Exporiment-8.

Avm3- To study & plot bode plot of any higher order system.

Software Used: Medlab 2016 b.

Theory's Bode Plot is a quaphical representation at the transfer function for determining the stability of the control system. Bode plot contain consists of two seperate plots one is a plot of the log of magnitude of a sinusoidal tuansfer function the other is a plot of phase angle. The curves are drawn on semilog graph paper using the log scale for frequency and linear scale for magnitude (in db) Or phase angle (in degrees)

1: 20 log, 16 (w) | vs log w

2. Mase Shift is log w

Gain Margin: - It is defined as the margin in gain and le increased till system allowable by which gain can be increased till system reaches on the verige of instability. Mathematically gain margen is defined as the recipercial of the magnetude gain margin of G(10)+ JW & Pulse oue frequency.

GM = 1/G(jw)+jw/w; W= Phase cross over

This frequency is the point where phase and coss the 180° line.

thase Margin; For gain the additional phase log can be defined as the amount of additional phase log which can be introduced in the system till system reaches on the verge of instability.

PM = 1/9(w)Hw)|w41-(180°)

PM = 180 + 290w) Hw.

Where $W_c = gain$ crossover frequency

The point at which the magnitude curve crosses

the Odlo line is the gain crossover frequency.

Practical Solution: let the transfer function 6e:

GO) MO) = 5(3+2)

0°. (400) μ(co) = -90'-tan'w-tan w + tan w

Acc to definition:

-180 - - 90 - tan w - tan w + tan w

tan'w + tan'w + tan'w = 90.

laking tangent on both sides, tan fran W- tan W-tan W) = tan 90

« Phase Geossover w=5.87 gad/s+

Now G(ω) U(ω) = S(ω+2)

(ω+1) (ω+4)

For ω=5.87 gad (s

(gω) U(ω) = S(x5.87+2)

(x5.87+1) (1×5.87-14)

« Gain Geossover Frequency = 6.68 gad /s

Result: Successfully cooled this on MATICAB.