

# Polymorphism

- The fourth pillar of OOP -

# Polymorphism – An Introduction

- The ability for objects of different classes related by inheritance to respond differently to the same message.
- Polymorphism is implemented in C++ via **inheritance** and **virtual functions**.
- This is also called as dynamic polymorphism. i.e. when a request is made through a base class pointer to use a virtual function, C++ chooses the correct overridden function in the appropriate derived class associated with the object
- Other types of polymorphism are obtained through function or operator overloading are called **static polymorphism**.
- This powerful feature of C++ helps in **reducing complexity** of the system.

# Static Binding

- When the information is known to the compiler at the compiled time and therefore, compiler is able to select appropriate function for a particular call at the compile time itself, this is called early binding or static binding.
- Static binding is the compile-time determination of which function to call for a particular object based on the type of the formal parameter

# Pointer to Objects

```
class A
{
    int x;
    public:
    void get()
    {
        cout<<"Enter the
value of x::";
        cin>>x;
    }

    void show()
    {
        cout<<x;
    }
};
```

```
int main()
{
    A *ptr,obj;
    ptr=&obj;
    ptr->get();
    ptr->show();
    return 0;
}
```

## Example (Pointer to Derived Class )

```
class A{
    public:
        int b;
        void show(){
            cout<<"b="<<b<<endl; }
};
```

```
class B: public A{
    public:
        int d;
        void show(){
            cout<<"b="<<b<<endl;
            cout<<"d="<<d<<endl; }
};
```

```
int main(){
    A *bptr, base;
    bptr=&base;
    bptr->b=100;
    bptr->show();
    B derived;
    bptr=&derived;
    bptr->b=200;
    bptr->d=300;
bptr->show();
    B *dptr;
    dptr=&derived;
    dptr->d=300;
    dptr->show();
}
```

# Dynamic Binding

- This is the **run-time determination** of which function to call for a particular object of a derived class based on the type of the argument
- Declaring a member function to be **virtual** instructs the compiler to generate code that guarantees dynamic binding
- Dynamic binding requires **pass-by-reference**

# Virtual function

- If a function is declared as "virtual" in the base class then the implementation will not be decided at compile time but at the run time.
- Keyword **virtual** instructs the compiler to use late binding and delay the object interpretation
- Once a function is declared virtual, it remains virtual **all the way down the inheritance hierarchy** from that point, even if it is not declared virtual explicitly when a derived class overrides it
- But for the program clarity declare these functions as virtual explicitly at every level of hierarchy

# Example- Dynamic Binding.

```
class Window{
public:
    virtual void Create(){
        cout <<"Base Window"<<endl;
    }
};

class CommandButton : public
Window{
public:
    void Create(){
        cout<<"Derived Command
        Button "<<endl;
    }
};
```

```
void main()
{
    Window *x, w;
    x = &w;
    x->Create();

    CommandButton cb;
    x=&cb;
    y->Create();
}
```

OUTPUT

Base Window  
Derived Command Button



# Polymorphism

- When you use virtual functions, compiler store additional information about the types of object available and created
- Polymorphism is supported at this additional overhead
- Important :
  - virtual functions work only with pointers/references
  - Not with objects even if the function is virtual
  - If a class declares any virtual methods, the destructor of the class should be declared as virtual as well. Why??

# Pure Virtual Functions

- It is a virtual function having no body  
syntax: `virtual void show()=0;`
- But this function can't be removed from the body. ( compiler error)
- It is because the base class pointer is allowed to refer the base class members only.
- Pure virtual functions may be inherited/overridden in derived classes.

# Abstract Class

- A class never used for instantiation is called an abstract class.
- The sole purpose of an abstract class is to provide an appropriate base class for derivation of sub classes.
- A class will be treated as an abstract base class if at least one member function of the class is purely virtual
- Attempting to instantiate an object of an abstract is a syntax error

# Abstract Class contd..

- If a class is derived from a class with a pure virtual function and if no definition for that function is supplied in the derived class also then ...
  - That virtual function also remains purely virtual in the derived class.
  - The consequence is that the derived class again becomes an abstract class
  - i.e. It is not possible now to instantiate the derived class also!!!

# Example of pure virtual Functions...

```
class Car
{
    public:
    virtual void brake()=0;
    virtual void steering()=0;
    virtual void regNo()=0;
};
```

```
class Santro:public Car
{
    int regn_no;
    public:
    Santro(int reg)
    {
        regn_no=reg;
    }

    void brake()
    {
        cout<<"AIR BRAKE"<<endl;
    }

    void steering()
    {
        cout<<"POWER STEERING"<<endl;
    }

    void regNo()
    {
        cout<<"REGISTRATION:::\t"<<regn_no<<endl;
    }
};
```

```
class Hyundai: public Car
{
    int regn_no;
public:
    Hyundai(int reg)
    {
        regn_no=reg;
    }
    void regNo()
    {
        cout<<"REGISTRATION:::"<<regn_no<<endl;
    }
    void brake()
    {
        cout<<"NORMAL BRAKE"<<endl;
    }
    void steering()
    {
        cout<<"ORDINARY STEERING"<<endl;
    }
};
```

```
int main()
{
    Car *ptr;
    Santro s(121);
    Hyundai h(234);

    ptr=&s;
    ptr->regNo();
    ptr->brake();
    ptr->steering();

    cout<<endl;

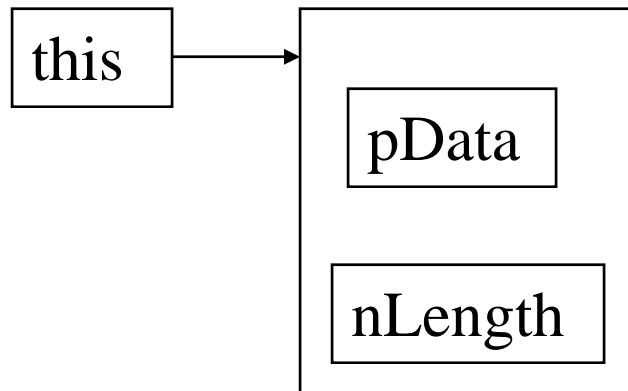
    ptr=&h;
    ptr->regNo();
    ptr->brake();
    ptr->steering();

    return 0;
}
```



# "this" pointer

- Within a member function, the *this* keyword is a pointer to the current object, i.e. the object through which the function was called
- C++ passes a hidden *this* pointer whenever a member function is called
- Within a member function definition, there is an implicit use of *this* pointer for references to data members



CStr object  
(\*this)

Data member reference	Equivalent to
pData	this->pData
nLength	this->nLength

## “this” Pointer

- Every object has access to its own address through a pointer called 'this'
- The this pointer is passed as an implicit first argument on every non-static member function call for an object.
- The this pointer is implicitly used to refer both the data and function members of an object
- It can also be used explicitly;

Example: `(*this).x=5;` or `this->x=5;`

## EXAMPLE OF **this** POINTER

```
class A
{
    int i;
    float f;

    public:

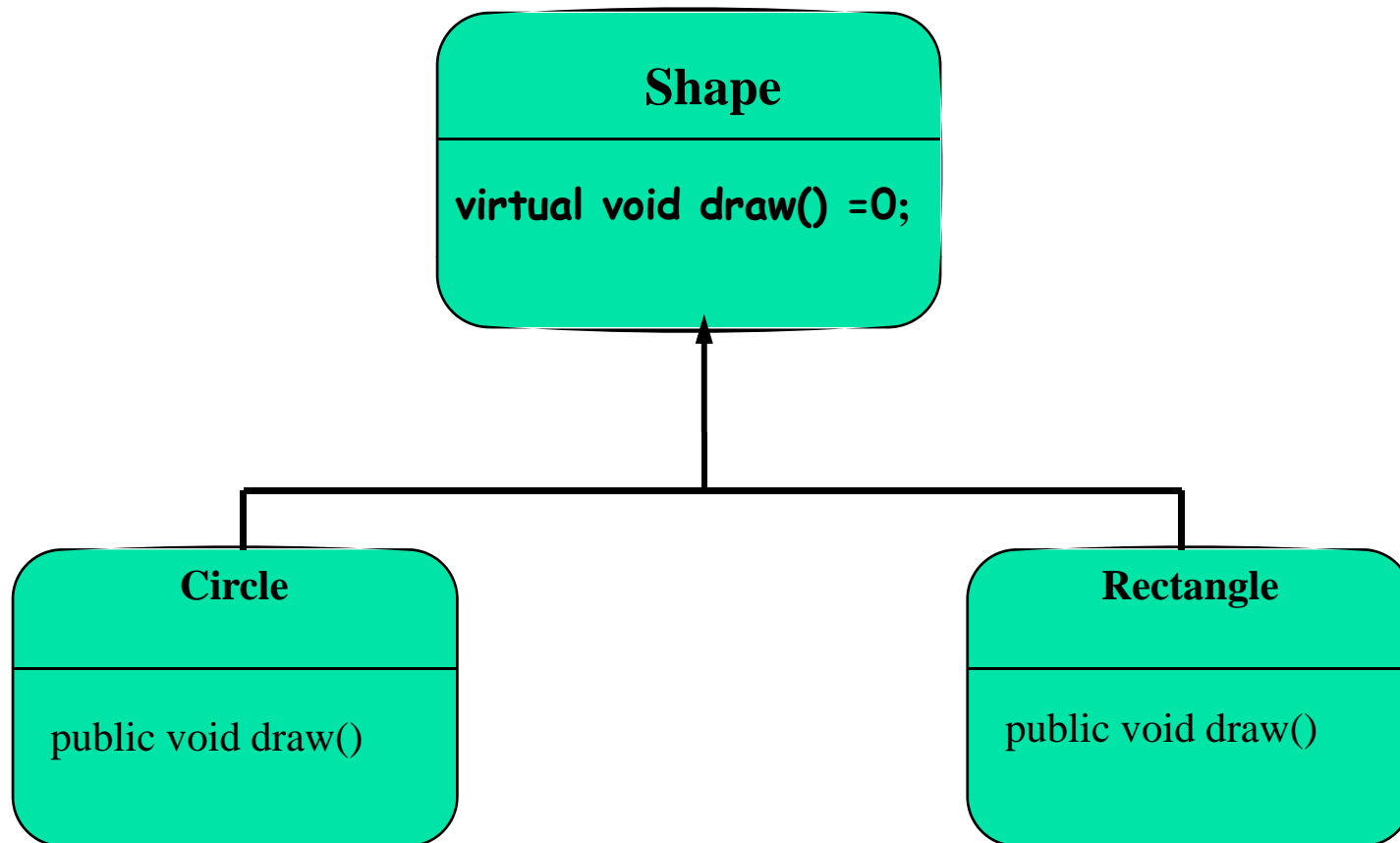
    A(int i, float f)
    {
        this->i=i;
        this->f=f;
    }
}
```

```
void set()
{
    cout<<"Value of i:"<<i<<endl;
    cout<<"Value of f:"<<f;
}

};

int main()
{
    A obj(10,20);
    obj.set();
}
```

# Example



## Example- contd..

```
class Circle : public Shape {  
    public :  
    void draw(){ //Override Shape::draw()  
        cout << "I am a Circle" << endl;  
    }  
  
class Rectangle : public Shape {  
    public :  
    void draw(){ // Override Shape::draw()  
        cout << "I am a Rectangle" << endl;  
    }
```

# ASSIGNMENT

For Manager

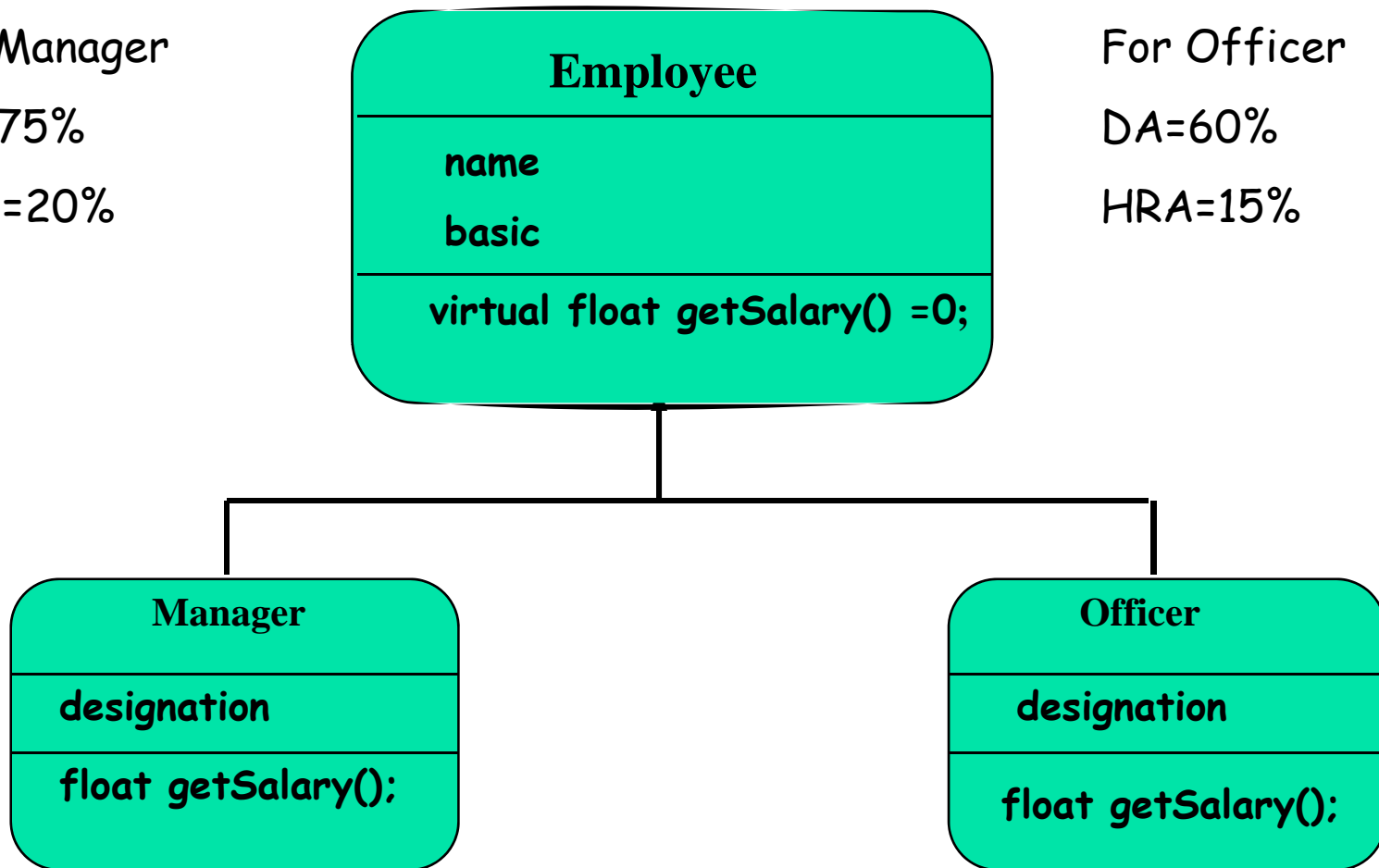
DA=75%

HRA=20%

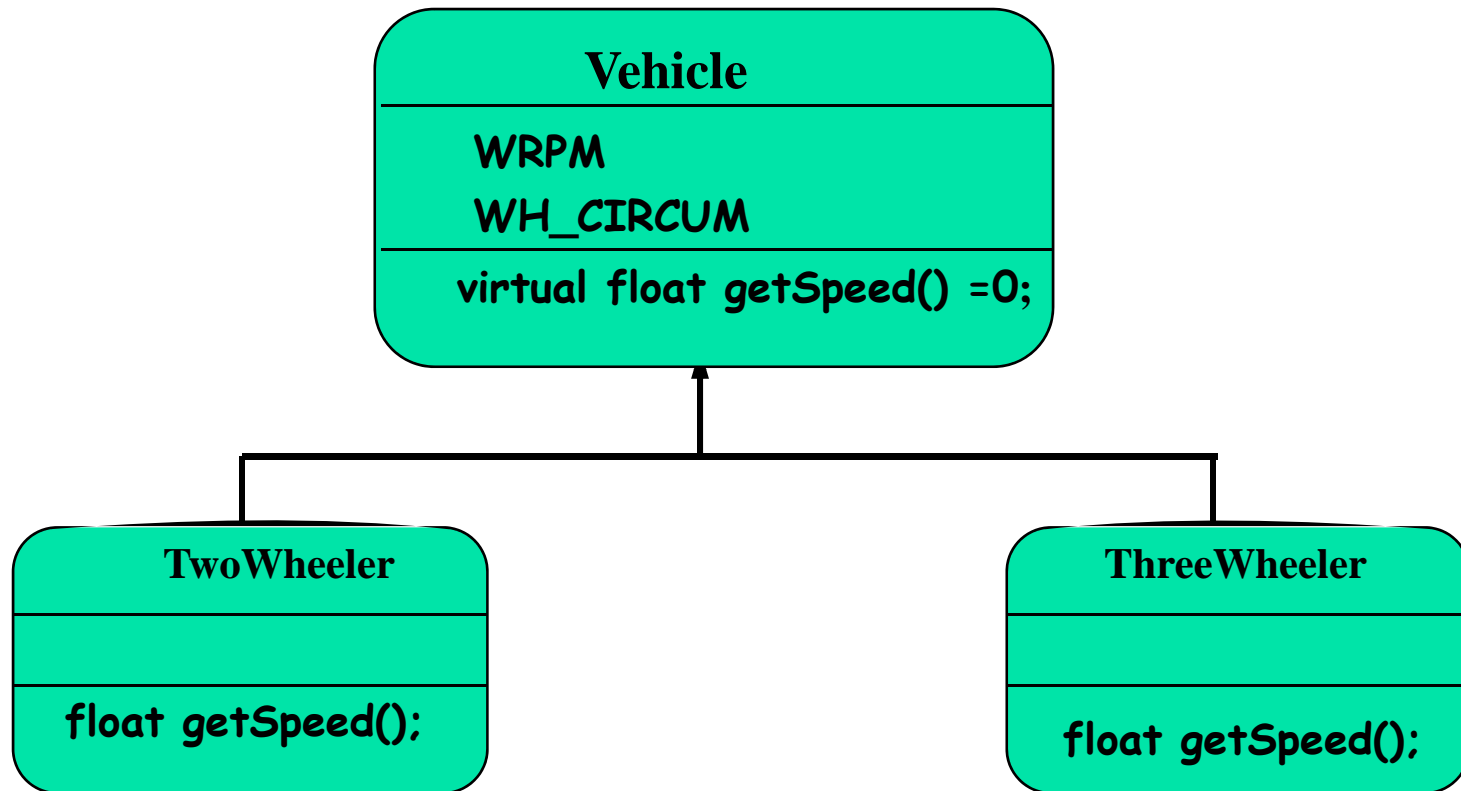
For Officer

DA=60%

HRA=15%

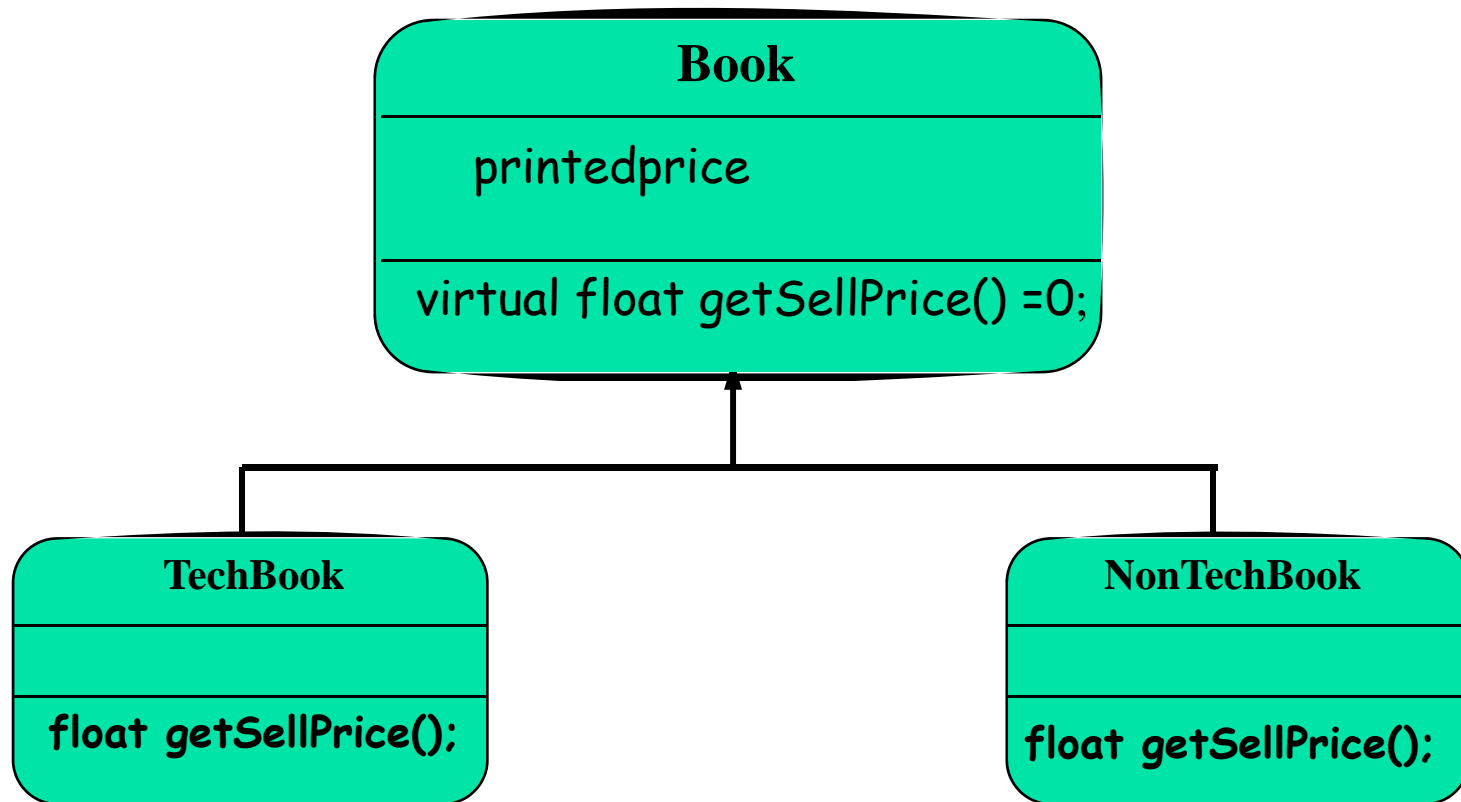


# ASSIGNMENT



WRPM- Wheel rotation per minute,  
WH\_CIRCUM- Wheel circumference

# ASSIGNMENT



Tech Book discount- 15%

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# ASSIGNMENT

- Use base pointer to call the overridden functions of derived class
- Handle Exception for each assignments