

Static & Dynamic Characteristics of Instruments

iitdelhi



P M V Subbarao

Professor

Mechanical Engineering Department

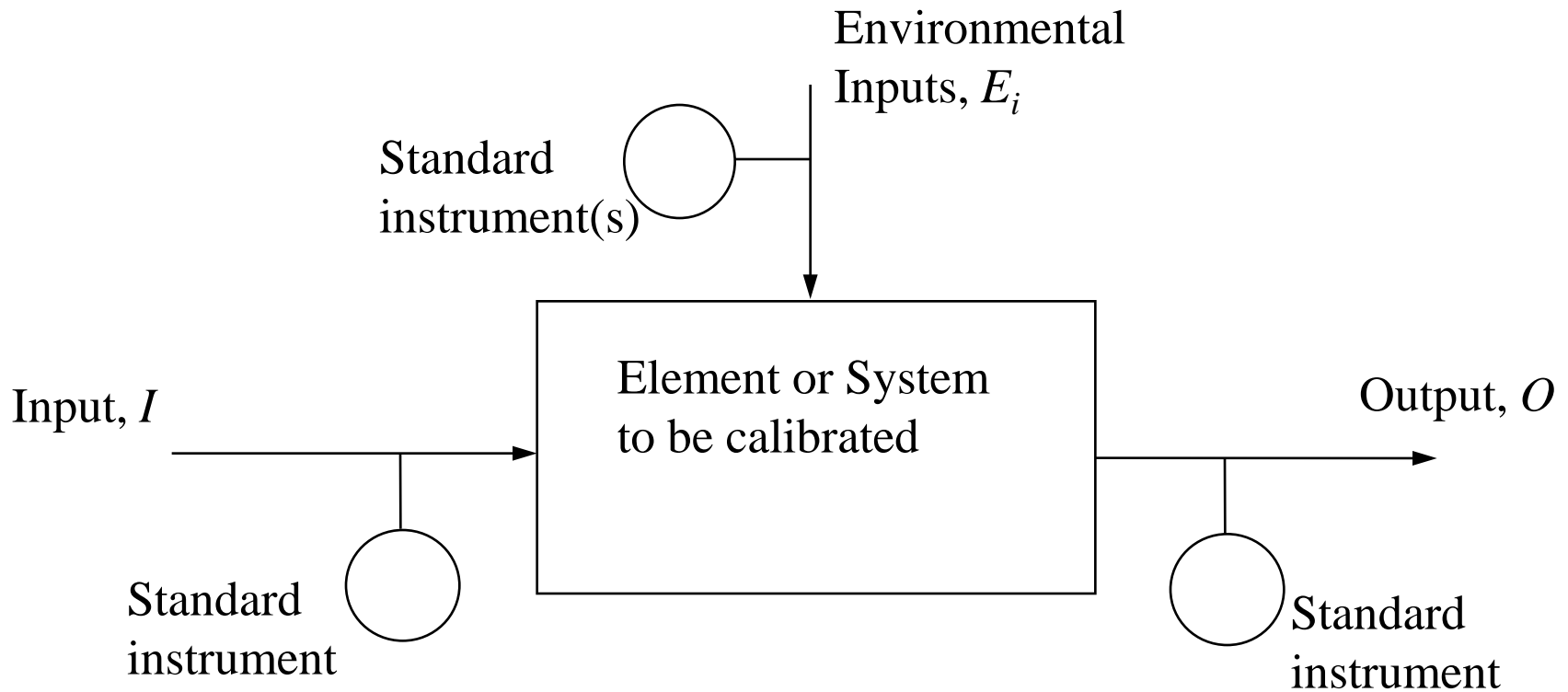
A Step Towards Design of Instruments....

Characteristics of measurement systems

- The system characteristics are to be known, to choose an instrument that most suited to a particular measurement application.
- The performance characteristics may be broadly divided into two groups, namely '*static*' and '*dynamic*' characteristics.
- **Static characteristics**
 - the performance criteria for the measurement of quantities that remain constant, or vary only quite slowly.
- **Dynamic characteristics**
 - the relationship between the system input and output when the measured quantity (measurand) is varying rapidly.

Static characteristics

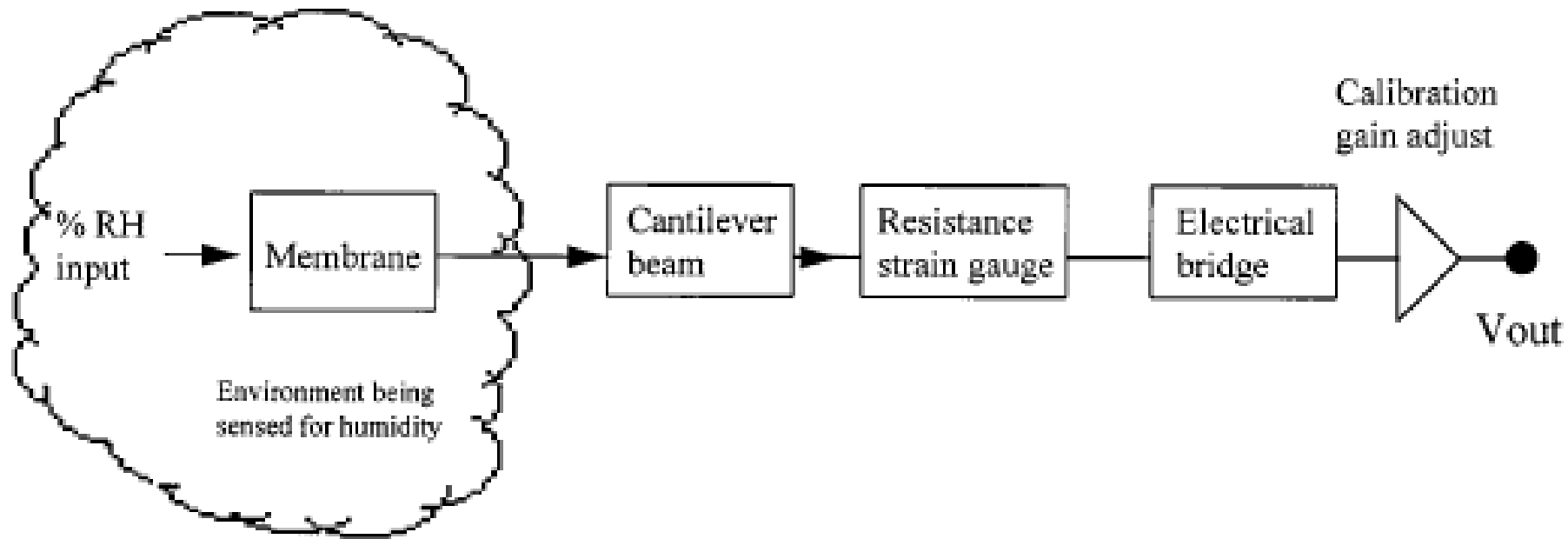
Determination of static characteristics is mostly done by calibration:



Static and Dynamic Characteristics

- Instrument systems are usually built up from a serial linkage of distinguishable building blocks.
- The actual physical assembly may not appear to be so but it can be broken down into a representative diagram of connected blocks.
- The sensor is activated by an input physical parameter and provides an output signal to the next block that processes the signal into a more appropriate state.
- A fundamental characterization of a block is to develop a relationship between the input and output of the block.
- All signals have a time characteristic.
- It is essential to consider the behavior of a block in terms of both the static and dynamic states.
- The behavior of the static regime alone and the combined static and dynamic regime can be found through use of an appropriate mathematical model of each block.

Instruments formed from a connection of blocks.



The output/input ratio of the whole cascaded chain of blocks 1, 2, 3, etc. is given as:

$$\left[\frac{\textit{output}}{\textit{input}} \right]_{total} = \left[\frac{\textit{output}}{\textit{input}} \right]_1 \times \left[\frac{\textit{output}}{\textit{input}} \right]_2 \times \left[\frac{\textit{output}}{\textit{input}} \right]_3 \dots$$

The output/input ratio of a block that includes both the static and dynamic characteristics is called the *transfer function* and is given the symbol G .

$$G_{total} = G_1 \times G_2 \times G_3 \dots$$

$$G_{total} = \prod_{i=1}^n G_i$$

The equation for G_i can be written as two parts multiplied together.

$$G_i = [Static \times dynamic]_i$$

- One expresses the static behavior of the block, that is, the value it has after all transient (time varying) effects have settled to their final state.
- The other part tells us how that value responds when the block is in its dynamic state.
- The static part is known as the *transfer characteristic* and is often all that is needed to be known for block description.
- The static and dynamic response of the cascade of blocks is simply the multiplication of all individual blocks.

- As each block has its own part for the static and dynamic behavior, the cascade equations can be rearranged to separate the static from the dynamic parts.

$$G_{total} = [Static \times dynamic]_1 \times [Static \times dynamic]_2 \times [Static \times dynamic]_3 \dots$$

- Multiplying the static set and the dynamic set gets the overall response in the static and dynamic states.

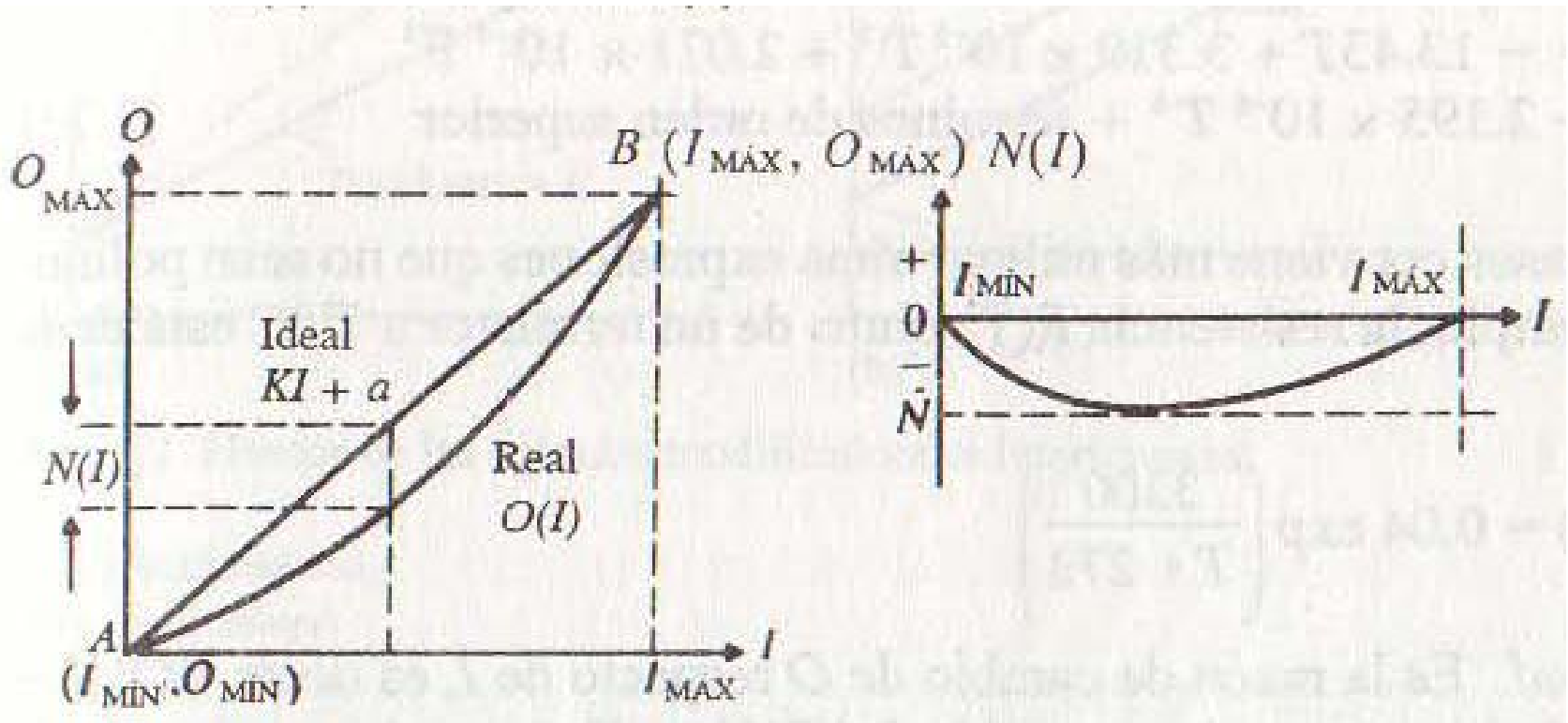
$$G_{total} = [Static_1 \times Static_2 \times Static_3 \dots] \times [dynamic_1 \times dynamic_2 \times dynamic_3 \dots]$$

$$G_{total} = [Static]_{total} \times [dynamic]_{total}$$

Static Performance of Instrument

- The static characteristics of instruments are related with steady state response.
- The relationship between the output and the input when the input does not change, or the input is changing at a slow rate.
- Range & Span
- Linearity & Sensitivity
- Environmental effects
- Hysteresis
- Resolution
- Repeatability
- Death space

Linearity & Sensitivity

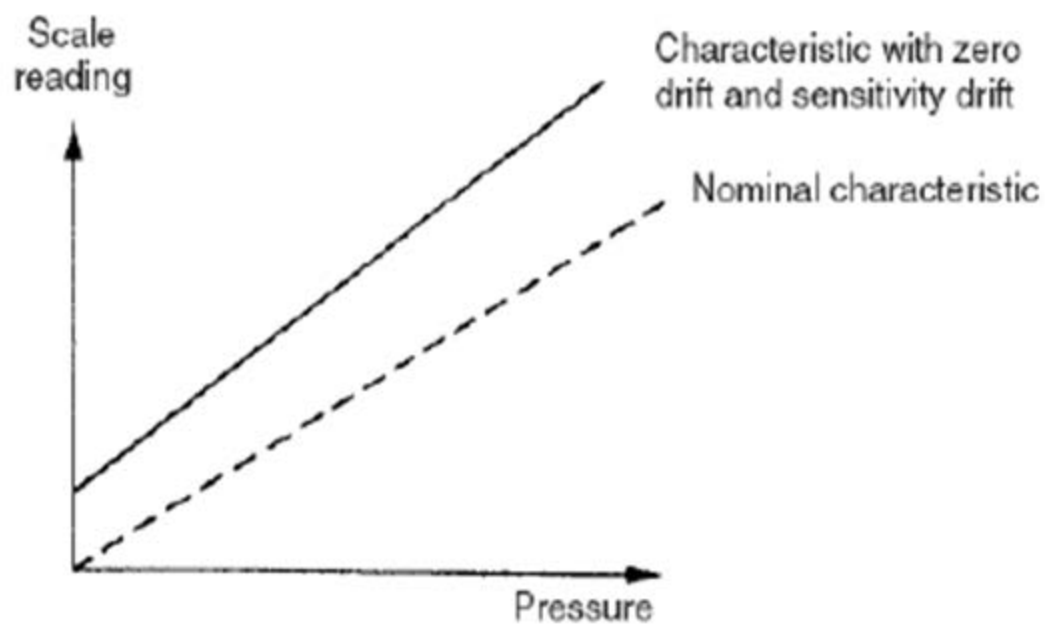
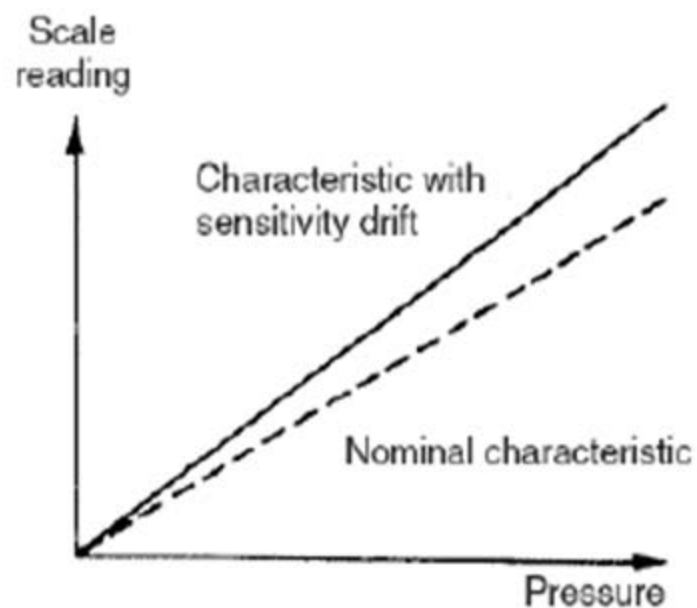
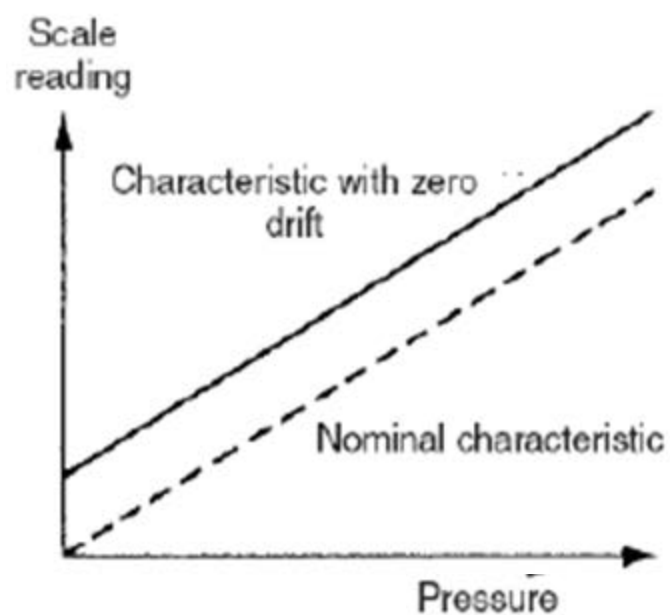


Environmental effects

- All calibrations and specifications of an instrument are only valid under controlled conditions of temperature, pressure etc.
- These standard ambient conditions are usually defined in the instrument specification.
- As variations occur in the ambient temperature, etc., certain static instrument characteristics change, and the sensitivity to disturbance is a measure of the magnitude of this change.
- Such environmental changes affect instruments in two main ways, known as zero drift and sensitivity drift.
- Zero drift is sometimes known by the alternative term, bias.

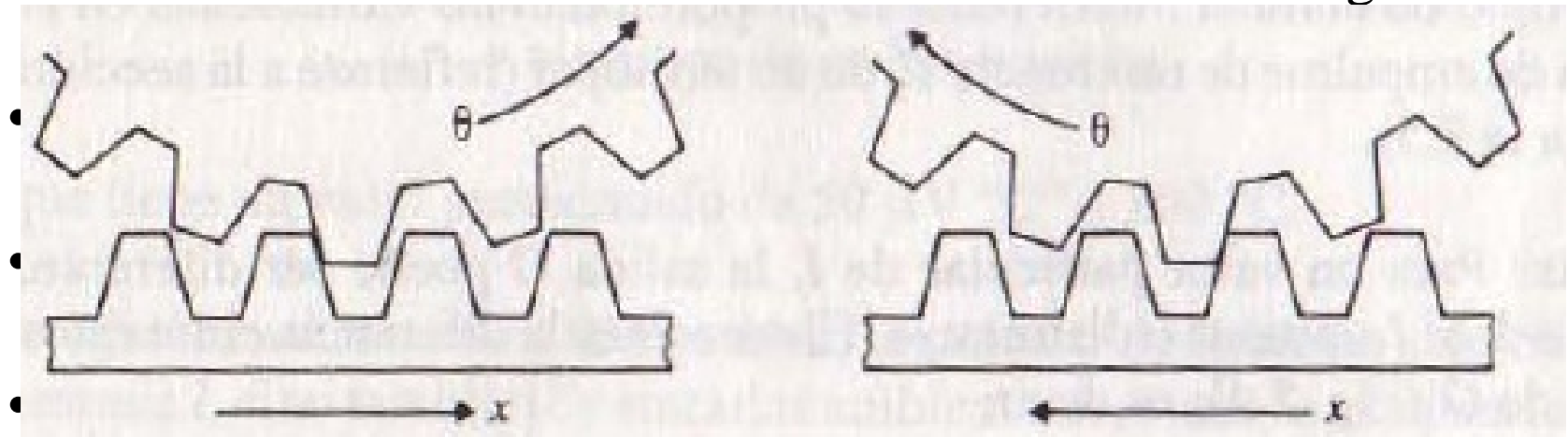
Instrument Drift

- This is caused by variations taking place in the parts of the instrumentation/environment over time.
- Prime sources occur as chemical structural changes and changing mechanical stresses.
- Drift is a complex phenomenon for which the observed effects are that the sensitivity and offset values vary.
- It also can alter the accuracy of the instrument differently at the various amplitudes of the signal present.

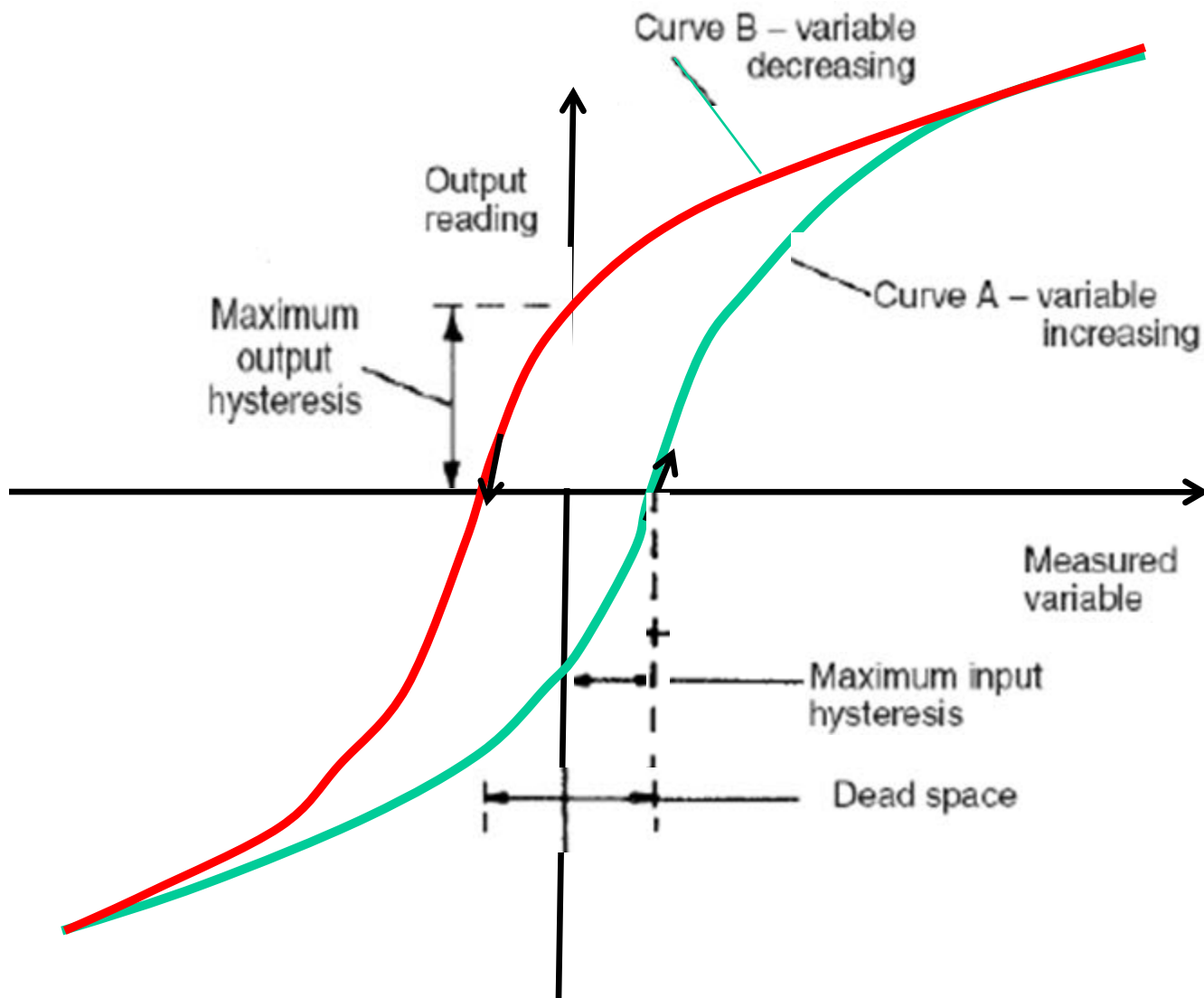


Hysteresis and Backlash

- Careful observation of the output/input relationship of a block will sometimes reveal different results as the signals



- Where this is caused by a mechanism that gives a sharp change, such as caused by the looseness of a joint in a mechanical joint, it is easy to detect and is known as *backlash*.



Repeatability

Repeatability: a measure of how well the output returns to a given value when the same precise input is applied several times.

Or the ability of an instrument to reproduce a certain set of reading within a given accuracy.

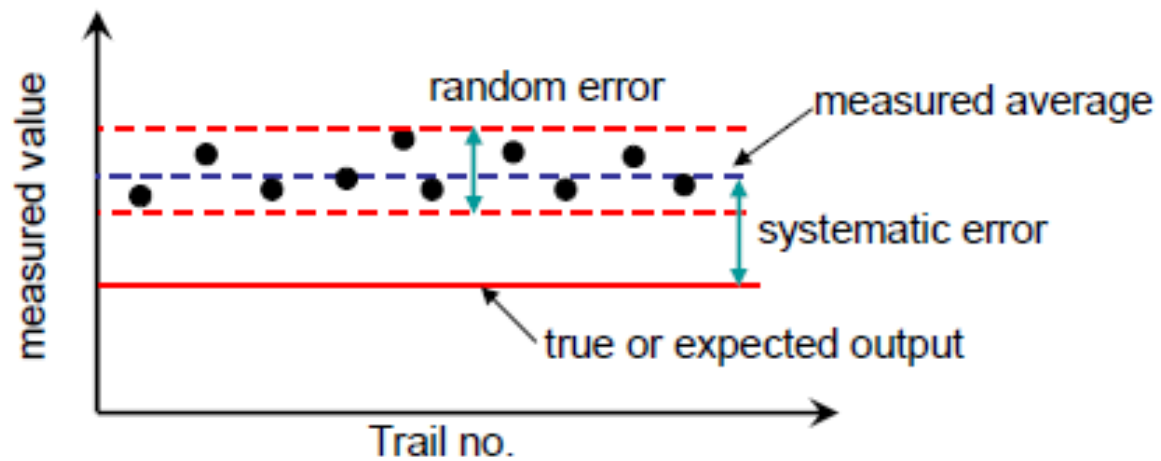
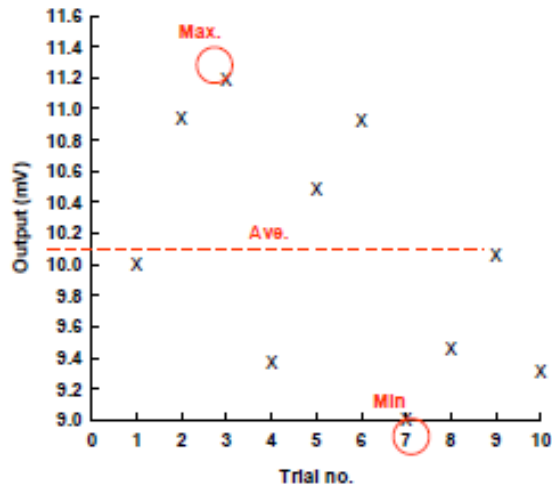
Precision: how exactly and reproducibly an unknown value is measured

$$\text{repeatability} = \frac{\text{maximum} - \text{minimum}}{\text{full scale}} \times 100\%$$

$$\text{repeatability} = \frac{\text{largest deviation} - \text{average}}{\text{full scale}} \times 100\%$$

Load cell A

- Global accurate but not repeatable



Death Space : Threshold

Dead space is defined as the range of different input values over which there is no change in output value.

