

## COMP20003 Algorithms and Data Structures Traversing Trees and Graphs

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## Traversal

- **Traverse**: to pass or move over, along, or through
- **Tree traversal**: the process of visiting (examining or updating) **each node exactly once**, in a **systematic** way
- **Graph traversal**: the process of visiting **all** the nodes in a graph

Tree traversal is a special case of graph traversal



## Traversal



## Graph traversal vs. Tree traversal

**Graph traversal complications** due to:

- Possible **cycles**
- **Not** necessarily **connected**

... Lets start with Tree traversal



## Starting with trees: bst dfs traversal depth-first search



Depth-first tree search can be done as:

- In-order
- Pre-order
- Post-order

## Recursive in-order search: binary tree



```
void inorder(node_t* t)
{
    if(t==NULL) return();
    inorder(t->left);
    visit(t); /* e.g. print value */
    inorder(t->right);
}
```

## Recursive pre-order search: binary tree



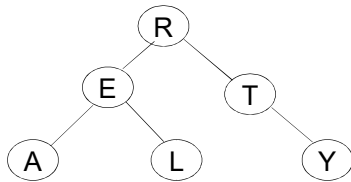
```
void preorder(node_t* t)
{
    if(t==NULL) return();
    visit(t); /* visit first */
    preorder(t->left);
    preorder(t->right);
}
```

## Non-recursive pre-order search: DFS - explicit stack



```
void preorder(stack_t* st, node_t* t)
{
    push(st,t);
    while(!stackempty(st))
    {
        t= pop(st); visit(t);
        if(t->r != NULL) push(st,t->r);
        if(t->l != NULL) push(st,t->l);
    }
    /* note: stack contains pointers into the tree */
}
```

## Depth-first search vs. breadth-first search



## Breadth-first tree search: use a queue

```

void preorder(queue* Q, node_t* t)
{
    enQ(Q, t);
    while(!emptyQ(Q))
    {
        t = deQ(Q); visit(t);
        if(t->l != NULL) enQ(Q, t->l);
        if(t->r != NULL) enQ(Q, t->r);
    }
}
/* note: queue contains pointers into the tree */
    
```

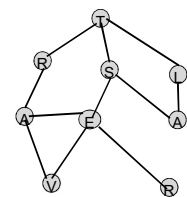
## Tree traversal: assumptions

- **Assumes** every node is **reachable** from the **root**
- **Assumes** every node has **only one parent**, can only be visited once

**Graph traversal** needs to make sure that:

- Every node is **reached**
- Every node is visited only **once**

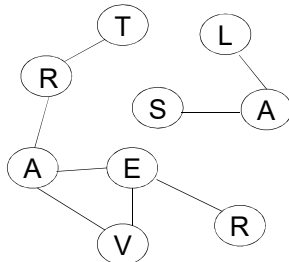
## Traversing a connected graph (depth first)



Need to **mark nodes** as **visited**

## Traversing an **un**connected graph (depth first)

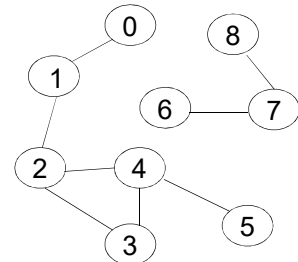
- Need to traverse **each** **connected component**
- Still need to **mark nodes** as visited



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## Traversing an **un**connected graph (depth first)

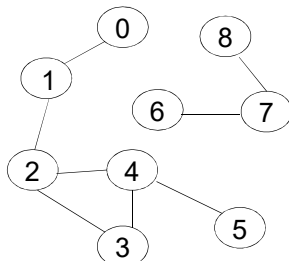


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## Traversing an unconnected graph (depth first)

```
int order=0;
```



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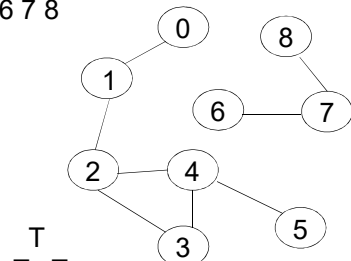
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## Traversing an unconnected graph (depth first)

Matrix

0 1 2 3 4 5 6 7 8

0 T  
1 T T  
2 T T T  
3 T T  
4 T T T  
5  
6  
7  
8



T  
T T  
T

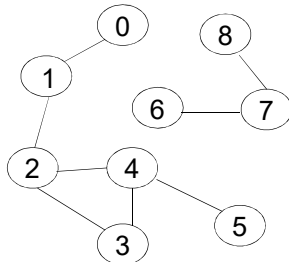
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## Traversing an unconnected graph (depth first)

### Adjacency List

0 → 1  
1 → 2  
2 → 3 → 4 → 1  
3 → 2 → 4  
4 → 3 → 2 → 5  
5 → 4  
6 → 7  
7 → 8 → 6  
8 → 7



## visited[] array: keeping track of what's been done

```
/* invoke an array to track whether or not a
node has already been visited */
int visited[V];
listdfs()
{
    int k;
    /* initialize - no nodes yet visited */
    for(k = 0; k < V; k++)
        visited[k] = 0;
}
```

## Adjacency list node

```
/* adjacency list is an array of pointers to
nodes; node is struct with value (nodeID)
and next ptr*/
struct node{
    int value;
    struct node *next;
};
struct node* adj[V];
```

## Visiting nodes; updating the visited[] array

```
int visited[V];
int order=0; /*keeps track of the order in
which nodes are visited */
void visitDFS(int k)
{
    struct node* t;
    visited[k] = ++order;
    for(t = adj[k]; t != NULL; t = t->next){
        if( !visited[t->v] )
            visitDFS( t->v );
    }
}
```

## Example dfs graph traversal

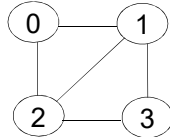
Adjacency List

0→1→2

1→0→2→3

2→0→1→3

3→1→2



## Example dfs graph traversal

Adjacency List

0→6

1→4→7

2→8

3→5→8

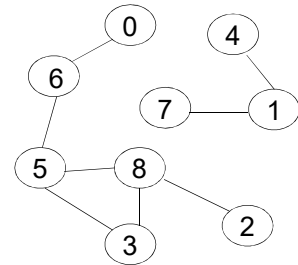
4→1

5→3→6→8

6→0→5

7→1

8→2→3→5



## Graph dfs: Analysis

- Fill in the **visited[]** array:
- **Examine** (at most) **each edge twice**:

## Graph dfs: Analysis

- Fill in the **visited[]** array:
  - **|V|**
- Examine (at most) each edge twice:
  - **|E|**
- Overall: **?**

## Graph *breadth*-first search

- Again, modify the tree bfs, to make sure that:

## Graph *breadth*-first search

- Again, modify the analogous tree search, to make sure that:
  - Every node is **visited**, even if the graph is **not connected**, and
  - Every node is **visited only once**

## brfs visit()

```
int visited[V]; int order=0;
void visitBFS(int k){
    struct node* t;
    enQ(Q,k);
    while(!Qempty(Q)){
        k = deQ(Q);
        if( !visited[k] ){
            visited[k] = ++order;
            for(t = adj[k]; t != NULL; t = t->next){
                if( !visited[t->num] )
                    enQ(Q,t->num);
            }
        }
    }
}
```

## Breadth-first graph search

```
int visited[V];
void listbfs()
{
    int k;
    for( k = 0; k < V; k++ ) visited[k]= 0;
    for( k = 0; k < V; k++ )
        if(!visited[k])
            visitBFS(k);
}
```

## Weighted graphs

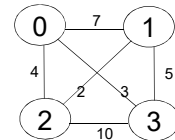
So far, we used **arbitrary ordering** of the connected nodes (determined by position in adjacency list or matrix)

- For **weighted** graphs, it might be nice to **get the nodes** out in **order** of distance
  - Distance = sum of weights

## Example weighted graph brfs

Adjacency List

0 → 1 → 2  
1 → 0 → 2 → 3  
2 → 0 → 1 → 3  
3 → 1 → 2



Previous visit order from node 0:

- But if these are restaurants and bars, and we want to go to a **nearby** bar

From restaurant 0...

## Priority Queues

We can **still use a queue**, but **we make that a priority queue** (PQ).

- Chapter 5, Skiena book