

1(a) The vector equation is equivalent to the matrix equation

$$\begin{matrix} \text{1st column} \nearrow \\ \begin{bmatrix} x_1 & x_2 & x_3 & x_4 \end{bmatrix} \end{matrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

or more explicitly

$$\begin{bmatrix} 1 & -1 & 1 & -2 \\ 2 & -1 & 1 & -1 \\ -1 & -1 & 1 & -4 \\ 1 & -1 & 0 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

As an augmented matrix, this reads

$$\left[\begin{array}{cccc|c} 1 & -1 & 1 & -2 & 0 \\ 2 & -1 & 1 & -1 & 0 \\ -1 & -1 & 1 & -4 & 0 \\ 1 & -1 & 0 & -1 & 0 \end{array} \right]$$

$$(b) \left[\begin{array}{cccc|c} 1 & -1 & 1 & -2 & \\ 2 & -1 & 1 & -1 & \\ -1 & -1 & 1 & -4 & \\ 1 & -1 & 0 & -1 & \end{array} \right] \begin{matrix} \\ R_2 - 2R_1 \\ R_3 + R_1 \\ R_4 - R_1 \end{matrix} \sim \left[\begin{array}{cccc|c} 1 & -1 & 1 & -2 & \\ 0 & 1 & -1 & 3 & \\ 0 & -2 & 2 & -6 & \\ 0 & 0 & -1 & 1 & \end{array} \right] \begin{matrix} \\ \\ R_3 + 2R_2 \\ \end{matrix}$$

$$\sim \left[\begin{array}{cccc|c} 1 & -1 & 1 & -2 & \\ 0 & 1 & -1 & 3 & \\ 0 & 0 & 0 & 0 & \\ 0 & 0 & -1 & 1 & \end{array} \right] \begin{matrix} \\ \\ R_3 \leftrightarrow R_4 \\ \end{matrix} \sim \left[\begin{array}{cccc|c} 1 & -1 & 1 & -2 & \\ 0 & 1 & -1 & 3 & \\ 0 & 0 & -1 & 1 & \\ 0 & 0 & 0 & 0 & \end{array} \right]$$

(c) From the answer to (b) we have that

$$\left[\begin{array}{cccc|c} 1 & -1 & 1 & -2 & 0 \\ 2 & -1 & 1 & -1 & 0 \\ -1 & -1 & 1 & -4 & 0 \\ 1 & -1 & 0 & -1 & 0 \end{array} \right] \sim \left[\begin{array}{cccc|c} 1 & -1 & 1 & -2 & 0 \\ 0 & 1 & -1 & 3 & 0 \\ 0 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

There is no leading entry for x_4 . Hence we set

$$x_4 = t, \quad t \in \mathbb{R}$$

Proceeding now by back substitution gives

$$x_3 = t$$

$$x_2 = x_3 - 3x_4 = -2t$$

$$x_1 = x_2 - x_3 + 2x_4 = -t$$

Hence the general solution is

$$(x_1, x_2, x_3, x_4) = (-t, -2t, t, t) = t(-1, -2, 1, 1) \quad t \in \mathbb{R}$$

(d) The row echelon form of $[\underline{x}_1, \underline{x}_3, \underline{x}_4]$ is the same as the row echelon form of $[\underline{x}_1, \underline{x}_2, \underline{x}_3, \underline{x}_4]$ with the second column deleted. Hence

$$[\underline{x}_1, \underline{x}_3, \underline{x}_4] \sim \left[\begin{array}{ccc} 1 & 1 & -2 \\ 0 & -1 & 3 \\ 0 & -1 & 1 \\ 0 & 0 & 0 \end{array} \right] \xrightarrow{R_3 - R_2} \left[\begin{array}{ccc} 1 & 1 & -2 \\ 0 & -1 & 3 \\ 0 & 0 & -2 \\ 0 & 0 & 0 \end{array} \right]$$

The rank of this matrix is 3 so the vectors are linearly independent.

$$2. (a) R = \{(x, y, z) : 2x + z = 0\}$$

3

This can be rewritten

$$R = \{(x, y, -2x) : x, y \in \mathbb{R}\}$$

We suspect that this is a subspace since it is equal to $\text{Span}\{(1, 0, -2), (0, 1, 0)\}$.

We are asked to check this using the definition of a subspace:

(0) Since $(0, 0, 0) \in R$, we see that R is nonempty.

(1) Let $\underline{u} = (x_1, y_1, -2x_1)$ and $\underline{v} = (x_2, y_2, -2x_2)$ be two general vectors in R . Then

$$\begin{aligned} \underline{u} + \underline{v} &= (x_1, y_1, -2x_1) + (x_2, y_2, -2x_2) \\ &= (x_1 + x_2, y_1 + y_2, -2(x_1 + x_2)) \\ &= (x_3, y_3, -2x_3) \quad \text{with } x_1 + x_2 = x_3 \in \mathbb{R} \\ &\in R \quad \quad \quad y_1 + y_2 = y_3 \in \mathbb{R} \end{aligned}$$

Hence R is closed under vector addition

(2) Let $\underline{u} = (x_1, y_1, -2x_1)$ be a general vector in R , and let α be a general scalar. We have that

$$\begin{aligned} \alpha \underline{u} &= \alpha (x_1, y_1, -2x_1) \\ &= (\alpha x_1, \alpha y_1, -2\alpha x_1) \\ &= (x', y', -2x') \quad \text{with } \alpha x_1 = x' \in \mathbb{R} \\ &\in R \quad \quad \quad \alpha y_1 = y' \in \mathbb{R} \end{aligned}$$

Hence R is closed under scalar multiplication

All 3 defining properties of a subspace hold true, so R is a subspace.

$$2(b) \quad S = \left\{ (x, y, z) : \frac{x}{2} = y + 1 = 3z \right\} \quad \underline{4}$$

We recognise this as the equation of a line not passing through the origin. We know that only lines passing through the origin are subspaces, so we suspect S is not a subspace. To prove this from the definition of a subspace, we see that

$$(0, -1, 0) \in S.$$

Also $\alpha = 0$ is a scalar. We have that

$$\alpha (0, -1, 0) = 0 (0, -1, 0) = (0, 0, 0) \notin S$$

Hence S is not closed under scalar multiplication

3 Vector form: $(x, y, z) = s(0, 1, 1) + t(1, 0, -2)$
with $s, t \in \mathbb{R}$

Parametric form: Equating components

$$x = t$$

$$y = s$$

$$z = s - 2t$$

Cartesian form: Substituting for s and t in the equation for z in the parametric form gives

$$z = y - 2x \Rightarrow -2x + y + z = 0$$

Alternatively: $\underline{n} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 0 & 1 & 1 \\ 1 & 0 & -2 \end{vmatrix} = \underline{i} \begin{vmatrix} 1 & 1 \\ 0 & -2 \end{vmatrix} - \underline{j} \begin{vmatrix} 0 & 1 \\ 1 & -2 \end{vmatrix} + \underline{k} \begin{vmatrix} 0 & 1 \\ 1 & 0 \end{vmatrix}$
 $= -2\underline{i} + \underline{j} - \underline{k}$

Equation of the plane: $(x, y, z) \cdot \underline{n} = 0$

$$\Rightarrow (x, y, z) \cdot (-2, 1, -1) = 0 \Rightarrow -2x + y - z = 0$$

$$\Rightarrow 2x - y + z = 0$$

as before.