# **Groups Revision Notes IA 2020**

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Life is meaningless

— Ashutosh Tripathi

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# §1 All the Stuff with no Proofs

# §1.1 Groups

**Definition 1 (Groups)** G, is defined as a Group structure if it obeys the following axioms:

- (G0) Closure:  $\forall x, y \in G, xy \in G$
- (G1) Associative :  $\forall x, y, z \in G, x(yz) = (xy)z \in G$
- (G2) Identity:  $\exists e \in G \text{ s.t } \forall x \in G, ex = x = xe$
- (G3) Inverse:  $\forall x \in G, \exists x^{-1} \in G \text{ s.t } xx^{-1} = e = x^{-1}x$

# **Proposition 1.1** For a given group, G, the following are true

- 1.  $a, b \in G$ ,  $ab = e \implies ba = e$
- $2. \ a \in G, \ ae = a \implies ea = a$
- 3.  $a, b \in G$ ,  $ab = e \implies ba = e$
- 4.  $a, e, e' \in G$ ,  $ae = a \land ae' = a \implies e = e'$

# §1.2 Subgroups

**Definition 2**  $H \leq G$  if it satisfies the following axioms

- (G0) Closure
- (G1) Identity
- (G2) Inverse

#### Lemma 1.2 (Subgroup Lemma)

$$H \leqslant G \iff H \neq \emptyset \land \forall a, b \in H, ab^{-1} \in H$$

**Definition 3**  $\langle X \rangle$  is the notation for the

- Smallest Subgroup of G containing X
- $\bigcup_{X\subseteq Y\leqslant G}Y$
- $\left\{ \prod_{i=1}^k x_i^{\alpha_i} \mid x_i \in X, \alpha_i \in \{\pm 1\}, k \in \mathbb{N}^{>0} \right\}$

# §1.3 Homomorphism

**Definition 4 (Group homomorphism)** Let (G, \*) and  $(H, \times)$  be groups. A function

 $f: G \to H$  is a group homomorphism iff

$$(\forall g_1, g_2 \in G) \phi(g_1) \times \phi(g_2) = \phi(g_1 * g_2),$$

**Definition 5 (Group isomorphism)** Isomorphisms are bijective homomorphisms. Two groups are isomorphic if there exists an isomorphism between them. We write  $G \cong H$ .

**Definition 6 (Image of homomorphism)** If  $\phi: G \to H$  is a homomorphism, then the *image* of  $\phi$  is

$$\operatorname{im} \phi = \phi(G) = \{\phi(g) : g \in G\}.$$

**Definition 7 (Kernel of homomorphism)** The kernel of  $\phi$ , written as

$$\ker \phi = \phi^{-1}(\{e_H\}) = \{g \in G : \phi(g) = e_H\}.$$

**Proposition 1.3** Suppose that  $\phi: G \to H$  is a homomorphism. Then

1. Homomorphisms send the identity to the identity, i.e.

$$\phi(e_G) = e_H$$

2. Homomorphisms send inverses to inverses, i.e.

$$\phi(a^{-1}) = \phi(a)^{-1}$$

- 3. The composite of 2 group homomorphisms is a group homomorphism.
- 4. The inverse of an isomorphism is an isomorphism.

**Proposition 1.4** Both the image and the kernel are subgroups of the respective groups, i.e. im  $\phi \leq H$  and ker  $\phi \leq G$ .

**Proposition 1.5** For all homomorphisms  $f: G \to H$ , f is

- 1. surjective iff im  $\phi = H$
- 2. injective iff  $\ker \phi = \{e\}$

# §1.4 Direct Products

**Definition 8 (Direct product of groups)** Given two groups  $(G, \circ)$  and  $(H, \bullet)$ , we can define a set  $G \times H = \{(g, h) : g \in G, h \in H\}$  and an operation  $(a_1, a_2) * (b_1, b_2) = (a_1 \circ b_1, a_2 \bullet b_2)$ . This forms a group.

#### Theorem 1.6 (Direct product theorem)

Let  $H_1, H_2 \leq G$ . Suppose the following are true:

- 1.  $H_1 \cap H_2 = \{e\}.$
- 2.  $(\forall a_i \in H_i) a_1 a_2 = a_2 a_1$ .
- 3.  $(\forall a \in G)(\exists a_i \in H_i) a = a_1 a_2$ . We also write this as  $G = H_1 H_2$ .

Then  $G \cong H_1 \times H_2$ .

#### §1.5 Cosets

**Definition 9 (Cosets)** Cosets are fun! They are equivalence classes of an equivalence relation on a group G. Basically if  $H \leq G$  then the **left coset** is the set gH where  $g \in G$  and

$$gH = \{ g * h \mid h \in H \}$$

Similarly, we can define Hg.

Also G/H is the **quotient**, the set of all left cosets. Similarly can define  $H\backslash G$  for right cosets.

|G/H| = [G:H], and this is called the **Index of H in G** 

**Proposition 1.7** If aH = bH then  $b^{-1}a \in H$ 

**Proposition 1.8** There is a natural bijection between gH and H and thus |gh| = |H|

# Theorem 1.9 (Lagrange's Theorem)

$$|G| = [G:H]|H|$$

**Proposition 1.10** Some easy propositions as a consequence of Lagrange's Theorem

- if |G| = p where p is a prime, then G is a cyclic group
- $\operatorname{ord}(g) \mid |G|$

**Definition 10**  $U_n = \{ a \in \mathbb{N}^{>0} \mid (a, n) = 1 \}$ 

#### Theorem 1.11 (Euler-Fermat)

$$a^{\phi(n)-1} \equiv 1 \bmod n$$

# §1.6 Normal Groups

**Definition 11**  $H \leq G$  then if either of the following holds:

- $gH = Hg \forall g \in G$
- $gHg^{-1} = H \forall g \in G$
- $ghg^{-1} \in H \forall g \in G, \forall h \in H$

Then we say  $H \subseteq G$ , and we say that **H** is normal in **G** 

#### **Proposition 1.12** New Usual Stuff

- $\bullet$  if index of H is 2 then is normal in G
- ALl subgroups in abelian groups are abelian

#### §1.7 Quotient Groups

**Proposition 1.13** Multiplication of cosets naturally is well defined that is (aH)(bH) = (abH)

**Definition 12 (Quotient Groups)** If  $H \subseteq G$  then the quotient of H in G, G/H forms a group under coset multiplication, and is known as the **Quotient Group** 

**Definition 13** We define the **Quotient Map** as

$$\pi: G \to G/H$$

$$g\mapsto gH$$

This is a surjective group homomorphism.

# §1.8 Isomorphism Theorems

Very Important!

# Theorem 1.14 (The First Isomorphism Theorem)

If  $\phi: G \to H$  is a group homomorphism then

$$G/\ker\phi\cong\operatorname{im}(\phi)$$

Theorem 1.15 (The Second Isomorphism Theorem)

If  $K \subseteq G$  and  $H \leqslant G$  then

$$H/H \cap K \cong HK/K$$

# Theorem 1.16 (The Third Isomorphism Theorem)

If  $K \subseteq G$  and  $H \subseteq G$  and  $K \leqslant H$  then

$$G/H \cong (G/K)/(H/K)$$

#### **Theorem 1.17 (The Subgroup Correspondence Theorem)**

Let  $K \subseteq G$ .

There is a bijjection between the subgroups of G containing K and the subgroups of G/K.

This bijjection preserves almost anything you can think of, normality, index, containment.

#### §1.9 Cyclic Groups

**Definition 14**  $C_n$  exiss lol

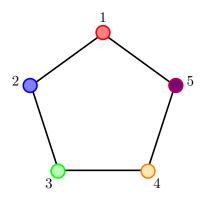
**Proposition 1.18** All subgroups of a cyclic group are cyclic

**Proposition 1.19** All possible cyclic groups are isomorphic to either  $C_n$  for some n or  $\mathbb{Z}$ 

# §1.10 Dihedral Groups

#### **Definition 15**

$$D_{2n} = \langle r, s | r^n = s^2 = e, srs = r^{-1} \rangle$$



#### §1.11 Symmetric Groups

**Definition 16**  $S_n$  exists lol and so does  $A_n$ 

**Definition 17**  $\epsilon(\sigma)$  is the parity of the permutation  $\sigma \in S_n$ . It is equal to

 $(-1)^{\mathrm{No.\ of\ transpositions}}.$  Fun fact, it is a surjective group homomorphism from G to  $\{\pm 1\}$ 

# **Proposition 1.20** Disjoint Cycles Commute

**Proposition 1.21** All permutations in  $S_n$  are expressible as unique product of disjoint cycles

**Proposition 1.22** The order of a permutation is the lcm of the orders of all the disjoint cycles

**Proposition 1.23** All elements in  $S_n$  are expressible as a product of transpositions(not necessarily unique)

**Proposition 1.24** The above mentioned product of transpositions preserves parity

**Proposition 1.25**  $A_n$  is the kernel of the sign homomorphism

**Proposition 1.26** Some Generator Shit:

- $S_n = \langle (1i) \rangle$
- $S_n = \langle (i, i+1) \rangle$
- $S_n = \langle (12)(12\dots n) \rangle$

**Proposition 1.27**  $A_n$  can be generated by 3-cycles for all  $n \ge 3$ 

**Proposition 1.28**  $A_n$  is simple for  $n \ge 5$ 

**Proposition 1.29** The size of conjugacy classes of  $S_n$  for  $\sigma$  of cycle-type  $1^{a_1}2^{a_2}\dots n^{a_n}$  is

$$|\operatorname{ccl}(\sigma)| = \frac{n!}{\prod_{i=1}^{n} (a_i! i^{a_i})}$$

**Proposition 1.30** Conjugacy Classes in  $S_n$  can either split or remain the same to form conjugacy classes for  $A_n$ , with splitting happening iff  $C_{A_n}(\sigma)$  contains an odd permutatation.

**Definition 18** Conjugacy Classes may split if  $\sigma$ 's disjoint cycle representation has distinct odd-length cycles.

**Definition 19** A subgroup  $H \leq S_n$  has either 0 or exactly half the number of odd permutations

# §1.12 Groups of Small Order

**Definition 20 (Quarternion)** 

$$Q_8 = \langle -1, i, j, k | (-1)^2 = 1, i^2 = j^2 = k^2 = ijk = -1 \rangle$$

Proposition 1.31 Well let's just list some stuff, besides the obvious for primes

- $4: C_2 \times C_2, C_4$
- $6: C_6, S_3$
- $8: C_2 \times C_2 \times C_2, C_4 \times C_2, D_8, Q_8, C_8$

# §1.13 Group Actions-an Intro

**Definition 21 (Group Action)** Group actions are binary operations of a group G on a set X defined from  $G \times X \to X$  such that

- Closure :  $g(x) \in X \forall x \in X, \forall g \in G$
- Associativity:  $g(g'(x)) = gg'(x) \forall g, g' \in G, x \in X$
- Identity : e(x) = x

#### **Definition 22 (Orbits)**

$$orb(x) = \{ g(x) \mid g \in G \}$$

If  $orb(x) = X \forall x \in X$  then the group action is transitive

**Definition 23 (Stabilizer)** 

$$stab(x) = \{ g \in G \mid g(x) = x \}$$

**Definition 24 (Kernel)** 

$$\bigcap_{x\in X}\operatorname{stab}(X)$$

If kernel of a group action is trivial, then the group action is faithful

**Proposition 1.32** Group action is a homomorphism, that is if  $G \subset X \iff \exists \rho \text{ s.t } \rho : G \to X$ 

# Theorem 1.33 (Cayley)

 $G \cong M \leqslant \operatorname{Sym}(G)$ 

**Proposition 1.34** This is easy to see:

- $\operatorname{stab}(x) \leq G$
- orb(x) partitions X

#### Theorem 1.35 (Orbit-Stabilizer)

Assume  $G \subset X$ 

 $|G| = |\operatorname{orb}(x)||\operatorname{stab}(x)| \forall x \in X$ 

#### Theorem 1.36 (Cauchy)

If  $p \mid |G| \implies \exists g \in G \text{ s.t. } \operatorname{ord}(g) = p$ 

# §1.14 Conjugation Action

**Definition 25 (Conjugation Action)**  $G \subset G$  such that  $g(\alpha) = g\alpha g^{-1}$ 

**Definition 26 (Centralizer)** The stabilizer of g for conjugation group action is the **Centralizer**,  $C_G(g)$ 

**Definition 27 (Conjugacy Classes)** The orbit of the conjugation group action for g, ccl(g)

**Definition 28 (Center)** The kernel of the conjugation action, Z(G)

**Proposition 1.37** Conjugation preserves order, thus conjugacy classes consist of elements that have the same order

**Proposition 1.38** Normal Subgroups of G are unions of conjugacy classes

**Proposition 1.39**  $Z(G) \subseteq G$ 

**Proposition 1.40** Z(G) consists of elements with singleton conjugacy classes

**Definition 29 (Normalizer)** For any subgroup H of G the **normalizer** of H is defined as

$$N_G(H) \stackrel{\text{def}}{=} \left\{ g \in G \mid gHg^{-1} = H \right\}.$$

In other words, it is the stabilizer of H under the conjugation action.

#### §1.15 Sylow's Theorems

#### **Theorem 1.41** (The Sylow theorems)

Let G be a group of order  $p^n m$ , where gcd(p, m) = 1 and p is a prime. A **Sylow** p-subgroup is a subgroup of order  $p^n$ . Let  $n_p$  be the number of Sylow p-subgroups of G. Then

- (a)  $n_p \equiv 1 \pmod{p}$ . In particular,  $n_p \neq 0$  and a Sylow p-subgroup exists.
- (b)  $n_p$  divides m.
- (c) Any two Sylow p-subgroups are conjugate subgroups (hence isomorphic).

#### **Proposition 1.42** These are direct results of sylow's theorems

- A Sylow p-subgroup is normal if and only if  $n_p = 1$ .
- Any group G of order pq, where p < q are primes, must have  $n_q = 1$ , since  $n_q \equiv 1 \pmod{q}$  yet  $n_q \mid p$ . Thus G has a normal subgroup of order q.
- Since any abelian group has all subgroups normal, it follows that any abelian group has exactly one Sylow p-subgroup for every p dividing its order.
- If  $p \neq q$ , the intersection of a Sylow p-subgroup and a Sylow q-subgroup is just  $\{1_G\}$ . That's because the intersection of any two subgroups is also a subgroup, and Lagrange's theorem tells us that its order must divide both a power of p and a power of q; this can only happen if the subgroup is trivial.

#### §1.16 Mobius Groups

**Definition 30 (Mobius Maps)** It is a map  $f: \hat{\mathbb{C}} \to \hat{\mathbb{C}}$  such that

$$f(z) = \begin{cases} \frac{a}{c} & \text{if } z = \infty \\ \infty & \text{if } z = \frac{-d}{c} \\ \frac{az+b}{cz+d} & \text{otherwise} \end{cases}$$

**Definition 31 (Mobius Groups)** The set of mobius maps  $\mathcal{M}$  under composition forms a non-abelian group

**Proposition 1.43** Mobius Group Acts on the extended complex numbers set  $\hat{\mathbb{C}}$ 

**Proposition 1.44** Mobius Group is generated by

- Dilation/Rotation
- Translation
- Inversion

**Proposition 1.45** A mobius map with  $\geq 3$  fixed points is identity map.

**Proposition 1.46** If two mobius maps f and g agree at at least 3 points then f = g

**Proposition 1.47** A Mobius map can be completely determined by knowing what happens to 3 points. If f is a mobius map such that  $(z_1, z_2, z_3) \mapsto (0, 1\infty)$  then

$$f(z) = \frac{(z_2 - z_3)(z - z_1)}{(z_2 - z_1)(z - z_3)}$$

**Proposition 1.48** Conjugation of mobius maps preserves order and also if f has fixed point g then the fixed point of  $hfh^-1$  is h(g)

**Proposition 1.49** A non-identity mobius map has either 1 or 2 fixed points and depending on the number of fixed points:

- 1  $\Longrightarrow$  Conjugate to z + 1
- 2  $\Longrightarrow$  Conjugate to  $\alpha z$

**Definition 32 (Circles)**  $Az\bar{z} + B\bar{z} + \bar{B}z + C = 0$ 

Proposition 1.50 Mobius Maps takes a circle to another circle

**Definition 33 (Cross Ratio)** If f is a mobius map such that  $(z_1, z_2, z_3) \mapsto (0, 1, \infty)$  for distinct  $z_1, z_2, z_3, z_4 \in \hat{\mathbb{C}}$  then

$$[z_1, z_2, z_3, z_4] = f(z_4)$$

#### **Proposition 1.51**

$$[f(z_1), f(z_2), f(z_3), f(z_4)] = [z_1, z_2, z_3, z_4]$$

#### **Proposition 1.52**

 $z_1, z_2, z_3, z_4$  lie on the same circle  $\iff [z_1, z_2, z_3, z_4] \in \mathbb{R}$ 

#### §1.17 Matrix Groups

**Definition 34** The set of all nxn matrices over field  $\mathbb{F}$  form a group  $M_{nxn}(\mathbb{F})$ 

**Definition 35 (General Linear Group)** The set of all nxn invertible matrices over field  $\mathbb{F}$  such that the determinant is 1 is the **General Linear Group**.  $GL_n(\mathbb{F})$ 

**Definition 36 (Special Linear Group)** The set of all nxn invertible matrices over field  $\mathbb{F}$  such that the determinant is 1 is the **Special Linear Group**.  $SL_n(\mathbb{F})$ 

**Proposition 1.53**  $det: GL_n(\mathbb{F}) \to \mathbb{F}^*$  has kernel  $SL_n(\mathbb{F})$ 

**Definition 37 (Orthogonal Group)** The set of all nxn Real Orthogonal Matrices  $A^TA = I$ 

**Definition 38 (Special Orthogonal Group)** The set of all nxn Real Orthogonal Matrices  $A^TA = I$  and det(A) = 1

**Definition 39 (Unitary Group)** The set of all *nxn* Unitary Matrices.

**Definition 40 (Special Unitary Group)** The set of all nxn Unitary Matrices with determinant 1

**Proposition 1.54** The Mobius group can also be seen as matrix shit:

$$\theta: SL_2 \to \mathcal{M}$$

 $\theta$  is a surjective homorphism with kernel  $\{\pm I\}$  and the quotient group  $SL_2/\{\pm I\} \cong PSL_2$ , the projective special linear group.

Proposition 1.55 The Matrix Groups can act on their respective Fields, kinda sick.

**Proposition 1.56** Change of Basis is basically if A is a matrix that represents a particular transformation wrt basis  $\{e_i\}$ , and A' represents the same transformation wrt basis  $\{f_a\}$  then there exists a matrix P called the change of basis matrix such that  $f_a = P_i a e_i$  (summation convention applies) such that  $A' = P^{-1}AP$ 

**Proposition 1.57** Change of Basis is basically a conjugation action. Jordan Normal Form is also a conjugation action

Proposition 1.58 This is recap stuff from V+M about orthogonal matrices

- Orthogonal Matrices' columns are orthonormal to each other thus form an orthonormal basis
- Orthogonal Matrices preserve length and angles
- Reflection matrix is a type of orthogonal matrix
- $\bullet P^{-1}R_aP = R_{Pa}$
- Determinant of  $R_a$  is -1 always
- if working in  $\mathbb{R}^3$  then if an orthogonal matrix has determinant 1 then 1 is an eigenvalue

**Proposition 1.59**  $SO_2$  consists of rotation matrices, of the form  $\begin{pmatrix} \cos(\theta) & -\sin(\theta) \\ \sin(\theta) & \cos(\theta) \end{pmatrix}$ 

**Proposition 1.60**  $O_2/SO_2$  consists of only reflections

**Proposition 1.61** Every element in  $O_2$  can be generated by, at max, product of 2 reflection matrices

**Proposition 1.62**  $SO_3$  consists of matrices of the form  $\begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos(\theta) & -\sin(\theta) \\ 0 & \sin(\theta) & \cos(\theta) \end{pmatrix}$ 

**Proposition 1.63**  $O_3/SO_3$  consists of only reflections

**Proposition 1.64** Every element in  $O_3$  can be represented by a product of maximum 3 reflection matrices

#### §1.18 Symmetries of Platonic Solids

**Proposition 1.65** Platonic Solids kinda cool, and all are subgroups of  $O_3$ 

- Tetrahedron symmetries are the group  $A_4$
- Cube symmetries are the group  $S_4$ . Since Octhedral is a dual of cubes, implies the orientation preserving symmetries are  $S_4$  and all symmetries are  $S_4 \times C_2$  and this is known as the Octahedral Group
- Dodecaheron Symmetries are the group  $A_5$ . Since icosahedron is a dual

of dodacehdron implies the orientation preserving symmetries are  $A_5$  and all symmetries are  $A_5 \times C_2$  and this is known as the **Icosahedral Group**