Experiment No. 10

10.1 Experiment Name

LED ON/OFF using 8253, 8255 & 8259

10.2 Objectives

- To get acquainted with the "MDA 8086" Trainer Board and its operation
- To understand working procedure of LED ON/OFF using 8253, 8255, and 8259
- To learn how to implement program in "MDA 8086" Trainer Board and interconnect it with "Emu 8086"

10.3 Theory

The **8255** is a **Programmable Peripheral Interface**, is a general purpose programmable I/O device designed to interface the CPU with its outside world such as ADC, DAC, keyboard etc.

On the contrary, the **8253** is a **Programmable Timer Interval IC** which are designed for microprocessors to perform timing and counting functions using three 16-bit registers.

The **8259** is a **Priority/Programmable Interrupt Control IC** which combines the multi-interrupt input sources into a single interrupt output.

For this experiment, in order to turn on or off the LEDs concurrently with the specified time delay, the 8086 will control the 8255 PPI. The 8255 PPI IC's Port B is linked to the LEDs in the following way:

Port name	LED no.
PB ₀	11
PB ₁	12
PB ₂	13
PB ₃	14

The LEDs will be on and off in the following sequence by turning on each separately,

LED-11(PB0) -- LED-12(PB1) -- LED-13(PB2) -- LED-14(PB3)

The MDA 8086 kit contains I/O mapped memory. So, to communicate with the peripherals, the commands "in" and "out" are needed. The 8255 PPI-CS-2 is used to connect the LEDs. So, port addresses for 8255, 8253 PTIC, and 8259 PICIC respectively are,

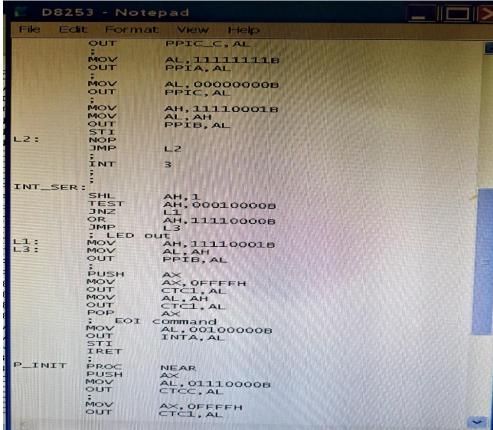
8255		8253		8259	
Port name	Port address	Port name	Port address	Port name	Port address
Port A	18H	Counter - 0	09H	INTA	10H
Port B	1AH	Counter - 1	0BH	(Command	
				Register)	
Port C	1CH	Counter - 2	0DH	INTA ₂ (Data	12H
Control register	1EH	Control register	0FH	Register)	

10.4 Apparatus

• MDA 8086 - Trainer Board

10.5 Code and Output as Z pattern

```
* MDE-8086 EXPERIMENT PROGRAM
* Chapter 8-4 (Example 1)
* PROGRAM BY MIDAS ENGINEER
File Edit Format View Help
                            FILENAME : D8253.ASM
PROCESSOR : I8086
VER. : V1.1
              SEGMENT
ASSUME
CODE
                            CS:CODE, DS:CODE, ES:CODE, SS:CODE
              EQU
EQU
PPIC_C
PPIC
PPIB
                            1FH
1DH
1BH
19H
              FOLL
PPIA
              EQU
              EQU
EQU
              EQU
EQU
INTA
INTA2
                            10H
INTA+2
INT_V
              ÉQU
                            40H*4
              ÓRG
                           1000H
              XOR
MOV
                            BX, BX
ES, BX
              ;
Mov
                            AX,OFFSET INT_SER
BX,INT_V
WORD PTR ES:[BX],AX
              MOV
              XOR
MOV
                           A\times, A\times WORD PTR ES:[B×+2], A\times
              CALL
CALL
MOV
OUT
                            INIT
P_INIT
                            AL,10000000B
PPIC_C,AL
              MOV
OUT
                            AL,11111111B
PPIA,AL
              MOV
                           AL,00000000B
```



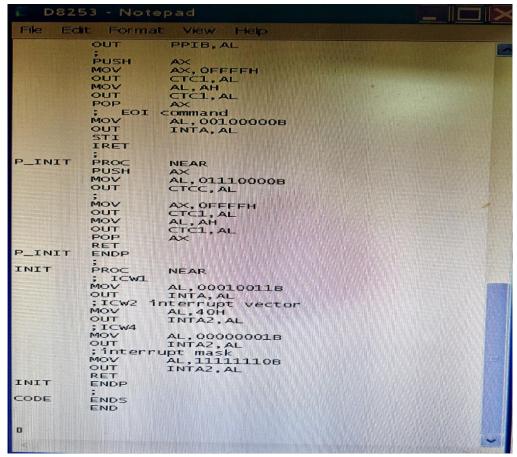


Fig. 9.1: Writing program on notepad



Fig. 9.2: Output

10.6 **Discussion & Conclusion**

In this experiment, we used code to perform the LED interfacing in 8255, 8253, and 8259. A program was developed in notepad and saved as '.asm' file, which was then translated to '.obj' and later into a '.abs' file. This was then executed and the output was observed using direct execution.

To turn ON and OFF each LED sequentially and concurrently with a predetermined interval, the 8253 PTI IC provided the necessary time delay and pushed the pin IR0 of the 8259 PIC IC with an interrupt. The 8255 PPI IC, which is coupled to the LEDs, was managed by the 8086, which received this interrupt. The 8086, which was in charge of the associated 8255 LEDs, lighted them up one at a time while maintaining the required time delay.

Thus, the experiment was a success.