

```

options = optimoptions('fmincon', "Display","iter","Algorithm","sqp");
fun = @(x)((-1*sin(2*pi*x(1)))^3*sin(2*pi*x(2)))/(x(1)^3*(x(1) + x(2)));
lb = [0, 0];
ub = [10, 10];
A = [];
b = [];
Aeq = [];
beq = [];

```

generate random number and load non linear constraint

```
x0 = randn(2,1,"double")
```

```

x0 = 2×1
    0.5377
    1.8339

```

```
nonlcon = @conQ2;
```

solve the equation

```
[x, fval] = fmincon(fun, x0, A, b, Aeq, beq, lb, ub, nonlcon, options)
```

Iter	Func-count	Fval	Feasibility	Step Length	Norm of step	First-order optimality
0	3	-3.022224e-02	5.154e+00	1.000e+00	0.000e+00	2.181e+00
1	6	-1.372851e-02	1.764e+00	1.000e+00	1.595e+00	3.314e+00
2	9	1.963830e-05	1.954e-01	1.000e+00	5.664e-01	1.074e+00
3	12	-2.825333e-12	1.515e-02	1.000e+00	1.236e-01	3.865e-02
4	15	-2.933447e-09	1.193e-04	1.000e+00	1.094e-02	7.904e-04
5	18	-3.139222e-09	8.802e-09	1.000e+00	9.479e-05	1.541e-05
6	21	-4.144586e-09	0.000e+00	1.000e+00	3.831e-04	1.900e-05
7	24	-1.487836e-08	0.000e+00	1.000e+00	2.304e-03	4.451e-05
8	27	-1.816361e-06	0.000e+00	1.000e+00	2.693e-02	1.076e-03
9	35	-2.478430e-03	0.000e+00	2.401e-01	9.544e-01	1.303e-01
10	38	-9.345002e-03	4.705e-04	1.000e+00	3.796e-01	3.863e-01
11	41	-3.395573e-02	0.000e+00	1.000e+00	2.993e-01	5.351e-01
12	48	-3.652522e-02	0.000e+00	2.401e-01	2.006e-01	4.920e-01
13	53	-7.056574e-02	0.000e+00	4.900e-01	2.040e-01	6.601e-01
14	56	-8.717167e-02	0.000e+00	1.000e+00	1.127e-01	3.628e-01
15	59	-9.442412e-02	0.000e+00	1.000e+00	6.799e-02	1.014e-01
16	62	-9.450627e-02	0.000e+00	1.000e+00	4.712e-02	1.253e-01
17	65	-9.581469e-02	0.000e+00	1.000e+00	2.113e-02	1.387e-02
18	68	-9.582464e-02	0.000e+00	1.000e+00	1.942e-03	1.893e-03
19	71	-9.582504e-02	0.000e+00	1.000e+00	4.019e-04	1.962e-05
20	74	-9.582504e-02	0.000e+00	1.000e+00	5.519e-06	8.244e-07

Local minimum found that satisfies the constraints.

Optimization completed because the objective function is non-decreasing in feasible directions, to within the value of the optimality tolerance, and constraints are satisfied to within the value of the constraint tolerance.

<stopping criteria details>

```

x = 2×1
    1.2280
    4.2454
fval = -0.0958

```

```
conQ2(x)
```

```
ans = 1x2  
    -1.7375    -0.1678
```