## Experiment-2.

Aim? To plot open loop and closed loop speed control of DC servomotors

Apparatus: Motor Unit & Control Unit

Throng: - Motor Unit; which comprises a small permanent magnet de motor, rated voltage 12 VDC, rated werent 0.25 Amp, at normal run & 0.4 Amp at full land, the torque 75gm/cm & manspeed in excess of 3200 rpm (open loop).

An overcurrent protection circuit incorporated to exceed Current 0.3A Am Eddy Current break system for adding distrubance an opto interruptor based speed sensi system.

The control unit has speed measurement system, electronic tachogenerator error detection and forward gain amplifier, motor dunce circult, signal source, break control and digital voltmeter for measurement

1. Speed Measurement System: A uniformly based disc is attached with motion shaft which interrupt the LEO's light following upon a photoducile.

2. Tachogenerator: From signal conditioner a proportion it wollage is generated by a frequency to wollage Conversors which is brought to a socked upon janel.

3. Euror Detector & forward Gain Ampageis: In open loop, the levier signals are fed to an amplifier (kn) the gain of which can be alloted in uniform stops from 3 to 10 in open loop & 3-10 & 20 in close loop. 4 Motor Duney Assembly: It is a untily gain amp. designed to deliver necessary arrient to the motor A current limit is incorporated with this circuit. A 31/2 augit digital wolfmeter howing +19.99V fsd is provided upon the panel. G. Signal Source: A DC reference woltage Potentioneter perouded for set point voltage Vs, a rectangular cure of 14, having I upp ampleteled for time 6. Break Control: A shree Position switch applies regulated De wollage to an electermagned fitted in motor unit for constant studies. breaking purpose.

Proactives: -1. Set up VR= 0.7V, the reference voltage which is adjusted by guien potentiometer & measured at gues 2º Connect DVM with the fledback signal socket 4: Tocho output.
3. Note the speed. 4 Record RPM & V7 Voets for successive gavns Result: 4.3 V is the open loop at off voltage.

Spon Loop:

Gain 3 4 5 6 7 8 9	Voltage 1.85 2.8 3.5 4.1 4.2 3.8 2.75	RPM 2080 3045 3700 4760 5430 5500 5580
10	3.75	5500

Close Loop:

1	01 - 0	RPM
Gain	voltage	
	0.41	uss
3	0-91	990
4		1495
5	1.38	2050
	1.9	
6	2.34	2513
7		3020
8	2.31	3510
9	3.26	zaus
10	3-71	3443
10	1	