT module specific clock prescaler value.

Note with STM:

- STM prescaler should be between 1-256.

Note with EMIOS:

- EMIOS prescaler should be between 1-4

| Property | Value |
|----------|------------------------|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |

| Property | Value |
|------------------------------|----------------------------------|
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | 1 |
| max | 256 |
| min | 1 |

4.77 Parameter GptFreezeEnable

Vendor specific: Select to set Freeze enable for the hw resources.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | true |

4.78 Reference GptChannelClkSrcRef

Reference to the GptClockReferencePoint from which the channel clock is derived.

| Property | Value |
|------------------------------|--------------------|
| type | ECUC-REFERENCE-DEF |
| origin | NXP |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |

| Property | Value |
|---------------------------|--|
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| requiresSymbolicNameValue | False |
| destination | /AUTOSAR/EcuDefs/Gpt/GptDriverConfiguration/GptClockReferencePoint |

4.79 Container GptPredefTimer_1us_24Bit

This container contains the 1U_24BIT predef timer configuration (parameters) of the GPT Driver

Included subcontainers:

- None

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 0 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | false |
| multiplicityConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |

4.80 Parameter GptHwChannel

Vendor specific: Selects the physical GPT Channel.

| Property | Value |
|------------------------------|--|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | STM_0_PREDEF |
| literals | ['STM_0_PREDEF', 'STM_1_PREDEF', 'STM_2_PREDEF'] |

4.81 Parameter GptChannelPrescaler

Vendor specific: The GPT module specific clock prescaler value.

Note with STM:

- STM prescaler should be between 1-256.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | 1 |
| max | 256 |
| min | 1 |

4.82 Parameter GptFreezeEnable

Vendor specific: Select to set Freeze enable for the hw resources.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | true |

4.83 Reference GptChannelClkSrcRef

Reference to the GptClockReferencePoint from which the channel clock is derived.

| Property | Value |
|------------------------------|--|
| type | ECUC-REFERENCE-DEF |
| origin | NXP |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| requiresSymbolicNameValue | False |
| destination | /AUTOSAR/EcuDefs/Gpt/GptDriverConfiguration/GptClockReferencePoint |

4.84 Container GptPredefTimer__1us__32Bit

This container contains the predef timer configuration (parameters) of the GPT Driver

Included subcontainers:

- None

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 0 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | false |
| multiplicityConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |

4.85 Parameter GptHwChannel

Vendor specific: Selects the physical GPT Channel.

| Property | Value |
|----------|----------------------------|
| type | ECUC-ENUMERATION-PARAM-DEF |

| Property | Value |
|------------------------------|--|
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | STM_0_PREDEF |
| literals | ['STM_0_PREDEF', 'STM_1_PREDEF', 'STM_2_PREDEF'] |

4.86 Parameter GptChannelPrescaler

Vendor specific: The GPT module specific clock prescaler value.

Note with STM:

- STM prescaler should be between 1-256.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | 1 |
| max | 256 |
| min | 1 |

4.87 Parameter GptFreezeEnable

Vendor specific: Select to set Freeze enable for the hw resources.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| default Value | true |

4.88 Reference GptChannelClkSrcRef

Reference to the GptClockReferencePoint from which the channel clock is derived.

| Property | Value |
|------------------------------|---|
| type | ECUC-REFERENCE-DEF |
| origin | NXP |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| requiresSymbolicNameValue | False |
| destination | /AUTOSAR/EcucDefs/Gpt/GptDriverConfiguration/GptClockReferencePoint |

4.89 Container GptPredefTimer__100us__32Bit

This container contains the channel-wide configuration (parameters) of the GPT Driver

Included subcontainers:

- None

| Property | Value |
|----------|-------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |

| Property | Value |
|------------------------------|----------------------------------|
| lowerMultiplicity | 0 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | false |
| multiplicityConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: PRE-COMPILE |

4.90 Parameter GptHwChannel

Vendor specific: Selects the physical GPT Channel. PIT not use for this feature

| Property | Value |
|------------------------------|--|
| type | ECUC-ENUMERATION-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | STM_0_PREDEF |
| literals | ['STM_0_PREDEF', 'STM_1_PREDEF', 'STM_2_PREDEF'] |

4.91 Parameter GptChannelPrescaler

Vendor specific: The GPT module specific clock prescaler value.

Note with STM:

- STM prescaler should be between 1-256.

| Property | Value |
|------------------------------|------------------------|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |

| Property | Value |
|---------------------------|----------------------------------|
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | 1 |
| max | 256 |
| min | 1 |

4.92 Parameter GptFreezeEnable

Vendor specific: Select to set Freeze enable for the hw resources.

| Property | Value |
|------------------------------|----------------------------------|
| type | ECUC-BOOLEAN-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| defaultValue | true |

4.93 Reference GptChannelClkSrcRef

Reference to the GptClockReferencePoint from which the channel clock is derived.

| Property | Value |
|------------------------------|--|
| type | ECUC-REFERENCE-DEF |
| origin | NXP |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | true |
| valueConfigClasses | VARIANT-PRE-COMPILE: PRE-COMPILE |
| | VARIANT-POST-BUILD: POST-BUILD |
| requiresSymbolicNameValue | False |
| destination | /AUTOSAR/EcuDefs/Gpt/GptDriverConfiguration/GptClockReferencePoint |

4.94 Container CommonPublishedInformation

Common container, aggregated by all modules. It contains published information about vendor and versions.

Included subcontainers:

- None

| Property | Value |
|------------------------------|-------------------------------|
| type | ECUC-PARAM-CONF-CONTAINER-DEF |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |

4.95 Parameter ArReleaseMajorVersion

Major version number of AUTOSAR specification on which the appropriate implementation is based on.

| Property | Value |
|------------------------------|---|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-POST-BUILD: PUBLISHED-INFORMATION VARIANT-PRE-COMPILE: PUBLISHED-INFORMATION |
| defaultValue | 4 |
| max | 4 |
| min | 4 |

4.96 Parameter ArReleaseMinorVersion

Minor version number of AUTOSAR specification on which the appropriate implementation is based on.

| Property | Value |
|----------|------------------------|
| type | ECUC-INTEGER-PARAM-DEF |

| Property | Value |
|------------------------------|--|
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-POST-BUILD: PUBLISHED-INFORMATION |
| | VARIANT-PRE-COMPILE: PUBLISHED-INFORMATION |
| defaultValue | 7 |
| max | 7 |
| min | 7 |

4.97 Parameter ArReleaseRevisionVersion

Revision version number of AUTOSAR specification on which the appropriate implementation is based on.

| Property | Value |
|------------------------------|--|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-POST-BUILD: PUBLISHED-INFORMATION |
| | VARIANT-PRE-COMPILE: PUBLISHED-INFORMATION |
| defaultValue | 0 |
| max | 0 |
| min | 0 |

4.98 Parameter ModuleId

Module ID of this module from Module List.

| Property | Value |
|-------------------|------------------------|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |

| Property | Value |
|------------------------------|--|
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-POST-BUILD: PUBLISHED-INFORMATION |
| | VARIANT-PRE-COMPILE: PUBLISHED-INFORMATION |
| defaultValue | 100 |
| max | 100 |
| min | 100 |

4.99 Parameter SwMajorVersion

Major version number of the vendor specific implementation of the module. The numbering is vendor specific.

| Property | Value |
|------------------------------|--|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-POST-BUILD: PUBLISHED-INFORMATION |
| | VARIANT-PRE-COMPILE: PUBLISHED-INFORMATION |
| defaultValue | 3 |
| max | 3 |
| min | 3 |

4.100 Parameter SwMinorVersion

Minor version number of the vendor specific implementation of the module. The numbering is vendor specific.

| Property | Value |
|-------------------|------------------------|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |

| Property | Value |
|------------------------------|--|
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-POST-BUILD: PUBLISHED-INFORMATION |
| | VARIANT-PRE-COMPILE: PUBLISHED-INFORMATION |
| defaultValue | 0 |
| max | 0 |
| min | 0 |

4.101 Parameter SwPatchVersion

Patch level version number of the vendor specific implementation of the module. The numbering is vendor specific.

| Property | Value |
|------------------------------|--|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-POST-BUILD: PUBLISHED-INFORMATION |
| | VARIANT-PRE-COMPILE: PUBLISHED-INFORMATION |
| defaultValue | 0 |
| max | 0 |
| min | 0 |

4.102 Parameter VendorApiInfix

In driver modules which can be instantiated several times on a single ECU, BSW00347 requires that the name of APIs is extended by the VendorId and a vendor specific name.

This parameter is used to specify the vendor specific name. In total, the implementation specific name is generated as follows:

<ModuleName>_>VendorId>_<VendorApiInfix>.

E.g. assuming that the VendorId of the implementor is 123 and the implementer chose a VendorApiInfix of "v11r456" a api name Can_Write defined in the SWS will translate to Can_123_v11r456Write.

This parameter is mandatory for all modules with upper multiplicity > 1. It shall not be used for modules with upper multiplicity =1.

| Property | Value |
|------------------------------|--|
| type | ECUC-STRING-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 0 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | false |
| multiplicityConfigClasses | VARIANT-POST-BUILD: PUBLISHED-INFORMATION |
| | VARIANT-PRE-COMPILE: PUBLISHED-INFORMATION |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-POST-BUILD: PUBLISHED-INFORMATION |
| | VARIANT-PRE-COMPILE: PUBLISHED-INFORMATION |
| defaultValue | |

4.103 Parameter VendorId

Vendor ID of the dedicated implementation of this module according to the AUTOSAR vendor list.

| Property | Value |
|------------------------------|--|
| type | ECUC-INTEGER-PARAM-DEF |
| origin | NXP |
| symbolicNameValue | false |
| lowerMultiplicity | 1 |
| upperMultiplicity | 1 |
| postBuildVariantMultiplicity | N/A |
| multiplicityConfigClasses | N/A |
| postBuildVariantValue | false |
| valueConfigClasses | VARIANT-POST-BUILD: PUBLISHED-INFORMATION |
| | VARIANT-PRE-COMPILE: PUBLISHED-INFORMATION |
| defaultValue | 43 |
| max | 43 |
| min | 43 |



Chapter 5

Module Index

5.1 Software Specification

Here is a list of all modules:

| | |
|----------------------|----|
| Emios IPL | 66 |
| Gpt Driver | 69 |
| Pit IPL | 79 |
| Rtc IPL | 81 |
| Stm IPL | 84 |

Chapter 6

Module Documentation

6.1 Emios IPL

6.1.1 Detailed Description

Data Structures

- struct [Emios_Gpt_Ip_ChannelConfigType](#)
Structure to configure the EMIOS. [More...](#)
- struct [Emios_Gpt_Ip_State](#)
internal context structure [More...](#)

Types Reference

- typedef void(* [Emios_Gpt_Ip_CallbackType](#)) (uint8 callbackParam)
Callback type for each channel.

Enum Reference

- enum [Emios_Gpt_Ip_ChannelModeType](#)
Prescaler type. Indicates of whether the clock channel mode is "NORMAL" or "ALTERNATE".

6.1.2 Data Structure Documentation

6.1.2.1 struct [Emios_Gpt_Ip_ChannelConfigType](#)

Structure to configure the EMIOS.

This structure holds the configuration settings for the ChannelConfigType

Definition at line 128 of file [Emios_Gpt_Ip_Types.h](#).

Data Fields

| Type | Name | Description |
|--|-----------------|---|
| boolean | stopInDebugMode | Allows the timer counter to be stopped in debug mode. |
| uint8 | clockPrescaler | Clock divide value for the clockPrescaler |
| uint8 | hwChannel | Timer channel number |
| Emios_Gpt_Ip_CallbackType | callback | callback |
| uint8 | callbackParam | callbackParam |
| Emios_Gpt_Ip_ChannelModeType | channelMode | channelMode |

6.1.2.2 struct Emios_Gpt_Ip_State

internal context structure

This structure is used by the IPL driver for internal logic. The content is populated on InitChannel

Definition at line 147 of file Emios_Gpt_Ip_Types.h.

Data Fields

| Type | Name | Description |
|--|-------------------------|--|
| boolean | chInit | chInit |
| Emios_Gpt_Ip_CallbackType | callback | callback |
| uint8 | callbackParam | callbackParam |
| uint8 | clockPrescaler | Clock divide value for the NormalPrescaler |
| uint8 | clockAlternatePrescaler | Clock divide value for the AlternatePrescaler. |
| Emios_Gpt_Ip_ChannelModeType | channelMode | channelMode |

6.1.3 Types Reference**6.1.3.1 Emios_Gpt_Ip_CallbackType**

```
typedef void(* Emios_Gpt_Ip_CallbackType) (uint8 callbackParam)
```

Callback type for each channel.

[Emios_Gpt_Ip_CallbackType](#)

Definition at line 120 of file Emios_Gpt_Ip_Types.h.

6.1.4 Enum Reference

6.1.4.1 Emios_Gpt_Ip_ChannelModeType

enum `Emios_Gpt_Ip_ChannelModeType`

Prescaler type. Indicates of whether the clock channel mode is "NORMAL" or "ALTERNATE".

This enumeration specifies the possible types of prescalers used to configure base-clock timers

Channel mode type. Indicates of whether the channel mode is "CONTINUOUS" or "ONE SHOT".

ChannelModeType of channel.

Enumerator

| | |
|---------------------------------|--------------------------------|
| EMIOS_GPT_IP_CH_MODE_CONTINUOUS | channel mode - continuous mode |
| EMIOS_GPT_IP_CH_MODE_ONESHOT | channel mode - one-shot mode. |

Definition at line 107 of file `Emios_Gpt_Ip_Types.h`.

6.2 Gpt Driver

6.2.1 Detailed Description

Macros

- `#define GPT_E_PARAM_CHANNEL`
Function Gpt_StartTimer is called when the driver is in sleep mode for a channel which is not wakeup enabled.
- `#define GPT_E_BUSY`
Function called with parameter value out of range.
- `#define GPT_E_TIMEOUT`
Function called when a timeout is occurred.
- `#define GPT_E_PARAM_CONFIG`
Function called with invalid the parameter in function Gpt_Init.
- `#define GPT_STARTTIMER_ID`
API service ID for Gpt_GetVersionInfo function.
- `#define GPT_PROCESSCOMMONINTERRUPT_ID`
API service ID for Gpt_StopTimer function.
- `#define GPT_INSTANCE_ID`
API service ID for Gpt_ChangeNextTimeoutValue function.
- `#define GPT_VALIDATE_GLOBAL_CALL`
GPT_VALIDATE_GLOBAL_CALL.
- `#define GPT_VALIDATE_CHANNEL_CALL`
GPT_VALIDATE_CHANNEL_CALL.
- `#define GPT_VALIDATE_STATE`
GPT_VALIDATE_STATE.
- `#define GPT_VALIDATE_PARAM`
GPT_VALIDATE_PARAM.

Types Reference

- `typedef uint8 Gpt_ChannelType`
Prescaler type. Indicates of whether the clock channel mode is "GPT_NORMAL" or "GPT_ALTERNATE".

Enum Reference

- `enum Gpt_ModeType`
This enumerated type allows the selection of different power modes.
- `enum Gpt_ChannelModeType`
Gpt channel mode type. Indicates of whether the channel mode is "CONTINUOUS" or "ONE SHOT".

Function Reference

- void [Gpt_Init](#) (const Gpt_ConfigType *configPtr)
GPT driver initialization function.
- void [Gpt_StartTimer](#) ([Gpt_ChannelType](#) channel, Gpt_ValueType value)
GPT driver function for starting a timer channel.
- void [Gpt_StopTimer](#) ([Gpt_ChannelType](#) channel)
GPT driver function for stopping a timer channel.
- void [Gpt_ProcessCommonInterrupt](#) (uint8 channel)
Gpt common handler to implements generic part of the ISR.

6.2.2 Macro Definition Documentation

6.2.2.1 GPT_E_PARAM_CHANNEL

```
#define GPT_E_PARAM_CHANNEL
```

Function [Gpt_StartTimer](#) is called when the driver is in sleep mode for a channel which is not wakeup enabled.

Errors and exceptions that will be detected by the GPT driver.

Function called without module initialization.

Errors and exceptions that will be detected by the GPT driver.

Initialization called when already initialized.

Errors and exceptions that will be detected by the GPT driver.

Function called for invalid channel.

Errors and exceptions that will be detected by the GPT driver.

Definition at line 172 of file Gpt.h.

6.2.2.2 GPT_E_BUSY

```
#define GPT_E_BUSY
```

Function called with parameter value out of range.

Errors and exceptions that will be detected by the GPT driver

Function called when timer channel is still running.

Errors and exceptions that will be detected by the GPT driver.

Definition at line 211 of file Gpt.h.

6.2.2.3 GPT_E_TIMEOUT

```
#define GPT_E_TIMEOUT
```

Function called when a timeout is occurred.

Errors and exceptions that will be detected by the GPT driver.

Definition at line 228 of file Gpt.h.

6.2.2.4 GPT_E_PARAM_CONFIG

```
#define GPT_E_PARAM_CONFIG
```

Function called with invalid the parameter in function Gpt_Init.

Errors and exceptions that will be detected by the GPT driver

API Gpt_SetClockMode service called with wrong parameter.

Parameters used when raising an error/exception

Function called with invalid mode param.

Errors and exceptions that will be detected by the GPT driver

function called for invalid channel on the current core

Errors and exceptions that will be detected by the GPT driver

Definition at line 264 of file Gpt.h.

6.2.2.5 GPT_STARTTIMER_ID

```
#define GPT_STARTTIMER_ID
```

API service ID for Gpt_GetVersionInfo function.

API SERVICE IDs

Parameters used when raising an error/exception

API service ID for Gpt_Init function

Parameters used when raising an error/exception

API service ID for Gpt_DeInit function

Parameters used when raising an error/exception

API service ID for Gpt_GetTimeElapsed function

Parameters used when raising an error/exception

API service ID for Gpt_GetTimeRemaining function

Parameters used when raising an error/exception

API service ID for Gpt_StartTimer function

Parameters used when raising an error/exception

Definition at line 311 of file Gpt.h.

6.2.2.6 GPT_PROCESSCOMMONINTERRUPT_ID

```
#define GPT_PROCESSCOMMONINTERRUPT_ID
```

API service ID for Gpt_StopTimer function.

Parameters used when raising an error/exception

API service ID for Gpt_SetMode function

Parameters used when raising an error/exception

API service ID for Gpt_ProcessCommonInterrupt generic ISR handler

Parameters used when raising an error/exception

Definition at line 372 of file Gpt.h.

6.2.2.7 GPT_INSTANCE_ID

```
#define GPT_INSTANCE_ID
```

API service ID for Gpt_ChangeNextTimeoutValue function.

Parameters used when raising an error/exception

API service ID for Gpt_SetClockMode function

Parameters used when raising an error/exception

API service ID for Gpt_GetPredefTimerValue function

Parameters used when raising an error/exception

API service ID for Gpt_Channel_EnableChainMode function

Parameters used when raising an error/exception

Instance ID of this GPT driver.

Definition at line 411 of file Gpt.h.

6.2.2.8 GPT_VALIDATE_GLOBAL_CALL

```
#define GPT_VALIDATE_GLOBAL_CALL
```

```
GPT_VALIDATE_GLOBAL_CALL.
```

Validates the global call uses all the channels - Gpt_Init, Gpt_DeInit, Gpt_SetMode.

Definition at line 72 of file Gpt_EnvCfg.h.

6.2.2.9 GPT_VALIDATE_CHANNEL_CALL

```
#define GPT_VALIDATE_CHANNEL_CALL
```

```
GPT_VALIDATE_CHANNEL_CALL.
```

Validates the call for a specific channel.

Definition at line 78 of file Gpt_EnvCfg.h.

6.2.2.10 GPT_VALIDATE_STATE

```
#define GPT_VALIDATE_STATE
```

```
GPT_VALIDATE_STATE.
```

Validates the channel status.

Definition at line 84 of file Gpt_EnvCfg.h.

6.2.2.11 GPT_VALIDATE_PARAM

```
#define GPT_VALIDATE_PARAM
```

```
GPT_VALIDATE_PARAM.
```

Validates the time value parameter.

Definition at line 90 of file Gpt_EnvCfg.h.

6.2.3 Types Reference

6.2.3.1 Gpt_ChannelType

```
typedef uint8 Gpt_ChannelType
```

Prescaler type. Indicates of whether the clock channel mode is "GPT_NORMAL" or "GPT_ALTERNATE".

This enumeration specifies the possible types of prescalers used to configure base-clock timers

Definition at line 459 of file Gpt.h.

6.2.4 Enum Reference

6.2.4.1 Gpt_ModeType

```
enum Gpt_ModeType
```

This enumerated type allows the selection of different power modes.

Modes of the GPT driver.

Enumerator

| | |
|-----------------|---------------------------------------|
| GPT_MODE_NORMAL | GPT Normal operation mode of the GPT. |
| GPT_MODE_SLEEP | GPT Sleep mode. |

Definition at line 422 of file Gpt.h.

6.2.4.2 Gpt_ChannelModeType

```
enum Gpt_ChannelModeType
```

Gpt channel mode type. Indicates of whether the channel mode is "CONTINUOUS" or "ONE SHOT".

ChannelModeType of channel.

Enumerator

| | |
|------------------------|-------------------------------------|
| GPT_CH_MODE_CONTINUOUS | GPT channel mode - continuous mode. |
| GPT_CH_MODE_ONESHOT | GPT channel mode - one-shot mode. |

Definition at line 432 of file Gpt.h.

6.2.5 Function Reference

6.2.5.1 Gpt_Init()

```
void Gpt_Init (
    const Gpt_ConfigType * configPtr )
```

GPT driver initialization function.

This service is a non reentrant function used for driver initialization. The Initialization function shall initialize all relevant registers of the configured hardware with the values of the structure referenced by the parameter ConfigPtr. All time units used within the API services of the GPT driver shall be of the unit ticks. This function shall only initialize the configured resources. Resources that are not configured in the configuration file shall not be touched. The following rules regarding initialization of controller registers shall apply to the GPT Driver implementation: [1] If the hardware allows for only one usage of the register, the driver module implementing that functionality is responsible for initializing the register [2] If the register can affect several hardware modules and if it is an IO register it shall be initialized by the PORT driver [3] If the register can affect several hardware modules and if it is not an IO register it shall be initialized by the MCU driver [4] One-time writable registers that require initialization directly after reset shall be initialized by the startup code [5] All other registers shall be initialized by the startup code

Parameters

| | | |
|----|------------------|---|
| in | <i>configPtr</i> | Pointer to a selected configuration structure |
|----|------------------|---|

Returns

void

Precondition

The data structure including the configuration set required for initializing the GPT driver..

6.2.5.2 Gpt_StartTimer()

```
void Gpt_StartTimer (
    Gpt_ChannelType channel,
    Gpt_ValueType value )
```

GPT driver function for starting a timer channel.

The function Gpt_StartTimer shall start the selected timer channel with a defined time-out period. The function Gpt_StartTimer shall invoke the configured notification for that channel (see also GPT292) after the time-out period referenced via the parameter value (if enabled). All time units used within the API services of the GPT driver shall be of the unit ticks. In production mode no error is generated. The rational is that it adds no additional functionality to the driver. In this case the timer will be restarted with the time-out value, given as a parameter to the service. Usage of re-entrant capability is only allowed if the callers take care that there is no simultaneous usage of the same channel. To get times out of register values it is necessary to know the oscillator frequency, pre-scalers and so on. Since these settings are made in MCU and(or) in other modules it is not possible to calculate such times. Hence the conversions between time and ticks shall be part of an upper layer. The driver needs to be initialized before calling [Gpt_StartTimer\(\)](#). Otherwise, the function Gpt_StartTimer shall raise the development error GPT_E_UNINIT.

Parameters

| | | |
|----|----------------|--|
| in | <i>channel</i> | channel id |
| in | <i>value</i> | time-out period (in number of ticks) after a notification or a wakeup event shall occur. |

Returns

void

Precondition

The driver needs to be initialized.

6.2.5.3 Gpt_StopTimer()

```
void Gpt_StopTimer (
    Gpt_ChannelType channel )
```

GPT driver function for stopping a timer channel.

Service for stopping the selected timer channel Stopping a timer channel, not been started before will not return a development error Timer channels configured in one shot mode are stopped automatically, when the time-out period has expired. Usage of re-entrant capability is only allowed if the callers take care that there is no simultaneous usage of the same channel. The driver needs to be initialized before calling [Gpt_StopTimer\(\)](#). Otherwise, the function shall raise the development error GPT_E_UNINIT.

Parameters

| | | |
|----|----------------|------------|
| in | <i>channel</i> | channel id |
|----|----------------|------------|

Returns

void

Precondition

The driver needs to be initialized. Gpt_StartTimer must be called before.

6.2.5.4 Gpt_ProcessCommonInterrupt()

```
void Gpt_ProcessCommonInterrupt (
    uint8 channel )
```

Gpt common handler to implements generic part of the ISR.

Generic function used by all interrupt service routines to call notification functions and wakeup the EcuM

Module Documentation

Parameters

| | | |
|----|----------------|----------------------|
| in | <i>channel</i> | logic channel number |
|----|----------------|----------------------|

Returns

void

Precondition

The driver needs to be initialized.

6.3 Pit IPL

6.3.1 Detailed Description

Enum Reference

- enum [Pit_Ip_StatusType](#)
Pit Status error.
- enum [Pit_Ip_ChannelModeType](#)
Channel mode type. Indicates of whether the channel mode is "CONTINUOUS" or "ONE SHOT".

6.3.2 Enum Reference

6.3.2.1 Pit_Ip_StatusType

enum [Pit_Ip_StatusType](#)

Pit Status error.

Status error

Enumerator

| | |
|----------------|--------------------------|
| PIT_IP_SUCCESS | Status value is SUCCESS. |
| PIT_IP_ERROR | Status value is ERROR |

Definition at line 107 of file Pit_Ip_Types.h.

6.3.2.2 Pit_Ip_ChannelModeType

enum [Pit_Ip_ChannelModeType](#)

Channel mode type. Indicates of whether the channel mode is "CONTINUOUS" or "ONE SHOT".

ChannelModeType of channel.

Enumerator

| | |
|---------------------------|-------------------------------|
| PIT_IP_CH_MODE_CONTINUOUS | hannel mode - continuous mode |
| PIT_IP_CH_MODE_ONESHOT | hannel mode - one-shot mode. |

Module Documentation

Definition at line 117 of file Pit_Ip_Types.h.

6.4 Rtc IPL

6.4.1 Detailed Description

Enum Reference

- enum [Rtc_Ip_ClockSelectType](#)
Enum containing the RTC module clock sources.
- enum [Rtc_Ip_InterruptType](#)
Enum containing RTC interrupt type.
- enum [Rtc_Ip_ModeType](#)
Enum containing RTC interrupt mode.
- enum [Rtc_Ip_StatusType](#)
Rtc Status error.
- enum [Rtc_Ip_ChannelModeType](#)
Channel mode type. Indicates of whether the channel mode is "CONTINUOUS" or "ONE SHOT".

6.4.2 Enum Reference

6.4.2.1 Rtc_Ip_ClockSelectType

enum [Rtc_Ip_ClockSelectType](#)

Enum containing the RTC module clock sources.

[Rtc_Ip_ClockSelectType](#)

Enumerator

| | |
|---|---------------------|
| RTC_IP_CLOCK_SOURCE↵ _0 | RTC clock source 0. |
| RTC_IP_CLOCK_SOURCE↵ _1 | RTC clock source 1. |
| RTC_IP_CLOCK_SOURCE↵ _2 | RTC clock source 2. |
| RTC_IP_CLOCK_SOURCE↵ _3 | RTC clock source 3. |

Definition at line 121 of file [Rtc_Ip_Types.h](#).

6.4.2.2 Rtc_Ip_InterruptType

enum [Rtc_Ip_InterruptType](#)

Enum containing RTC interrupt type.

Rtc_Ip_InterruptType

Enumerator

| | |
|---------------------------|-------------------------|
| RTC_IP_COUNTER_INTERRUPT | RTC_COUNTER_INTERRUPT |
| RTC_IP_API_INTERRUPT | RTC_API_INTERRUPT |
| RTC_IP_ROLLOVER_INTERRUPT | RTC_ROLLOVER_INTERRUPT. |

Definition at line 134 of file Rtc_Ip_Types.h.

6.4.2.3 Rtc_Ip_ModeType

```
enum Rtc_Ip_ModeType
```

Enum containing RTC interrupt mode.

Rtc_Ip_ModeType

Enumerator

| | |
|-----------------|---|
| RTC_IP_API_MODE | API(Autonomous periodic interrupt) Mode |
| RTC_IP_RTC_MODE | RTC Mode |

Definition at line 146 of file Rtc_Ip_Types.h.

6.4.2.4 Rtc_Ip_StatusType

```
enum Rtc_Ip_StatusType
```

Rtc Status error.

Status error

Enumerator

| | |
|----------------|--------------------------|
| RTC_IP_SUCCESS | Status value is SUCCESS. |
| RTC_IP_ERROR | Status value is ERROR |

Definition at line 157 of file Rtc_Ip_Types.h.

6.4.2.5 Rtc_Ip_ChannelModeType

enum [Rtc_Ip_ChannelModeType](#)

Channel mode type. Indicates of whether the channel mode is "CONTINUOUS" or "ONE SHOT".

ChannelModeType of channel.

Enumerator

| | |
|---------------------------|--------------------------------|
| RTC_IP_CH_MODE_CONTINUOUS | channel mode - continuous mode |
| RTC_IP_CH_MODE_ONESHOT | channel mode - one-shot mode. |

Definition at line 168 of file Rtc_Ip_Types.h.

6.5 Stm IPL

6.5.1 Detailed Description

Macros

- `#define GPT_STOP_SEC_CODE`
Stm_Ip_SetUserAccessAllowed.

Enum Reference

- enum `Stm_Ip_ChannelModeType`
Channel mode type. Indicates of whether the channel mode is "CONTINUOUS" or "ONE SHOT".

6.5.2 Macro Definition Documentation

6.5.2.1 GPT_STOP_SEC_CODE

```
#define GPT_STOP_SEC_CODE
```

`Stm_Ip_SetUserAccessAllowed.`

This function is called externally by OS Application

Parameters

| | | |
|----|--------------------|----------------------------|
| in | <i>StmBaseAddr</i> | - The base address of Stm. |
|----|--------------------|----------------------------|

Definition at line 117 of file `Stm_Ip_TrustedFunctions.h`.

6.5.3 Enum Reference

6.5.3.1 Stm_Ip_ChannelModeType

```
enum Stm_Ip_ChannelModeType
```

Channel mode type. Indicates of whether the channel mode is "CONTINUOUS" or "ONE SHOT".

ChannelModeType of channel.

Enumerator

| | |
|---------------------------|--------------------------------|
| STM_IP_CH_MODE_CONTINUOUS | channel mode - continuous mode |
| STM_IP_CH_MODE_ONESHOT | channel mode - one-shot mode. |

Definition at line 119 of file Stm_Ip_Types.h.

How to Reach Us:

Home Page:

nxp.com

Web Support:

nxp.com/support

Information in this document is provided solely to enable system and software implementers to use NXP products. There are no express or implied copyright licenses granted hereunder to design or fabricate any integrated circuits based on the information in this document. NXP reserves the right to make changes without further notice to any products herein.

NXP makes no warranty, representation, or guarantee regarding the suitability of its products for any particular purpose, nor does NXP assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters that may be provided in NXP data sheets and/or specifications can and do vary in different applications, and actual performance may vary over time. All operating parameters, including "typicals," must be validated for each customer application by customer's technical experts. NXP does not convey any license under its patent rights nor the rights of others. NXP sells products pursuant to standard terms and conditions of sale, which can be found at the following address: nxp.com/SalesTermsandConditions.

NXP, the NXP logo, NXP SECURE CONNECTIONS FOR A SMARTER WORLD, COOLFLUX, EMBRACE, GREENCHIP, HITAG, I2C BUS, ICODE, JCOP, LIFE VIBES, MIFARE, MIFARE CLASSIC, MIFARE DESFire, MIFARE PLUS, MIFARE FLEX, MANTIS, MIFARE ULTRALIGHT, MIFARE4MOBILE, MIGLO, NTAG, ROADLINK, SMARTLX, SMARTMX, STARPLUG, TOPFET, TRENCHMOS, UCODE, Freescale, the Freescale logo, Altivec, C-5, CodeTEST, CodeWarrior, ColdFire, ColdFire+, C-Ware, the Energy Efficient Solutions logo, Kinetis, Layerscape, MagniV, mobileGT, PEG, PowerQUICC, Processor Expert, QorIQ, QorIQ Qonverge, Ready Play, SafeAssure, the SafeAssure logo, StarCore, Symphony, VortiQa, Vybrid, Airfast, BeeKit, BeeStack, CoreNet, Flexis, MXC, Platform in a Package, QUICC Engine, SMARTMOS, Tower, TurboLink, and UMEMS are trademarks of NXP B.V. All other product or service names are the property of their respective owners. ARM, AMBA, ARM Powered, Artisan, Cortex, Jazelle, Keil, SecurCore, Thumb, TrustZone, and Vision are registered trademarks of ARM Limited (or its subsidiaries) in the EU and/or elsewhere. ARM7, ARM9, ARM11, big.LITTLE, CoreLink, CoreSight, DesignStart, Mali, mbed, NEON, POP, Sensinode, Socrates, ULINK and Versatile are trademarks of ARM Limited (or its subsidiaries) in the EU and/or elsewhere. All rights reserved. Oracle and Java are registered trademarks of Oracle and/or its affiliates. The Power Architecture and Power.org word marks and the Power and Power.org logos and related marks are trademarks and service marks licensed by Power.org.

© 2023 NXP B.V.

