

VISVESVARAYA TECHNOLOGICAL UNIVERSITY

“JnanaSangama”, Belgaum -590014, Karnataka.



LAB REPORT on

Artificial Intelligence (23CS5PCAIN)

Submitted by

Ashwini L (1BM24CS402)

in partial fulfillment for the award of the degree of
BACHELOR OF ENGINEERING
in
COMPUTER SCIENCE AND ENGINEERING



B.M.S. COLLEGE OF ENGINEERING
(Autonomous Institution under VTU)
BENGALURU-560019
Sep-2024 to Jan-2025

**B.M.S. College of Engineering,
Bull Temple Road, Bangalore 560019**
(Affiliated To Visvesvaraya Technological University, Belgaum)
Department of Computer Science and Engineering



CERTIFICATE

This is to certify that the Lab work entitled “Artificial Intelligence (23CS5PCAIN)” carried out by **Ashwini L (1BM24CS402)**, who is bonafide student of **B.M.S. College of Engineering**. It is in partial fulfillment for the award of **Bachelor of Engineering in Computer Science and Engineering** of the Visvesvaraya Technological University, Belgaum. The Lab report has been approved as it satisfies the academic requirements in respect of an Artificial Intelligence (23CS5PCAIN) work prescribed for the said degree.

| | |
|--|--|
| Sandhya A Kulkarni Assistant Professor Department of CSE, BMSCE | Dr. Kavitha Sooda Professor & HOD Department of CSE, BMSCE |
|--|--|

Index

| Sl. No. | Date | Experiment Title | Page No. |
|--------------------|-------------|---|-----------------|
| 1 | 26/08/2025 | Implement Tic –Tac –Toe Game Implement vacuum cleaner agent | |
| 2 | 03/09/2025 | Implement 8 puzzle problems using Depth First Search (DFS) Implement Iterative deepening search algorithm | |
| 3 | 10/09/2025 | Implement A* search algorithm | |
| 4 | 08/10/2025 | Implement Hill Climbing search algorithm to solve N-Queens problem | |
| 5 | 08/10/2025 | Simulated Annealing to Solve 8-Queens problem | |
| 6 | 15/10/2025 | Create a knowledge base using propositional logic and show that the given query entails the knowledge base or not. | |
| 7 | 29/10/2025 | Implement unification in first order logic | |
| 8 | 29/10/2025 | Create a knowledge base consisting of first order logic statements and prove the given query using forward reasoning. | |
| 9 | 09/12/2025 | Create a knowledge base consisting of first order logic statements and prove the given query using Resolution | |
| 10 | 09/12/2025 | Implement Alpha-Beta Pruning. | |

Github Link:

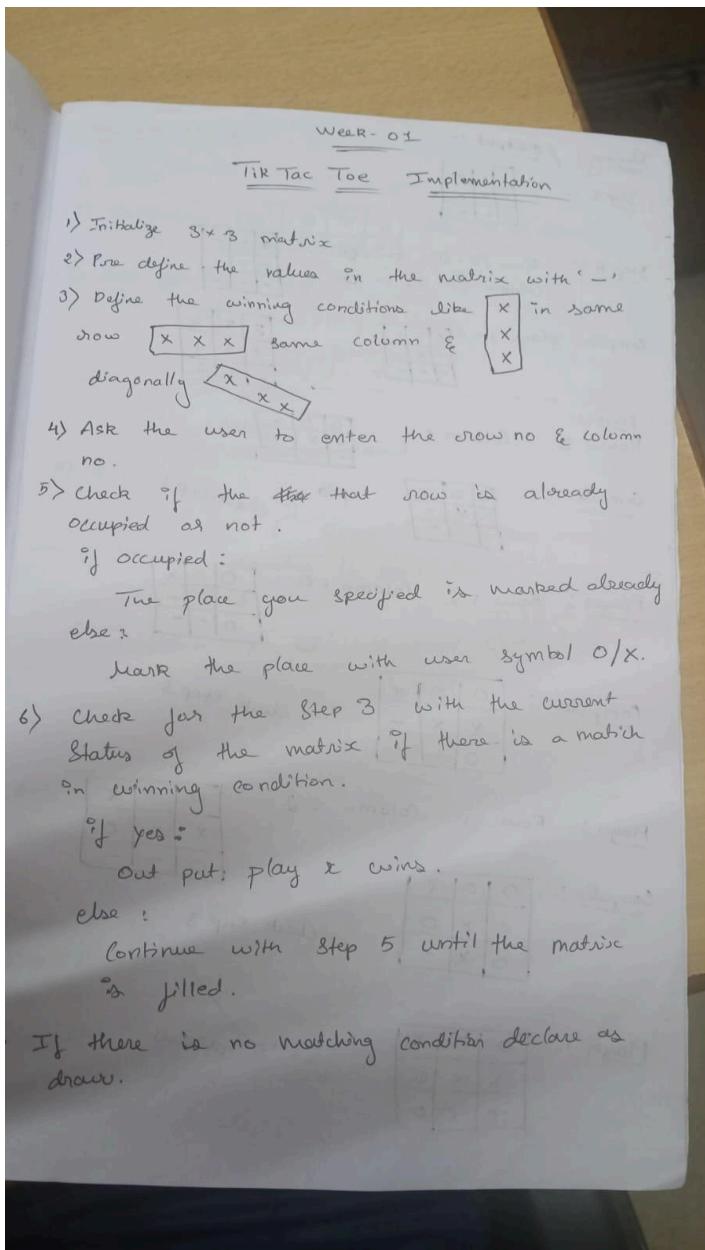
<https://github.com/Ashvinigowda/AI>

Program 1

Implement Tic - Tac - Toe Game

Implement vacuum cleaner agent

Algorithm:



Tic Tac Toe code:

```
import math

def print_board(board):
    for row in board:
        print(" | ".join(row))
        print("-" * 5)

def check_winner(board, player):
    # Rows, columns, diagonals
    for row in board:
        if all(cell == player for cell in row):
            return True

    for col in range(3):
        if all(board[row][col] == player for row in range(3)):
            return True

        if all(board[i][i] == player for i in range(3)) or \
           all(board[i][2-i] == player for i in range(3)):
            return True

    return False

def is_full(board):
    return all(cell != " " for row in board for cell in row)

def minimax(board, depth, is_maximizing):
    if check_winner(board, "O"): # Computer wins
        return 1

    if check_winner(board, "X"): # Player wins
        return -1
```

```
return -1

if is_full(board):
    return 0

if is_maximizing: # Computer's move
    best_score = -math.inf

    for i in range(3):
        for j in range(3):
            if board[i][j] == " ":
                board[i][j] = "O"

                score = minimax(board, depth + 1, False)

                board[i][j] = " "

                best_score = max(score, best_score)

    return best_score

else: # Player's move
    best_score = math.inf

    for i in range(3):
        for j in range(3):
            if board[i][j] == " ":
                board[i][j] = "X"

                score = minimax(board, depth + 1, True)

                board[i][j] = " "

                best_score = min(score, best_score)

    return best_score

def best_move(board):
```

```

best_score = -math.inf

move = None

for i in range(3):

    for j in range(3):

        if board[i][j] == " ":

            board[i][j] = "O"

            score = minimax(board, 0, False)

            board[i][j] = " "

            if score > best_score:

                best_score = score

                move = (i, j)

return move

def tic_tac_toe():

    board = [[" " for _ in range(3)] for _ in range(3)]

    print("Welcome to Tic-Tac-Toe! You are 'X' and computer is 'O'.") 

    print_board(board)

    while True:

        # Player move

        while True:

            try:

                row = int(input("Enter row (0-2):"))

                col = int(input("Enter col (0-2):"))

                if board[row][col] == " ":

                    board[row][col] = "X"

```

```
        break

    else:

        print("Cell already taken, try again.")

    except (ValueError, IndexError):

        print("Invalid input! Enter numbers 0-2.")

    print_board(board)

    if check_winner(board, "X"):

        print("🎉 You win!")

        break

    if is_full(board):

        print("It's a draw!")

        break

    # Computer move

    print("Computer's turn...")

    move = best_move(board)

    if move:

        board[move[0]][move[1]] = "O"

        print_board(board)

        if check_winner(board, "O"):

            print("💻 Computer wins!")

            break

        if is_full(board):

            print("It's a draw!")

            break
```

```
if __name__ == "__main__":
    tic_tac_toe()
```

Vaccum cleaner code:

```
import random
rooms=[1,1,1,1]
botpos =(int(input("Enter Initial Position: "))-1)
cleanedpos=[]
cost=0

def movebot(pos):
    while True:
        n= random.randint(0,3)
        if n != pos and n not in cleanedpos:
            pos = n
            break
    return pos

while True:
    print(str(rooms))
    print(botpos+1)
    if rooms[botpos]==1:
        rooms[botpos]=0
        cleanedpos.append(botpos)
        cost+=1
    if len(cleanedpos) == 4:
```

```
break

botpos=movebot(botpos)

elif rooms[botpos]==0:

    cleanedpos.append(botpos)

    if len(cleanedpos) == 4:

        break

    botpos = movebot(botpos)

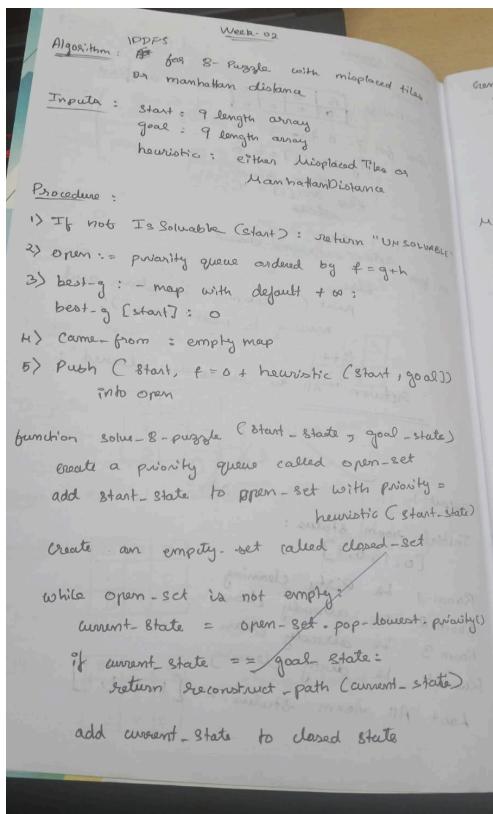
print("cost="+str(cost))
```

Program 2

Implement 8 puzzle problems using Depth First Search (DFS)

Implement Iterative deepening search algorithm

Algorithm:



DFS code:

```
import time

def find_possible_moves(state):
    index = state.index('_')
    moves = {
        0: [1, 3],
        1: [0, 2, 4],
        2: [1, 5],
```

```
3: [0, 4, 6],
4: [1, 3, 5, 7],
5: [2, 4, 8],
6: [3, 7],
7: [6, 8, 4],
8: [5, 7],
}

return moves.get(index, [])

def dfs(initial_state, goal_state, max_depth=50):

    stack = [(initial_state, [], 0)]
    visited = {tuple(initial_state)}
    states_explored = 0
    printed_depths = set()

    while stack:

        current_state, path, depth = stack.pop()
        if depth > max_depth:
            continue
        if depth not in printed_depths:
            print(f"\n--- Depth {depth} ---")
            printed_depths.add(depth)
        states_explored += 1
        print(f"State #{states_explored}: {current_state}")
        if current_state == goal_state:
            print(f"\n Goal reached at depth {depth} after exploring {states_explored} states.\n")
```

```

    return path, states_explored

possible_moves_indices = find_possible_moves(current_state)

for move_index in reversed(possible_moves_indices): # Reverse for DFS order

    next_state = list(current_state)

    blank_index = next_state.index('_')

    next_state[blank_index], next_state[move_index] = next_state[move_index],
next_state[blank_index]

    if tuple(next_state) not in visited:

        visited.add(tuple(next_state))

        stack.append((next_state, path + [next_state], depth + 1))

print(f"\n Goal state not reachable within depth {max_depth}. Explored {states_explored} states.\n")

return None, states_explored

# ----- TEST -----

initial_state = [1, 2, 3,
                 4, 8, '_',
                 7, 6, 5]

goal_state = [1, 2, 3,
              4, 5, 6,
              7, 8, '_']

# Measure execution time

start_time = time.time()

solution_path, explored = dfs(initial_state, goal_state, max_depth=50)

end_time = time.time()

if solution_path is None:

    print("No solution found.")

```

```
else:  
    print("Solution path:")  
  
    for step, state in enumerate(solution_path, start=1):  
        print(f"Step {step}: {state}")  
  
    print("\nExecution time: {:.6f} seconds".format(end_time - start_time))  
  
    print("Total states explored:", explored)
```

IDDFS code:

```
import time  
  
# ----- MOVE GENERATOR -----  
  
def find_possible_moves(state):  
    index = state.index('_')  
  
    if index == 0:  
        return [1, 3]  
  
    elif index == 1:  
        return [0, 2, 4]  
  
    elif index == 2:  
        return [1, 5]  
  
    elif index == 3:  
        return [0, 4, 6]  
  
    elif index == 4:  
        return [1, 3, 5, 7]  
  
    elif index == 5:  
        return [2, 4, 8]
```

```

        elif index == 6:
            return [3, 7]
        elif index == 7:
            return [4, 6, 8]
        elif index == 8:
            return [5, 7]
        return []

# ----- DEPTH LIMITED SEARCH -----

def depth_limited_dfs(state, goal_state, limit, path, visited):
    if state == goal_state:
        return path
    if limit <= 0:
        return None
    visited.add(tuple(state))
    for move_index in find_possible_moves(state):
        next_state = list(state)
        blank_index = next_state.index('_')
        next_state[blank_index], next_state[move_index] = next_state[move_index], next_state[blank_index]
        if tuple(next_state) not in visited:
            result = depth_limited_dfs(next_state, goal_state, limit - 1, path + [next_state], visited)
            if result is not None:
                return result
    return None

# ----- ITERATIVE DEEPENING DFS -----

```

```

def iddfs(initial_state, goal_state, max_depth=30):
    for depth in range(max_depth):
        print(f"Searching at depth limit = {depth}")
        visited = set()
        result = depth_limited_dfs(initial_state, goal_state, depth, [initial_state], visited)
        if result is not None:
            return result, depth
    return None, max_depth

# ----- TEST -----
initial_state = [1, 2, 3,
                 4, 8, '_',
                 7, 6, 5]
goal_state = [1, 2, 3,
              4, 5, 6,
              7, 8, '_']

# Measure execution time
start_time = time.time()
solution_path, depth_reached = iddfs(initial_state, goal_state, max_depth=30)
end_time = time.time()

if solution_path is None:
    print("Goal state is not reachable within given depth limit.")
else:
    print("\n\nSolution path found:")
    for step, state in enumerate(solution_path, start=0):

```

```
print(f"Step {step}: {state}")

print("\nExecution time: {:.6f} seconds".format(end_time - start_time))

print("Depth reached:", depth_reached)
```

Program 3

Implement A* search algorithm

Algorithm:

work - 3

```

function A* (start-state, goal-state)
    open-list = previously queue ordered by f
    closed-set = empty set
    start-state.g = 0
    start-state.h = heuristic (start-state, goal-state)
    start-state.f = start-state.g + start-state.h
    open-list.push (start-state, f = start-state.g + start-state.h)

    while open-list is not empty:
        current = open-list.pop()
        if current == goal-state:
            return reconstruct-path (current)
        closed-set.add (current)
        for neighbour in neighbours (current):
            if neighbour in closed-set:
                continue
            tentative_g = current.g + 1
            if neighbour not in open-list or tentative_g < neighbour.g:
                neighbour.g = tentative_g
                neighbour.h = heuristic (neighbour, goal-state)
                f = neighbour.g + neighbour.h
                if neighbour not in open-list:
                    open-list.push (neighbour, f)
    return failure.

```

A* code:

```

import heapq

def state_key(state):
    return ",".join(map(str, state))

def is_solvable(state):
    inversions = 0
    arr = [x for x in state if x != 0]
    for i in range(len(arr)):
        for j in range(i+1, len(arr)):
            if arr[i] > arr[j]:
                inversions += 1
    return inversions % 2 == 0

```

```
def manhattan(state):
    total = 0

    for index, val in enumerate(state):
        if val == 0:
            continue

        goal_idx = val - 1
        curr_row, curr_col = divmod(index, 3)
        goal_row, goal_col = divmod(goal_idx, 3)

        total += abs(curr_row - goal_row) + abs(curr_col - goal_col)

    return total

def get_neighbours(state):
    neighbours = []

    blank_idx = state.index(0)
    row, col = divmod(blank_idx, 3)
    moves = []

    if row > 0: moves.append(blank_idx - 3)
    if row < 2: moves.append(blank_idx + 3)
    if col > 0: moves.append(blank_idx - 1)
    if col < 2: moves.append(blank_idx + 1)

    for m in moves:
        new_state = list(state)
        new_state[blank_idx], new_state[m] = new_state[m], new_state[blank_idx]
        neighbours.append(tuple(new_state))

    return neighbours
```

```

def reconstruct_path(came_from, current_key):
    path = []
    while current_key in came_from:
        path.append(tuple(map(int, current_key.split(", "))))
        current_key = came_from[current_key]
    path.append(tuple(map(int, current_key.split(", "))))
    path.reverse()
    return path

def a_star(start_state, goal_state):
    if not is_solvable(start_state):
        return "UNSOLVABLE"
    start_key = state_key(start_state)
    goal_key = state_key(goal_state)
    if start_key == goal_key:
        return [start_state]
    open_heap = []
    g_score = {start_key: 0}
    f_score = {start_key: manhattan(start_state)}
    came_from = {}
    heapq.heappush(open_heap, (f_score[start_key], manhattan(start_state), start_state))
    closed = set()
    while open_heap:
        f_current, h_current, current_state = heapq.heappop(open_heap)
        current_key = state_key(current_state)

```

```

if f_current > f_score.get(current_key, float("inf")):
    continue

if current_key == goal_key:
    return reconstruct_path(came_from, current_key)

closed.add(current_key)

for neighbour in get_neighbours(current_state):
    neighbour_key = state_key(neighbour)

    tentative_g = g_score[current_key] + 1

    if neighbour_key in closed and tentative_g >= g_score.get(neighbour_key, float("inf")):
        continue

    if tentative_g < g_score.get(neighbour_key, float("inf")):
        came_from[neighbour_key] = current_key
        g_score[neighbour_key] = tentative_g
        h = manhattan(neighbour)
        f = tentative_g + h
        f_score[neighbour_key] = f
        heapq.heappush(open_heap, (f, h, neighbour))

return "FAILURE"

if __name__ == "__main__":
    print("Enter start state of the puzzle (9 numbers, 0 for blank space):")
    user_input = input().strip().split()
    if len(user_input) != 9:
        print("Invalid input! Please enter exactly 9 numbers")
        exit()

```

```
try:  
    start = tuple(map(int, user_input))  
  
except ValueError:  
    print("Invalid input! Please enter integers only")  
    exit()  
  
goal = (1, 2, 3,  
        4, 5, 6,  
        7, 8, 0)  
  
solution = a_star(start, goal)  
  
if solution == "UNSOLVABLE":  
    print("Puzzle cannot be solved!")  
  
elif solution == "FAILURE":  
    print("No solution found")  
  
else:  
    print("Solution found in", len(solution) - 1, "moves:")  
  
    for state in solution:  
        for i in range(0, 9, 3):  
            print(state[i:i+3])  
            print("----")
```

Program 4

Implement Hill Climbing search algorithm to solve N-Queens problem

Algorithm:

Week - 4

N- Queens using Hill Climbing

```
function hill-climbing (problem)
    returns a state that is a local maximum
    current ← Make-Node (problem • initial-state)
    loop do
        neighbour ← highest-valued successor of current
        if neighbour-value ≤ current . Value then
            return current . state
        current ← neighbour
```

Hill Climbing code:

```
def print_board(state):
    """Prints the 4x4 board representation with 'Q' and '.'"""
    n = len(state)

    for row in range(n):
        for col in range(n):
            if state[col] == row:
                print("Q", end=" ")
            else:
                print(".", end=" ")

    print()

print()

def calculate_cost(state):
```

```

"""Returns number of attacking pairs of queens."""

cost = 0

n = len(state)

for i in range(n):

    for j in range(i + 1, n):

        # same row

        if state[i] == state[j]:

            cost += 1

        # same diagonal

        elif abs(state[i] - state[j]) == abs(i - j):

            cost += 1

return cost

def get_neighbors(state):

    """Generates all neighbors by swapping two queen positions."""

    neighbors = []

    n = len(state)

    for i in range(n):

        for j in range(i + 1, n):

            neighbor = state.copy()

            neighbor[i], neighbor[j] = neighbor[j], neighbor[i]

            neighbors.append((neighbor, (i, j)))

    return neighbors

def hill_climbing(state):

    print("\nInitial State:", state)

```

```

print_board(state)

current_cost = calculate_cost(state)

step = 1

while True:

    print(f"Step {step}: Current cost = {current_cost}")

    neighbors = get_neighbors(state)

    neighbor_costs = []

    # Calculate cost for all neighbors

    for neighbor, swapped in neighbors:

        cost = calculate_cost(neighbor)

        neighbor_costs.append((cost, neighbor, swapped))

    # Sort by cost and then by smallest column pair as per rules

    neighbor_costs.sort(key=lambda x: (x[0], x[2][0], x[2][1]))

    # Display neighbor costs

    print("Neighbor states and their costs:")

    for cost, neighbor, swapped in neighbor_costs:

        print(f"Swap x{swapped[0]} & x{swapped[1]} => {neighbor}, Cost = {cost}")

    best_cost, best_state, swap = neighbor_costs[0]

    print("\nBest Neighbor after swap", swap, "is", best_state, "with cost =", best_cost)

    print_board(best_state)

    if best_cost >= current_cost: # No improvement (local minimum)

        print("No better neighbor found. Hill Climbing terminated.")

        print("Final state:", state)

        print_board(state)

```

```
        break

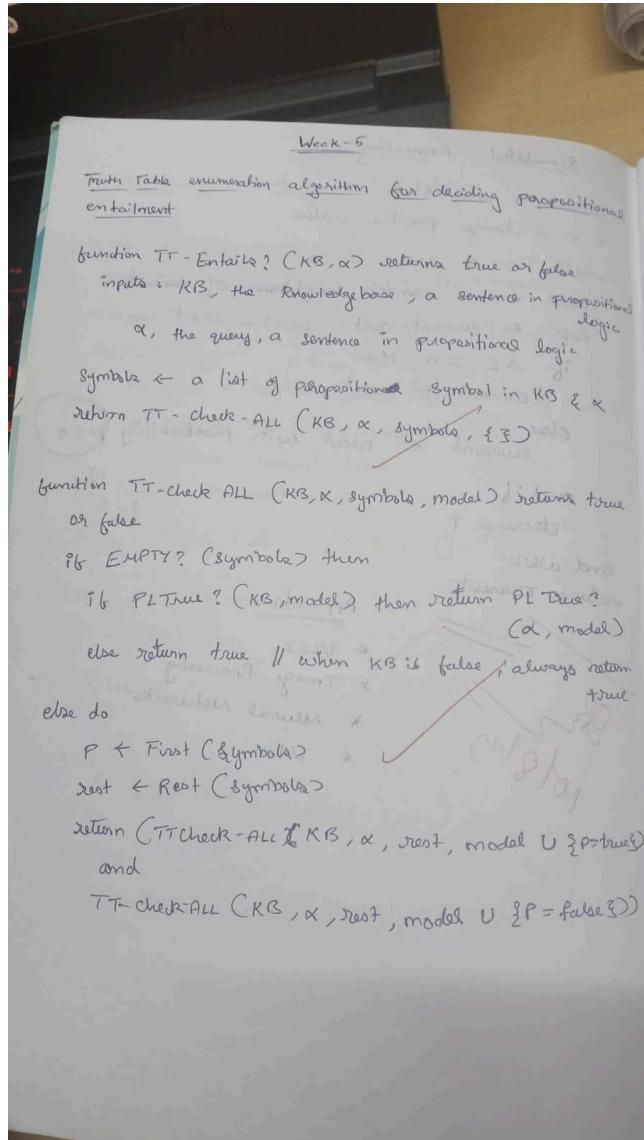
    else:
        state = best_state
        current_cost = best_cost
        if current_cost == 0:
            print("Goal state reached!")
            print_board(state)
            break
        step += 1

# ----- MAIN -----
if __name__ == "__main__":
    print("Hill Climbing for 4-Queens Problem")
    print("Enter the row positions of 4 queens (each between 0 and 3):")
    state = list(map(int, input("Example (1 2 0 3): ").split()))
    hill_climbing(state)
```

Program 5

Simulated Annealing to Solve 8-Queens problem

Algorithm:



Simulated annealing code:

```
import random
import math

# ----- Helper functions -----

def random_state(n):
```

```

"""Generate a random state: one queen per column."""
return [random.randint(0, n - 1) for _ in range(n)]

def cost(state):
    """Compute the number of attacking pairs of queens (lower is better)."""
    n = len(state)
    conflicts = 0
    for i in range(n):
        for j in range(i + 1, n):
            if state[i] == state[j] or abs(state[i] - state[j]) == abs(i - j):
                conflicts += 1
    return conflicts

def random_neighbour(state):
    """Generate a neighbour by moving one queen to another row."""
    n = len(state)
    neighbour = state.copy()
    col = random.randint(0, n - 1)      # random column
    new_row = random.randint(0, n - 1) # new random row
    neighbour[col] = new_row
    return neighbour

# ----- Simulated Annealing -----

def simulated_annealing(n, initial_temp=1000, cooling_rate=0.95, stop_temp=1e-3, max_iterations=10000):
    current = random_state(n)
    current_cost = cost(current)
    T = initial_temp

```

```
iteration = 0

print("\nInitial state:", current, "Cost:", current_cost)

while T > stop_temp and iteration < max_iterations:

    next_state = random_neighbour(current)

    next_cost = cost(next_state)

    deltaE = current_cost - next_cost

    # Acceptance condition

    if deltaE > 0:

        accepted = True

    else:

        p = math.exp(deltaE / T)

        accepted = random.random() < p

    # Print current step info

    print(f"\nStep {iteration+1}:")

    print(f" Current: {current} (Cost={current_cost})")

    print(f" Next: {next_state} (Cost={next_cost})")

    print(f" ΔE = {deltaE:.3f}, T = {T:.3f}")

    print(f" Accepted: {accepted}")

    # Accept or reject

    if accepted:

        current = next_state

        current_cost = next_cost

    # Cooling

    T *= cooling_rate
```

```
iteration += 1

# Stop if solved

if current_cost == 0:

    break

return current, current_cost, iteration

# ----- Main -----

if __name__ == "__main__":
    n = int(input("Enter the number of queens (N):"))

    solution, cost_val, iterations = simulated_annealing(n)

    print("\nFinal state:", solution)

    print("Conflicts:", cost_val)

    print("Iterations:", iterations)

    if cost_val == 0:

        print("\nSolution found:\n")

        for row in range(n):

            print(" ".join("Q" if solution[col] == row else "." for col in range(n)))

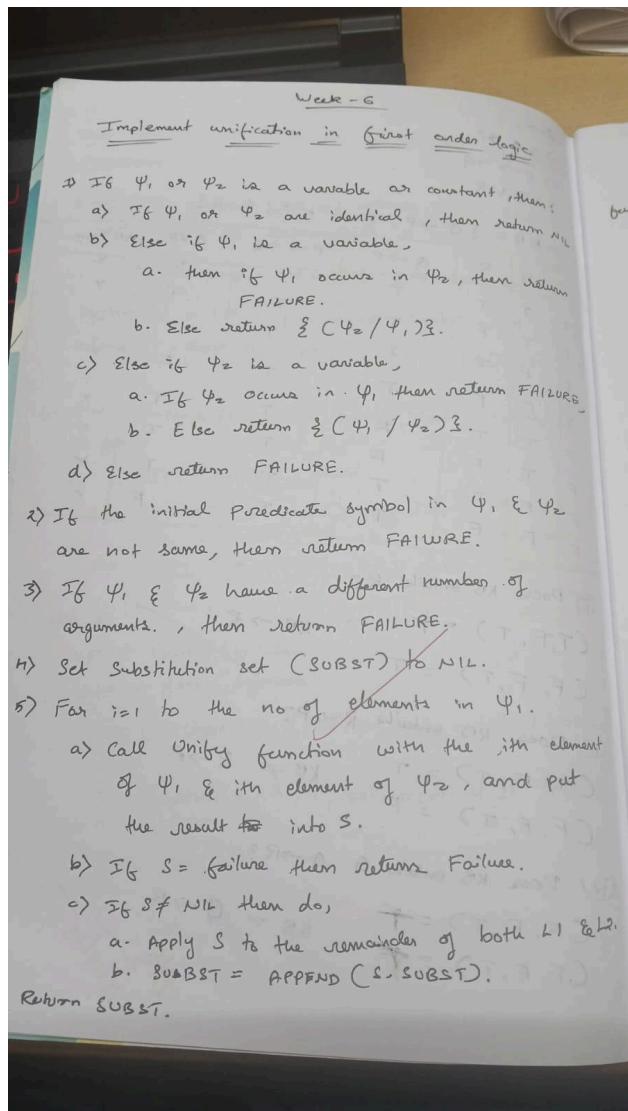
    else:

        print("\nNo perfect solution found (try rerunning; SA is stochastic).")
```

Program 6

Create a knowledge base using propositional logic and show that the given query entails the knowledge base or not.

Algorithm:



Propositional logic code:

```
from itertools import product
```

```
# Function to safely evaluate logical expressions from user input
```

```
def eval_expr(expr, model):
```

```
# Replace logical symbols for Python syntax
```

```

expr = expr.replace('∨', 'or').replace('∧', 'and').replace('¬', 'not ')

return eval(expr, {}, model)

# Generate all possible truth assignments (models)

def all_models(symbols):
    for values in product([False, True], repeat=len(symbols)):
        yield dict(zip(symbols, values))

# Check entailment: KB ⊨ α

def entails(KB_expr, alpha_expr, symbols):
    for model in all_models(symbols):
        kb_val = eval_expr(KB_expr, model)
        alpha_val = eval_expr(alpha_expr, model)
        if kb_val and not alpha_val:
            print(" Counterexample found:", model)
            return False
    return True

# Display truth table

def truth_table(KB_expr, alpha_expr, symbols):
    headers = " ".join(f'{s}:'^6 for s in symbols)
    print(f'{headers} {KB} {alpha}'^8)
    print("-" * (10 * len(symbols) + 20))
    for model in all_models(symbols):
        values = " ".join(f'{str(model[s])}:'^6 for s in symbols)
        kb_val = eval_expr(KB_expr, model)
        alpha_val = eval_expr(alpha_expr, model)

```

```

print(f'{values} {str(kb_val):^8} {str(alpha_val):^8} ")

# === Main Program ===

print("== Propositional Entailment using Truth Table Enumeration ==")

# Input propositional variables

symbols = input("Enter propositional symbols (comma separated, e.g., A,B,C): ").replace(" ", "").split(",")

# Input Knowledge Base (KB) and Query ( $\alpha$ )

KB_expr = input("Enter Knowledge Base (use and/or/not or  $\wedge/\vee/\neg$ ): ")

alpha_expr = input("Enter Query  $\alpha$  (use and/or/not or  $\wedge/\vee/\neg$ ): ")

# Display truth table

print("\n--- Truth Table ---")

truth_table(KB_expr, alpha_expr, symbols)

# Check entailment

result = entails(KB_expr, alpha_expr, symbols)

print("\nResult:")

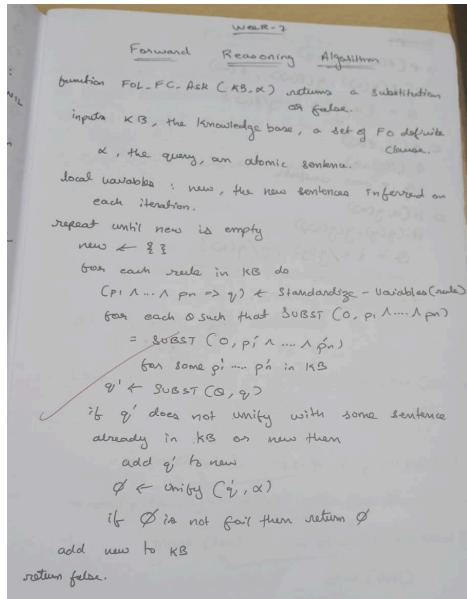
print(" KB entails  $\alpha$ " if result else " KB does NOT entail  $\alpha$ ")

```

Program 7

Implement unification in first order logic

Algorithm:



Unification code:

```

import re

# Utility: parse the expression into function/operator and arguments

def parse(expr):

    expr = expr.strip()

    if '(' not in expr:
        return expr, []

    func = expr[:expr.index('(')].strip()
    args = expr[expr.index('(')+1:-1]

    args = [a.strip() for a in split_args(args)]

    return func, args

# Split arguments correctly (handles nested brackets)

```

```
def split_args(args_str):  
    args, level, start = [], 0, 0  
  
    for i, ch in enumerate(args_str):  
        if ch == ',' and level == 0:  
            args.append(args_str[start:i].strip())  
            start = i + 1  
  
        elif ch == '(':  
            level += 1  
  
        elif ch == ')':  
            level -= 1  
  
    args.append(args_str[start:].strip())  
  
    return args
```

```
# Apply substitution to an expression
```

```
def substitute(expr, subs):  
  
    for var, val in subs.items():  
        expr = re.sub(rf'\b{var}\b', val, expr)  
  
    return expr
```

```
# Check if variable occurs inside term (Occurs check)
```

```
def occurs_check(var, term):  
  
    if var == term:  
        return True  
  
    if '(' not in term:  
        return False  
  
    _, args = parse(term)
```

```

return any(occurs_check(var, arg) for arg in args)

# Unification algorithm

def unify(e1, e2, subs=None):

    if subs is None:
        subs = {}

    e1 = substitute(e1, subs)
    e2 = substitute(e2, subs)

    if e1 == e2:
        return subs

    f1, args1 = parse(e1)
    f2, args2 = parse(e2)

    # Case 1: Both are compound terms

    if args1 and args2:
        if f1 != f2 or len(args1) != len(args2):
            print(f"✖ Function symbols or arity mismatch: {f1} vs {f2}")
            return None

        for a1, a2 in zip(args1, args2):
            subs = unify(a1, a2, subs)

        if subs is None:
            return None

        return subs

    # Case 2: Variable binding

    elif e1.islower() and e1.isalpha(): # e1 is variable
        if occurs_check(e1, e2):

```

```
print(f"X Occurs check failed: {e1} occurs in {e2}")

return None

subs[e1] = e2

return subs

elif e2.islower() and e2.isalpha(): # e2 is variable

    if occurs_check(e2, e1):

        print(f"X Occurs check failed: {e2} occurs in {e1}")

        return None

    subs[e2] = e1

    return subs

# Otherwise mismatch

else:

    print(f"X Cannot unify {e1} with {e2}")

    return None

# --- MAIN PROGRAM ---

print("== Unification Algorithm ==")

expr1 = input("Enter first expression: ").strip()

expr2 = input("Enter second expression: ").strip()

result = unify(expr1, expr2)

if result:

    print("\n✓ Unification Successful!")

    print("Substitutions:")

    for k, v in result.items():

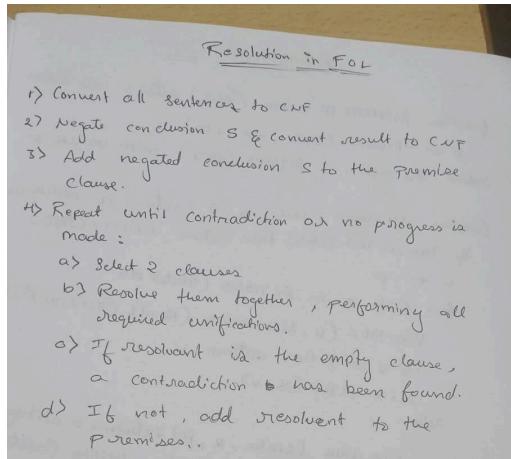
        print(f" {k} / {v}")
```

```
else:  
    print("\n✖ Unification Failed.")
```

Program 8

Create a knowledge base consisting of first order logic statements and prove the given query using forward reasoning.

Algorithm:



Forward reasoning code:

```
import re

def isVariable(x):
    return len(x) == 1 and x.islower() and x.isalpha()

def getAttributes(string):
    expr = r'\([^\)]+\)'
    matches = re.findall(expr, string)
    return matches

def getPredicates(string):
    expr = r'([a-zA-Z]+)([^&|]+)'
    return re.findall(expr, string)

class Fact:
    def __init__(self, expression):
        self.expression = expression
        predicate, params = self.splitExpression(expression)
```

```

self.predicate = predicate

self.params = params

self.result = any(self.getConstants())

def splitExpression(self, expression):
    predicate = getPredicates(expression)[0]
    params = getAttributes(expression)[0].strip(')').split(',')
    return [predicate, params]

def getResult(self):
    return self.result

def getConstants(self):
    return [None if isVariable(c) else c for c in self.params]

def getVariables(self):
    return [v if isVariable(v) else None for v in self.params]

def substitute(self, constants):
    constants_copy = constants.copy()
    expr = f'{self.predicate}({','.join([constants_copy.pop(0) if isVariable(p) else p for p in self.params])})'
    return Fact(expr)

class Implication:

    def __init__(self, expression):
        self.expression = expression
        l = expression.split('=>')
        self.lhs = [Fact(f) for f in l[0].split('&')]
        self.rhs = Fact(l[1])

    def evaluate(self, facts):

```

```

constants = {}

new_lhs = []

for fact in facts:

    for val in self.lhs:

        if val.predicate == fact.predicate:

            for i, v in enumerate(val.getVariables()):

                if v:

                    constants[v] = fact.getConstants()[i]

            new_lhs.append(fact)

    predicate = getPredicates(self.rhs.expression)[0]

    attributes = str(getAttributes(self.rhs.expression)[0])

    for key in constants:

        if constants[key]:

            attributes = attributes.replace(key, constants[key])

    expr = f'{predicate} {attributes}'

    return Fact(expr) if len(new_lhs) and all([f.getResult() for f in new_lhs]) else None

class KB:

    def __init__(self):

        self.facts = set()

        self.implications = set()

    def tell(self, e):

        if '=>' in e:

            self.implications.add(Implication(e))

        else:

```

```

    self.facts.add(Fact(e))

    for i in self.implications:

        res = i.evaluate(self.facts)

        if res:

            self.facts.add(res)

    def ask(self, e):

        facts = set([f.expression for f in self.facts])

        print(f'\nQuerying {e}:')

        i = 1

        found = False

        for f in facts:

            if Fact(f).predicate == Fact(e).predicate:

                print(f'\t{i}. {f}')

                i += 1

                found = True

        if not found:

            print("\tNo matching facts found.")

    def display(self):

        print("\nAll facts:")

        for i, f in enumerate(set([f.expression for f in self.facts])):

            print(f'\t{i+1}. {f}')

    def main():

        kb = KB()

        print("Enter the number of FOL expressions present in KB:")

```

```
n = int(input())

print("Enter the expressions:")

for i in range(n):

    fact = input().strip()

    kb.tell(fact)

print("Enter the query:")

query = input().strip()

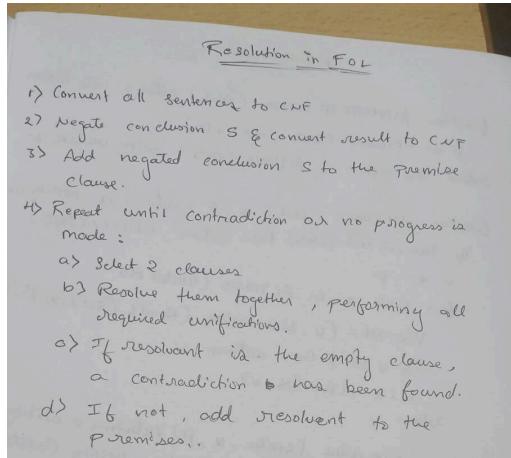
kb.ask(query)

kb.display()

if __name__ == "__main__":
    main()
```

Program 9

Create a knowledge base consisting of first order logic statements and prove the given query using Resolution



Algorithm:

Resolution code:

```
def parse_clause(clause_str):
```

```
    return set(clause_str.split('v'))
```

```
def get_complement(literal):
```

```
    return literal[1:] if literal.startswith('~') else '~' + literal
```

```
def resolve(ci, cj):
```

```
    resolvents = set()
```

```
    for literal in ci:
```

```
        complement = get_complement(literal)
```

```
        if complement in cj:
```

```
            new_clause = (ci - {literal}) | (cj - {complement})
```

```
            resolvents.add(frozenset(new_clause))
```

```
    return resolvents
```

```
def resolution(kb_clauses, query):
```

```
    negated_query = get_complement(query)
```

```
    kb = [parse_clause(clause) for clause in kb_clauses] + [parse_clause(negated_query)]
```

```
print("\n-----")
print("KnowledgeBase - Resolution")
print("-----")
print(f"\nKnowledge Base Clauses: {kb_clauses}")
print(f"Query: {query}")
print(f"Negated Query Added: {negated_query}")
print("\nResolution Steps:\n")
new = set()
while True:
    pairs = [(kb[i], kb[j]) for i in range(len(kb)) for j in range(i + 1, len(kb))]
    for (ci, cj) in pairs:
        resolvents = resolve(ci, cj)
        for resolvent in resolvents:
            print(f"Resolving {set(ci)} and {set(cj)} => {set(resolvent)}")
            if not resolvent:
                print("\n Knowledge Base entails the query (empty clause derived).")
                return True
            new.add(resolvent)
    if new.issubset(set(map(frozenset, kb))):
        print("\n Knowledge Base does NOT entail the query (no empty clause derived).")
        return False
    for clause in new:
        if clause not in kb:
            kb.append(clause)
```

```
print("KnowledgeBase - Resolution")
print("-----")
print("Enter clauses for the Knowledge Base.")
print("Use 'v' for OR between literals (e.g., 'qv~pvr'), and separate each clause with a space.\n")
kb_input = input("Enter clauses: ").split()
query_input = input("Enter the query: ")
resolution(kb_input, query_input)
```

Program 10

Implement Alpha-Beta Pruning.

Algorithm:

Adversarial Search

function ALPHABETA SEARCH (s_{t+1}) returns an action
 $v \leftarrow \text{MAXvalue} (s_{t+1}, -\infty, +\infty)$
return the action in $\text{ACTIONS}(s_{t+1})$ with value v

function MAXvalue (s_t , α , β) returns a utility value
if Terminal Test (s_t) then return UTILITY (s_t)
 $v \leftarrow -\infty$
for each a in $\text{ACTIONS}(s_t)$ do
 $v \leftarrow \text{MAX} (v, \text{MIN-value} (\text{Result} (s, a), \alpha, \beta))$
 if $v \geq \beta$ then return v
 $\alpha \leftarrow \text{MAX} (\alpha, v)$
return v

function MINvalue (s_t , α , β) returns a utility value
if terminal Test (s_t) then return UTILITY (s_t)
 $v \leftarrow +\infty$
for each a in $\text{ACTIONS}(s_t)$ do
 $v \leftarrow \text{MIN} (v, \text{MAX-VALUE} (\text{Result} (s, a), \alpha, \beta))$
 if $v \leq \alpha$ then return v
 $\beta \leftarrow \text{MIN} (\beta, v)$
return v

Alpha Beta Pruning code:

```
import math
import random

# Use an external "real" board only for the main game loop; recursive functions use state parameters.

board = [" " for _ in range(9)] # 3x3 board

def print_board(state):
    print("\n")
```

```
for i in range(3):
    print(" " + " | ".join(state[i*3:(i+1)*3]))
    if i < 2:
        print(" ---+---+---")
    print("\n")
def is_winner(state, player):
    win_combinations = [
        [0, 1, 2], [3, 4, 5], [6, 7, 8],
        [0, 3, 6], [1, 4, 7], [2, 5, 8],
        [0, 4, 8], [2, 4, 6]
    ]
    return any(all(state[i] == player for i in combo) for combo in win_combinations)
def is_full(state):
    return " " not in state
def actions(state):
    return [i for i in range(9) if state[i] == " "]
def result(state, action, player):
    new_state = state.copy()
    new_state[action] = player
    return new_state
def utility(state):
    if is_winner(state, "O"):
        return +1
    elif is_winner(state, "X"):
        return -1
    else:
        return 0
```

```

    return -1

else:
    return 0

def terminal_test(state):
    return is_winner(state, "X") or is_winner(state, "O") or is_full(state)

# --- Alpha-Beta Functions ---

def max_value(state, alpha, beta):
    if terminal_test(state):
        return utility(state)

    v = -math.inf

    for a in actions(state):
        v = max(v, min_value(result(state, a, "O"), alpha, beta))

        if v >= beta:
            return v

        alpha = max(alpha, v)

    return v

def min_value(state, alpha, beta):
    if terminal_test(state):
        return utility(state)

    v = math.inf

    for a in actions(state):
        v = min(v, max_value(result(state, a, "X"), alpha, beta))

        if v <= alpha:
            return v

    return v

```

```
    beta = min(beta, v)

    return v

def alpha_beta_search(state):
    best_score = -math.inf
    best_action = None
    if not actions(state):
        return None
    for a in actions(state):
        value = min_value(result(state, a, "O"), -math.inf, math.inf)
        if value > best_score:
            best_score = value
            best_action = a
    # Fallback: if something goes wrong, return a random legal move
    if best_action is None:
        legal = actions(state)
        return random.choice(legal) if legal else None
    return best_action

# --- Game Loop ---

def human_move():
    while True:
        try:
            move = int(input("Enter your move (1-9): ")) - 1
        except ValueError:
            print("Please enter a number 1-9.")
```

```
    continue

    if move < 0 or move > 8:

        print("Move out of range. Choose 1-9.")

        continue

    if board[move] != " ":

        print("Cell already taken. Try another.")

        continue

    return move

def choose_first():

    while True:

        ans = input("Who goes first? (me/ai) [me]: ").strip().lower()

        if ans == "" or ans.startswith("m"):

            return "me"

        if ans.startswith("a"):

            return "ai"

        print("Type 'me' or 'ai' (or press Enter for me).")

def main():

    global board

    board = [" " for _ in range(9)]

    print("Welcome to Tic-Tac-Toe! You are X, AI is O.")

    first = choose_first()

    print_board(board)

    while True:

        if first == "me":
```

```
# Human turn

move = human_move()

board[move] = "X"

print_board(board)

if is_winner(board, "X"):

    print("You win!")

    break

if is_full(board):

    print("It's a draw!")

    break

# AI turn

print("AI is thinking... ")

ai_move = alpha_beta_search(board)

if ai_move is None:

    print("AI could not find a move — it's a draw.")

    break

board[ai_move] = "O"

print_board(board)

if is_winner(board, "O"):

    print("AI wins!")

    break

if is_full(board):

    print("It's a draw!")

    break
```

```
else: # AI first

    print("AI is thinking...")

    ai_move = alpha_beta_search(board)

    if ai_move is None:

        print("AI could not find a move — it's a draw.")

        break

    board[ai_move] = "O"

    print_board(board)

    if is_winner(board, "O"):

        print("AI wins!")

        break

    if is_full(board):

        print("It's a draw!")

        break

# Human turn

move = human_move()

board[move] = "X"

print_board(board)

if is_winner(board, "X"):

    print("You win!")

    break

if is_full(board):

    print("It's a draw!")

    break
```

```
if __name__ == "__main__":
    main()
```

Certificate:



CERTIFICATE OF ACHIEVEMENT

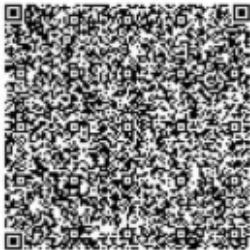
The certificate is awarded to

Ashwini L

for successfully completing

Artificial Intelligence Foundation Certification

on November 25, 2025



Issued on: Tuesday, November 25, 2025
To verify, scan the QR code at <https://verify.onwingsoan.com>

Infosys | Springboard

Congratulations! You make us proud!

Satheesha B.N.
Satheesha B. Nanjappa
Senior Vice President and Head
Education, Training and Assessment
Infosys Limited



COURSE COMPLETION CERTIFICATE

The certificate is awarded to

Ashwini L

for successfully completing the course

Introduction to Natural Language Processing

on November 25, 2025

Infosys | Springboard

Congratulations! You make us proud!

Satheesha B.N.
Satheesha B. Nanjappa
Senior Vice President and Head
Education, Training and Assessment
Infosys Limited



Issued on: Tuesday, November 25, 2025
To verify, scan the QR code at <https://verify.onwingsoan.com>



COURSE COMPLETION CERTIFICATE

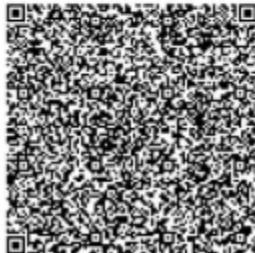
The certificate is awarded to

Ashwini L

for successfully completing the course

Introduction to Deep Learning

on November 20, 2025



Issued on: Tuesday, November 25, 2025
To verify, scan the QR code at <https://verify.onwingspan.com>

Infosys | Springboard

Congratulations! You make us proud!

Sathesha B.N.

Sathesha B. Nanjappa
Senior Vice President and Head
Education, Training and Assessment
Infosys Limited



COURSE COMPLETION CERTIFICATE

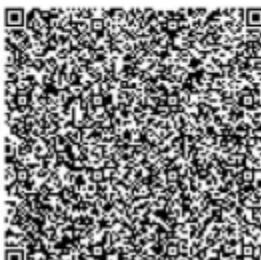
The certificate is awarded to

Ashwini L

for successfully completing the course

Introduction to Artificial Intelligence

on November 20, 2025



Issued on: Tuesday, November 25, 2025
To verify, scan the QR code at <https://verify.onwingspan.com>

Infosys | Springboard

Congratulations! You make us proud!

Sathesha B.N.

Sathesha B. Nanjappa
Senior Vice President and Head
Education, Training and Assessment
Infosys Limited