

Machine Learning

Distributions

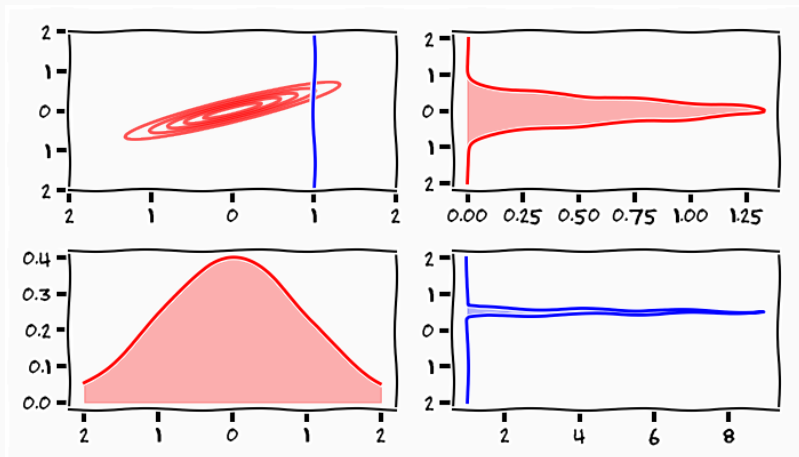
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Introduction

Basic Probabilities



The Rules of Probability

Sum Rule

$$p(X) = \sum_Y p(X, Y)$$

Product Rule

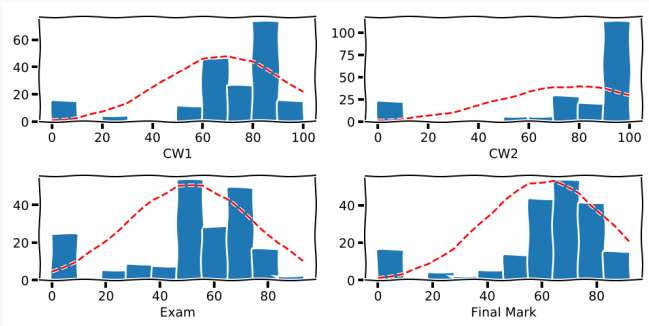
$$p(X, Y) = p(Y|X)p(X)$$

\Rightarrow Bayes Rule

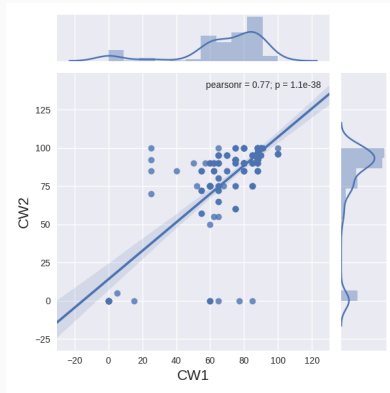
$$p(X|Y) = \frac{P(Y|X)p(X)}{p(Y)}$$

$$p(\text{CW1}, \text{CW2}, \text{Exam})$$

Marginals



Marginal



$$p(\text{CW1}, \text{CW2}) = \sum_{x=1}^{100} p(\text{CW1}, \text{CW2}, \text{Exam} = x) = \sum_{x=1}^{100} p(\text{CW1}, \text{CW2} | \text{Exam} = x) p(\text{Exam} = x)$$

Exam

$$p(\text{Exam} = 100 | \text{CW1} = 20, \text{CW2} = 30)$$

- What is the probability of me getting Exam=100 if CW1=20 and CW2=30
- As you will get a result on the exam the probability for all results sums to 1

$$\sum_{x=0}^{x=100} p(\text{Exam} = x | \text{CW1} = 20, \text{CW2} = 30) = 1.0$$

Coursework

$$p(\text{Exam} = 70 | \text{CW1} = 70) = \sum_{x=0}^{x=100} p(\text{Exam} = 70, \text{CW2} = x | \text{CW1} = 70)$$

- What is the probability that I will get Exam=70 if I got 70 on the coursework CW1

Questions

- Remember that each conditional is a probability
- However rare it is that you get 100% on both courseworks the conditional probability over all possible exam results will sum to one

$$\sum_{x=1}^{x=100} p(\text{Exam} = x | \text{CW1} = 100, \text{CW2} = 100) = 1.0$$

Questions

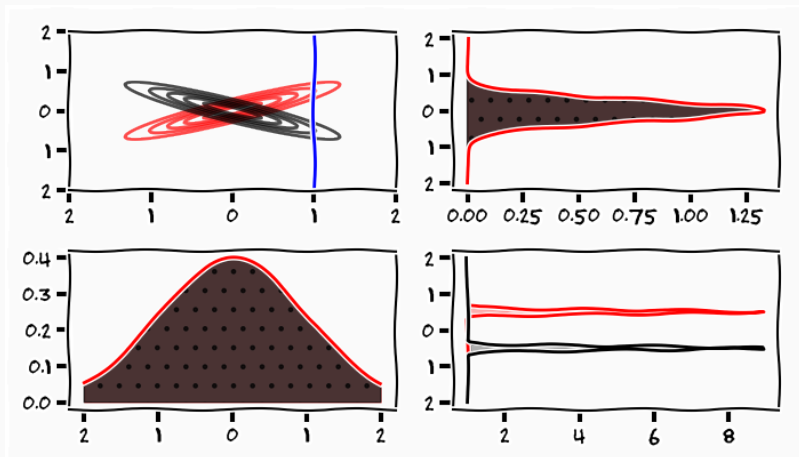
- Remember that each conditional is a probability
- However rare it is that you get 100% on both courseworks the conditional probability over all possible exam results will sum to one

$$\sum_{x=1}^{x=100} p(\text{Exam} = x | \text{CW1} = 100, \text{CW2} = 100) = 1.0$$

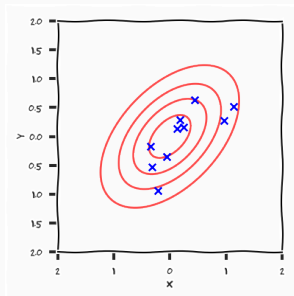
- What shows that it is rare is that the probability for getting

$$\begin{aligned} \sum_{x=1}^{x=100} p(\text{Exam} = x, \text{CW1} = 100, \text{CW2} = 100) \\ = p(\text{CW1} = 100, \text{CW2} = 100) \leq 1.0 \end{aligned}$$

Dangers of Marginals

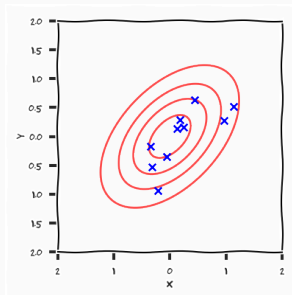


Learning with Distributions



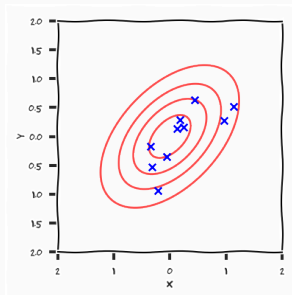
- Our goal is to understand realisations of a system

¹https://en.wikipedia.org/wiki/All_models_are_wrong



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- If we can, then we can "equate" our model with the system

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- Our goal is to understand realisations of a system
- If we can, then we can "equate" our model with the system
- Importantly not as **truth**, but as a **useful** hypothesis related to our assumptions¹

¹https://en.wikipedia.org/wiki/All_models_are_wrong

$$p(\theta|Y) = \frac{p(Y|\theta)p(\theta)}{p(Y)}$$

Bayes Rule

$$\underbrace{p(\theta|Y)}_{\text{posterior}} = \underbrace{P(Y|\theta)}_{\text{likelihood}} \cdot \underbrace{p(\theta)}_{\text{prior}} \cdot \frac{1}{\underbrace{p(Y)}_{\text{evidence}}}$$

Likelihood how likely is the data to come from the model **specific** model indexed by θ

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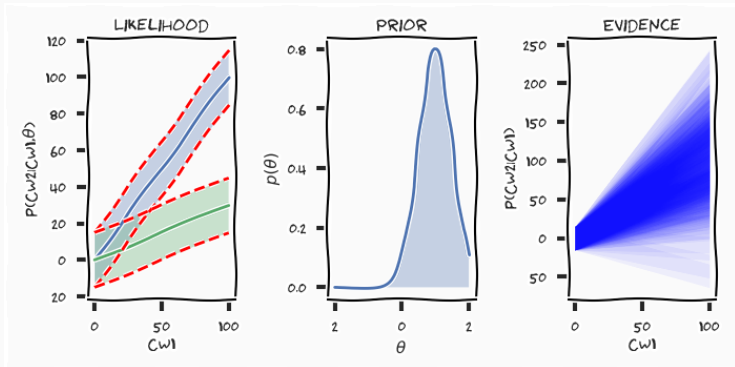
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Posterior which distributions of models do I believe have generated this data

Machine Learning



$$CW2 = \theta \cdot CW1 \pm 15\%$$

$$\theta \sim \mathcal{N}(1.0, 0.5)$$



Discrete Distributions

Bernoulli Distribution

- Distribution over binary random variable $x \in \{0, 1\}$

$$p(x = 1|\mu) = \mu$$

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- Due to binary outcome

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- Distribution

$$\text{Bern}(x|\mu) = \mu^x(1 - \mu)^{1-x}$$



- We want to figure out what μ is for a specific coin
- Toss the coin N times, $\mathcal{D} = \{x_1, x_2, \dots, x_N\}$

$$p(\mathcal{D}|\mu) = \prod_{n=1}^N p(x_n|\mu) = \prod_{n=1}^N \mu^{x_n} (1 - \mu)^{1-x_n}$$

- What happens if we blindly trust this one experiment?

$$\mu_{ML} = \operatorname{argmax}_{\mu} p(\mathcal{D}|\mu) = \frac{1}{N} \sum_{n=1}^N x_n$$

- if we get 3 heads in a row, we believe it will always be heads
- we need to include an assumption as a prior over μ

$$p(\mu|\mathcal{D}) = \frac{p(\mathcal{D}|\mu)p(\mu)}{p(\mathcal{D})}$$

- Also gives us an uncertainty related to our knowledge

$$p(\mu|\mathcal{D}) = \frac{p(\mathcal{D}|\mu)p(\mu)}{p(\mathcal{D})}.$$

- if we can specify a prior $p(\mu)$ we can reach the posterior belief

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- what do we know about coins?

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- if we can specify a prior $p(\mu)$ we can reach the posterior belief
- what do we know about coins?
- how do I make that knowledge mathematicall explicit?

Conjugate Prior

- If we have a prior belief μ we want the posterior belief to have the same functional form

$$\text{posterior} \propto \text{likelihood} \times \text{prior}$$

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$$p(\mu|\theta) = f_1(\theta) \mu^{f_2(\theta)} (1 - \mu)^{f_3(\theta)}$$

$$\int_0^1 p(\mu|\theta) d\mu = 1$$

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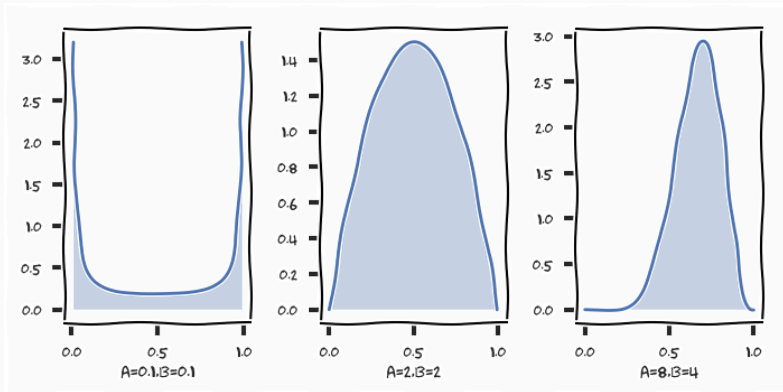
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$$\int_0^1 p(\mu|\theta) d\mu = 1$$

- *Does this make philosophical sense?*

Beta Distribution



$$\text{Beta}(\mu|a, b) = \frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} \mu^{a-1} (1-\mu)^{b-1}$$

$$p(\mu|\mathcal{D}) \propto p(\mathcal{D}|\mu)p(\mu)$$

$$\begin{aligned} p(\mu|\mathcal{D}) &\propto p(\mathcal{D}|\mu)p(\mu) \\ &= \prod_{i=1}^N \text{Bern}(x_i|\mu) \text{Beta}(\mu|a, b) \end{aligned}$$

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Churn the handle

$$p(\mu|\mathcal{D}) = \frac{p(\mathcal{D}|\mu)p(\mu)}{p(\mathcal{D})} = \frac{p(\mathcal{D}|\mu)p(\mu)}{\underbrace{\int p(\mathcal{D}|\mu)p(\mu)d\mu}_{\text{This is hard}}}$$

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- We know the functional form of the posterior

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Conjugacy

- We know the functional form of the posterior
- We know that the posterior is proportional to the likelihood times the prior
- *Use these facts to avoid the integral*

Posterior

- Because we know the form of the posterior, we can *identify* its parameters

$$\text{Beta}(\mu|a_n, b_n) \propto \frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} \mu^{\underbrace{\sum_i x_i + a}_{a_n}} (1-\mu)^{\underbrace{\sum_i (1-x_i) + b-1}_{b_n}}$$

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$$\text{Beta}(\mu|a, b) = \frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} \mu^{a-1} (1-\mu)^{b-1}$$

- This leads to the following posterior

$$\text{Beta}(\mu|a_n, b_n) = \frac{\Gamma(\sum_i x_i + a) \Gamma(\sum_i (1-x_i) + b)}{\Gamma(\sum_i x_i + a) \Gamma(\sum_i (1-x_i) + b)} \mu^{\sum_i x_i + a} (1-\mu)^{\sum_i (1-x_i) + b-1}$$



`bin/bin/computerlab.jpg`

- If we have a variable that can take K different states

$$\mathbf{x} = [0, 0, 1, 0, 0, 0]^T$$

Multinomial

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- Multinomial

$$p(\mathbf{x}|\boldsymbol{\mu}) = \prod_{k=1}^K \mu_k^{x_k}$$

$$\boldsymbol{\mu} = [\mu_1, \dots, \mu_K]^T, \sum_k \mu_k = 1$$

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- Likelihood

$$p(\mathbf{D}|\boldsymbol{\mu}) = \prod_{n=1}^N \prod_{k=1}^K \mu_k^{x_{nk}}$$

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$$p(\mathbf{x}|\boldsymbol{\mu}) = \prod_{k=1}^K \mu_k^{x_k}$$

- Conjugate prior

$$p(\boldsymbol{\mu}|\boldsymbol{\alpha}) \propto \prod_{k=1}^K \mu_k^{\alpha_k-1}$$

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$$p(\boldsymbol{\mu}|\boldsymbol{\alpha}) \propto \prod_{k=1}^K \mu_k^{\alpha_k-1}$$

- Dirichlet Distribution

$$\text{Dir}(\boldsymbol{\mu}|\boldsymbol{\alpha}) = \frac{\Gamma(\alpha_0)}{\Gamma(\alpha_1) \cdot \dots \cdot \Gamma(\alpha_K)} \prod_{k=1}^K \mu_k^{\alpha_k-1}$$

- Posterior

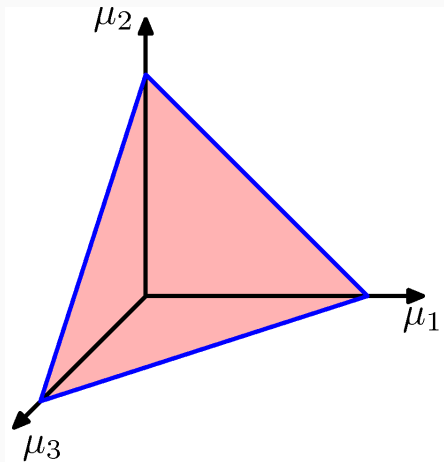
$$p(\boldsymbol{\mu}|\mathcal{D}, \boldsymbol{\alpha}) \propto p(\mathcal{D}|\boldsymbol{\mu})p(\boldsymbol{\mu}|\boldsymbol{\alpha}) \propto \prod_{k=1}^K \mu_k^{\alpha_k + m_k + 1}$$

$$m_k = \sum_n x_{nk}$$

- Normalised Form

$$p(|\mathcal{D}, \boldsymbol{\alpha}) = \frac{\Gamma(\alpha_0 + N)}{\Gamma(\alpha_1 + m_1) \cdot \dots \cdot \Gamma(\alpha_K + m_K)} \prod_{k=1}^K \mu_k^{\alpha_k + m_k + 1}$$

Dirichlet Prior



Spans the plane $\mu_1 + \mu_2 + \mu_3 = 1$

$$p(\mu|\mathcal{D}, \alpha) = \frac{p(\mathcal{D}|\mu)p(\mu|\alpha)}{p(\mathcal{D}|\alpha)}$$

- all these priors have parameters, where do they come from?

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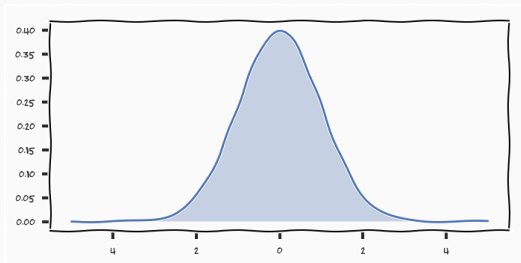
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- if we don't then place a prior over the priors parameters and go again

$$p(\mu|\mathcal{D}, \alpha) = \frac{p(\mathcal{D}|\mu)p(\mu|\alpha)}{p(\mathcal{D}|\alpha)}$$

- all these priors have parameters, where do they come from?
- either we know them
- if we don't then place a prior over the priors parameters and go again
- the idea is to build up a hierarchy until you can input your knowledge/assumptions

Continuous Distributions

Gaussian Distribution



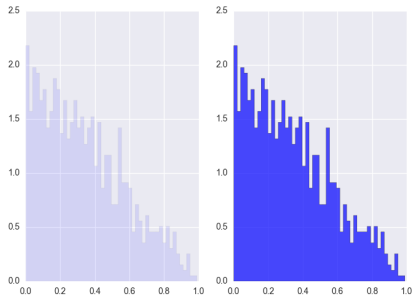
$$p(\mathbf{x}|\boldsymbol{\mu}, \boldsymbol{\Sigma}) = \frac{1}{(2\pi)^{\frac{D}{2}} |\boldsymbol{\Sigma}|^{\frac{1}{2}}} e^{-\frac{1}{2}(\mathbf{x}-\boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x}-\boldsymbol{\mu})}$$

Central Limit Theorem²

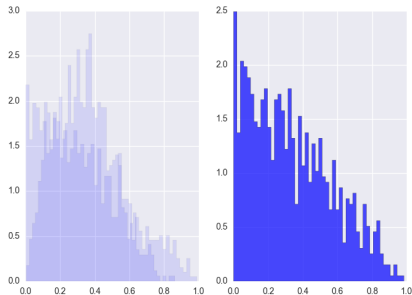
The central limit theorem states that the distribution of the sum (or average) of a large number of independent, identically distributed variables will be approximately normal, regardless of the underlying distribution.

²<https://www.youtube.com/watch?v=wadzSURQFT4>

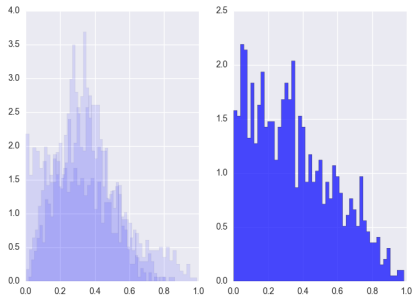
Central Limit Theorem



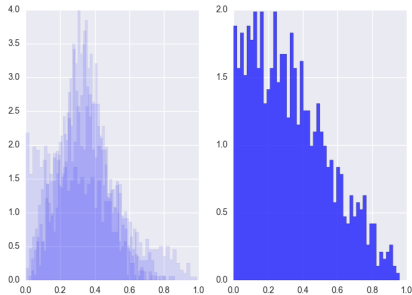
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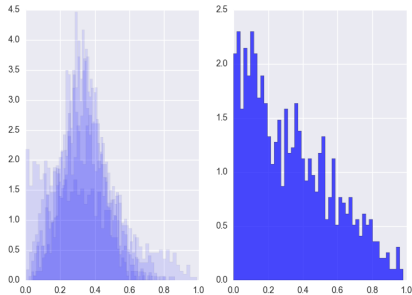
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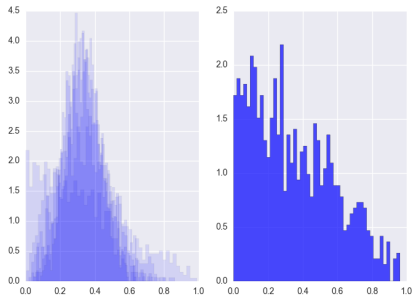
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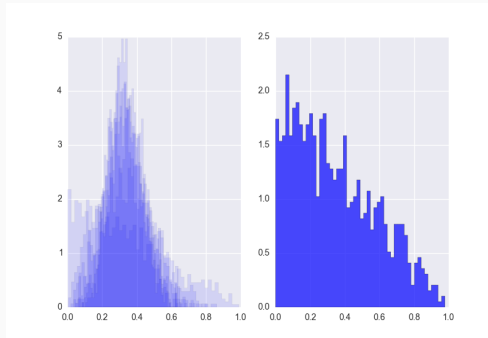
Central Limit Theorem



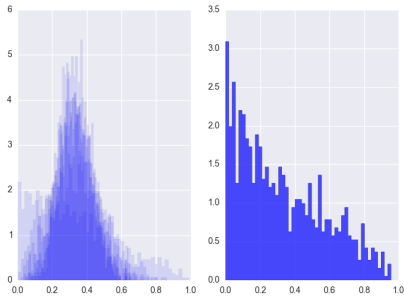
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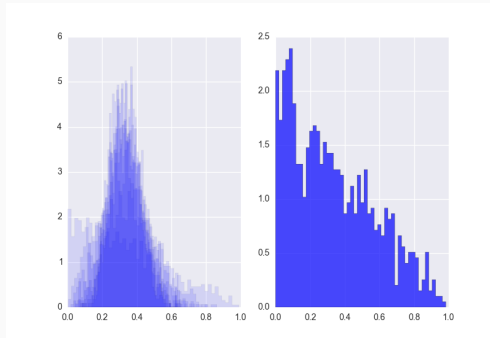
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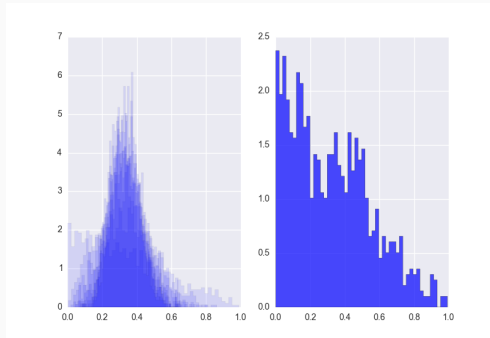
Central Limit Theorem



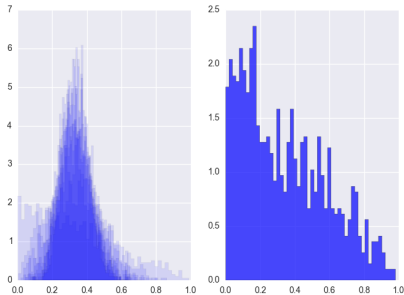
Central Limit Theorem



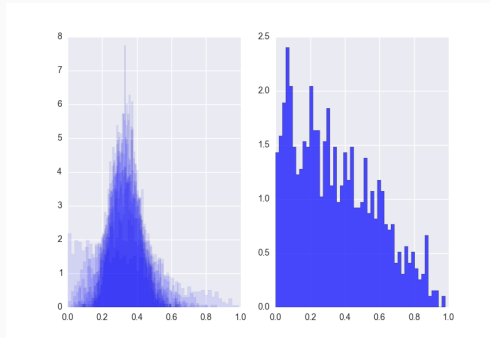
Central Limit Theorem



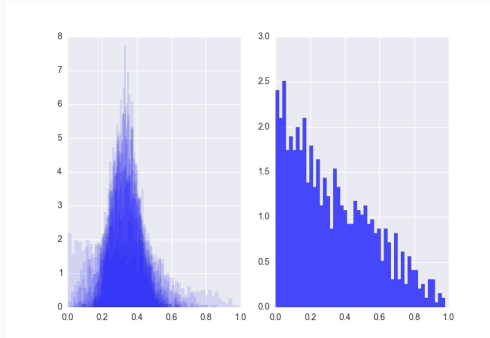
Central Limit Theorem



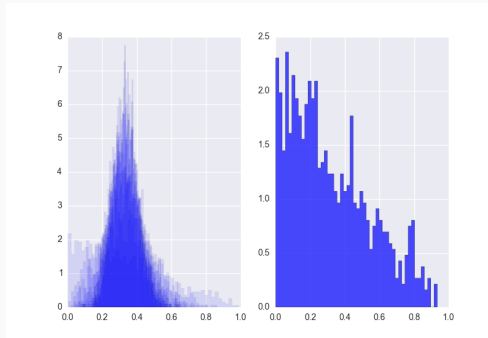
Central Limit Theorem



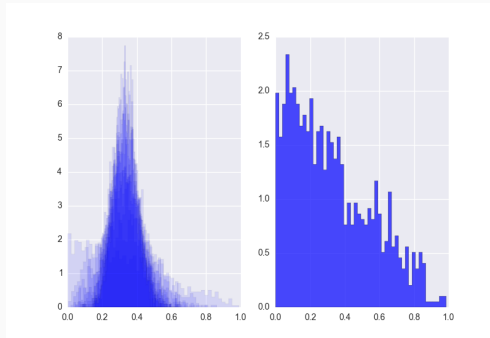
Central Limit Theorem



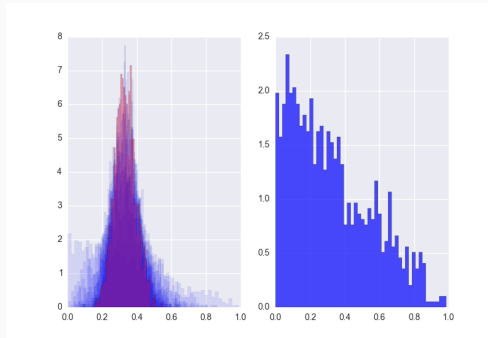
Central Limit Theorem

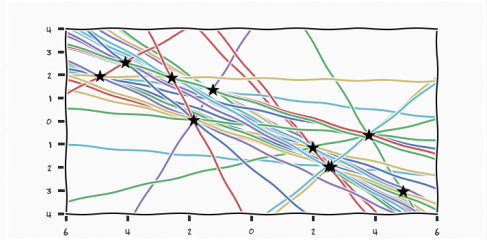


Central Limit Theorem



Central Limit Theorem





The search for Cerces

Gauss made the assumption that Piazzi's measurement errors were *independent* draws from a *unknown* distribution that was *fixed*. This we often know as *i.i.d Independent and Identically Distributed*

- Gaussians are self-conjugate
 - Gaussian likelihood + Gaussian Prior \rightarrow Gaussian Posterior
- Gaussian distribution
 - Conjugate prior for μ is Gaussian
 - Conjugate prior for Σ is Inverse-Wishard

³https://en.wikipedia.org/wiki/Conjugate_prior

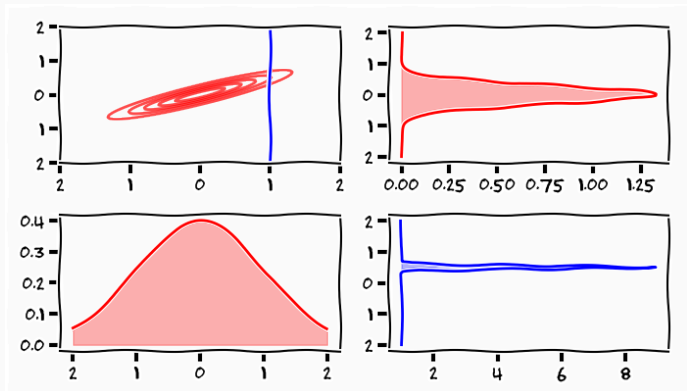
$$p(x_1, x_2) = \mathcal{N} \left(\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix} \right)$$

Posterior $p(x_1|x_2) \propto p(x_2|x_1)p(x_1)$

Marginal $p(x_1) = \int p(x_1, x_2) dx_2$

Conditional $p(x_1|x_2) = \frac{p(x_1, x_2)}{p(x_2)}$

Gaussian Identities



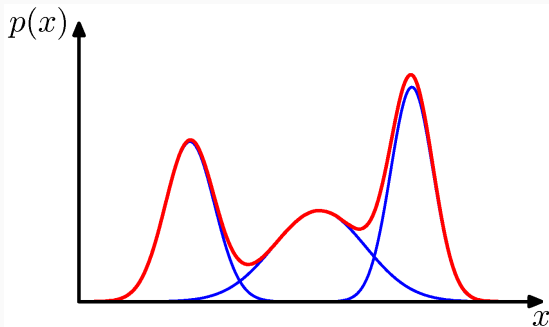
Tuesday Lecture

- Most distributions are parametrised using exponentials
- Exponential family natural parametrisation

$$p(\mathbf{x}|\boldsymbol{\eta}) = h(\mathbf{x})g(\boldsymbol{\eta})e^{\boldsymbol{\eta}^T \mathbf{u}(\mathbf{x})}$$

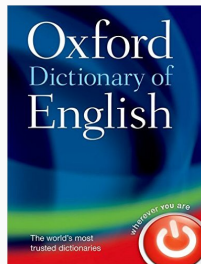
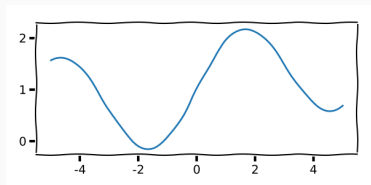
- Conjugate prior

$$p(\boldsymbol{\eta}|\boldsymbol{\chi}, \nu) = f(\boldsymbol{\chi}, \nu)g(\boldsymbol{\chi})^\nu e^{\nu \boldsymbol{\eta}^T \boldsymbol{\chi}}$$



$$p(\mathbf{x}) = \sum_{k=1}^K p(k) \underbrace{p(\mathbf{x}|k)}_{\mathcal{N}(\mu_k, \Sigma_k)}$$





Kologrovs Existence Theorem

Defines what a distribution needs to fulfill in order for a process to exist. Each finite instantiation of the process is this distribution.

Example

Decisions



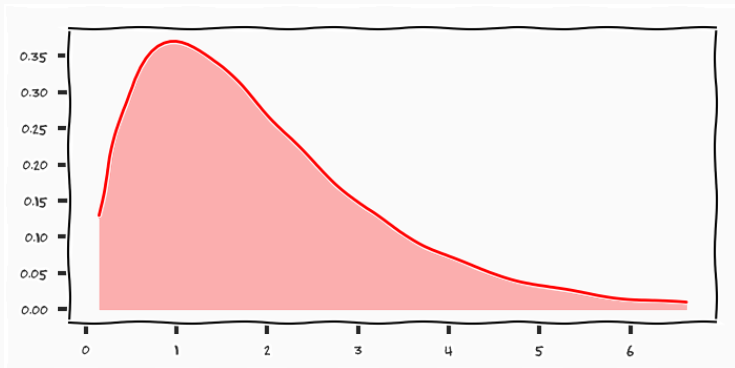
4

⁴Reservoir Dogs Tipping Scene [YouTube](#)

$$p(y)$$

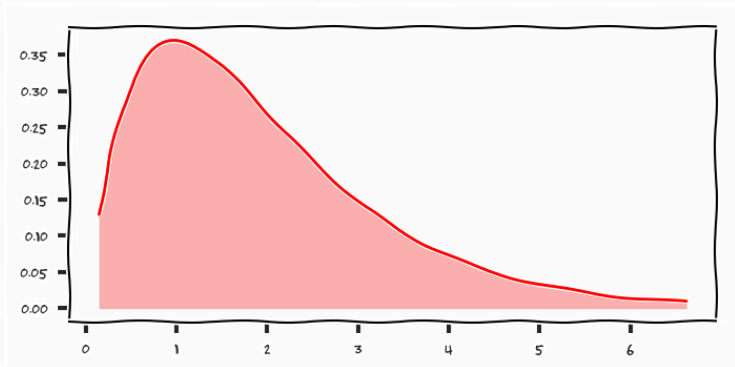
- what do I believe about tip **before** I see data?
- what is a sensible tip?

Tipping



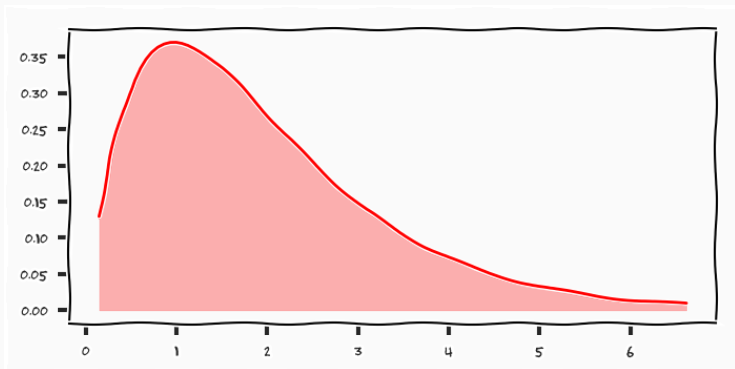
- I believe that 1£ is a sensible tip
- You cannot tip negative
- There is potentially an upper bound

Tipping



- I believe that 1£ is a sensible tip
- You cannot tip negative
- There is potentially an upper bound
- This is not a model, its just a belief in a variable

Tipping



- I believe that 1£ is a sensible tip
- You cannot tip negative
- There is potentially an upper bound
- This is not a model, its just a belief in a variable
- *a model relates new phenomenon to knowledge*



- it is quite hard to say something about tip without any other knowledge
- **Assumption** the value of tip is related to the quality of the food

$$p(y|x)$$

- how likely do I think the observed data y is to come from this specific x .

Tipping if I know the quality of the food what do I believe the tip should be

What is the tip that I should expect to get?

$$\mathbb{E}_{p(x)}[p(y|x)] = \int p(y|x)p(x)dx = p(y)$$

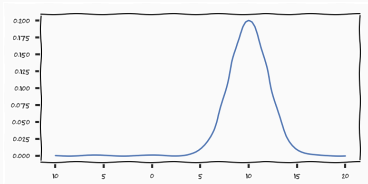
- What should I expect to get in tip
- I have an idea of the general distribution of quality of food
- *Understanding is when we can relate knowledge to new phenomenon*

$$p(x|c)$$

Hierarchical distribution

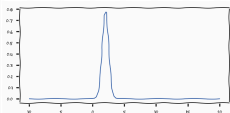
- Its quite hard to think of a prior over quality of food
- Can we parametrise the quality?

$$p(x|c) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu_c)(x-\mu_c)}{2\sigma^2}}$$

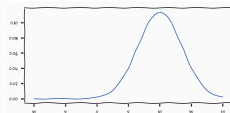


Hierarchical distribution

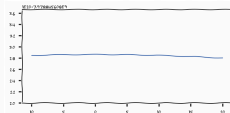
- Its quite hard to think of a prior over quality of food
- Can we parametrise the quality?
- Lets assume that if we know the cuisine we have an idea



Swedish



Italian



Uzbeki

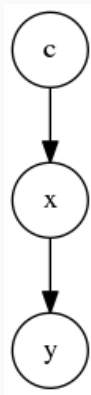
Hierarchical distribution

- Its quite hard to think of a prior over quality of food
- Can we parametrise the quality?
- Lets assume that if we know the cuisine we have an idea
- *Relating to knowledge!*

Tipping model

$$p(y, x, c) = p(y|x)p(x|c)p(c)$$

- Graphical Model shows dependency structure
- Shows "minimal" factorisation of joint distribution (model)



Knowing the tip

- Which cuisine did they eat if?
 - $p(c|y)$
- What was the quality of the food?
 - $p(x|y)$



Summary

- Distributions allows us to make our assumptions explicit
- Conjugacy implies that the posterior and the prior is in the same family
- Now we have the tools that allows us to do Machine Learning

eof

Appendix

$$p(x_1|x_2) \propto p(x_2|x_1)p(x_1)$$

1. Multiply right-hand side
2. Look at the exponents
3. Find the three terms, **constant**, **mixed** and **quadratic**
4. Complete the square to find the parameters

$$p(x_1) = \int p(x_1, x_2) dx_2 = \mathcal{N}(\mu_1, \Sigma_{11})$$

1. Write out the exponent of the joint distribution
2. Complete Square and collect terms with $x_1 - \mu_1$ (as we know the result)
3. Compute integral by knowing that densities always integrates to one

$$p(x_1|x_2) = \frac{p(x_1, x_2)}{p(x_2)}$$

1. Factorise the problem as $p(x_1, x_2) = p(x_1|x_2)p(x_2)$
2. We know the marginal and the joint
3. Use Schur complement to re-write the covariance matrix on block form

References



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