

# COMP20003

## Algorithms and Data Structures Dictionaries and Data Structures

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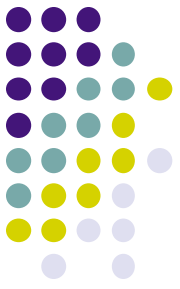
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Information Systems  
University of Melbourne  
Semester 2





# So far...

- We have:
  - Looked at algorithms, fast and slow.
  - Estimated computation time by counting operations.
  - Formalized a system for classifying algorithm efficiency.



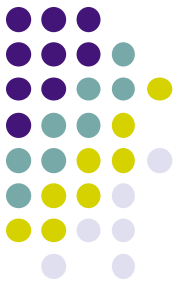
# Outline of the first few lectures

- Algorithms: general
- This subject: details
- Algorithm efficiency: intuitive
- Computational complexity
- ● Data structures
  - Basic data structures
  - Algorithms on basic data structures
  - Complexity analysis of algorithms on basic ds's



# Textbook

- Skiena: Chapter 3, Data Structures



# This section

- A lightning tour of fundamental data structures used for search:
  - Arrays
  - Linked Lists
  - Trees

# Abstract Data Types vs. Data Structures



- *Abstract* data type: what it does
  - Stack, queue.
  - Dictionary: look up by key.
  - Does not specify an implementation.
- *Concrete* data structure:
  - Array, linked list, tree
  - Can be used to implement abstract data type.



# Data structures

- Organizing data is important.
- It is helpful to organize with the task in mind.
- For searching, e.g.:
  - Some high-level languages have inbuilt “dictionaries”, or associative arrays (Python, awk).
  - In lower-level languages, dictionaries are implemented directly using a fundamental data structure.



# Searching

- Search Question:
  - Given a search **key**,
  - Find the **record(s)** that correspond to this key.
  - Typically we describe record simplistically with fields **key** and **info** (or just key).
- Examples:
  - Students and seat numbers.
  - Telephone books.
- How you organize the data is important.





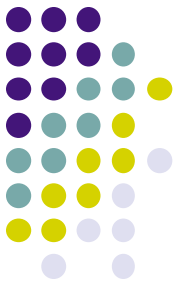
# Dictionaries

- Python built-in dictionary structure.

```
>>> tel = {'jack': 4098, 'sape': 4139}
>>> tel['guido'] = 4127
>>> tel
{'sape': 4139, 'guido': 4127, 'jack': 4098}
>>> tel['jack']
4098
```

- The dictionary is implemented using one of the underlying data structures.





# Outline of the first few lectures

- Algorithms: general
- This subject: details
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  - Basic data structures
  - Algorithms on basic data structures
  - Complexity analysis of algorithms on basic ds's



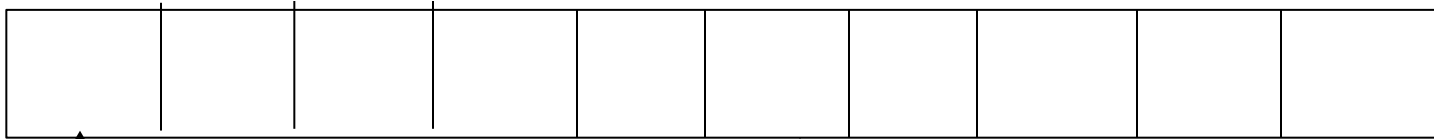
# Array

- An array: given an index (location), we can retrieve any item in unit time.
- Mimics the structure of random access memory (RAM), where the index is the memory address.
- If items are in arbitrary order, finding a key in array of size  $n$  requires  $O(n)$  time.



# Arrays in C (lightening review)

```
int A[10];
```



To access the  
value of the first  
element of the  
array:

**A[0]**

**\*A or \*(A+0)**



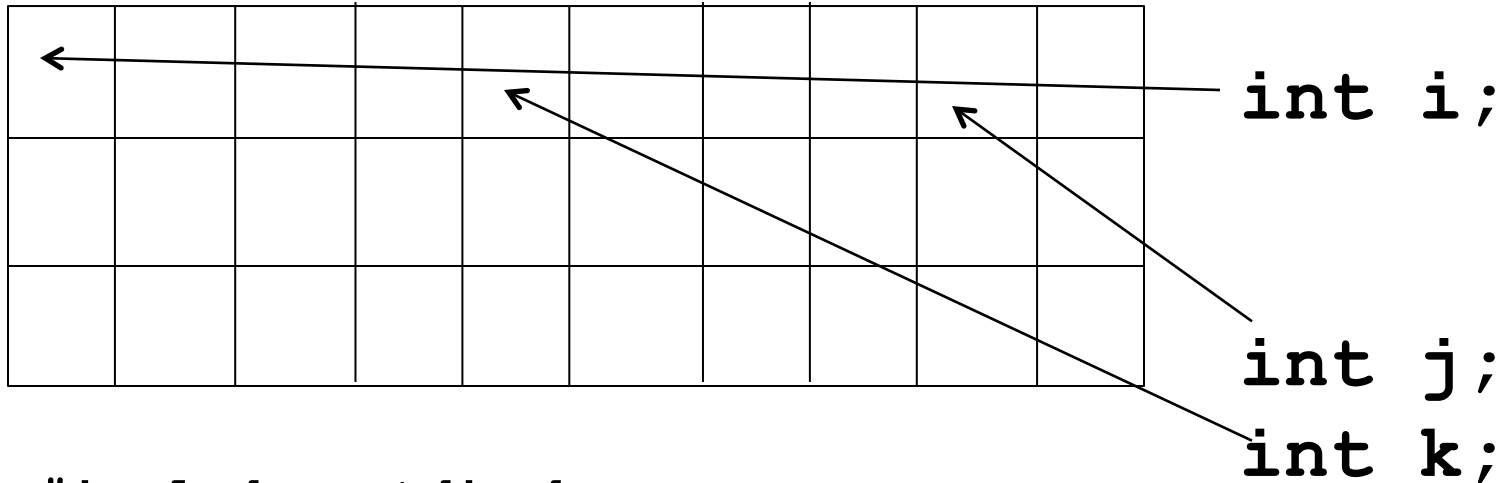
To access the value  
of the sixth element:

**A[5]**

**\*(A+5)**



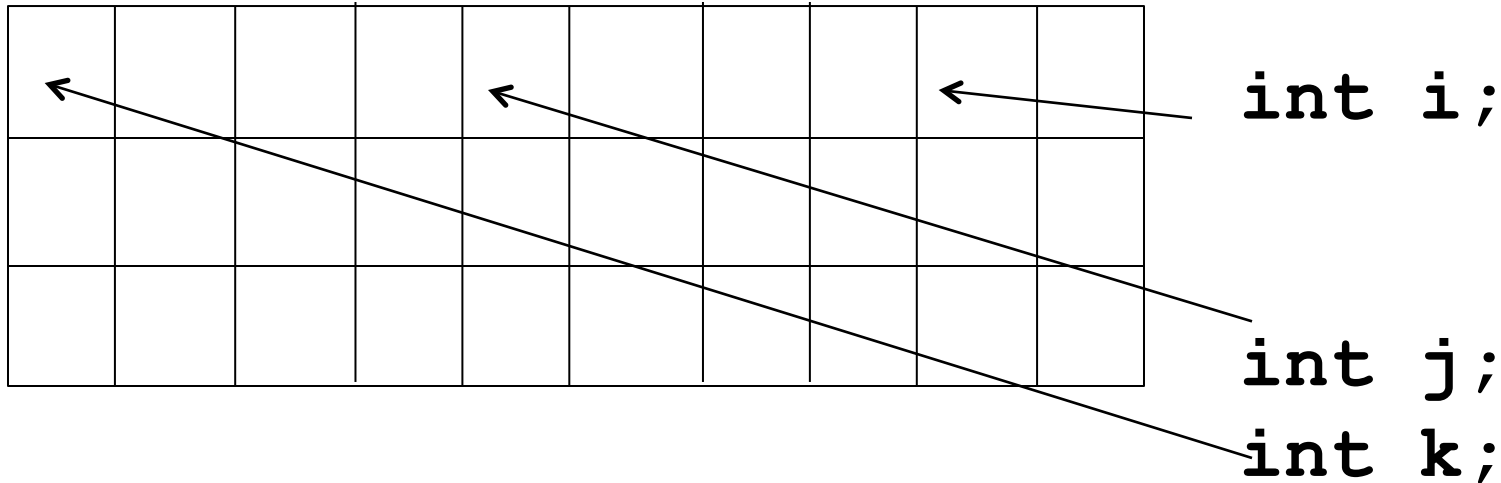
# Random Access Memory



```
#include <stdio.h>
int main(argc, argv)
{
    int i,j,k;
    i = 5; j = 10; k = 15;
    printf("i: value = %d; address = %d\n", i, &i);
    printf("j: value = %d; address = %d\n", j, &j);
    printf("k: value = %d; address = %d\n", k, &k);
}
```



# Random Access Memory



**i: value = 5; address = 134509652**  
**j: value = 10; address = 134509648**  
**k: value = 15; address = 134509644**

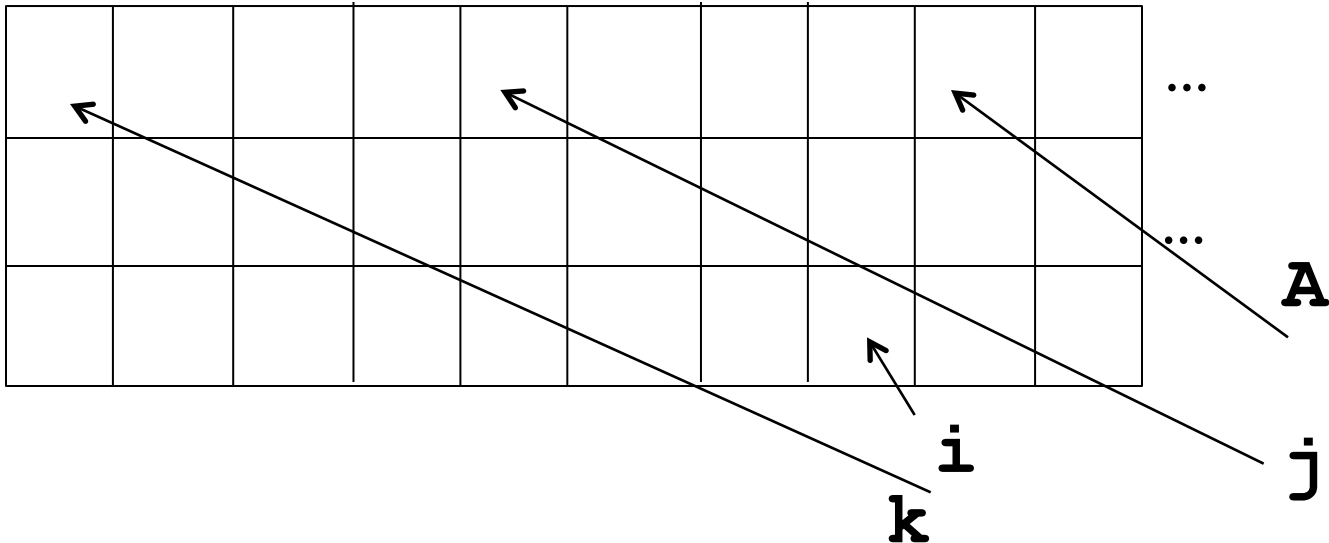


# Random Access Memory


```
int i;  
int  A[100];  
int j,k;  
i = 5; j = 10; k = 15;  
printf("i: value = %.2d; address = %d\n", i, &i);  
printf("A:           ; address = %d\n", A );  
printf("j: value = %.2d; address = %d\n", j, &j);  
printf("k: value = %.2d; address = %d\n", k, &k);
```



# Random Access Memory



i: value = 05; address = 134509644

A: ; address = 134509232

j: value = 10; address = 134509228

k: value = 15; address = 134509224

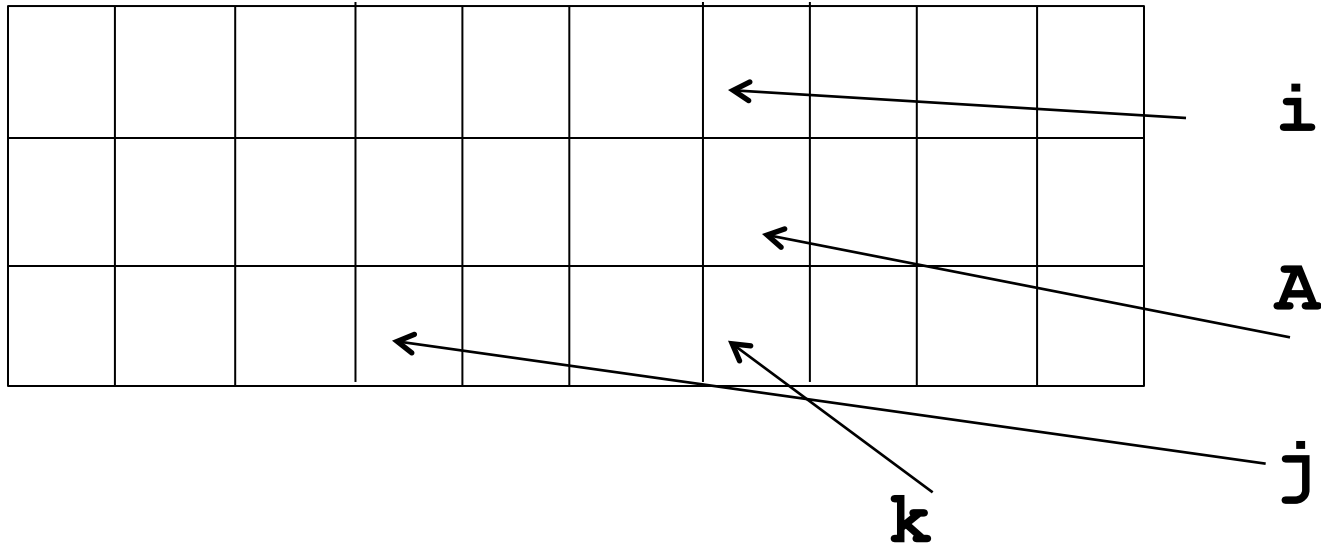
Element address =

Base + index \* element\_size





# Random Access Memory



Note: Although we often draw RAM to *look* like a 2-dimensional array,  
*it is actually a linear (1-dimensional) array.*



# A 2-Dimensional Array in C


- `int A[rows][cols]`
- `int A[5][10]`



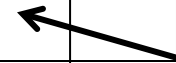
# A 2-Dimensional Array in C


- `int A[5][10]`

Actually, **A** is an array of size 5,  
each element of **A** is an array of 10 ints.



# A 2-Dimensional Array in C

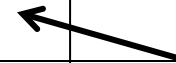
**A[2][8]**

**\* (A + 2 \* 10 \* 4  
+ 8 \* 4)**

- Address of element[thisrow][thiscolumn] =  
Base + thisrow \* num\_cols \* sizeof(element)  
+ thiscol \* sizeof(element)



# A 2-Dimensional Array in C

**A[2][8]**

**\* (A + 2 \* 10 \* 4  
+ 8 \* 4)**

- Address of element[thisrow][thiscolumn] =  
base + thisrow \* num\_cols \* sizeof(element)  
+ thiscol \* sizeof(element)
- num\_cols \* sizeof(element) = size of one row



# Homework

- What is the difference between:
  - `int a[10][20];`
  - `int *b[10];`
- ?
- Hint 1: Think memory allocation.
- Hint 2: See K&R section 5.9.
- Hint 3: How could you test your answer?



# Back to arrays as dictionaries

- To sort or not to sort?
- How to determine which is best?



# Sorting: fine points

- Sorting assumes the keys are “sortable”, *i.e.* comparable.
  - *e.g.* categories, colors are not sortable, unless you associate an identifier .
- The computer science definition of sorting means to put things into a *well-defined* order.
  - Other ways of sorting: binning, topological sort.





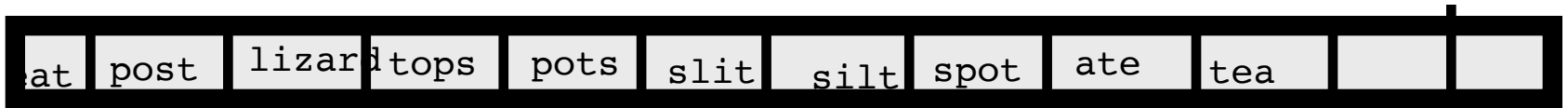
# Sorting: fine points

- In computing applications of sorting, there is a *key*, and associated *information*.
- We sort by *key*, and the *information* comes along for the ride.
  - e.g. Student database, sorted on student ID.  
The information is name, address, degree, *etc.*
- In our examples, we often do not show the *information* explicitly.



# Unsorted arrays

- Just put the item in at the end of the array:
  - Insertion is in  $O(1)$



- How many comparisons you need to insert?





# Unsorted array: search

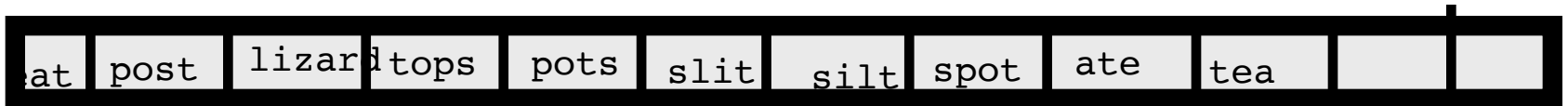
```
for(i=0;A[i]!=EMPTY;i++)    /*A[] is an array of integers */
{
    cmps++;
    if (A[i] == searchkey)
    {
        printf("Found key %d at position %d\n",
                searchkey,i);
        printf("Key comparisons: %d\n", cmps);
        return FOUND;
    }
}

printf("Key not found\n");
printf("Key comparisons: %d\n", cmps);
return NOTFOUND;
```



# Unsorted arrays

- Just put the item in at the end of the array:
  - Insertion is in  $O(1)$

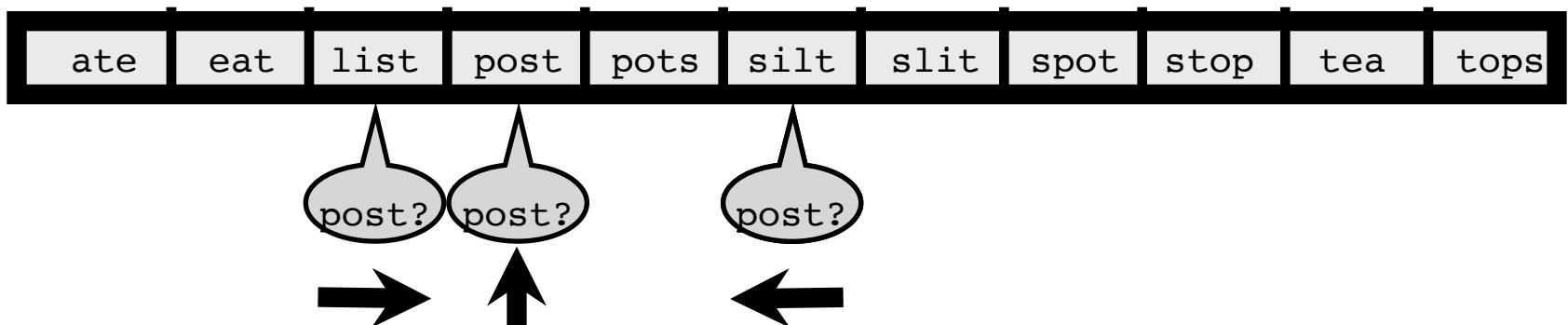


- What is the complexity of search?
  - $O(?)$

# Sorted arrays



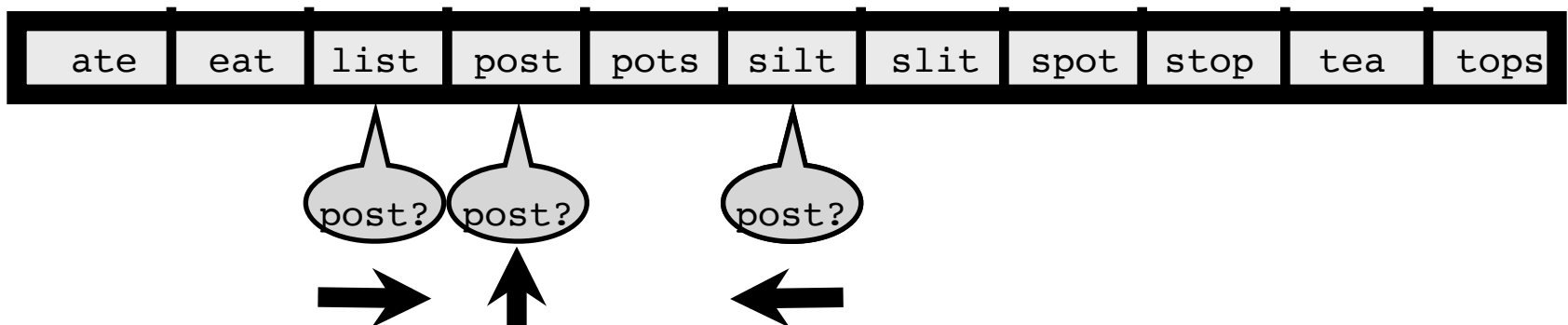
- How do you search for “post”?





# Sorted arrays

- Binary search in sorted array:





# Sorted array: binary search

```
int i=0;
int j=ARRAYFILL-1;
while(i<=j)
{
    cmps++; mid = (i+j)/2;
    /*diagnostic*/
    if(DEBUG) printf("i:%d; end:%d; mid:%d\n",i,j,mid);

    if (A[mid]==searchkey)
    {
        printf("Found key %d at position %d, comparisons: %d \n",
                searchkey,i,cmps);
        return FOUND;
    }
    if (searchkey<A[mid] j=mid-1;
    else i=mid+1;
}

printf("Key not found, comparisons: %d\n", cmps);
return NOTFOUND;
```



# Searching: analysis

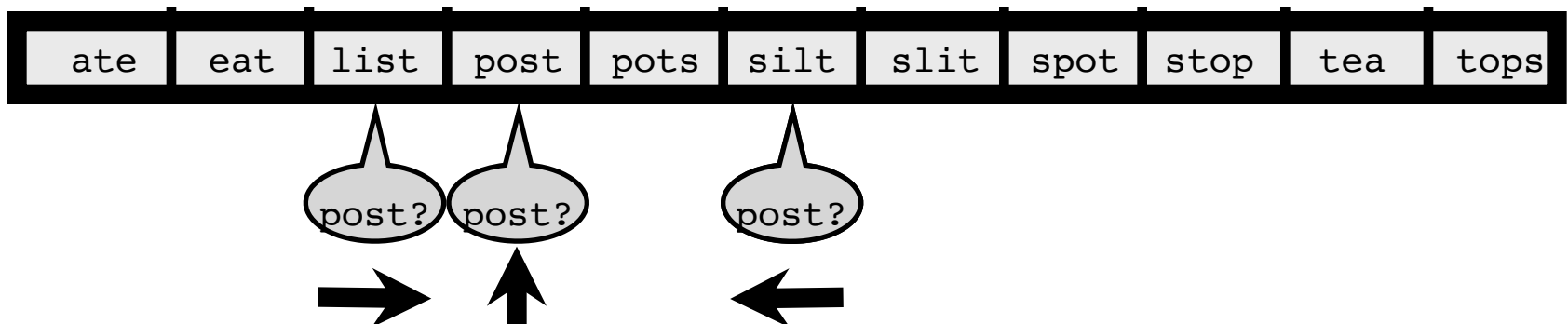
- Unsorted array:  $O(?)$
- Sorted array (binary search):  $O(?)$





# Sorted arrays

- Binary search in sorted array:
  - Search is in  $O(\log n)$



- What about insertion?



```
i=ArrayFill-1;
while (A[i]>INSERTNUM && i>=0)
{
    A[i+1] = A[i];
    i--;
}
A[i+1] = INSERTNUM;  /** only get here if A[i] <=
                      * INSERTNUM, have already moved
                      * previous contents
                      **/
ArrayFill++;  /* to accomodate the new item */

/* test */
for(i=0;i<ArrayFill;i++) printf("%d    ",A[i]);
printf("\n");

/* any assumptions? */
```



# Sorted and unsorted arrays

- How to compare?
  - Key comparisons: usually the most expensive operation in searching.



# Analysis

- Search:
  - Unsorted array:  $O(n)$  per search
  - Sorted array (binary search):  $O(\log n)$  per search
- Insert:
  - Unsorted array:  $O(1)$  per insertion
  - Sorted array:  $O(n)$  per insertion



# Search: m lookups on n items

- Unsorted array, linear search:
  - n insertions @ 1 operation  $\rightarrow$  n operations  $O(n)$
  - m lookups @ n operations  $\rightarrow m \cdot n$  (worst case)
  - $O(n + m \cdot n) = O(mn)$
- Sorted array, binary search:
  - n insertions @ n comparisons and n data movements each  $\rightarrow O(n^2)$
  - m searches @  $\log n$  comps each  $\rightarrow m \cdot \log_2 n$
  - $O(n^2 + m \log n)$



# Search: $m$ lookups on $n$ items

- Unsorted array, linear search:
  - $n + m \cdot n \sim m \cdot n$
- Sorted array, binary search:
  - $n^2 + m \log n$
- For  $m \ll n$ , unsorted arrays are better!
- But usually  $m > n$ , so use sorted array...
- ...or even something better.



# Something better?

- What are the worst properties of a sorted array?



# Limited size

- We can overcome the limited size problem using dynamic memory allocation.
- C library functions:
  - `void *calloc(size_t nobj, size_t size)`
  - `void *realloc(void *p, size_t size)`
  - also, of course `void *malloc(size_t size)`
  - All defined in `stdlib.h`





# **malloc(): size\_t**

- **malloc(size\_t size)**
- **size\_t** is:
  - an unsigned integer type
  - the type returned by the **sizeof** operator
  - widely used in the standard library (**stdlib**) to represent sizes and counts.
- *e.g.* **malloc(sizeof(int) )**



# malloc() example (part 1)

```
#define NUMBER 5
int
main (argc, argv)
{
    int    var;
    var = NUMBER;
    printf("%d - %d\n", &var, var);
    return 0;
}
```

>a.out

134509940 - 5



# malloc() example: (part 2)

```
#define NUMBER 5
int
main (argc, argv)
{
    int    *ptr;
    ptr =  (int *)malloc(sizeof(int));
    *ptr = NUMBER; /* note '*' */
    printf("%d - %d\n", ptr, *ptr);
    return 0;
}
>a.out
134613280 - 5
```

# malloc(): check return value



- Be aware: malloc() can fail!
  - If malloc() fails, it returns NULL.
- Never use a pointer to something where the memory allocation has failed!

```
int *B;  
B=(int *)malloc(NUMBER*sizeof(int));  
/* always check return value of malloc() */  
If( B == NULL )  
{  
    printf("malloc() error\n");  
    exit(1);  
}
```

- Or write a function safemalloc() that does this.

# Getting memory for an array using malloc()



```
int A[NUMBER];  
/* while insertions < NUMBER array is OK  
 * BUT... has a limit  
 **/  
  
int *B;  
/* always check return value of malloc() */  
if((B=(int *)malloc(NUMBER*sizeof(int)))==NULL)  
{  
    printf("malloc() error\n");  
    exit(1);  
}  
/** B can now be used like A  
 * better to use calloc(NUMBER,sizeof(int)) */
```

# Getting memory for an array using malloc()



```
int A[NUMBER];  
/** while insertions < NUMBER array is OK  
 * BUT... has a limit  
 **/  
  
int *B;  
/* always check return value of malloc() */  
if((B=(int *)malloc(NUMBER*sizeof(int)))==NULL)  
{  
    printf("malloc() error\n");  
    exit(1);  
}  
/** B can now be used like A  
 * better to use calloc(NUMBER,sizeof(int)) */
```

# Getting memory for an array using calloc()



```
int *B;
/* always check return value of malloc() */
if((B=(int *)calloc(NUMBER,sizeof(int)))==NULL)
{
    printf("malloc() error\n");
    exit(1);
}

/* B now comes with each slot initialized to 0 */
```



# realloc()

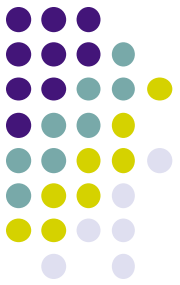
```
int *B;
/** as previously, used malloc(),calloc()
 * RESIZE when insertions == NUMBER *
 **/
B = realloc(B, (NUMBER*2)*sizeof(int));
/* should also check realloc() for NULL*/

/* now initialize new part of array */
for(i=NUMBER; i<NUMBER*2; i++)
    B[i] = NULL;

/* now we have a bigger array, first half
copied from the old B */
```

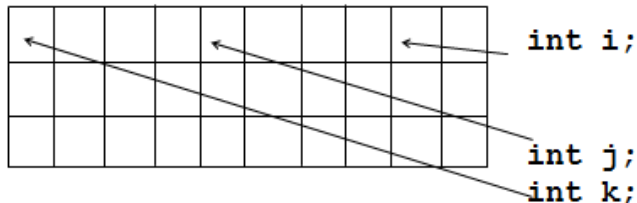


# Details about malloc() and friends



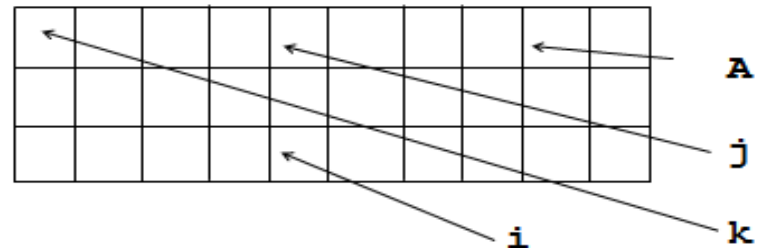
- `malloc()` returns a pointer to a place in memory.
- Argument to `malloc()` specifies how much space to reserve in memory, *i.e.* not allocate to other variables:

## Random Access Memory



i: value = 5; address = 134509652  
j: value = 10; address = 134509648  
k: value = 15; address = 134509644  
Element address =  
Base + index \* element\_size

## Random Access Memory



i: value = 05; address = 134509644  
A: ; address = 134509232  
j: value = 10; address = 134509228  
k: value = 15; address = 134509224



# What's a pointer?

- A pointer is an address in memory.
- What is the output of this code?

```
int    *ptr;  
ptr = (int *)malloc(sizeof(int));  
*ptr = 5;  
printf("%d, %d", ptr, *ptr);
```

- Now what is the output of *this* code?

```
int    *ptr;  
ptr = (int *)malloc(sizeof(int));  
ptr = 5;  
printf("%d, %d", ptr, *ptr);
```

# Details about malloc() and friends



- `#include<stdlib.h>`
- Read the documentation for fine points:
  - `malloc()` returns uninitialized space
  - `calloc()` returns space initialized to 0
  - `realloc(void *p, size_t size)`  
returns space where the start is copied from p  
and the rest is uninitialized.
- Check return value of all memory alloc functions.



# malloc() and free()

- `malloc()` allocates memory.
- `free()` use to deallocate memory

```
void    *ptr;  
ptr = malloc(NUMBER_OF_BYTES) ;  
/* do things until finished with the  
   contents pointed to by ptr */  
free(ptr) ;
```



# Back to sorted arrays...

- Space limitations:
  - Can use `realloc()`.
  - Or can use linked list (sorted linked list).



# Pointers

- For an excellent exposition of pointers in C, see the excellent tutorial by Ted Jensen:
  - LMS Resources → Pointers and Arrays in C



# Pointers

- A pointer in C is an address.

```
int k;  
int *ptr;  
  
k=5;  
ptr = &k;  
printf("%d", *ptr);
```

<5>



# Pointers

- A pointer in C is an address.
- \* is the dereferencing operator.

```
int k;
```

```
int *ptr;
```

```
k=5;
```

```
ptr = &k;
```

```
printf("%d", *ptr);
```

<5>





# Pointers

- A pointer in C is an address.
- Where  $A$  is the name of an array,  $A$  is a pointer to the array, and
  - $A[0]$  is equivalent to  $*(A+0)$ ,
  - $A[5]$  is equivalent to  $*(A+5)$ ...



# Memory Allocation: Summary

- `malloc()`, `calloc()`, and `realloc()` return:
  - The (untyped) address of allocated memory;
  - *i.e.* a pointer to allocated memory.

```
struct node *ptr; /*allocates just enough  
                  room for an address */  
ptr = (struct node *)malloc(sizeof(struct  
node)); /* allocates enough room for the  
        node */
```



- We have discussed the strong and weak points of sorted arrays as search structures:

# Linked lists: flexibility, but overheads



- In a linked list, each item (or key) is located in an arbitrary place in memory, with a link (pointer) to the next item.
- If arbitrary order, finding item is still  $\Theta(n)$ -time.
- Once **insertion point** has been determined, easy to insert (or delete) a new item, by rearranging links.

# Linked lists: flexibility, but overheads

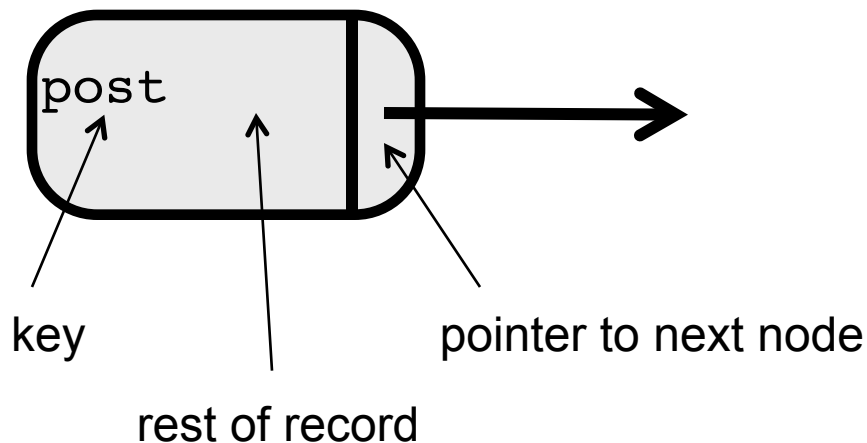


- Takes extra space for each item in the list.
- Takes extra time to allocate the memory for the node for each item.



# The node

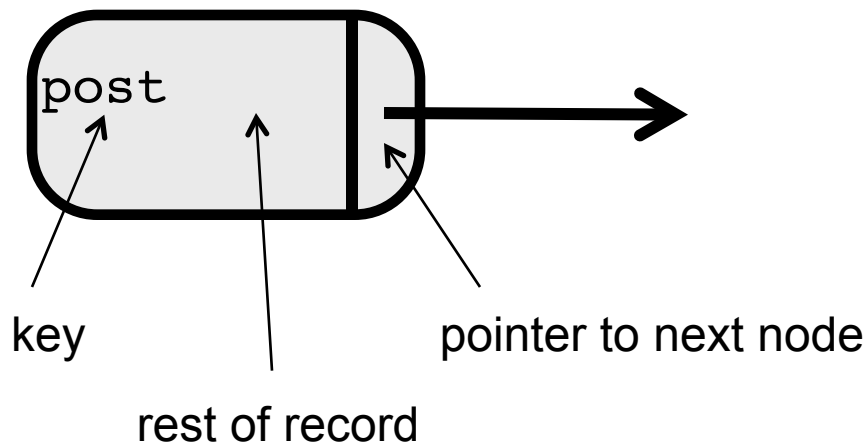
```
struct node{  
    record r;  
    struct node *next;};
```





# The node

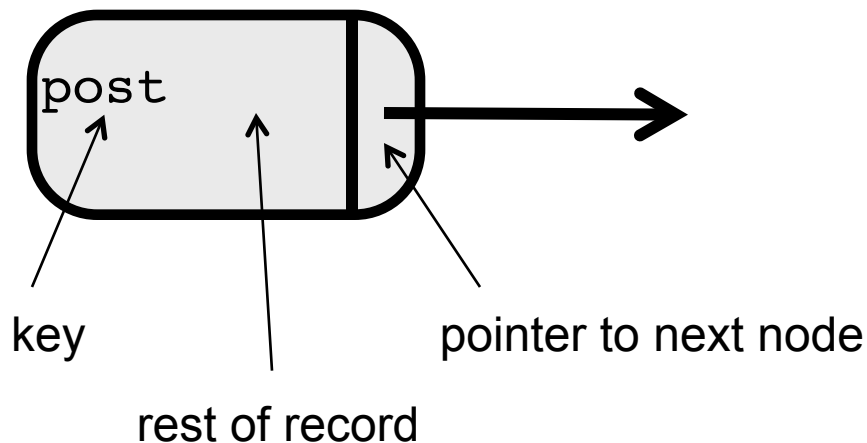
```
typedef
struct node{
    record r;
    struct node *next; }
node_t;
```





# The node

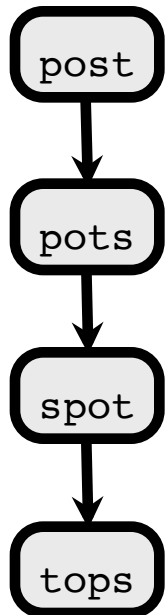
```
typedef
struct node{
    record r;
    struct node *next; }
node_t;
```







# A linked list of nodes



```
struct node
```

```
{
```

```
    char    *key;
```

```
    char    *info;
```

```
    struct node  *next;
```

```
};
```

```
struct node    *newnode;
```

```
newnode = /*malloc space and  
put in the key and info */
```

```
/* suggested declaration style for  
beginner and intermediate */
```



# A (sorted) linked list of nodes

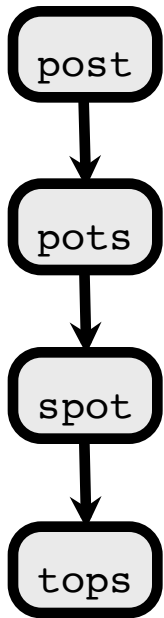
OR

```
typedef
struct node{
    record r;
    struct node *next;}
node_t;

typedef node_t *node_ptr;

node_ptr    newnode;

/* more advanced style */
```





# A (sorted) linked list of nodes

```
struct node
```

```
{
```

```
    char    *key;
```

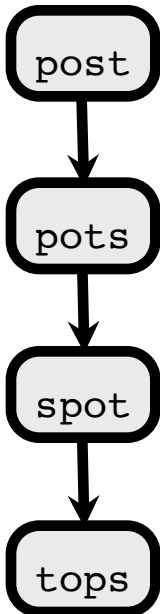
```
    struct node  *next;
```

```
};
```

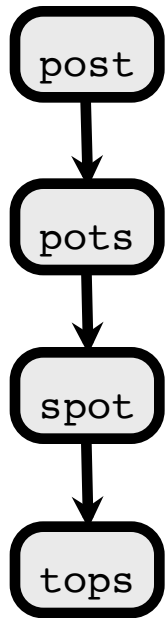
```
struct node    *newnode;
```

```
newnode = /*malloc space  
and put in the key and  
info */
```

```
/* suggested declaration style for  
beginner and intermediate */
```



# Traverse the list





# Traverse the list

```
p = listhead;
if (p==NULL) /* empty list */
else
    while( p->next !=NULL)
    {
        printf("%d\n", p->key);
        p = p->next;
    }
printf("%d\n",p->key);
```

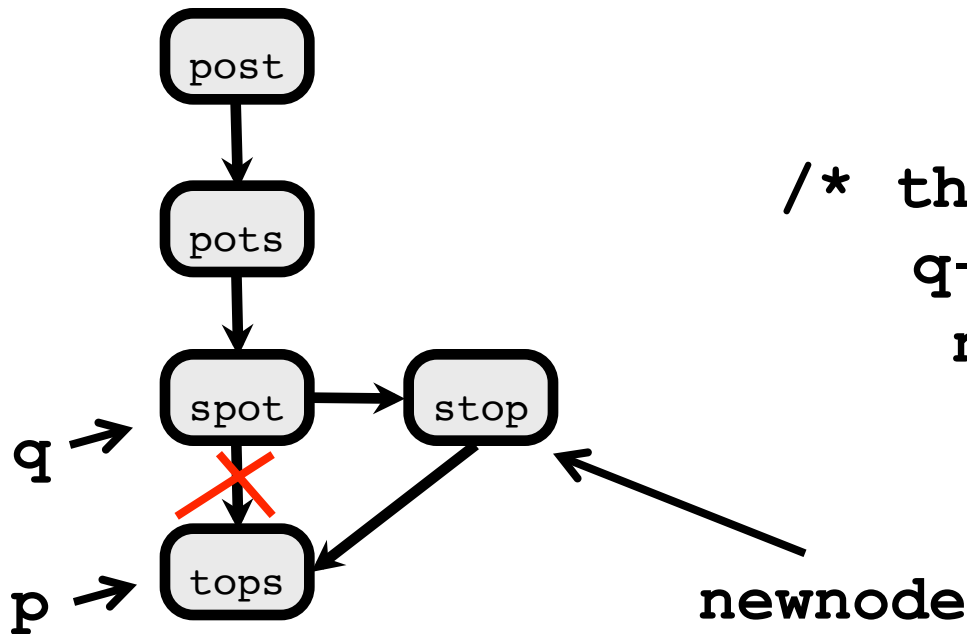


# Traverse the list

```
p = listhead;
if (p==NULL)
{
    printf("List empty\n");
    return;
}

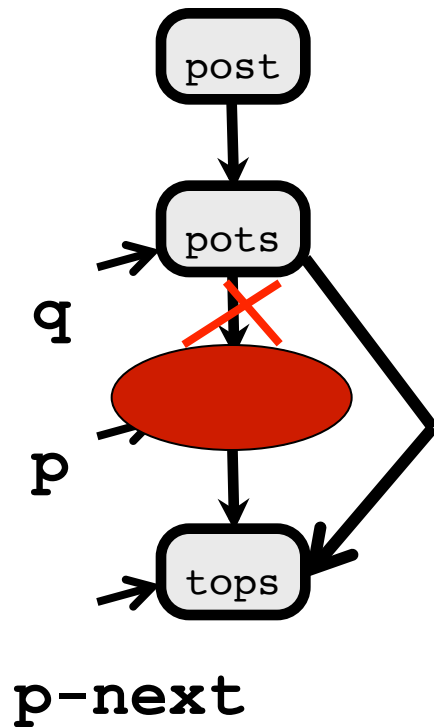
/* traverse and print key */
while (p->next !=NULL)
{
    printf("%d\n", p->key);
    p = p->next;
}
printf("%d\n", p->key); /* why? */
return;
```

# Inserting a new node into a sorted linked list



```
/* find correct place in list
   to insert */
/* how? */
/* then adjust pointers*/
q->next = newnode;
newnode->next=p;
```

# Deleting a node



```
/* p points to the node  
we want to delete */  
q->next = p->next;  
free(p);
```



# Linked lists: sorted vs. unsorted



- What are the advantages of keeping a linked list in sorted order?
- What are the disadvantages?



# Search: Arrays vs. Linked Lists

- Sorted arrays:
  - Fast search (binary search), but
  - Slow insertion (keeping sorted order).
- Sorted array:
  - Fixed size, but
  - Can grow with `realloc()`
  - Usual growth is factor of 2
- Array needs only one memory allocation.
- Linked list needs many.



# Table of “running times”

	One Search	One Insert
Unsorted array		
Sorted array		
Unsorted linked list		
Sorted linked list		



# Table of “running times”

	One Search	One Insert
Unsorted array	$n$	1
Sorted array	$\log n$	$n$
Unsorted linked list	$n$	1
Sorted linked list	$n$	$n$



# Exercise

How many operations are needed for  $m$  searches in a dictionary of  $n$  items?

	Each Insertion	Each Search	Build + Search
Unsorted array	$O(1)$	$O(n)$	$O(mn)$
Sorted array	$O(n)$ comps + $O(n)$ data movements	$O(\log n)$	
Unsorted linked list	$O(1)$	$O(n)$	
Sorted linked list	$O(n)$ comps	$O(n)$	

# Practical complexity and algorithms



- $O(1)$ : Execute instructions once (or a few times), independent of input.
  - Example: pick a lottery winner.
- $O(\log n)$ : keep splitting the input, and only operate on *one* section of the input.
  - Example:
- $O(n)$ : Execute instruction(s) once for each data item:
  - Example:

# Practical complexity and algorithms



- $O(n \log n)$ : split the input repeatedly, and do something to *all* the segments
  - Example: Many sorting algorithms
- $O(n^2)$ : For each item, do something to all the others. (Nested loops.)
  - Example:
  - Note: getting slow for large data...
- $O(n^3)$ :
- $O(2^n)$ :



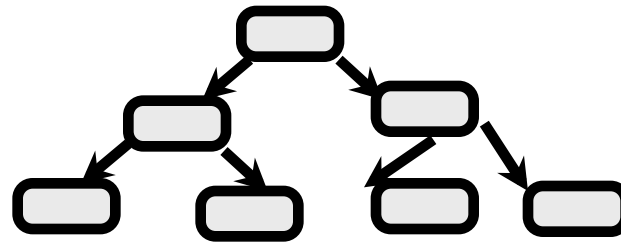
# Breaking out of linearity

- Compare:

- Linked list



- Binary tree



- If we reliably know whether the desired item is in the left subtree or the right subtree, we could find it more quickly.





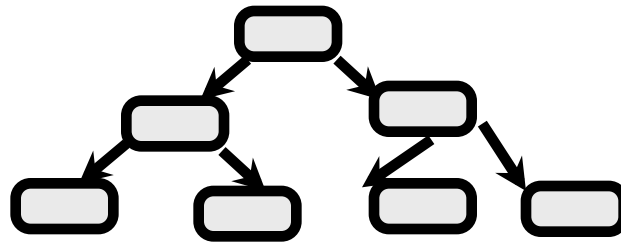
# Breaking out of linearity

- Compare:

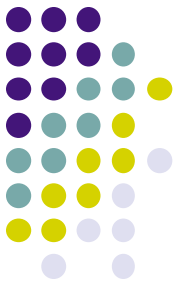
- Linked list



- Binary tree

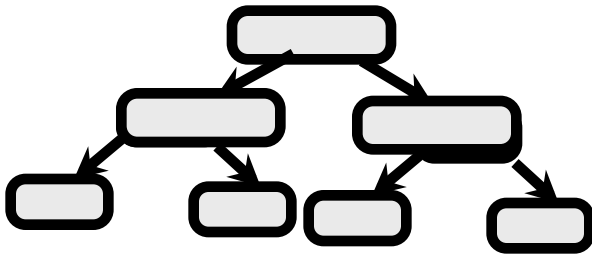


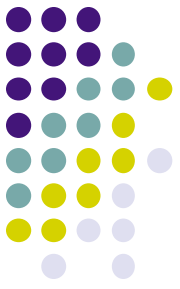
- Note for a complete binary tree, half the nodes are at the bottom level...



# What is a complete binary tree?

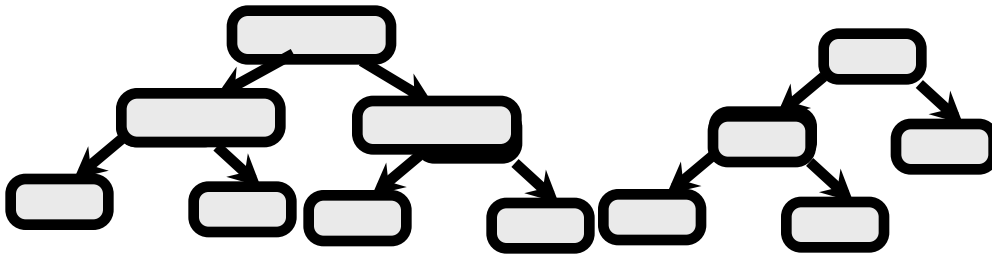
- A **complete** binary tree is a binary tree in which **every level, except possibly the last**, is completely filled, and **all nodes are as far left as possible**.





# What is a complete binary tree?

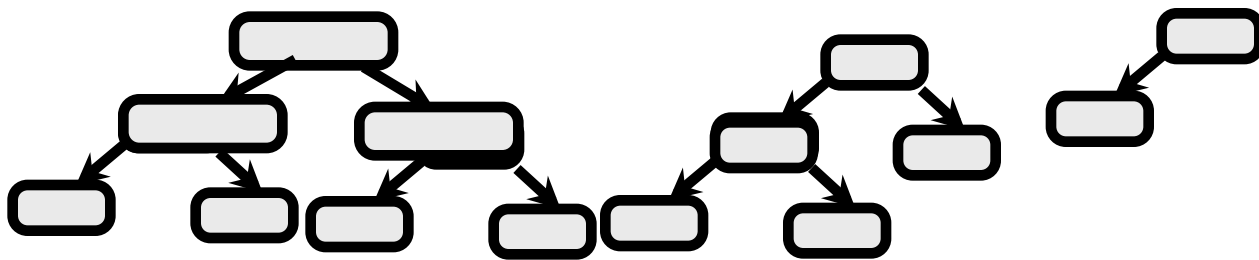
- A **complete** binary tree is a binary tree in which **every level, except** possibly the **last**, is completely filled, and **all nodes are as far left** as possible.





# What is a complete binary tree?

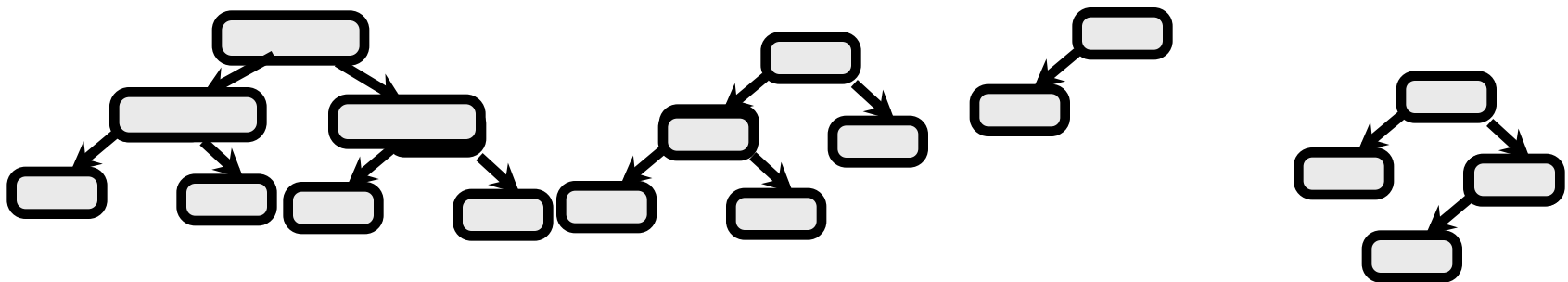
- A **complete** binary tree is a binary tree in which **every level, except possibly the last**, is completely filled, and **all nodes are as far left as possible**.





# What is a complete binary tree?

- A **complete** binary tree is a binary tree in which **every level, except possibly the last**, is completely filled, and **all nodes are as far left as possible**.



# Looking at a complete binary tree



Nodes

$2^0$

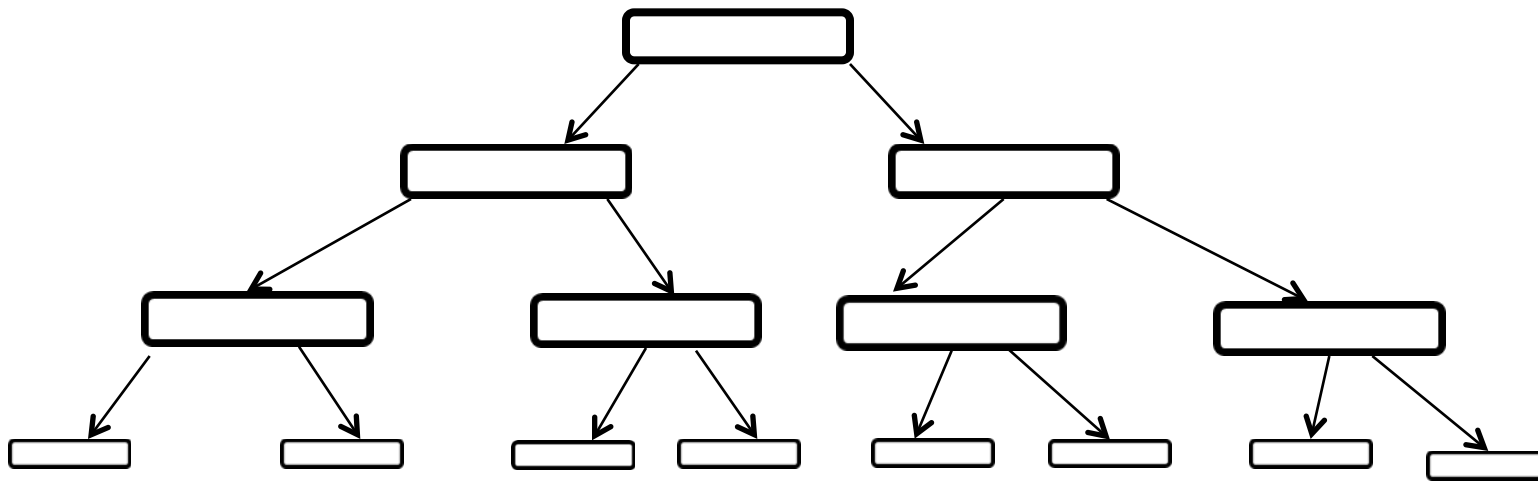
$2^1$

$2^2$

$2^3$

....

$\sim 2^{\log n}$



A complete binary tree of  $n$  nodes has depth approximately  $\log_2 n$ .



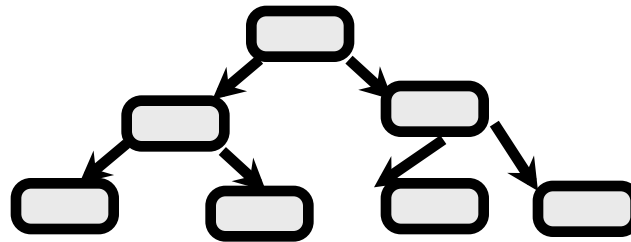
# Breaking out of linearity

- Compare:

- Linked list

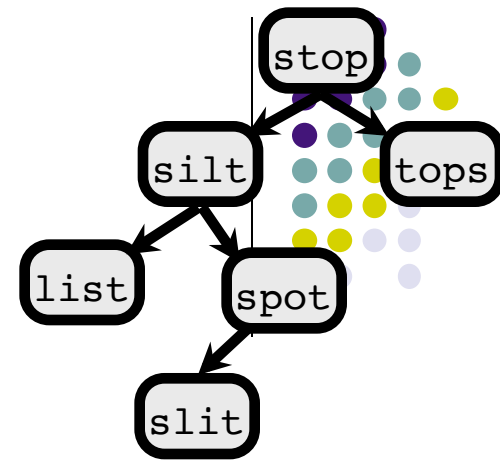


- Binary tree



- As we will see, both insertion and search are  $\log n$ -time operations.

# How a binary search tree work?



- In a sorted linked list, **next** links to a record with a key  $\geq$  this one.
- In a BST, **left** links to items with key  $<$  current key
- **right** links to items with key  $\geq$  current key.
- Find node with key **slit** in this tree.



# Looking at a complete binary tree



Nodes

$2^0$

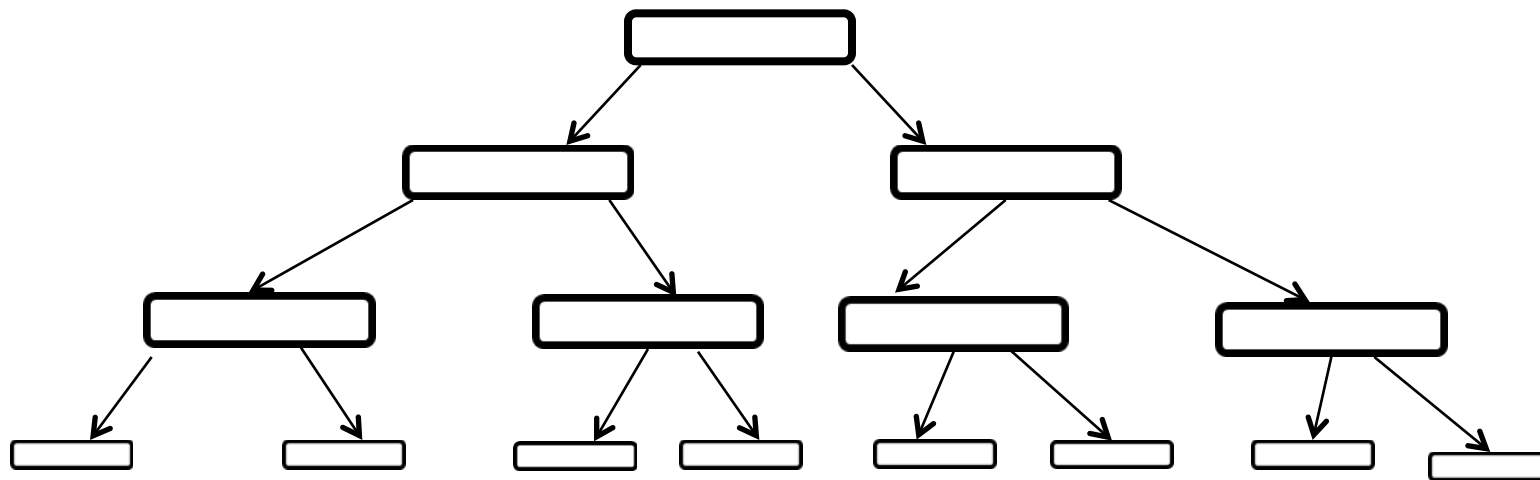
$2^1$

$2^2$

$2^3$

....

$2^{\log n - 1}$



- For a **complete** binary tree of  $n$  nodes, to get to the bottom will take not more than  $\log_2 n$  key comparisons.
- Contrast with linked list, to get to the end....



# Binary tree exercises

- Put the following numeric keys into a bst:
  - 45, 37, 86, 90, 50, 16, 37
  - How long (how many key comparisons) does it take to search for key=5?
- Put the following numeric keys into a bst:
  - 90, 86, 50, 45, 37, 32, 16
  - How long does it take to search for key=5?

# Best case run time in bst:

## Perfectly balanced tree



- Best case for bst: perfectly balanced.
- Height of tree with  $n$  items:  $\log_2 n$ .
- Path from root to any node:
  - Maximum length:  $\log_2 n$
  - Average length: also  $\log_2 n$
- Insertion/search/deletion are all  $O(\log n)$  for a well-balanced tree.



# Average case run time in bst

- Average case for insertion/search/deletion in a binary search tree is also  $O(\log n)$ .
- More exactly  $\sim 1.4 \log n$ .

# Worst case run time in bst: Stick



- Worst case for bst: a stick.
  - e.g. when items are inserted in sorted order.
- The bst degenerates to a linked list!
- Height of tree with  $n$  items:  $n$
- Path from root to any node:
  - maximum length:  $n$
  - average length:  $n/2$
- Insertion/search/deletion are  $O(n)$ !



# Binary search trees

- Deletion?



# Something to think about

- Why don't we just randomize the order of the items we insert into the binary search tree, to prevent worst case behavior?



# Binary search trees

- Good average case behavior –  $\log n$ .
- Bad worst case behavior –  $n$ .
- So overall bst  $O(n)$ .
  - Actual behavior usually not linear.
  - But potential linearity.
- Balanced trees: AVL, red-black; 2,3,4; B+tree.





# Dictionaries: Summary

- We have looked at various underlying data structures for implementing dictionaries:
  - 
  - 
  - 
  - 
  -



# Dictionaries: Summary

- We have analyzed the computational complexity for these data structures:
  - 
  - 
  - 
  - 
  -



# Dictionaries: Summary

- So far the best we have done is  $\log n$  search, where either:
  - Insertion is  $O(n)$ ; or
  - $O(\log n)$  average case but  $O(n)$  worst case.
- We can do better...



# Next section

- Balanced trees.