Agenda for Benji-2496W

2-16

* Code review for PID class during tutorial: includes writing comments (2-16)
  + Make a documentation format that you will consistently follow whenever writing the code
* Writing preliminary Class for Drive.cpp
* Writing the user control for chassis opControl()
* Write code for the moving average of the IMU (window = four, use std::vector)

2-21

* IN PROGRESS:
  + Writing the code for Chassis:opControl(); -> writing the movement functions
    - PENDING: write the turn functions
  + Finished the file config.cpp

2-22: