

What is not Cluster Analysis

Supervised classification

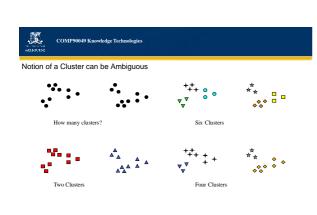
Have class label information

Simple segmentation

Dividing students into different registration groups alphabetically, by last name

Results of a query
Groupings are a result of an external specification

Graph partitioning
Some mutual relevance and synergy, but areas are not identical

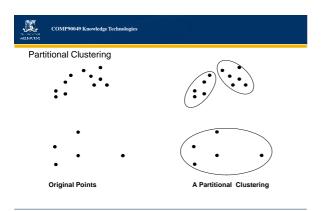


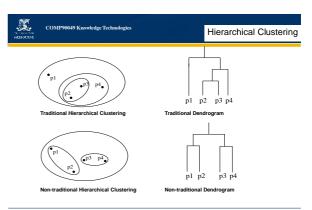
Types of Clustering
A clustering is a set of clusters
Important distinction between hierarchical and partitional sets of clusters
Partitional Clustering

• A division data objects into non-overlapping subsets (clusters) such that each data object is in exactly one subset

Hierarchical clustering
• A set of nested clusters organized as a hierarchical tree

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Other Distinctions Between Sets of Clusters

Exclusive versus non-exclusive

- In non-exclusive clusterings, points may belong to multiple clusters.
 Can represent multiple classes or 'border' points

Fuzzy versus non-fuzzy

- In fuzzy clustering, $\overset{^{\prime}}{a}$ point belongs to every cluster with some weight between 0 and 1
- Weights must sum to 1
 Probabilistic clustering has similar characteristics

Partial versus complete
In some cases, we only want to cluster some of the data
Heterogeneous versus homogeneous
Cluster of widely different sizes, shapes, and densities

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Types of Clusters

Well-separated clusters

Center-based clusters

Contiguous clusters

Density-based clusters

Property or Conceptual

Described by an Objective Function



Types of Clusters: Well-Separated (easiest clustering)

Well-Separated Clusters:

A cluster is a set of points such that any point in a cluster is closer (or more similar) to every other point in the cluster than to any point not in the cluster.

3 well-separated clusters



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Types of Clusters: Center-Based

Center-based

- A cluster is a set of objects such that an object in a cluster is closer (more similar) to the "center" of a cluster, than to the center of any other cluster
 The center of a cluster is often a centroid, the average of all the points in the cluster, or a medoid, the most "representative" point of a cluster



4 center-based clusters



Types of Clusters: Contiguity-Based

Contiguous Cluster (Nearest neighbor or Transitive)

A cluster is a set of points such that a point in a cluster is closer (or more similar) to one or more other points in the cluster than to any point not in the









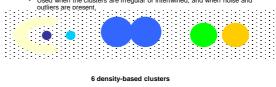
8 contiguous clusters

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Types of Clusters: Density-Based

Density-based

- A cluster is a dense region of points, which is separated by low-density regions, from other regions of high density.
- Used when the clusters are irregular or intertwined, and when noise and





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Types of Clusters: Conceptual Clusters

Shared Property or Conceptual Clusters

Finds clusters that share some common property or represent a particular concept.



2 Overlapping Circles

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Types of Clusters: Objective Function

Clusters Defined by an Objective Function

- Finds clusters that minimize or maximize an objective function.
- Enumerate all possible ways of dividing the points into clusters and evaluate the 'goodness' of each potential set of clusters by using the given objective function. (NP Hard)
- Can have global or local objectives.
 - Hierarchical clustering algorithms typically have local objectives Partitional algorithms typically have global objectives
- A variation of the global objective function approach is to fit the data to a parameterized model.
 - Parameters for the model are determined from the data.
 - Mixture models assume that the data is a 'mixture' of a number of statistical distributions.



Types of Clusters: Objective Function ...

Map the clustering problem to a different domain and solve a related problem in that domain

- Proximity matrix defines a weighted graph, where the nodes are the points being clustered, and the weighted edges represent the proximities between points
- Clustering is equivalent to breaking the graph into connected components, one for each cluster.
- Want to minimize the edge weight between clusters and maximize the edge weight within clusters



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Characteristics of the Input Data Are Important

Type of proximity or density measure

This is a derived measure, but central to clustering

Sparseness

- Dictates type of similarity
- Adds to efficiency Attribute type

- Dictates type of similarity

 Type of Data
- Dictates type of similarity Other characteristics, e.g., autocorrelation

Dimensionality

Noise and Outliers

Type of Distribution



K-means and its variants

Hierarchical clustering

Density-based clustering

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K-means Clustering

Partitional clustering approach Each cluster is associated with a c

troid (center point) Each point is assigned to the cluster with the closest centroid Number of clusters, K, must be specified The basic algorithm is very simple

- 1: Select K points as the initial centroids.
- 2: repeat
- 3: Form K clusters by assigning all points to the closest centroid.
- Recompute the centroid of each cluster.
- 5: until The centroids don't change



K-means Clustering - Details

Initial centroids are often chosen randomly.

Clusters produced vary from one run to another.
The centroid is (typically) the mean of the points in the cluster.
'Closeness' is measured by Euclidean distance, cosine similarity, correlation, etc.

K-means will converge for common similarity measures mentioned above.

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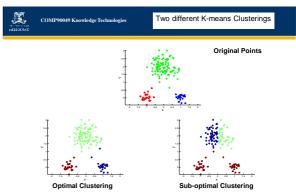
Most of the convergence happens in the first few iterations.

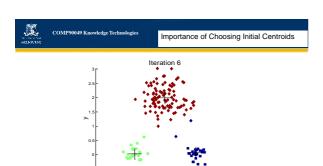
Often the stopping condition is changed to 'Until relatively few points change clusters' (this way the stopping criterion will not depend on the type of similarity or dimensionality)

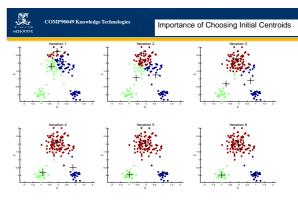
Complexity is O(n * K * 1 * d)

n = number of points, K = number of clusters.
I = number of iterations, d = number of attributes

Unfortunately we cannot a priory know the value of I!









Evaluating K-means Clusters

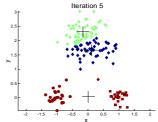
Most common measure is Sum of Squared Error (SSE)

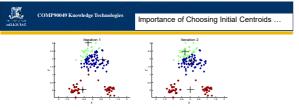
- For each point, the error is the distance to the nearest cluster
 To get SSE, we square these errors and sum them.

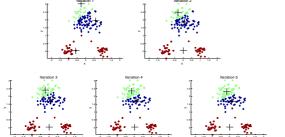
$$SSE = \sum_{i=1}^{K} \sum_{x \in C_i} dist^2(m_i, x)$$

- x is a data point in cluster C_i and m_i is the representative point for cluster C_i
 can show that m_i corresponds to the center (mean) of the cluster
- Given two clusters, we can choose the one with the smallest error
 One easy way to reduce SSE is to increase K, the number of clusters
 - A good clustering with smaller K can have a lower SSE than a poor clustering with higher K

Importance of Choosing Initial Centroids Iteration 5









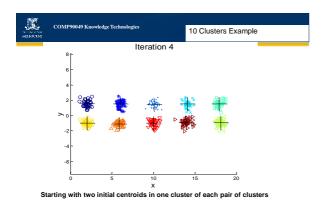
If there are K 'real' clusters then the chance of selecting one centroid from each cluster is small.

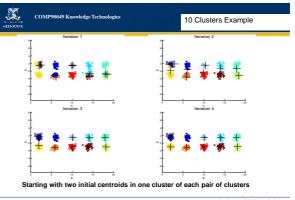
- Chance is relatively small when K is large If clusters are the same size, n, then

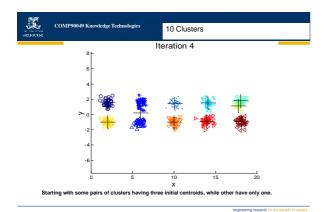
$$P = \frac{\text{\# of ways to select one centroid from each cluster}}{\text{\# of ways to select K centroids}} = \frac{\binom{n}{1}}{\binom{nK}{K}} \approx \frac{n^K}{\frac{(nK)^K}{K!}}$$

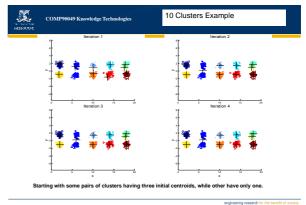
$$K!$$

- For example, if K = 10, then probability = $10!/10^{10} = 0.00036$ Sometimes the initial centroids will readjust themselves in 'right' way, and sometimes they don't Consider an example of five pairs of clusters









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Solutions to Initial Centroids Problem

Multiple runs

· Helps, but probability is not on your side

Sample and use hierarchical clustering to determine initial centroids Select more than k initial centroids and then select among these initial centroids

· Select most widely separated

Postprocessing

Bisecting K-means

· Not as susceptible to initialization issues



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Handling Empty Clusters

Basic K-means algorithm can yield empty clusters

Several strategies

- Choose the point that contributes most to SSE
- Choose a point from the cluster with the highest SSE
- If there are several empty clusters, the above can be repeated several times.

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Updating Centers Incrementally

In the basic K-means algorithm, centroids are updated after all points are assigned to a centroid

An alternative is to update the centroids after each assignment (incremental approach)

- Each assignment updates zero or two centroids
- More expensive
- Introduces an order dependency
- Never get an empty cluster
- Can use "weights" to change the impact



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Pre-processing and Post-processing

Pre-processing

- Normalize the data
- Eliminate outliers

Post-processing

- · Eliminate small clusters that may represent outliers
- Split 'loose' clusters, i.e., clusters with relatively high SSE
- Merge clusters that are 'close' and that have relatively low SSE
- Can use these steps during the clustering process

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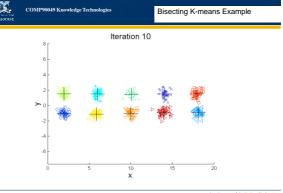
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Bisecting K-means algorithm

- Variant of K-means that can produce a partitional or a hierarchical clustering
- 1: Initialize the list of clusters to contain the cluster containing all points.

- repeat
 Select a cluster from the list of clusters
 for i = 1 to number_of_ilterations do
 Bisect the selected cluster using basic K-means
 end for
- Add the two clusters from the bisection with the lowest SSE to the list of clusters.
- 8: until Until the list of clusters contains K clusters



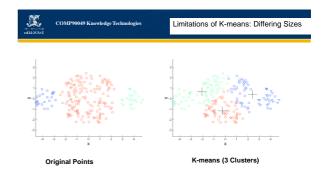


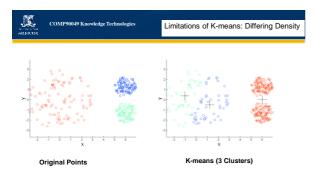
Limitations of K-means

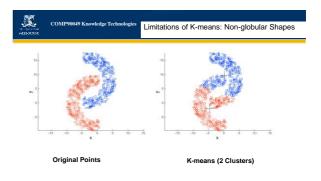
K-means has problems when clusters are of differing

- Densities
- · Non-globular shapes

K-means has problems when the data contains outliers.









Final Comment on Clustering

Clustering is in the eyes of the beholder

"The validation of clustering structures is the most difficult and frustrating part of cluster analysis.

Without a strong effort in this direction, cluster analysis will remain a black art accessible only to those true believers who have experience and great courage."

Algorithms for Clustering Data, Jain and Dubes

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