Lecture 5. Regularisation

COMP90051 Statistical Machine Learning

Semester 2, 2019
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THE UNIVERSITY OF
MELBOURNE

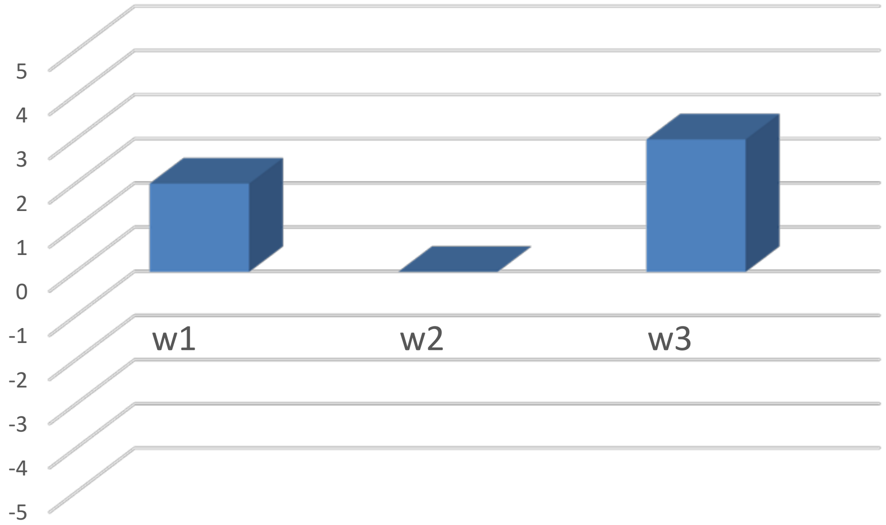
This lecture: Regularisation

Process of introducing additional information in order to solve an ill-posed problem or to prevent overfitting

- Major technique & theme, throughout ML
- Addresses one or more of the following related problems
  - Avoids ill-conditioning (a computational problem)
  - Avoids overfitting (a statistical problem)
  - Introduce prior knowledge into modelling
- This is achieved by augmenting the objective function
- In this lecture: we cover the first two aspects. We will cover more of regularisation throughout the subject

Example 1: Feature importance

- Linear model on three features
  - $\boldsymbol{X}$ is matrix on $n = 4$ instances (rows)
  - Model: $y = w_1 x_1 + w_2 x_2 + w_3 x_3 + w_0$



Question: Which feature is more important?

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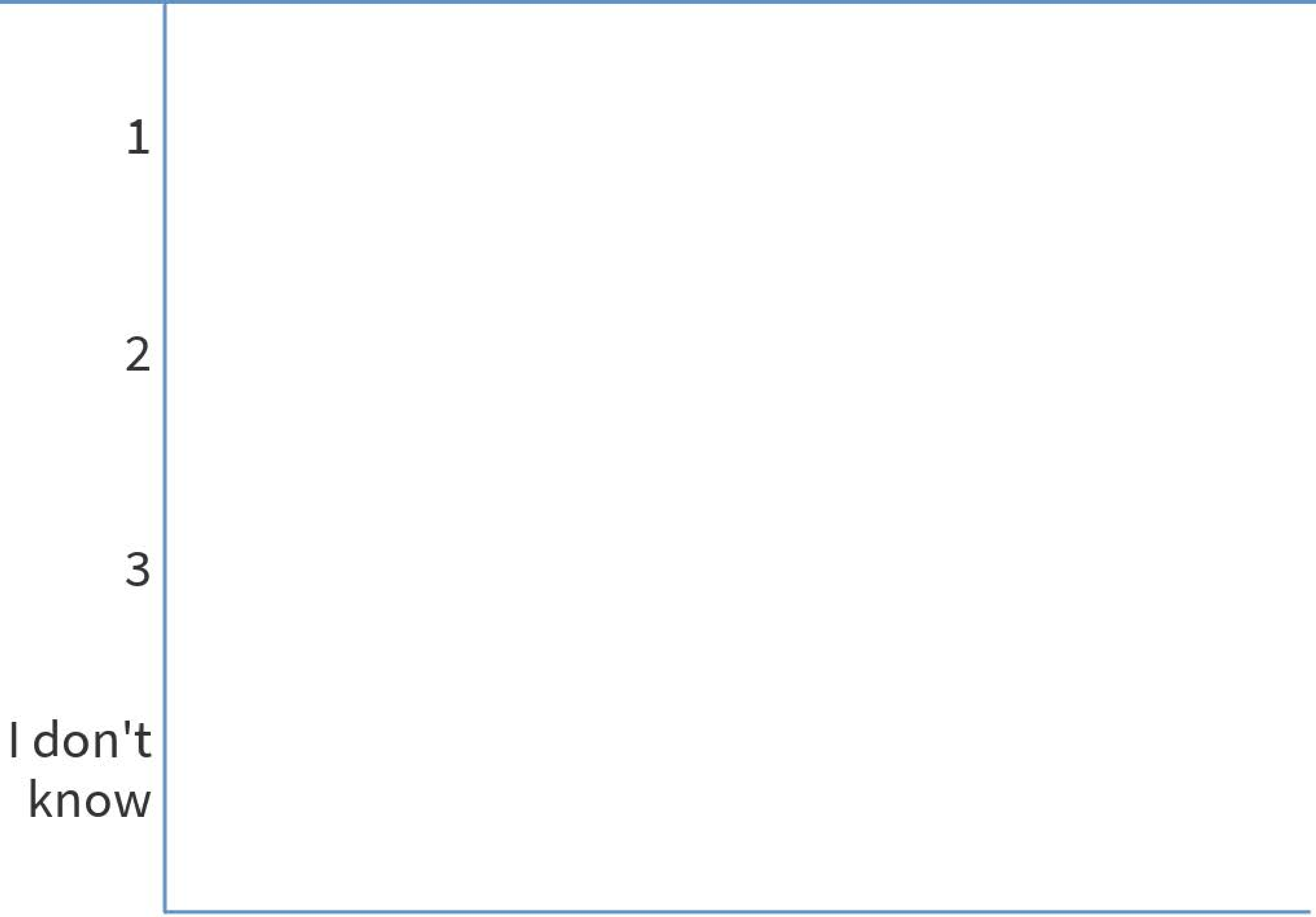

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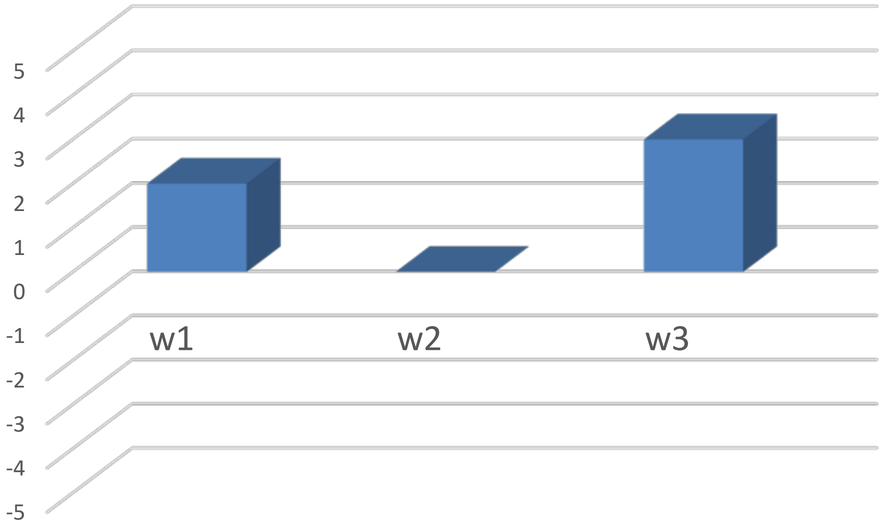
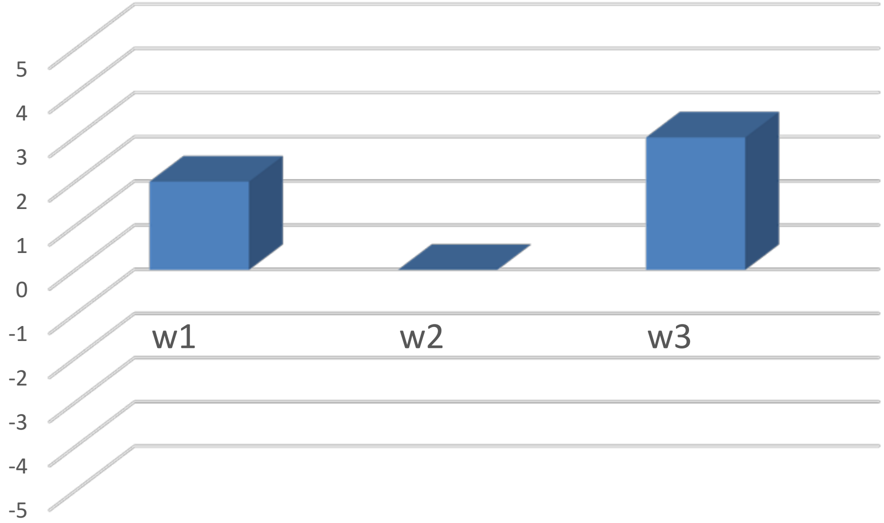


Example 1: Irrelevant features

- Linear model on three features, first two same
  - $\boldsymbol{X}$ is matrix on $n = 4$ instances (rows)
  - Model: $y = w_1x_1 + w_2x_2 + w_3x_3 + w_0$
  - First two columns of $\boldsymbol{X}$ identical
  - Feature 2 (or 1) is **irrelevant**

3	3	7
6	6	9
21	21	79
34	34	2



- Effect of perturbations on model predictions?
  - Add Δ to w_1
  - Subtract Δ from w_2

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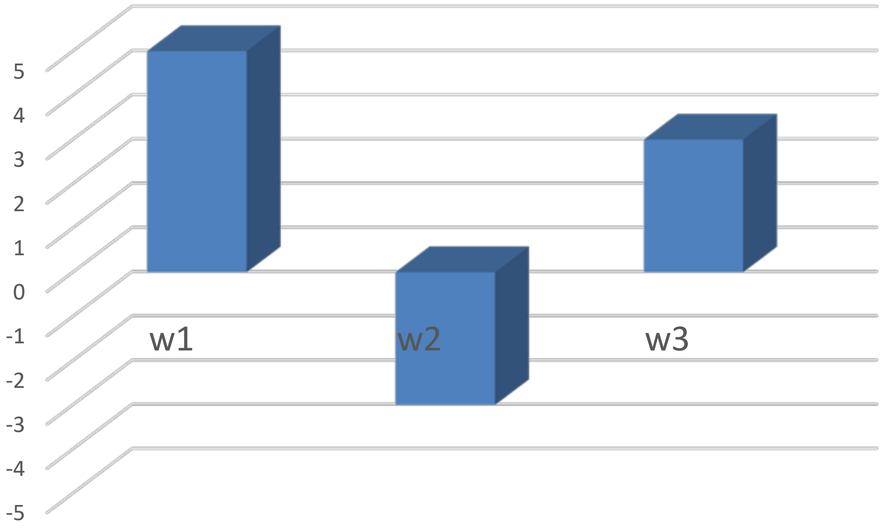

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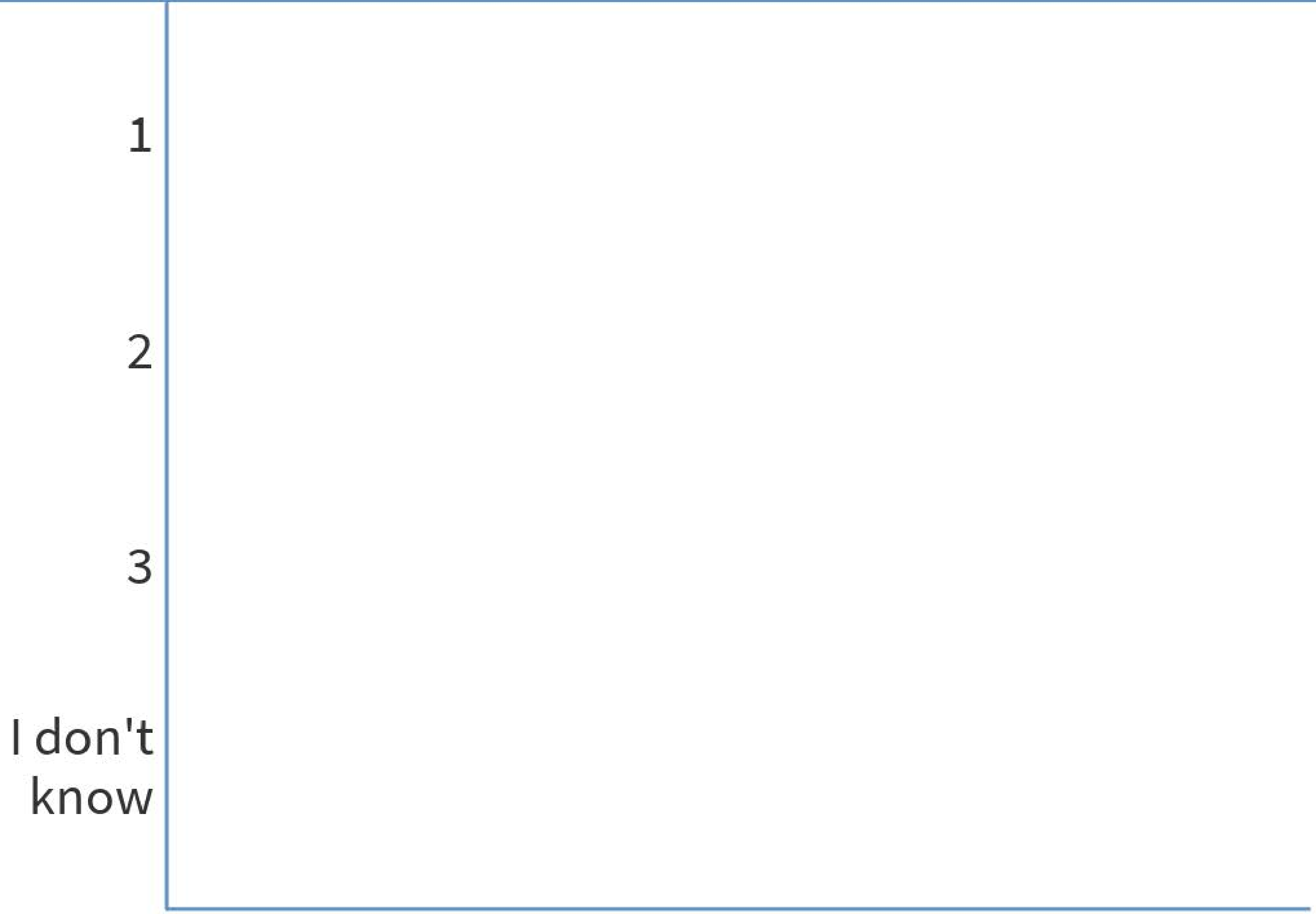
Question: Which feature is more important?



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Problems with irrelevant features

- In example, suppose $[\hat{w}_0, \hat{w}_1, \hat{w}_2, \hat{w}_3]'$ is “optimal”
- For any δ new $[\hat{w}_0, \hat{w}_1 + \delta, \hat{w}_2 - \delta, \hat{w}_3]'$ get
  - *Same* predictions!
  - *Same* sum of squared errors!
- Problems this highlights
  - The solution is not unique
  - Lack of interpretability
  - Optimising to learn parameters is ill-posed problem

Irrelevant (co-linear) features in general

- Extreme case: features complete clones
- For linear models, more generally
  - Feature $\boldsymbol{X}_{\cdot j}$ is irrelevant if
  - $\boldsymbol{X}_{\cdot j}$ is a linear combination of other columns

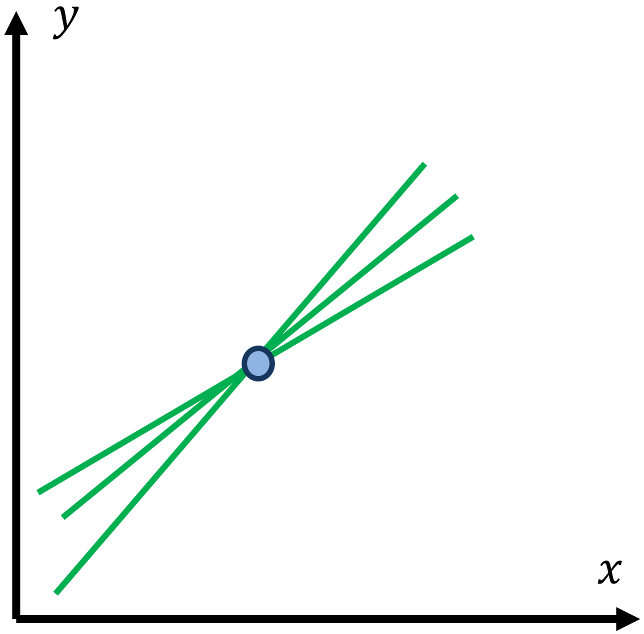
$$\boldsymbol{X}_{\cdot j} = \sum_{l \neq j} \alpha_l \boldsymbol{X}_{\cdot l}$$

  … for some scalars α_l. Also called multicollinearity
  - Equivalently: Some eigenvalue of $\boldsymbol{X}'\boldsymbol{X}$ is zero
- Even *near*-irrelevance/colinearity can be problematic
  - V small eigenvalues of $\boldsymbol{X}'\boldsymbol{X}$
- Not just a pathological extreme; *easy to happen!*

$\boldsymbol{X}_{\cdot j}$ denotes the j-th column of X

Example 2: Lack of data

- Extreme example:
  - Model has two parameters (slope and intercept)
  - Only one data point



- Underdetermined system

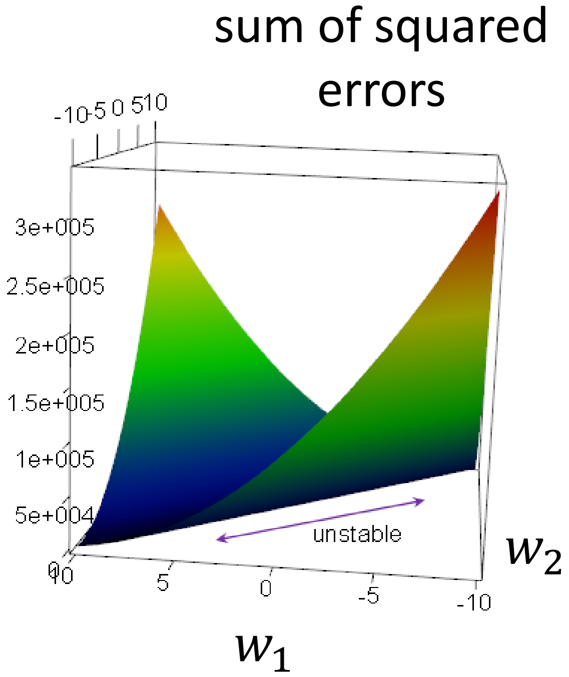
Ill-posed problems

- In both examples, finding the best parameters becomes an ill-posed problem

- This means that the problem solution is not defined
  - In our case w_1 and w_2 cannot be uniquely identified

- Remember normal equations solution of linear regression: $\hat{\boldsymbol{w}} = (\boldsymbol{X}'\boldsymbol{X})^{-1}\boldsymbol{X}'\boldsymbol{y}$

- With irrelevant/multicolinear features, matrix $\boldsymbol{X}'\boldsymbol{X}$ has no inverse



convex, but not strictly convex

Re-conditioning the problem

- Regularisation: introduce an additional condition into the system
- The original problem is to minimise $\|\boldsymbol{y} - \boldsymbol{X}\boldsymbol{w}\|_2^2$
- The regularised problem is to minimise

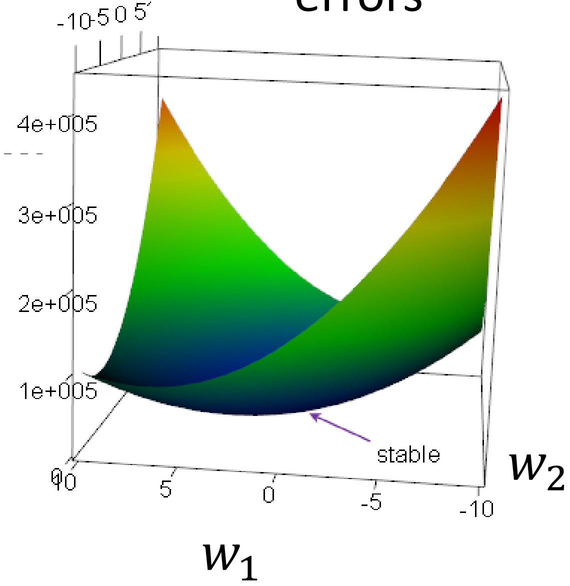
$$\|\boldsymbol{y} - \boldsymbol{X}\boldsymbol{w}\|_2^2 + \lambda\|\boldsymbol{w}\|_2^2 \text{ for } \lambda > 0$$

- The solution is now

$$\hat{\boldsymbol{w}} = (\boldsymbol{X}'\boldsymbol{X} + \lambda\boldsymbol{I})^{-1}\boldsymbol{X}'\boldsymbol{y}$$

- This formation is called ridge regression
  - Turns the ridge into a peak
  - Adds λ to eigenvalues of $\boldsymbol{X}'\boldsymbol{X}$: makes invertible

sum of squared errors



strictly convex

Regulariser as a prior

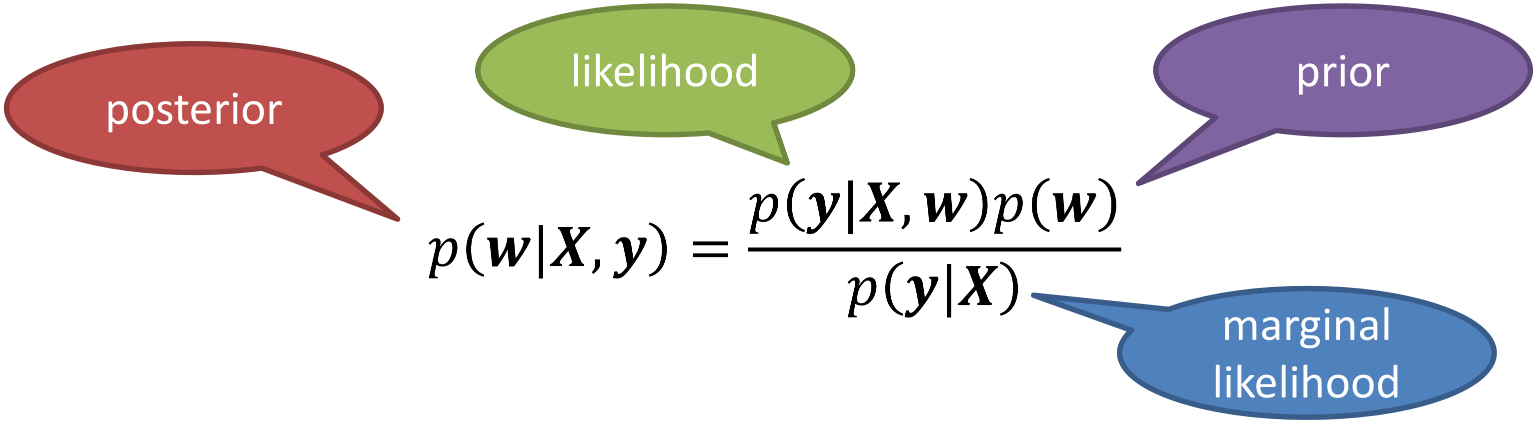
- Without regularisation, parameters found based entirely on the information contained in the training set $\boldsymbol{X}$
  - Regularisation introduces additional information
- Recall our probabilistic model $Y = \boldsymbol{x}'\boldsymbol{w} + \varepsilon$
  - Here Y and ε are random variables, where ε denotes noise
- Now suppose that $\boldsymbol{w}$ is also a random variable (denoted as $\boldsymbol{W}$) with a Normal prior distribution

$$\boldsymbol{W} \sim \mathcal{N}(0, 1/\lambda)$$

  - I.e. we expect small weights and that no one feature dominates
  - Is this always appropriate? E.g. data centring and scaling
  - We could encode much more elaborate problem knowledge

Computing posterior using Bayes rule

- The prior is then used to compute the posterior



posterior

likelihood

prior

$$p(\boldsymbol{w}|\boldsymbol{X},\boldsymbol{y}) = \frac{p(\boldsymbol{y}|\boldsymbol{X},\boldsymbol{w})p(\boldsymbol{w})}{p(\boldsymbol{y}|\boldsymbol{X})}$$

marginal likelihood

- Instead of maximum likelihood (MLE), take ***maximum a posteriori*** estimate (MAP)

- Apply log trick, so that

$$\log(posterior) = \log(likelihood) + \log(prior) \cancel{- \log(marg)}$$

- Arrive at the problem of minimising

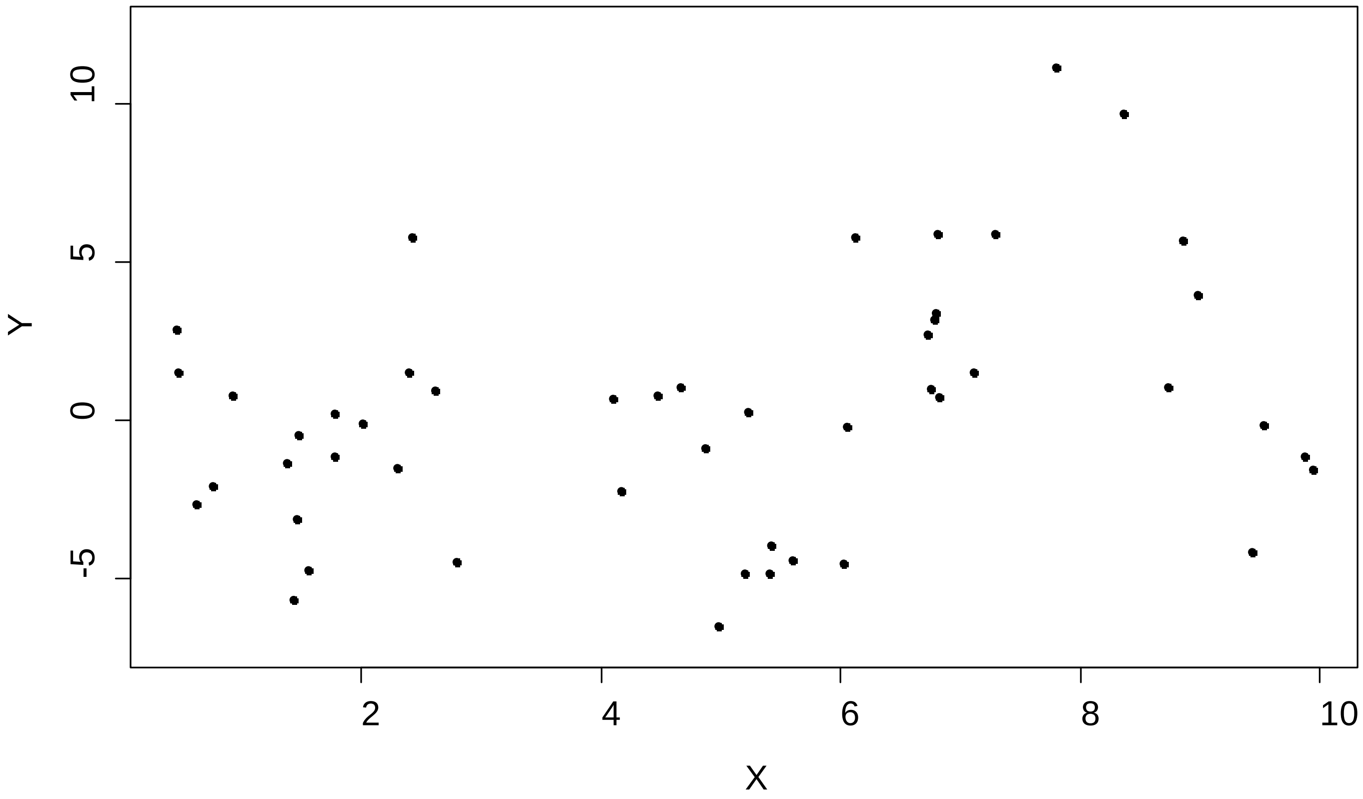
$$\|\boldsymbol{y} - \boldsymbol{X}\boldsymbol{w}\|_2^2 + \lambda\|\boldsymbol{w}\|_2^2$$

this term doesn't affect optimisation

Regularisation in Non-Linear Models

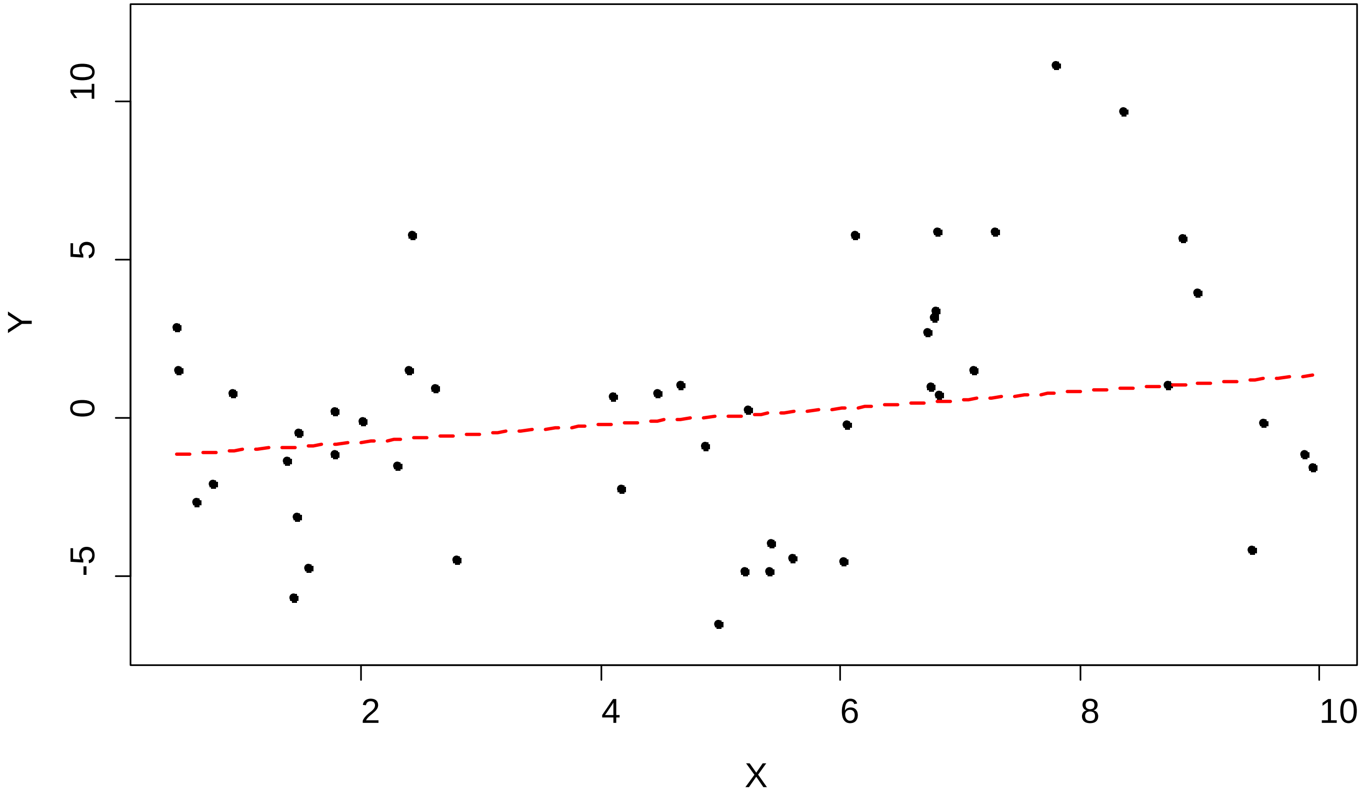
Model selection in ML

Example regression problem



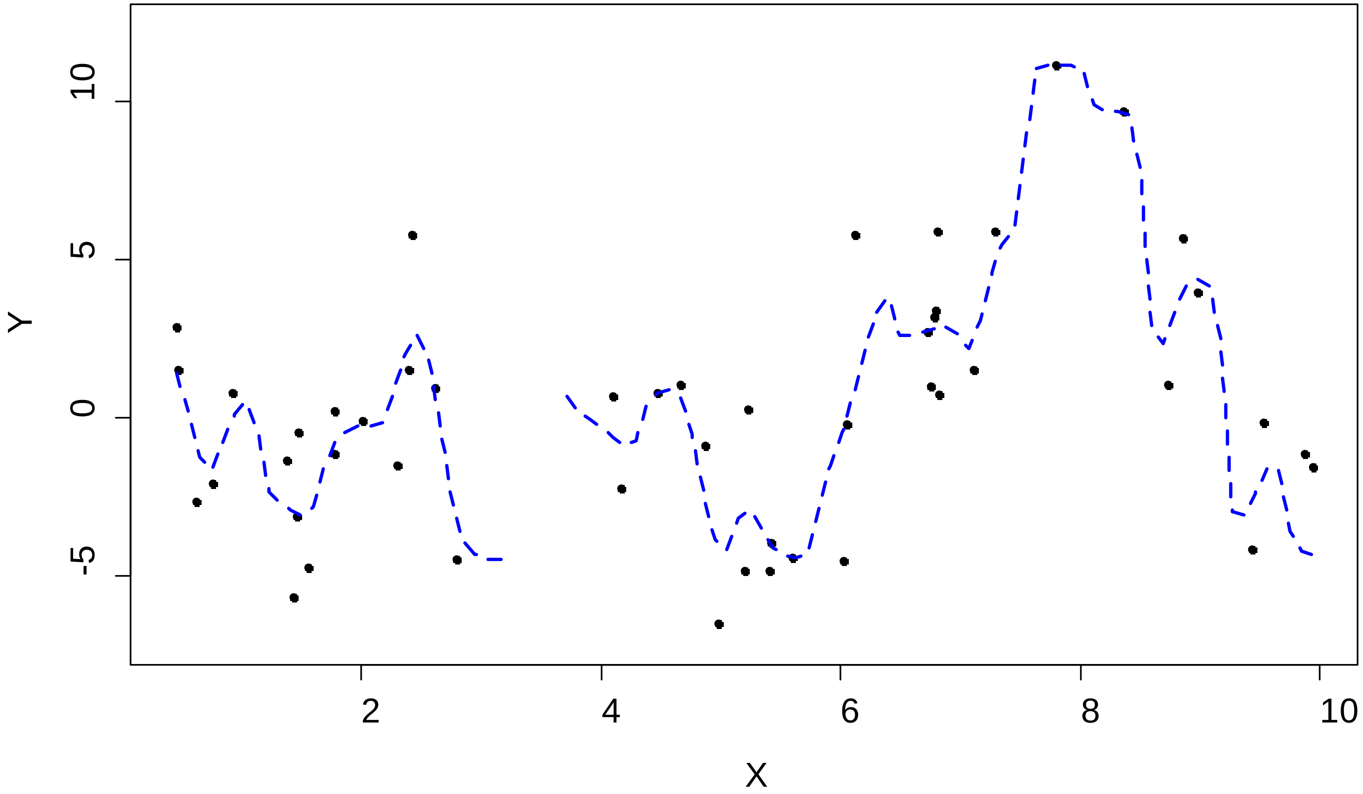
How complex a model should we use?

Underfitting (linear regression)



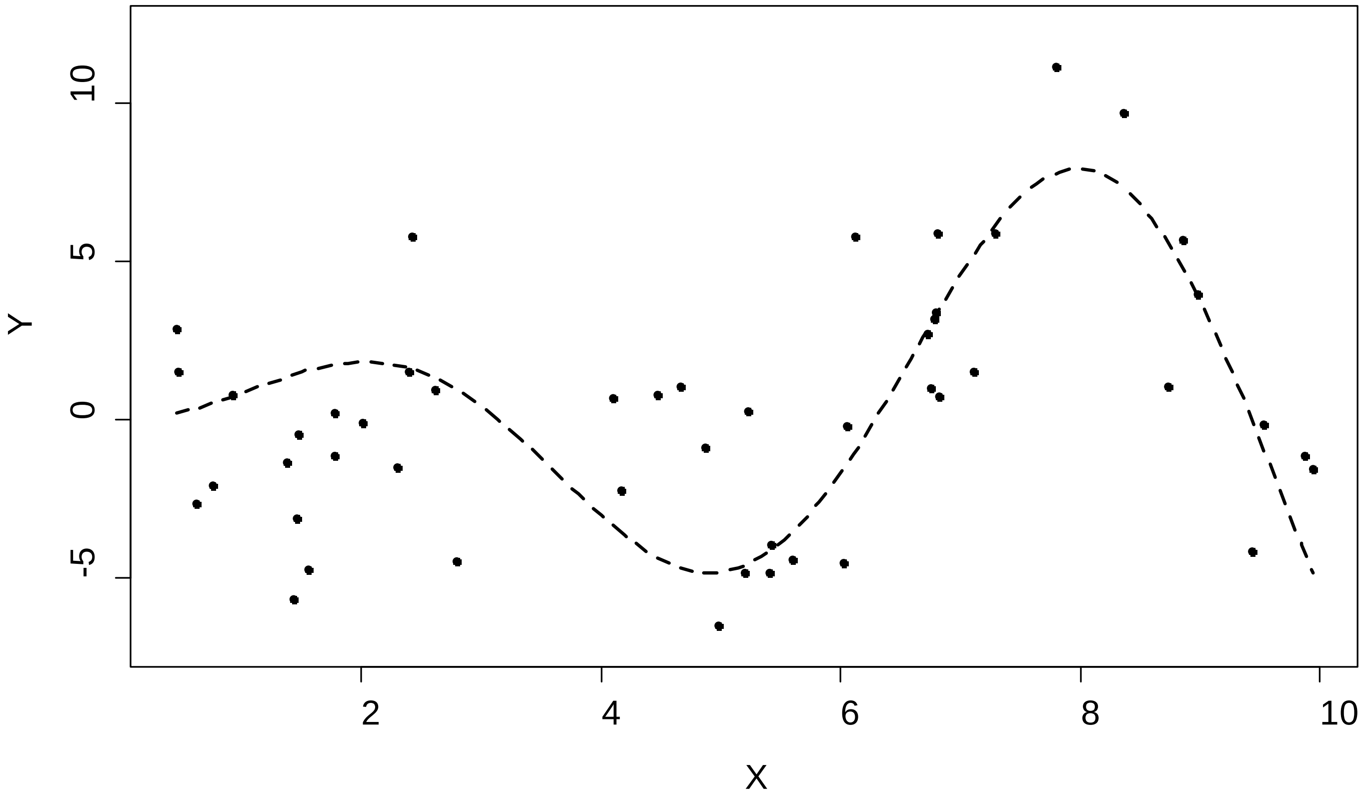
Model class Θ can be **too simple** to possibly fit true model.

Overfitting (non-parametric smoothing)



Model class Θ can be **so complex** it can fit true model + noise

Actual model ($x \sin x$)



The **right model class** Θ will sacrifice some training error, for test error.

How to “vary” model complexity

- Method 1: Explicit model selection
- Method 2: Regularisation
- Usually, method 1 can be viewed a special case of method 2

1. Explicit model selection

- Try different classes of models. Example, try polynomial models of various degree d (linear, quadratic, cubic, …)
- Use held out validation (cross validation) to select the model

1. Split training data into D_{train} and $D_{validate}$ sets
2. For each degree d we have model f_d
   1. Train f_d on D_{train}
   2. Test f_d on $D_{validate}$
3. Pick degree $\hat{d}$ that gives the best test score
4. Re-train model $f_{\hat{d}}$ using all data

2. Vary complexity by regularisation

- Augment the problem:

$$\hat{\boldsymbol{\theta}} \in \underset{\boldsymbol{\theta}\in\Theta}{\operatorname{argmin}}\left(L(data, \boldsymbol{\theta}) + \lambda R(\boldsymbol{\theta})\right)$$

- E.g., ridge regression

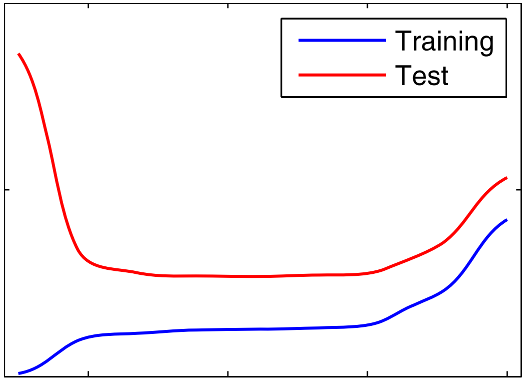
$$\hat{\boldsymbol{w}} \in \underset{\boldsymbol{w}\in W}{\operatorname{argmin}} ||\boldsymbol{y} - \boldsymbol{X}\boldsymbol{w}||_2^2 + \lambda||\boldsymbol{w}||_2^2$$

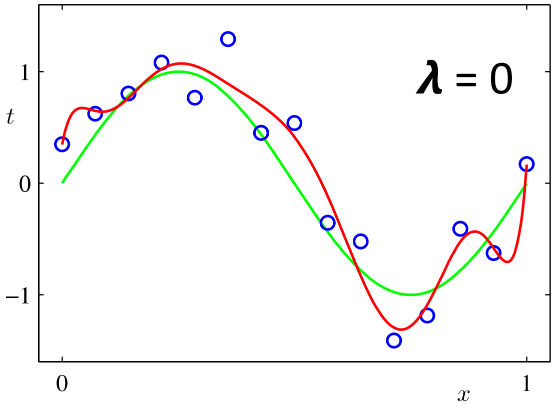
- Note that regulariser $R(\boldsymbol{\theta})$ does not depend on data

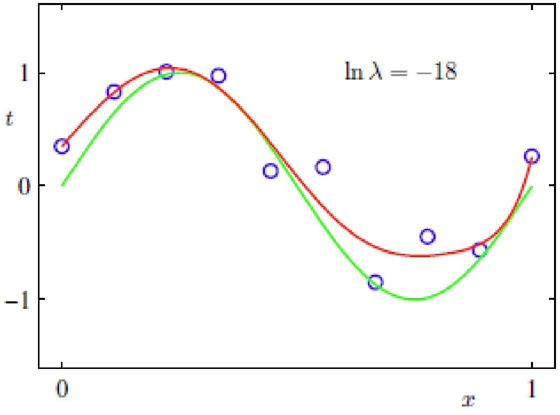
- Use held out validation/cross validation to choose λ

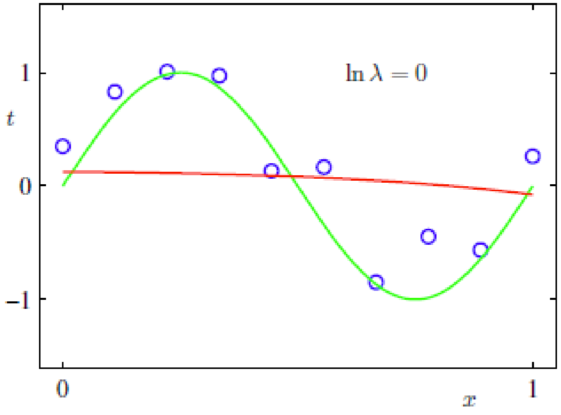
Example: Polynomial regression

- 9th-order polynomial regression
  - model of form
    $$\hat{f} = w_0 + w_1\, x + \ \dots + w_9 x^9$$
  - regularised with $\lambda \|\boldsymbol{w}\|_2^2$ term







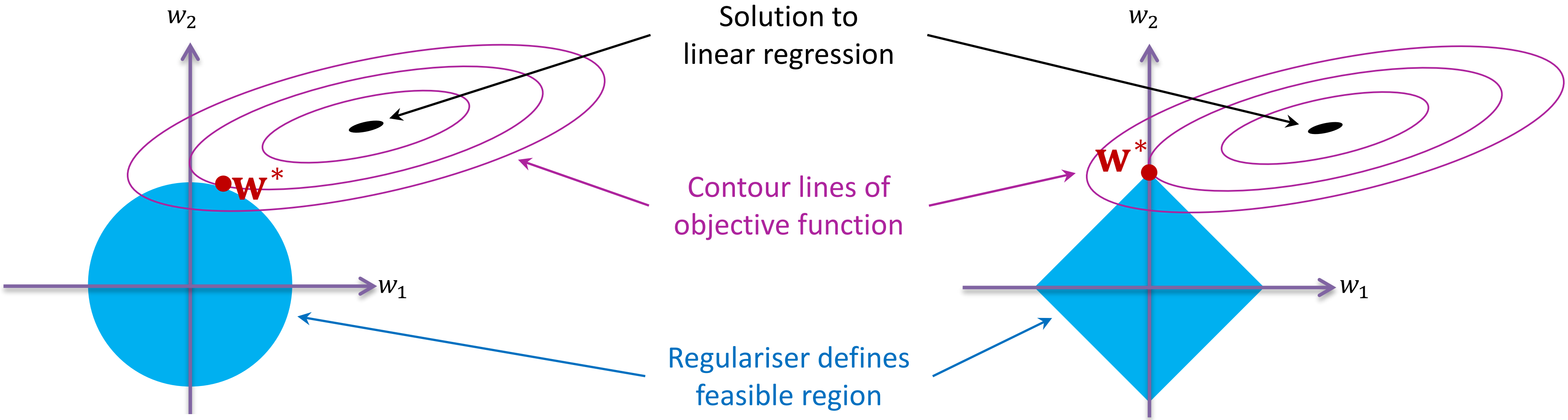


Figures from Bishop pp7-9,150

Regulariser as a constraint

- For illustrative purposes, consider a *modified problem*:

  minimise $\|\boldsymbol{y} - \boldsymbol{X}\boldsymbol{w}\|_2^2$ *subject to* $\|\boldsymbol{w}\|_2^2 \leq \lambda$ for $\lambda > 0$



Solution to linear regression

Contour lines of objective function

Regulariser defines feasible region

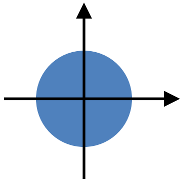
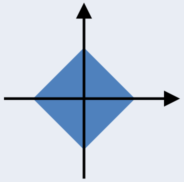
Ridge regression ($\|\boldsymbol{w}\|_2^2$)

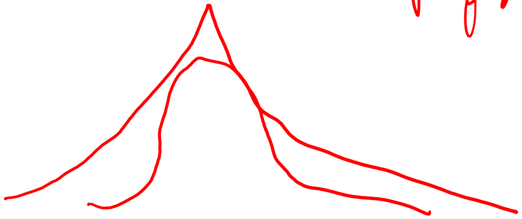
Lasso ($\|\boldsymbol{w}\|_1$)

- Lasso (L_1 regularisation) encourages solutions to sit on the axes

  → Some of the weights are set to zero → Solution is sparse

Regularised linear regression

Algorithm	Minimises	Regulariser	Solution
Linear regression	$\|\|\boldsymbol{y}-\boldsymbol{X}\boldsymbol{w}\|\|_2^2$	None	$(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}$ (if inverse exists)
Ridge regression	$\|\|\boldsymbol{y}-\boldsymbol{X}\boldsymbol{w}\|\|_2^2+\lambda\|\|\boldsymbol{w}\|\|_2^2$ Gaussian prior	L_2 norm 	$(\mathbf{X}'\mathbf{X}+\lambda\mathbf{I})^{-1}\mathbf{X}'\mathbf{y}$
Lasso	$\|\|\boldsymbol{y}-\boldsymbol{X}\boldsymbol{w}\|\|_2^2+\lambda\|\|\mathbf{w}\|\|_1$ Laplace prior	L_1 norm 	No closed-form, but solutions are sparse and suitable for high-dim data



Bias-variance trade-off

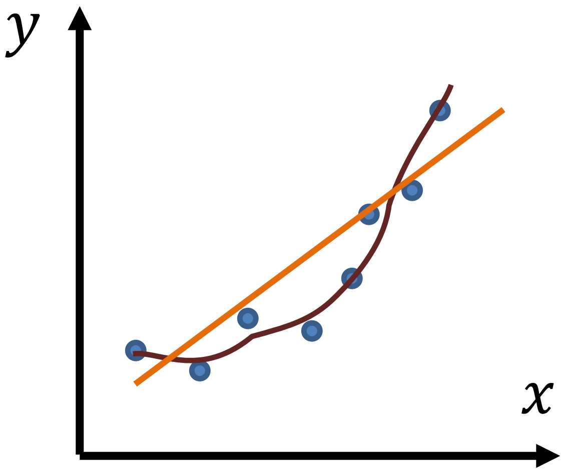
Analysis of relations between
train error, test error and
model complexity

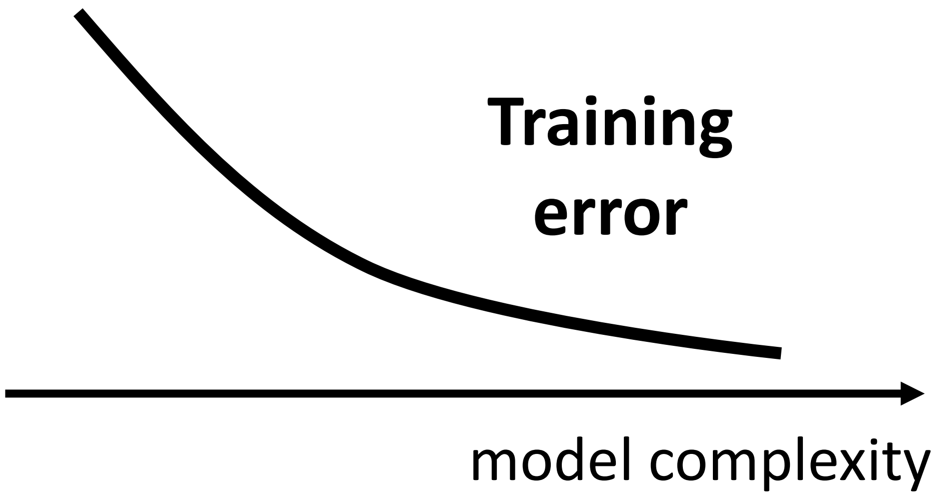
Assessing generalisation capacity

- Supervised learning: train the model on existing data, then make predictions on new data
- Training the model: ERM / minimisation of training error
- Generalisation capacity is captured by risk / test error
- Model complexity is a major factor that influences the ability of the model to generalise
- In this section, our aim is to explore relations between training error, test error and model complexity

Training error and model complexity

- More complex model → training error goes down
- Finite number of points → usually can reduce training error to 0 (is it always possible?)





(Another) Bias-variance decomposition

- Squared loss for supervised-regression predictions

$$l\left(Y, \hat{f}(\boldsymbol{X}_0)\right) = \left(Y - \hat{f}(\boldsymbol{X}_0)\right)^2$$

- Lemma: Bias-variance decomposition

$$\mathbb{E}\left[l\left(Y, \hat{f}(\boldsymbol{X}_0)\right)\right] = \left(\mathbb{E}[Y] - \mathbb{E}[\hat{f}]\right)^2 + Var[\hat{f}] + Var[Y]$$

Risk / test error for x_0	(bias)^2	variance	irreducible error

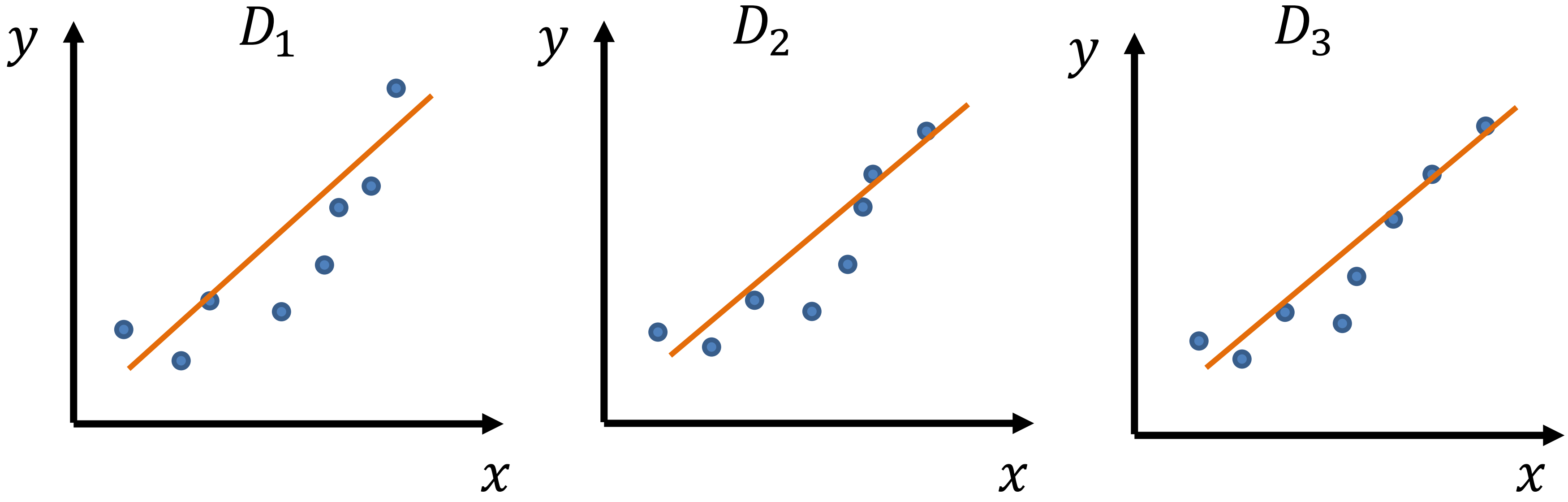
* Prediction randomness comes from randomness in test features AND training data

Decomposition proof sketch

- Here $(\boldsymbol{x})$ is omitted to de-clutter notation
- $\mathbb{E}\left[\left(Y - \hat{f}\right)^2\right] = \mathbb{E}\left[Y^2 + \hat{f}^2 - 2Y\hat{f}\right]$
- $= \mathbb{E}[Y^2] + \mathbb{E}\left[\hat{f}^2\right] - \mathbb{E}\left[2Y\hat{f}\right]$
- $= Var[Y] + \mathbb{E}[Y]^2 + Var\left[\hat{f}\right] + \mathbb{E}\left[\hat{f}\right]^2 - 2\mathbb{E}[Y]\mathbb{E}\left[\hat{f}\right]$
- $= Var[Y] + Var\left[\hat{f}\right] + \left(\mathbb{E}[Y]^2 - 2\mathbb{E}[Y]\mathbb{E}\left[\hat{f}\right] + \mathbb{E}\left[\hat{f}\right]^2\right)$
- $= Var[Y] + Var\left[\hat{f}\right] + \left(\mathbb{E}[Y] - \mathbb{E}\left[\hat{f}\right]\right)^2$

* Green slides are non-examinable

Training data as a random variable



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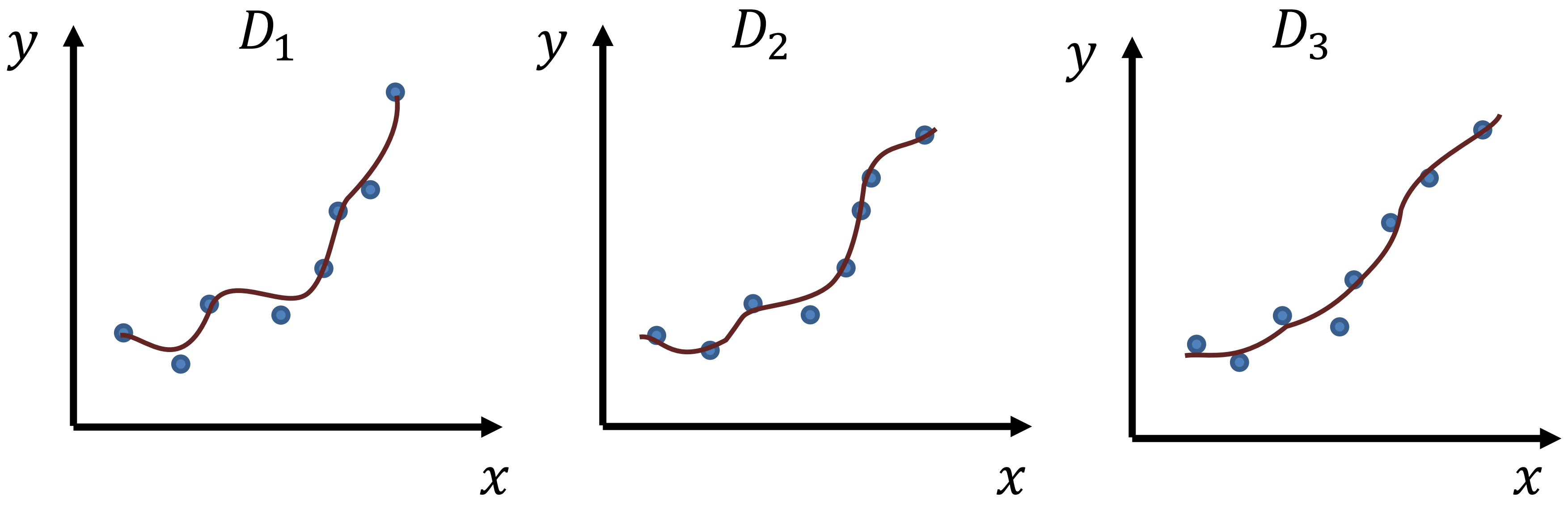
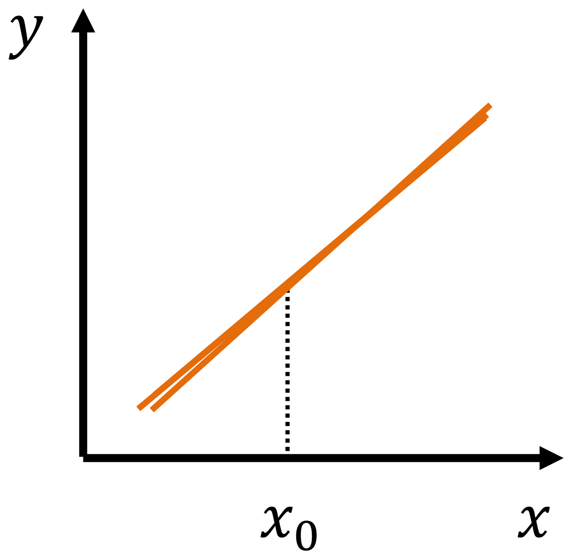
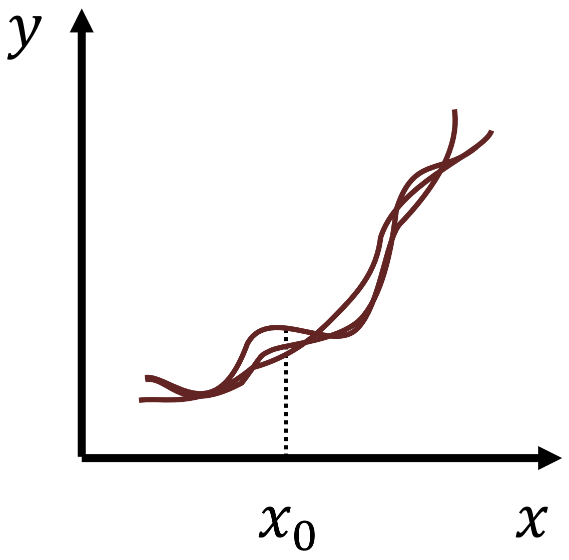


Model complexity and variance

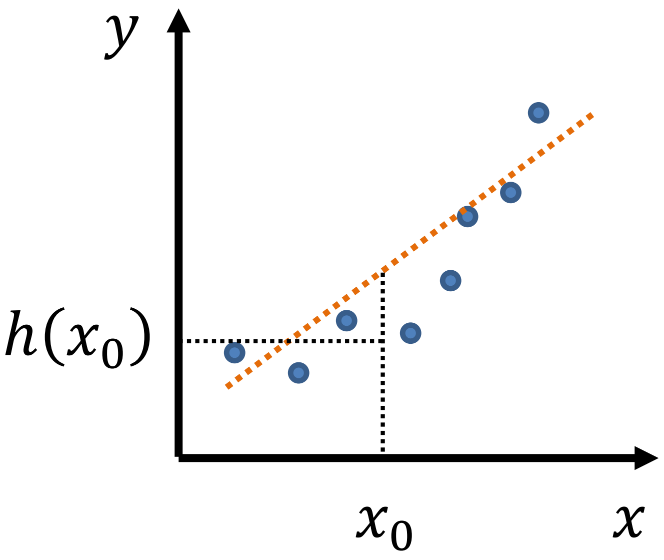
- simple model ➔ low variance
- complex model ➔ high variance

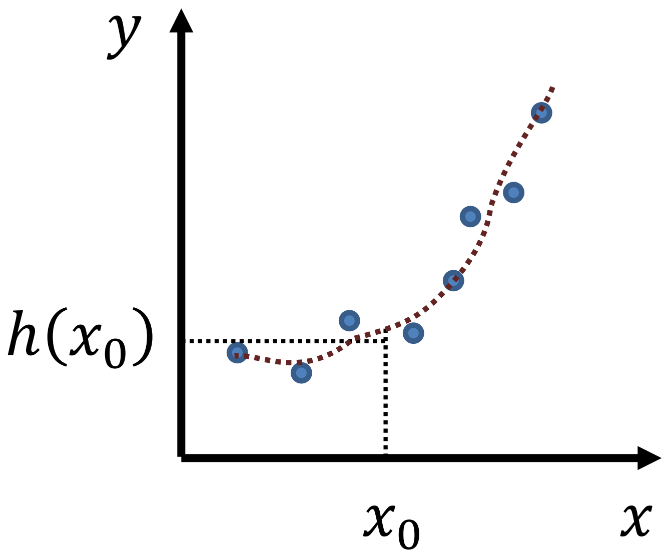




Model complexity and bias

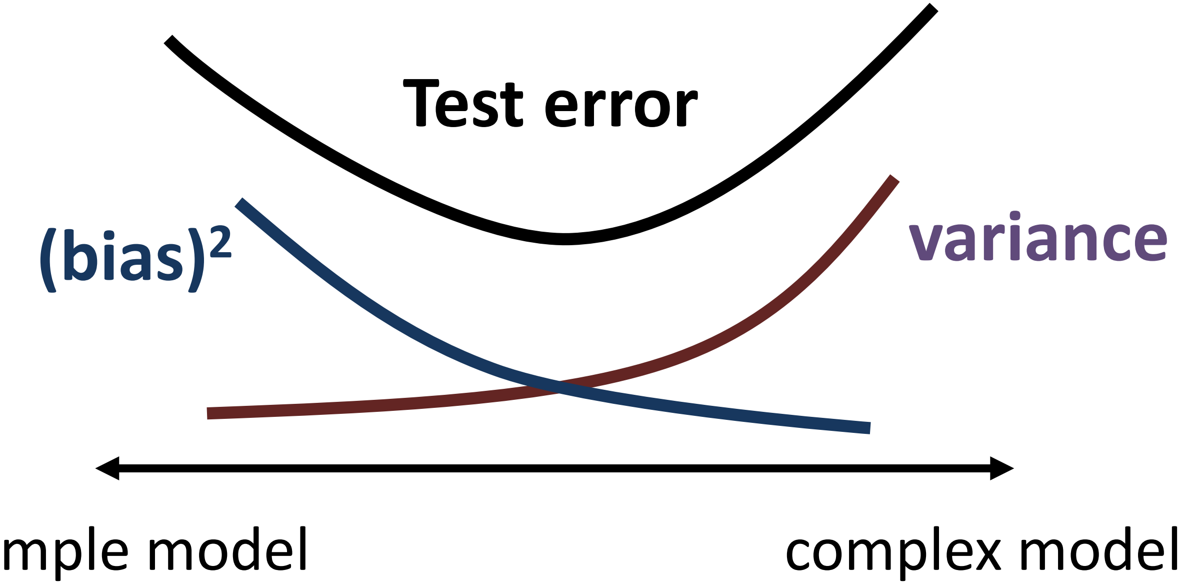
- simple model ➔ high bias
- complex model ➔ low bias



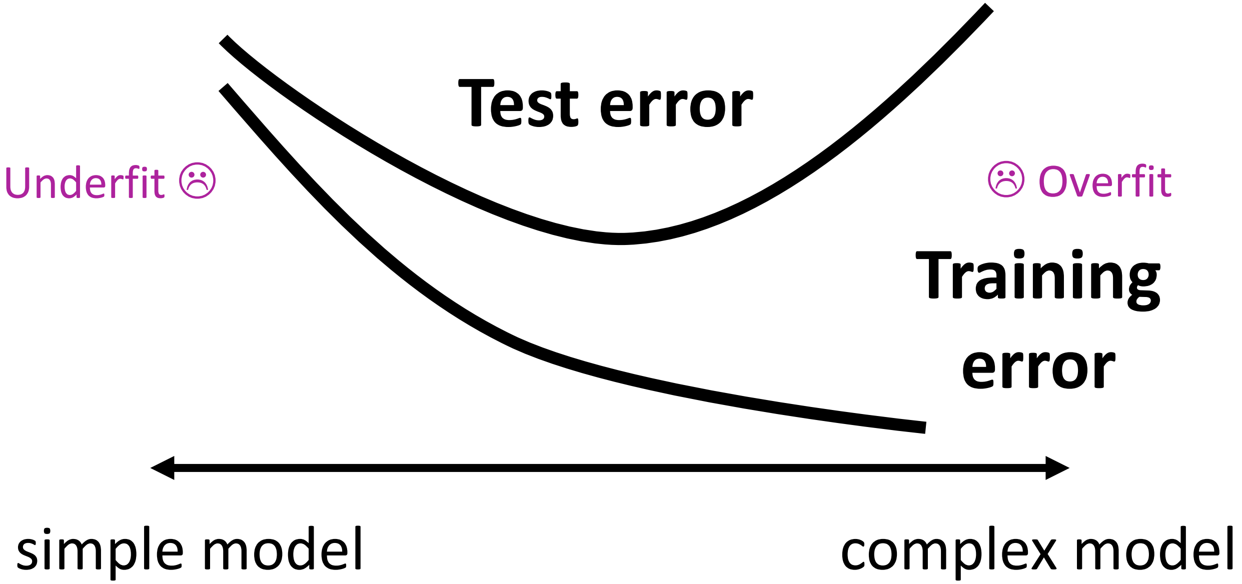


Bias-variance trade-off

- simple model ➔ high bias, low variance
- complex model ➔ low bias, high variance



Test error and training error



Test error

Underfit ☹

☹ Overfit

Training error

simple model

complex model

Summary

- Regularisation
  - Irrelevant/multicolinear features → ill-posed problems
  - Model complexity
  - Bias-variance trade-off

- Next lecture: Towards neural nets with perceptron