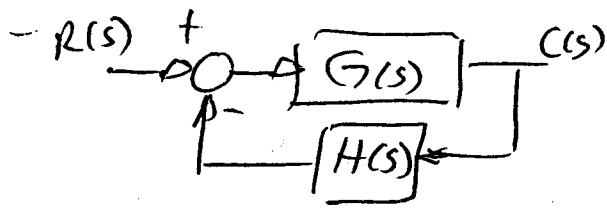


EEL 3657 HARALAMBOS NYQUIST DIAGRAM SUMMARY.

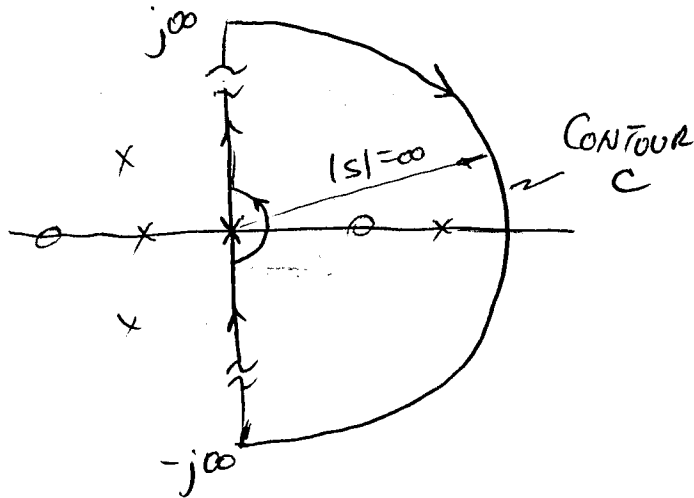
OBJECTIVE: USE THE NYQUIST DIAGRAM TO DETERMINE CLOSED-LOOP SYSTEM STABILITY.



$$\frac{C(s)}{R(s)} = \frac{G(s)}{1+G(s)H(s)}$$

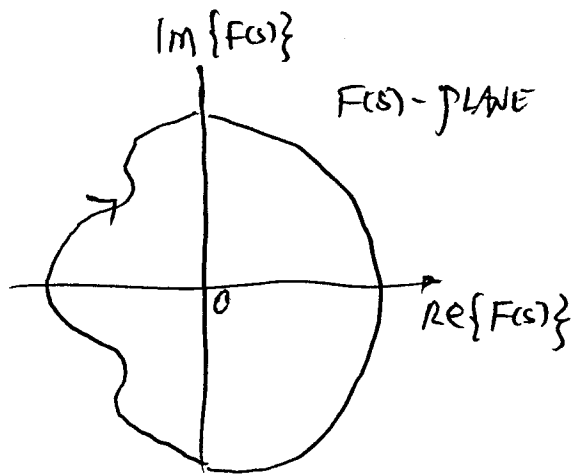
$$\begin{aligned} \text{LET } F(s) &\triangleq 1+G(s)H(s) \\ &= 1 + \frac{P(s)}{Q(s)} \end{aligned}$$

$$F(s) = \frac{P_1(s) + Q(s)}{Q(s)}$$

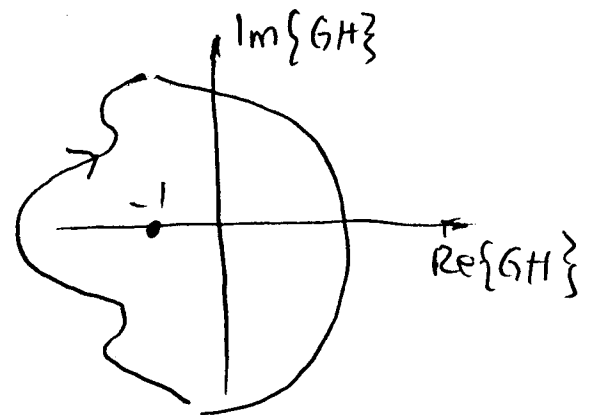


Z = # ZEROS OF $1+G(s)H(s)$ IN RHP
(= 0 FOR STABILITY)

P = # POLES OF $1+G(s)H(s)$ IN RHP
= # POLES OF $G(s)H(s)$ IN RHP.



$$G(s)H(s) = [1+G(s)H(s)] - 1$$



N = # CW ENCIRCLEMENTS OF
ORIGIN OF $1+GH$ PLANE

N = # CW ENCIRCLEMENTS OF
THE -1 POINT OF GH -PLANE

$$Z = N + P \geq 0$$

$Z = 0 \Rightarrow$ STABLE CL. LOOP Sys.

$Z > 0 \Rightarrow$ UNSTABLE CL. " " "