

# Machine Learning

## Classification: The Laplace Approximation

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November 6, 2018

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# Introduction

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- The second coursework will start next week.
- This week there are no lab sessions

- Classification (Task)
- Logistic Regression (Model)
- Bayesian Logistic Regression (Model)
- Laplace Approximation (Inference)

$$\text{posterior} \propto \text{likelihood} \times \text{prior}$$

- If we pick the conjugate prior to the likelihood parameter then the posterior is in the same family as the prior
- This means that we do not have to compute the proportionality (evidence)
- We can just multiply likelihood and prior and identify terms

$$\mathcal{N}(\mathbf{w}|\boldsymbol{\mu}_N, \Sigma_N) \propto \mathcal{N}(\boldsymbol{\mu}(\mathbf{w}), \Sigma_1)\mathcal{N}(\mathbf{w}|\boldsymbol{\mu}, \Sigma_2)$$

- Multiply right-hand side
- Identify the terms on the right-hand side

$$\mathcal{N}(\mathbf{w}|\boldsymbol{\mu}_N, \Sigma_N) \propto \mathcal{N}(\boldsymbol{\mu}(\mathbf{w}), \Sigma_1)\mathcal{N}(\mathbf{w}|\boldsymbol{\mu}, \Sigma_2)$$

- Multiply right-hand side
- Identify the terms on the right-hand side
- *what if conjugacy does not make sense?*

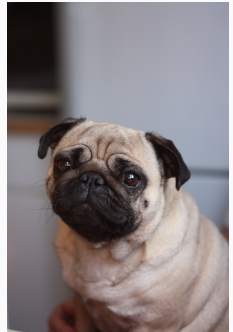
# Classification

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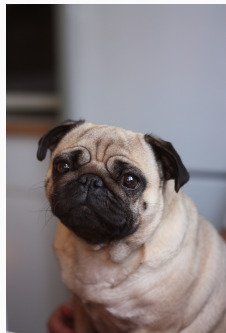
- Data  $\{\mathcal{D}, \mathcal{C}\}$ 
  - Variates:  $\mathcal{D} = \{x_i\}_{i=1}^N$
  - Features:  $x \in \mathbb{R}^D$
  - Labels:  $\mathcal{C} \in \{\mathcal{C}_1, \dots, \mathcal{C}_k\}$
- **Task:** given a set of observations and their corresponding class can we associate the correct class to new observations?

**Image** This is an image Stella, she was a pug!



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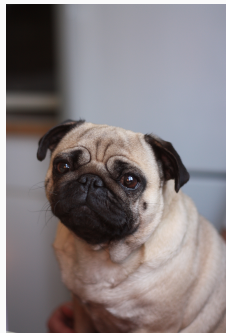
**Question** does the appearance of the image make her a pug?



**Image** This is an image Stella, she was a pug!

**Question** does the appearance of the image make her a pug?

**Question** does her being a pug make an image of her appear like this?



- The image appears this way because she was a pug

# Generative model

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- *Is it possible to have the same image while its not Stella?*

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  - Pug + Camera + lots of other stuff  $\rightarrow$  Image

$$f(x) = I$$

# Generative model

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- *Is it possible to have the same image while its not Stella?*
- *Is it possible to have the same image while its not a pug?*
- To handle all possible cases we need to think about how the data was created
  - Pug + Camera + lots of other stuff  $\rightarrow$  Image

$$f(x) = I$$

- *When we formulate models we want to formulate the generation of the data*

$$p(\mathcal{D}, \mathcal{C}) = p(\mathcal{D}|\mathcal{C})p(\mathcal{C})$$

1. Formulate the likelihood and the prior
2. Formulate the posterior
3. Get updated belief through posterior with new data

- Lets assume we want to update our belief of class  $\mathcal{C}_1$  from the information in  $x$

$$p(\mathcal{C}_1|x) = \frac{p(x|\mathcal{C}_1)p(\mathcal{C}_1)}{p(x)}$$

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- What is the evidence in this case?

$$p(x) = \int p(x|\mathcal{C})p(\mathcal{C})d\mathcal{C} = \sum_{i=1}^k p(x|\mathcal{C}_i)p(\mathcal{C}_i)$$

# Classification

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- Posterior

$$p(\mathcal{C}_1|x) = \frac{p(x|\mathcal{C}_1)p(\mathcal{C}_1)}{\sum_{i=1}^k p(x|\mathcal{C}_i)p(\mathcal{C}_i)}$$

- Lets assume we have only two classes i.e.  $\mathcal{C} \in \{\mathcal{C}_1, \mathcal{C}_2\}$

$$p(x) = p(x|\mathcal{C}_1)p(\mathcal{C}_1) + p(x|\mathcal{C}_2)p(\mathcal{C}_2)$$

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- Posterior:

$$p(\mathcal{C}_1|x) = \frac{p(x|\mathcal{C}_1)p(\mathcal{C}_1)}{p(x|\mathcal{C}_1)p(\mathcal{C}_1) + p(x|\mathcal{C}_2)p(\mathcal{C}_2)} =$$



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$$\begin{aligned} p(\mathcal{C}_1|x) &= \frac{p(x|\mathcal{C}_1)p(\mathcal{C}_1)}{p(x|\mathcal{C}_1)p(\mathcal{C}_1) + p(x|\mathcal{C}_2)p(\mathcal{C}_2)} = \\ &= \frac{\left(\frac{1}{p(x|\mathcal{C}_1)p(\mathcal{C}_1)}\right)}{\left(\frac{1}{p(x|\mathcal{C}_1)p(\mathcal{C}_1)}\right)} \cdot \frac{p(x|\mathcal{C}_1)p(\mathcal{C}_1)}{p(x|\mathcal{C}_1)p(\mathcal{C}_1) + p(x|\mathcal{C}_2)p(\mathcal{C}_2)} = \end{aligned}$$

# Binary Classification

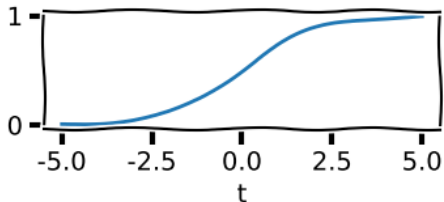
- Lets assume we have only two classes i.e.  $\mathcal{C} \in \{\mathcal{C}_1, \mathcal{C}_2\}$

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- Posterior:

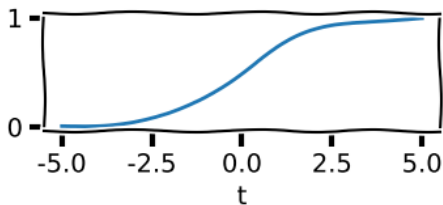
$$\begin{aligned} p(\mathcal{C}_1|x) &= \frac{p(x|\mathcal{C}_1)p(\mathcal{C}_1)}{p(x|\mathcal{C}_1)p(\mathcal{C}_1) + p(x|\mathcal{C}_2)p(\mathcal{C}_2)} = \\ &= \frac{\left(\frac{1}{p(x|\mathcal{C}_1)p(\mathcal{C}_1)}\right)}{\left(\frac{1}{p(x|\mathcal{C}_1)p(\mathcal{C}_1)}\right)} \cdot \frac{p(x|\mathcal{C}_1)p(\mathcal{C}_1)}{p(x|\mathcal{C}_1)p(\mathcal{C}_1) + p(x|\mathcal{C}_2)p(\mathcal{C}_2)} = \\ &= \frac{1}{1 + \frac{p(x|\mathcal{C}_2)p(\mathcal{C}_2)}{p(x|\mathcal{C}_1)p(\mathcal{C}_1)}} \end{aligned}$$

# Binary Classification



$$y = \frac{1}{1 + e^{-t}}$$

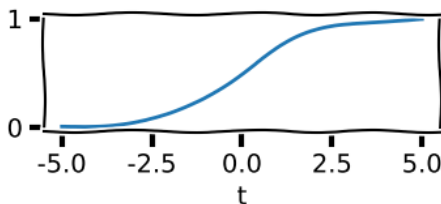
# Binary Classification



$$y = \frac{1}{1 + e^{-t}}$$

$$p(C_1|x) = \frac{1}{1 + \frac{p(x|C_2)p(C_2)}{p(x|C_1)p(C_1)}}$$

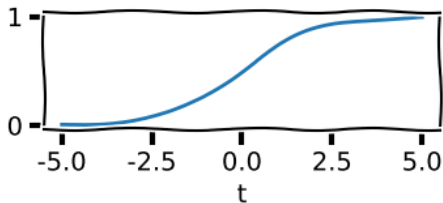
# Binary Classification



$$y = \frac{1}{1 + e^{-t}}$$

$$p(C_1|x) = \frac{1}{1 + \frac{p(x|C_2)p(C_2)}{p(x|C_1)p(C_1)}} = \frac{1}{1 + \exp\left(\log\left(\frac{p(x|C_2)p(C_2)}{p(x|C_1)p(C_1)}\right)\right)}$$

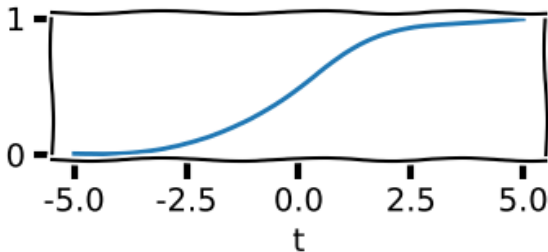
# Binary Classification



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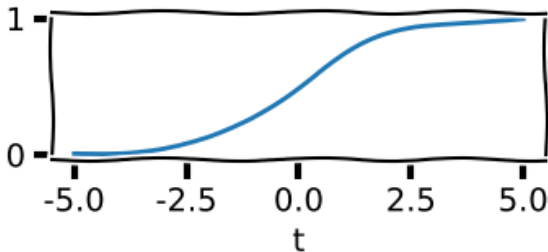
$$\begin{aligned} p(C_1|x) &= \frac{1}{1 + \frac{p(x|C_2)p(C_2)}{p(x|C_1)p(C_1)}} = \frac{1}{1 + \exp\left(\log\left(\frac{p(x|C_2)p(C_2)}{p(x|C_1)p(C_1)}\right)\right)} \\ &= \frac{1}{1 + \exp\left(-\log\left(\frac{p(x|C_1)p(C_1)}{p(x|C_2)p(C_2)}\right)\right)} \end{aligned}$$

# Binary Classification



$$t = \log \left( \frac{p(x|C_1)p(C_1)}{p(x|C_2)p(C_2)} \right)$$

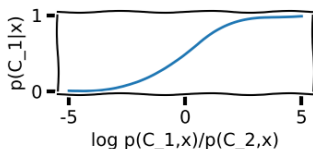
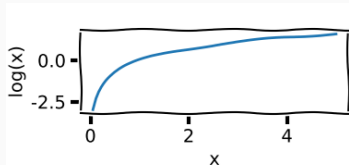
# Binary Classification



$$t = \log \left( \frac{p(x|C_1)p(C_1)}{p(x|C_2)p(C_2)} \right) = \log \left( \frac{p(x, C_1)}{p(x, C_2)} \right)$$



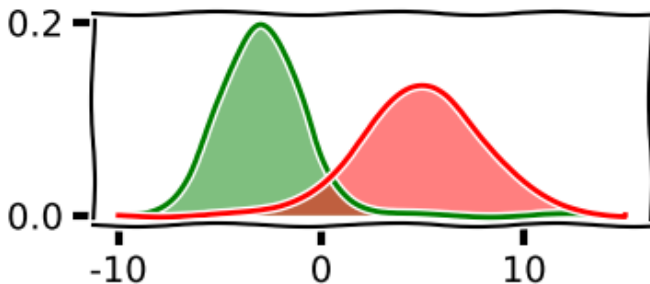
# Binary Classification



- $p(x, C_1) > p(x, C_2)$ 
  - $p(C_1|x) > 0.5$
- $p(x, C_1) < p(x, C_2)$ 
  - $p(C_1|x) < 0.5$
- $p(x, C_1) = p(x, C_2)$ 
  - $p(C_1|x) = 0.5$

- $p(x, C_1) = 0$ 
  - $p(C_1|x) = 0$
- $p(x, C_2) \rightarrow 0$ 
  - $p(C_1|x) \rightarrow 1$
- $p(x, C_1) = p(x, C_2) = 0$ 
  - Undefined

# Likelihoods



- We haven't specified the model yet, let's make a Gaussian likelihood

$$p(x|\mathcal{C}_i) = \mathcal{N}(x|\mu_i, \sigma_i) = \frac{1}{\sqrt{2\pi\sigma_i^2}} e^{-\frac{(x-\mu_i)^2}{2\sigma_i^2}}$$

$$t = \log \left( \frac{p(x|C_1)p(C_1)}{p(x|C_2)p(C_2)} \right)$$

$$t = \log \left( \frac{p(x|\mathcal{C}_1)p(\mathcal{C}_1)}{p(x|\mathcal{C}_2)p(\mathcal{C}_2)} \right) = \log \left( \frac{\frac{1}{\sqrt{2\pi\sigma_1^2}} e^{-\frac{(x-\mu_1)^2}{2\sigma_1^2}} p(\mathcal{C}_1)}{\frac{1}{\sqrt{2\pi\sigma_2^2}} e^{-\frac{(x-\mu_2)^2}{2\sigma_2^2}} p(\mathcal{C}_2)} \right)$$

$$\begin{aligned} t &= \log \left( \frac{p(x|\mathcal{C}_1)p(\mathcal{C}_1)}{p(x|\mathcal{C}_2)p(\mathcal{C}_2)} \right) = \log \left( \frac{\frac{1}{\sqrt{2\pi\sigma_1^2}} e^{-\frac{(x-\mu_1)^2}{2\sigma_1^2}} p(\mathcal{C}_1)}{\frac{1}{\sqrt{2\pi\sigma_2^2}} e^{-\frac{(x-\mu_2)^2}{2\sigma_2^2}} p(\mathcal{C}_2)} \right) \\ &= \log \left( \frac{A}{B} \right) = \log(A) - \log(B) \end{aligned}$$

$$\log(A) = \log \left( \frac{1}{\sqrt{2\pi\sigma_1^2}} e^{-\frac{(x-\mu_1)^2}{2\sigma_1^2}} p(\mathcal{C}_1) \right)$$

$$\begin{aligned}\log(A) &= \log\left(\frac{1}{\sqrt{2\pi\sigma_1^2}} e^{-\frac{(x-\mu_1)^2}{2\sigma_1^2}} p(\mathcal{C}_1)\right) = \\ &= -\frac{1}{2}\log(2\pi\sigma_1^2) - \frac{(x-\mu_1)^2}{2\sigma_1^2} + \log(p(\mathcal{C}_1))\end{aligned}$$

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$$\log(A) - \log(B)$$

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$$p(C_1|x) = \frac{1}{1 + e^{-t}}$$

- The posterior over  $\mathcal{C}_1$  (and its the same for  $\mathcal{C}_2$ ) depends on  $x$  as

$$-x^2 \left( \frac{1}{2\sigma_1^2} - \frac{1}{2\sigma_2^2} \right) + x \left( \frac{\mu_1}{\sigma_1^2} - \frac{\mu_2}{\sigma_2^2} \right)$$



## Posterior analysis

- The posterior over  $\mathcal{C}_1$  (and its the same for  $\mathcal{C}_2$ ) depends on  $x$  as

$$-x^2 \left( \frac{1}{2\sigma_1^2} - \frac{1}{2\sigma_2^2} \right) + x \left( \frac{\mu_1}{\sigma_1^2} - \frac{\mu_2}{\sigma_2^2} \right)$$

- if  $\sigma_1 = \sigma_2$

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  - the posterior is **linear** in  $x$

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- if  $\mu_2 = \mu_1$  and  $\sigma_1 = \sigma_2$

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- if  $\sigma_1 = \sigma_2$ 
  - the posterior is **linear** in  $x$
- if  $\mu_2 = \mu_1$  and  $\sigma_1 = \sigma_2$ 
  - the posterior does not depend on  $x$

$$p(\mathcal{C}_1|x) = \frac{1}{1 + e^{-\log \frac{p(\mathcal{C}_1)}{p(\mathcal{C}_2)}}} = \frac{p(\mathcal{C}_1)}{p(\mathcal{C}_1) + p(\mathcal{C}_2)} = \frac{p(\mathcal{C}_1)}{p(\mathcal{C})} = p(\mathcal{C}_1)$$

# Posterior analysis

- The posterior over  $\mathcal{C}_1$  (and its the same for  $\mathcal{C}_2$ ) depends on  $x$  as

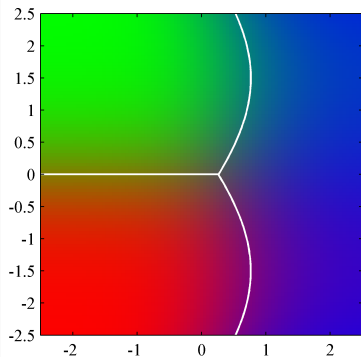
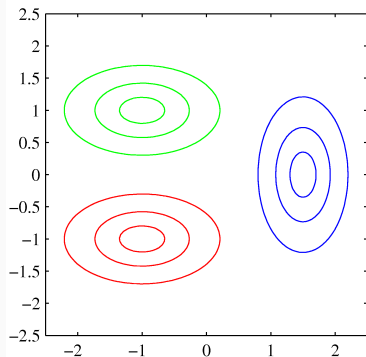
$$-x^2 \left( \frac{1}{2\sigma_1^2} - \frac{1}{2\sigma_2^2} \right) + x \left( \frac{\mu_1}{\sigma_1^2} - \frac{\mu_2}{\sigma_2^2} \right)$$

- if  $\sigma_1 = \sigma_2$ 
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$$p(\mathcal{C}_1|x) = \frac{1}{1 + e^{-\log \frac{p(\mathcal{C}_1)}{p(\mathcal{C}_2)}}} = \frac{p(\mathcal{C}_1)}{p(\mathcal{C}_1) + p(\mathcal{C}_2)} = \frac{p(\mathcal{C}_1)}{p(\mathcal{C})} = p(\mathcal{C}_1)$$

- *if the observations does not provide me with any information to update my belief my posterior belief is equal to my prior belief*

# Posterior analysis<sup>1</sup>



- Red & Green share the same covariance  $\Rightarrow$  linear separation
- Blue & (Red & Green) different covariance  $\Rightarrow$  curved separation

<sup>1</sup>Bishop, C. M. (2006). Figure 4.11

# Logistic Regression

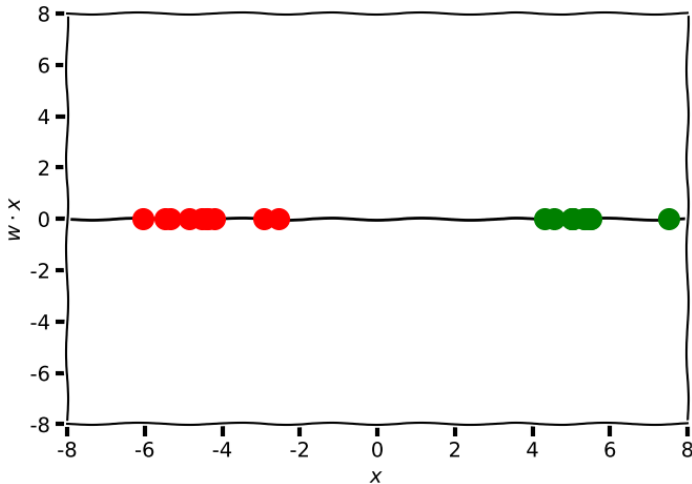
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$$p(\mathcal{C}_1|x) = \frac{1}{1 + \exp(-f(x))}$$

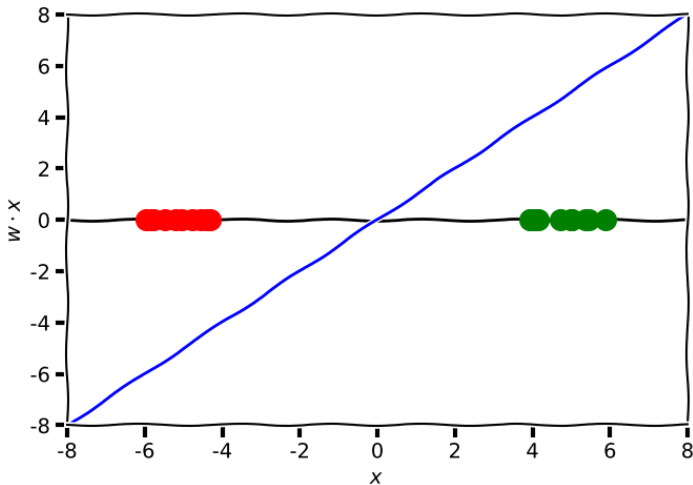
- We can derive the posterior through principle by Bayes Rule
  - This forces us to make our assumptions clear
- We can directly parametrise the posterior as we know its form
  - this is called **logistic regression**



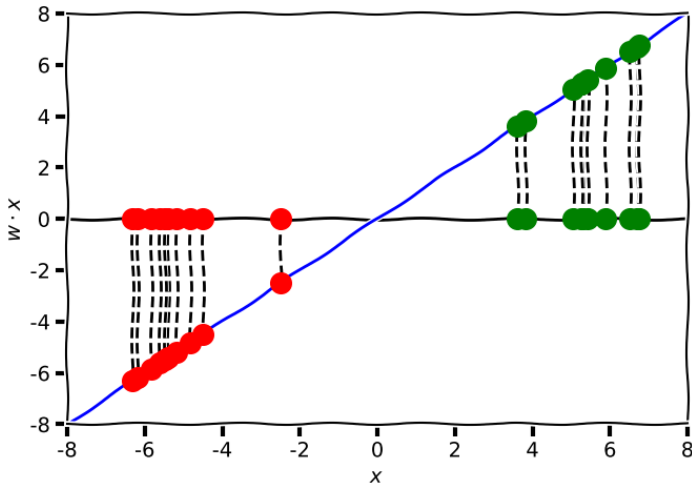
# Logistic Regression



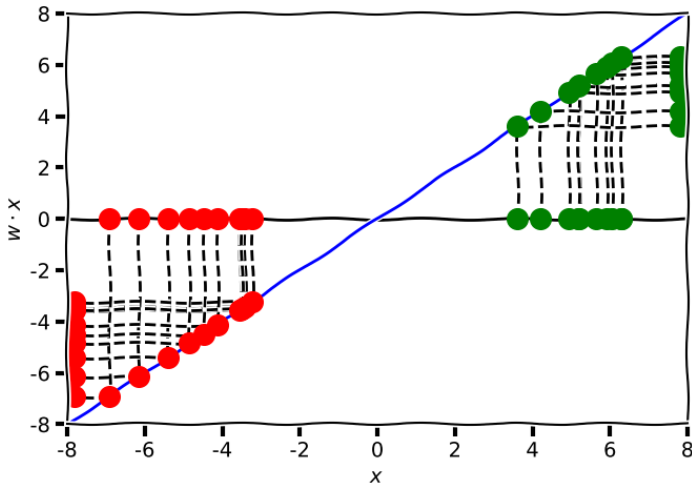
# Logistic Regression



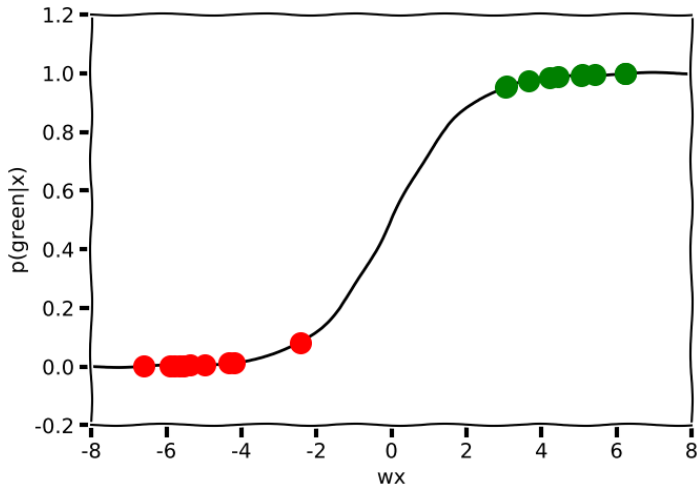
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# Why

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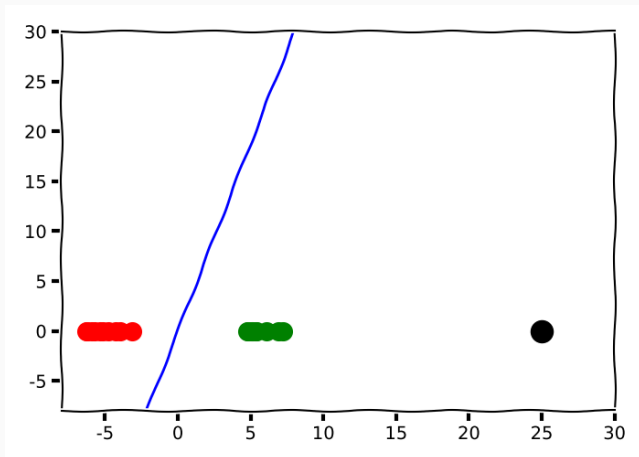
- Binary classification implies 20200 parameters
- However good our priors are this is likely to require a lot of data to learn
- Logistic regression implies 101

$$\mathbf{w} \in \mathbb{R}^{100}$$

$$p(C|\mathcal{D})$$

- Reaching this through principle makes it a posterior
- If we parametrise it directly we have to see it as a likelihood
  - we do not **model**  $\mathcal{D}$
  - we do not quantify our uncertainty in  $\mathcal{D}$ 
    - denominator in Bayes Rule  $p(\mathcal{D})$

# Why Not



$$t = \log \left( \frac{p(x|C_1)p(C_1)}{p(x|C_2)p(C_2)} \right)$$

$$p(\mathcal{C}_1|x) = \frac{1}{1 + \exp(-f(x))} = \sigma(x)$$

- We seek a function that is positive for  $\mathcal{C}_1$  and negative for  $\mathcal{C}_2$
- Linear classifier

$$f(x) = w^T x$$

- Maximum Likelihood

$$\hat{w} = \operatorname{argmax}_w p(\mathcal{C}|\mathcal{D}) = \operatorname{argmin}_w -\log(p(\mathcal{C}|\mathcal{D}))$$

$$E(w) = -\log p(\mathcal{C}|\mathcal{D}) = -\log \left( \prod_i^N \sigma(x_i)^{c_i} \cdot (1 - \sigma(x_i))^{1-c_i} \right)$$

- we want to minimise the above
- take derivatives with respect to  $w$

$$\frac{\delta E(w)}{\delta w} = \sum_i^N (\sigma(x_i) - c_i) x_i$$

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- $(\sigma(x_i) - c_i)$  is the classification error
  - if 0 no gradient
  - if  $\neq 0$  then the gradient goes in the direction of the data-point  $x$
- Using the gradient we can now update  $w$  and find a solution

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- We have seen how to do linear regression in a principled way
  - specify prior over  $\mathbf{w}$
  - derive posterior

# Bayesian Logistic Regression

We want to use the same motivation as we did for normal regression

- Prior

$$p(\mathbf{w}) = \mathcal{N}(\mathbf{m}_0, \mathbf{S}_0)$$

- Likelihood

$$p(c_i | \mathbf{w}, \mathbf{x}_i) = \sigma(\mathbf{w}^T \mathbf{x}_i)$$

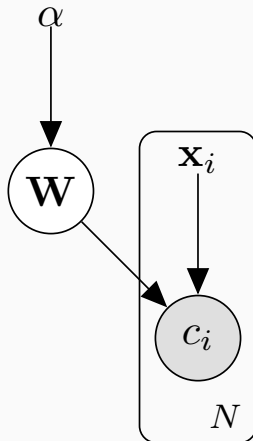
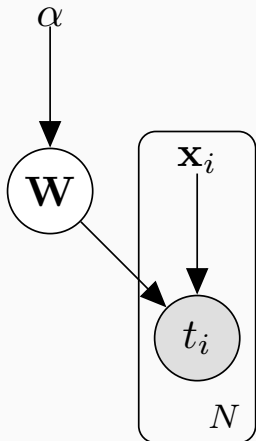
$$p(\mathbf{c} | \mathbf{w}, \mathbf{x}) = \prod_i^N \sigma(\mathbf{w}^T \mathbf{x}_i)^{c_i} \cdot (1 - \sigma(\mathbf{w}^T \mathbf{x}_i))^{1-c_i}$$

You can also do a feature mapping if you want and replace  $\mathbf{x}$  with  $\Phi(\mathbf{x})$

$$\mathcal{N}(\boldsymbol{\mu}_N, \mathbf{S}_N) \propto \log \left( \prod_i^N \sigma(x_i)^{c_i} \cdot (1 - \sigma(x_i))^{1-c_i} \right) \\ - \frac{1}{2}(\mathbf{w} - \mathbf{m}_0)^T \mathbf{S}_0^{-1}(\mathbf{w} - \mathbf{m}_0) - \log(Z)$$

- Previously we could use conjugacy to reach analytical posterior
- In this case we have changed the likelihood and the Gaussian prior is non-conjugate
- This posterior is intractable

# Bayesian Linear Regression



- want to reach posterior over weights

$$p(\mathbf{w}|\mathbf{t}) \propto p(\mathbf{t}|\mathbf{w})p(\mathbf{w})$$

- we cannot use conjugacy anymore as likelihood is sigmoid

# Laplace Approximation

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# Laplace Approximation

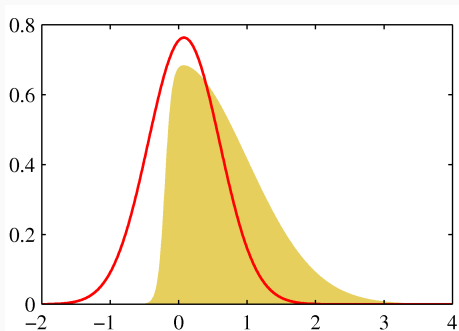
$$p(z|x) = \frac{1}{Z} f(z) = \frac{f(z)}{\int f(z) dz}$$

- Will use  $p(z)$  to refer to the posterior
- $p(z)$  is unknown as we cannot compute  $Z$
- $f(z)$  is possible to compute if we have likelihood and prior

$$f(z) = p(x|z)p(z)$$

$$\log p(z) = \log \left( \frac{1}{Z} f(z) \right) = \log(f(z)) + \text{const w.r.t. } z$$

- $p(z)$  and  $f(z)$  will have the same modes
  - *is this always true?*
- **Idea**: we can approximate each mode with a distribution we can normalise



- Find the mode of the posterior
- Fit Gaussian to this mode

# Taylor Expansion

$$f(x) = f(x_0) + \frac{\partial}{\partial x} f(x_0)(x - x_0) + \frac{1}{2} \frac{\partial^2}{\partial x^2} f(x_0)(x - x_0)^2 + \mathcal{O}((x - x_0)^3)$$

- A Taylor expansion is an approximation of a function around a specific value
- If we expand around a maxima  $x_0$

$$\frac{\partial}{\partial x} f(x_0) = 0$$

- This leads to

$$f(x) = f(x_0) - \frac{1}{2} \left| \frac{\partial^2}{\partial x^2} f(x_0) \right| (x - x_0)^2 + \mathcal{O}((x - x_0)^3)$$

$$f(\mathbf{w}) = p(\mathbf{t}|\mathbf{w})p(\mathbf{w})$$

- we want to find the mode of this, i.e. the maxima

$$\hat{\mathbf{w}} = \operatorname{argmax}_{\mathbf{w}} p(\mathbf{t}|\mathbf{w})p(\mathbf{w})$$

- This we know as the Maximum-a-Posterior (MAP) estimate

# Laplace Approximation

1. Find mode of  $p(z)$

$$\frac{\partial}{\partial z} p(z_0) = \frac{\partial}{\partial z} f(z_0) = 0$$

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$$\log f(z) \approx \log f(z_0) - \frac{1}{2} \frac{\partial^2}{\partial^2} \log(f(z_0))(z - z_0)^2$$

# Laplace Approximation

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3. Take exponential to get function

$$f(z) \approx f(z_0) e^{\underbrace{-\frac{1}{2} \frac{\partial^2}{\partial^2} \log(f(z_0))(z-z_0)^2}_A} = f(z_0) e^{-\frac{1}{2} A (z-z_0)^2}$$



# Laplace Approximation

$$f(z) \approx f(z_0)e^{-\frac{1}{2}A(z-z_0)^2}$$

- we want to find an approximation, to  $p(z)$  so we need to normalise to a distribution

$$p(z) = \frac{1}{Z}f(z) \approx q(z)$$

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$$p(z) = \frac{1}{Z}f(z) \approx q(z)$$

- assume that  $q(z)$  is Gaussian, i.e.  $f(z_0) = p(\text{mean})$

$$q(z) = \left(\frac{A}{2\pi}\right)^{\frac{1}{2}} e^{-\frac{A}{2}(z-z_0)^2}$$

# Laplace Approximation

- One dimensional

$$q(z) = \left( \frac{A}{2\pi} \right)^{\frac{1}{2}} e^{-\frac{A}{2}(z-z_0)^2}$$

- D dimensional

$$q(\mathbf{z}) = \frac{|\mathbf{A}|}{(2\pi)^{\frac{D}{2}}} e^{-\frac{1}{2}(\mathbf{z}-\mathbf{z}_0)^T \mathbf{A}(\mathbf{z}-\mathbf{z}_0)} = \mathcal{N}(\mathbf{z}|\mathbf{z}_0, \mathbf{A}^{-1})$$

$$\mathbf{A} = -\nabla \nabla \log f(\mathbf{z})|_{\mathbf{z}=\mathbf{z}_0}$$

- Where  $\mathbf{A}$  is the Hessian matrix

# Bayesian Logistic Regression

We want to use the same motivation as we did for normal regression

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$$p(\mathbf{w}) = \mathcal{N}(\mathbf{m}_0, \mathbf{S}_0)$$

- Likelihood

$$p(c_i | \mathbf{w}, \mathbf{x}_i) = \sigma(\mathbf{w}^T \mathbf{x}_i)$$

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You can also do a feature mapping if you want and replace  $\mathbf{x}$  with  $\Phi(\mathbf{x})$

$$q(\mathbf{w}|\mathbf{t}) = \mathcal{N}(\mathbf{m}_N, \mathbf{S}_N) \approx p(\mathbf{w}|\mathbf{t}) \propto p(\mathbf{t}|\mathbf{w})p(\mathbf{w}) = f(\mathbf{w})$$

- Compute  $f(\mathbf{w})$

$$\begin{aligned} \log p(\mathbf{w}|\mathbf{t}) = & \log \left( \prod_i^N \sigma(\mathbf{w}^T \mathbf{x}_i)^{t_i} \cdot (1 - \sigma(\mathbf{w}^T \mathbf{x}_i))^{1-t_i} \right) \\ & - \frac{1}{2}(\mathbf{w} - \mathbf{m}_0)^T \mathbf{S}_0^{-1}(\mathbf{w} - \mathbf{m}_0) - \log(Z) \end{aligned}$$

- The stationary point is the MAP estimate

$$\mathbf{S}_N^{-1} = -\nabla \nabla \log p(\mathbf{w}|\mathbf{t})|_{\mathbf{w}=\mathbf{w}_{MAP}} = \mathbf{S}_0^{-1} + \sum_{n=1}^N \sigma(\mathbf{w}^T \mathbf{x})(1 - \sigma(\mathbf{w}^T \mathbf{x})) \mathbf{x} \mathbf{x}^T$$

- we can compute the Hessian around  $\mathbf{w}_{MAP}$
- this leads to the final approximation

$$q(\mathbf{w}) = \mathcal{N}(\mathbf{w}|\mathbf{w}_{MAP}, \mathbf{S}_N)$$

## Summary

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- Compute a mode of the posterior distribution, i.e MAP estimate
- Perform Taylor expansion around mode
  - this gives us only a quadratic term left
- Identify elements in expansion as parameters of a Gaussian
- Normalise to a distribution
- *You can do exactly the same thing with a GP*

$$\begin{aligned} p(\mathcal{C}_1|\mathbf{x}, \mathbf{t}) &= \int p(\mathcal{C}_1|\mathbf{x}, \mathbf{w})p(\mathbf{w}|\mathbf{t})d\mathbf{w} \\ &\approx \int p(\mathcal{C}_1|\mathbf{x}, \mathbf{w})q(\mathbf{w})d\mathbf{w} \end{aligned}$$

- To compute predictions we can use our new approximate posterior in place of the true posterior

## Summary

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# Summary

- Classification often means non-conjugate prior
- Laplace Approximation
  - match modes with the true posterior
- As we often know the MAP estimate of different models we can often apply this method relatively easy
- Can be really bad if the posterior is far from Gaussian
- We can fit several modes and make a mixture

eof



## References

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