

Machine Learning

Deterministic Approximative Inference

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Introduction

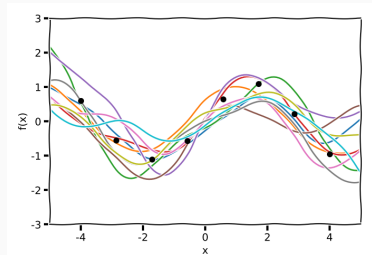
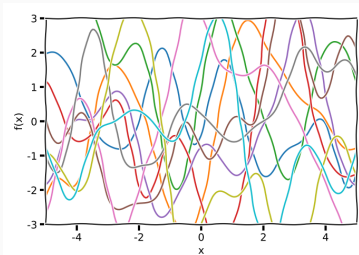
Dr. Raul Santos-Rodriguez

Lecture: 10th of December

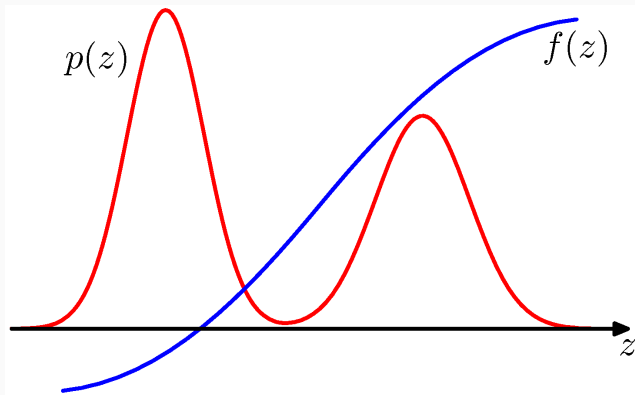
Topic: Fairness and Ethics in machine learning



Big Number



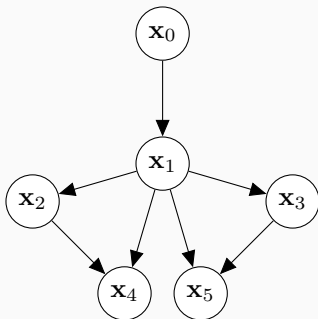
$$p(y|x) = \int p(y|f)p(f|x)df$$



$$\mathbb{E}_{p(z)}[f] = \int f(z)p(z)dz \approx \frac{1}{L} \sum_{l=1}^L f(z^{(l)})$$

$$z^{(l)} \sim p(z)$$

Ancestral Sampling

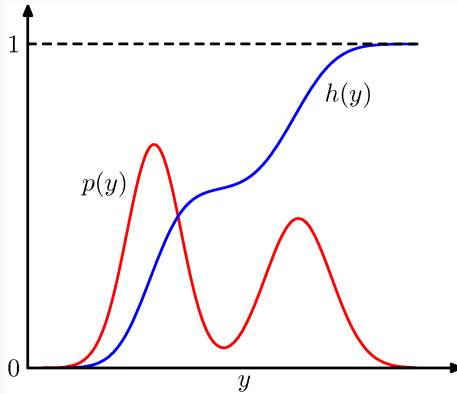


Sample from $p(\mathbf{x})$

1. pick top nodes and draw sample
2. fix the top nodes and sample from conditionals
3. arrive at sample from \mathbf{x}

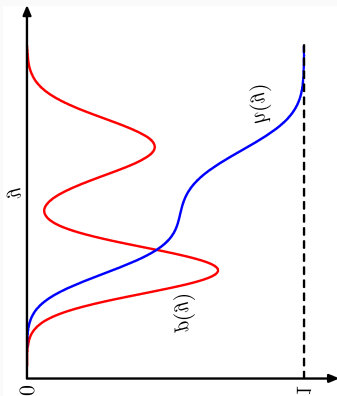
$$p(\mathbf{x}) = p(x_5|x_3, x_1)p(x_4|x_2, x_1)p(x_3|x_1)p(x_2|x_1)p(x_1|x_0)p(x_0)$$

Basic Probabilities



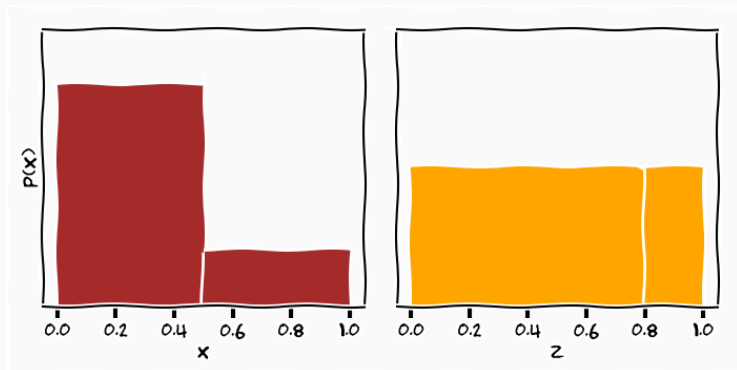
$$z = h(y) = \int_{-\infty}^y p(y) dy$$

Basic Probabilities



$$y = h^{-1}(z)$$

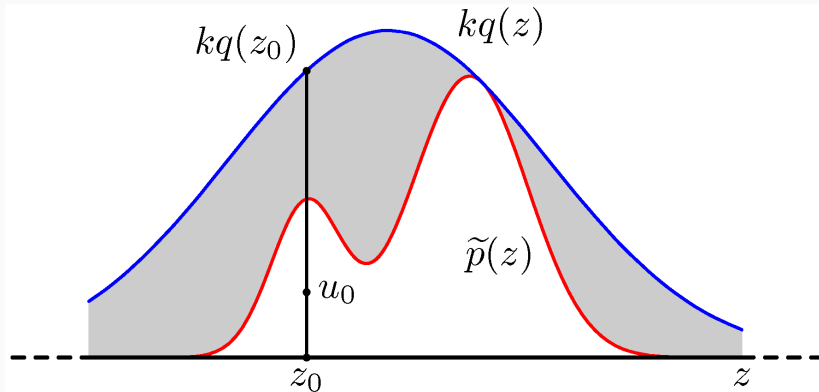
Change of Variables



Starting point

- We can sample random numbers from the uniform distribution
- We can use the indefinite integral to transform the uniform to any distribution
- Want to use these distributions as proxies

Rejection Sampling

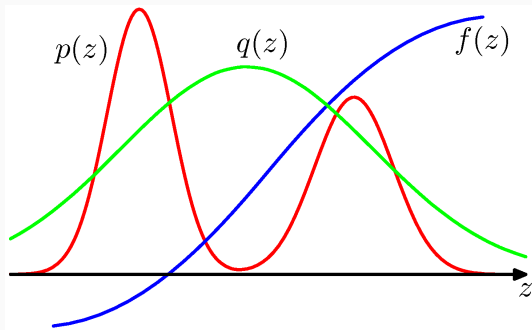


$$\mathbb{E}_{p(\mathbf{z})}[f] = \int f(\mathbf{z})p(\mathbf{z})d\mathbf{z} = \int f(\mathbf{z})\frac{p(\mathbf{z})}{q(\mathbf{z})}q(\mathbf{z})d\mathbf{z} = \mathbb{E}_{q(\mathbf{z})}\left[f(\mathbf{z})\frac{p(\mathbf{z})}{q(\mathbf{z})}\right]$$

$$\approx \frac{1}{L} \sum_{l=1}^L \frac{p(\mathbf{z}^{(l)})}{q(\mathbf{z}^{(l)})} \cdot f(\mathbf{z}^{(l)})$$

- Sample from proposal distribution and re-weight samples
- Accepts all samples

Importance Sampling



$$r_l = \frac{p(z^{(l)})}{q(z^{(l)})}$$

Metropolis Sampling

1. start with state $z^{(0)}$

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 - otherwise reject \mathbf{z}^* and start over

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5. cycle through variables

Deterministic Approximations

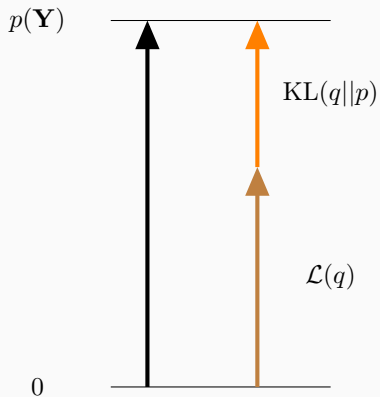
- Stochastic inference
 - approximate expectation with sum
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 - usually slow

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 - usually slow
- Idea
 - *can we reformulate inference as optimisation?*

$$p(\mathbf{Y})$$

- Given some observed data \mathbf{Y}
- Find a probabilistic model such that the probability of the data is maximised
- Idea: find an approximate model q that we can integrate

Deterministic Approximation



$$p(\mathbf{Y})$$

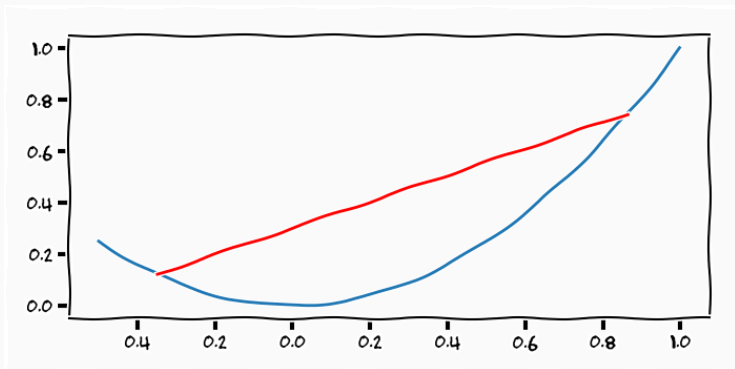
$$\log p(\mathbf{Y})$$

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$$\begin{aligned}\log p(\mathbf{Y}) &= \log \int p(\mathbf{Y}, \mathbf{X}) d\mathbf{X} = \log \int p(\mathbf{X}|\mathbf{Y}) p(\mathbf{Y}) d\mathbf{X} \\ &= \log \int \frac{q(\mathbf{X})}{q(\mathbf{X})} p(\mathbf{X}|\mathbf{Y}) p(\mathbf{Y}) d\mathbf{X}\end{aligned}$$

Jensen Inequality



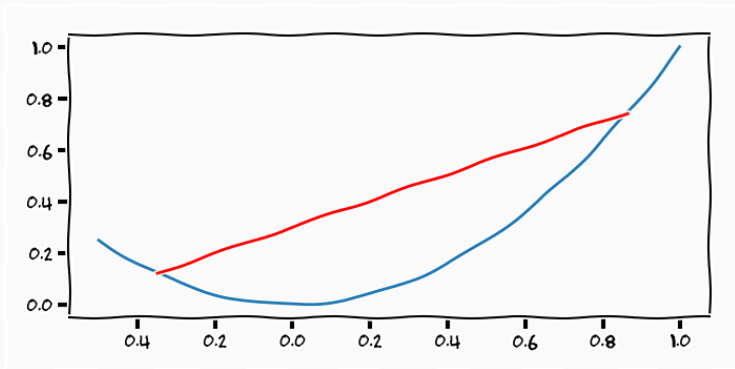
Convex Function

$$\lambda f(x_0) + (1 - \lambda)f(x_1) \geq f(\lambda x_0 + (1 - \lambda)x_1)$$

$$x \in [x_{min}, x_{max}]$$

$$\lambda \in [0, 1]$$

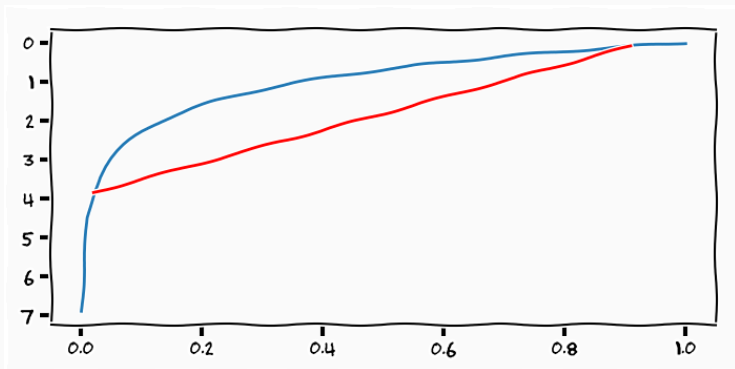
Jensen Inequality



$$\mathbb{E}[f(x)] \geq f(\mathbb{E}[x])$$

$$\int f(x)p(x)dx \geq f\left(\int xp(x)dx\right)$$

Jensen Inequality in Variational Bayes



$$\int \log(x)p(x)dx \leq \log\left(\int xp(x)dx\right)$$

moving the log inside the the integral is a lower-bound on the integral

$$\log p(\mathbf{Y}) = \log \int \frac{q(\mathbf{X})}{q(\mathbf{X})} p(\mathbf{X}|\mathbf{Y}) p(\mathbf{Y}) d\mathbf{X}$$

$$\begin{aligned}\log p(\mathbf{Y}) &= \log \int \frac{q(\mathbf{X})}{q(\mathbf{X})} p(\mathbf{X}|\mathbf{Y}) p(\mathbf{Y}) d\mathbf{X} \\ &\geq \int q(\mathbf{X}) \log \frac{p(\mathbf{X}|\mathbf{Y}) p(\mathbf{Y})}{q(\mathbf{X})} d\mathbf{X}\end{aligned}$$

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$$\text{KL}(q(\mathbf{X})||p(\mathbf{X}|\mathbf{Y})) = \int q(\mathbf{X}) \log \frac{q(\mathbf{X})}{p(\mathbf{X}|\mathbf{Y})} d\mathbf{X}$$

- Divergence measure between distributions
- Not a metric, (not symmetric), 0 only if $p = q$, strictly positive
- $\text{KL}(p(\mathbf{X}|\mathbf{Y})||p(\mathbf{X}))$ information gain

$$\log p(\mathbf{Y}) \geq -\text{KL}(q(\mathbf{X})||p(\mathbf{X}|\mathbf{Y})) + \log p(\mathbf{Y})$$

- if $q(\mathbf{X})$ is the true posterior we have an equality, therefore match the distributions
- i.e. $\text{argmin}_q \text{KL}(q(\mathbf{X})||p(\mathbf{X}|\mathbf{Y}))$
 - \Rightarrow variational distributions are approximations to intractable posteriors

$$\text{KL}(q(\mathbf{X})||p(\mathbf{X}|\mathbf{Y}))$$

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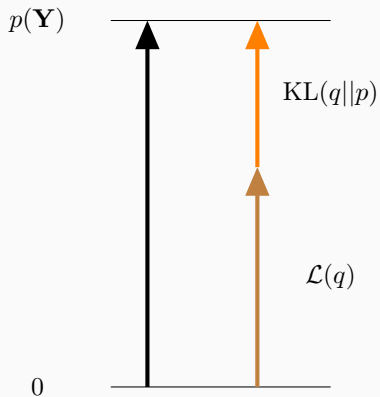
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$$\log p(\mathbf{Y}) = \text{KL}(q(\mathbf{X})||p(\mathbf{X}|\mathbf{Y})) + \underbrace{\mathbb{E}_{q(\mathbf{X})} [\log p(\mathbf{X}, \mathbf{Y})] - H(q(\mathbf{X}))}_{\text{ELBO}}$$

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$$\geq \mathbb{E}_{q(\mathbf{X})} [\log p(\mathbf{X}, \mathbf{Y})] - H(q(\mathbf{X})) = \mathcal{L}(q(\mathbf{X}))$$

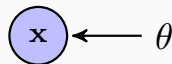
Deterministic Approximation



$$\log p(\mathbf{Y}) \geq \mathbb{E}_{q(\mathbf{X})} [\log p(\mathbf{X}, \mathbf{Y})] - H(q(\mathbf{X})) = \mathcal{L}(q(\mathbf{X}))$$

- if we maximise the ELBO we,
 - find an approximate posterior
 - lower bound the marginal likelihood
- *maximising* $p(\mathbf{Y})$ **is** learning
- finding $p(\mathbf{X}|\mathbf{Y}) \approx q(\mathbf{X})$ **is** prediction

Lower Bound



$$p(y) = \int_x p(y|x)p(x) = \frac{p(y|x)p(x)}{p(x|y)}$$

$$q_\theta(x) \approx p(x|y)$$

Why is this useful?

Why is this a sensible thing to do?

– Ryan Adams¹

¹[Talking Machines Season 2, Episode 5](#)

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Why is this useful?

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- If we can't formulate the joint distribution there isn't much we can do
- Taking the expectation of a log is usually easier than the expectation
- We are allowed to choose the distribution to take the expectation over

– Ryan Adams¹

¹Talking Machines Season 2, Episode 5

How to choose Q?

$$\mathcal{L}(q(\mathbf{X})) = \mathbb{E}_{q(\mathbf{X})} [\log p(\mathbf{X}, \mathbf{Y})] - H(q(\mathbf{X}))$$

- We have to be able to compute an expectation over the joint distribution
- The second term should be trivial

$$q(\mathbf{X}) = \prod_i q_i(\mathbf{x}_i)$$

$$\mathcal{L}(q_j) = \mathcal{L}_j(q_j) + \mathcal{L}_{\neg j}(q_{\neg j}),$$

- Model originating if Physics
- We model marginals rather than the full distribution
- We can update each distribution in turn and cycle

$$\mathcal{L}(q) = \int q(\mathbf{X}) \log \frac{p(\mathbf{Y}, \mathbf{X})}{q(\mathbf{X})} d\mathbf{X}$$

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Mean Field Approximation

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$$= \int_j q_j(\mathbf{x}_j) \log f_j(\mathbf{x}_j) d\mathbf{x}_j - \int_j q_j(\mathbf{x}_j) \log q_j(\mathbf{x}_j) d\mathbf{x}_j + \text{const.} \cdot \underbrace{\int_j q_j(\mathbf{x}_j) d\mathbf{x}_j}_{=1}$$

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$$= \int_j q_j(\mathbf{x}_j) \log \frac{f_j(\mathbf{x}_j)}{q_j(\mathbf{x}_j)} d\mathbf{x}_j + \text{const.}$$

Mean Field Approximation

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$$= \int_j q_j(\mathbf{x}_j) \log \frac{f_j(\mathbf{x}_j)}{q_j(\mathbf{x}_j)} d\mathbf{x}_j + \text{const.}$$

$$= - \int_j q_j(\mathbf{x}_j) \log \frac{q_j(\mathbf{x}_j)}{f_j(\mathbf{x}_j)} d\mathbf{x}_j + \text{const.}$$

Mean Field Approximation

$$= \int_j q_j(\mathbf{x}_j) \log f_j(\mathbf{x}_j) d\mathbf{x}_j - \int_j q_j(\mathbf{x}_j) \log q_j(\mathbf{x}_j) d\mathbf{x}_j + \text{const.} \cdot \underbrace{\int_j q_j(\mathbf{x}_j) d\mathbf{x}_j}_{=1}$$

$$= \int_j q_j(\mathbf{x}_j) \log \frac{f_j(\mathbf{x}_j)}{q_j(\mathbf{x}_j)} d\mathbf{x}_j + \text{const.}$$

$$= - \int_j q_j(\mathbf{x}_j) \log \frac{q_j(\mathbf{x}_j)}{f_j(\mathbf{x}_j)} d\mathbf{x}_j + \text{const.}$$

$$= -\text{KL}(q_j(\mathbf{x}_j) \parallel f_j(\mathbf{x}_j)) + \text{const.}$$

Mean Field Approximation

$$= \int_j q_j(\mathbf{x}_j) \log f_j(\mathbf{x}_j) d\mathbf{x}_j - \int_j q_j(\mathbf{x}_j) \log q_j(\mathbf{x}_j) d\mathbf{x}_j + \text{const.} \cdot \underbrace{\int_j q_j(\mathbf{x}_j) d\mathbf{x}_j}_{=1}$$

$$= \int_j q_j(\mathbf{x}_j) \log \frac{f_j(\mathbf{x}_j)}{q_j(\mathbf{x}_j)} d\mathbf{x}_j + \text{const.}$$

$$= - \int_j q_j(\mathbf{x}_j) \log \frac{q_j(\mathbf{x}_j)}{f_j(\mathbf{x}_j)} d\mathbf{x}_j + \text{const.}$$

$$= -\text{KL}(q_j(\mathbf{x}_j) || f_j(\mathbf{x}_j)) + \text{const.} = \mathcal{L}(q_j)$$

$$\mathcal{L}(q_j) = -\text{KL}(q_j(\mathbf{x}_j) || f_j(\mathbf{x}_j)) + \text{const.}$$

- Want to maximise lower bound
- Negative KL \rightarrow minimise KL term
- *we are free to choose the form of the distribution*

$$\begin{aligned}\log q_j(\mathbf{x}_j) &= \log f_j(\mathbf{x}_j) = \int_{\neg j} \underbrace{\prod_{i \neq j} q_i(\mathbf{x}_i)}_{q_{\neg j}(\mathbf{x}_{\neg j})} \log p(\mathbf{Y}, \mathbf{X}) d\mathbf{x}_{\neg j} \\ &= \mathbb{E}_{q_{\neg j}(\mathbf{x}_{\neg j})} [\log p(\mathbf{Y}, \mathbf{X})]\end{aligned}$$

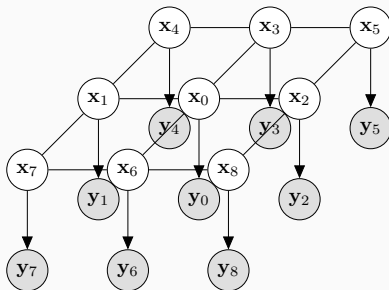
- Choose the marginal distribution that makes the bound tight
- Will not make the bound tight in general though

1. Formulate joint distribution over data and latent parameters

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2. Formulate fully factorised approximative posterior over latent variables

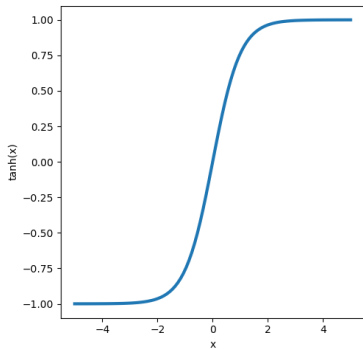
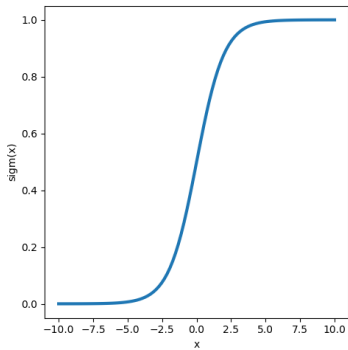
1. Formulate joint distribution over data and latent parameters
2. Formulate fully factorised approximative posterior over latent variables
3. Fit marginal approximation by making bound tight

1. Formulate joint distribution over data and latent parameters
2. Formulate fully factorised approximative posterior over latent variables
3. Fit marginal approximation by making bound tight
4. Iterate through variables



$$q(\mathbf{x}, \boldsymbol{\mu}) = \prod_i^N q(x_i, \mu_i)$$

$$\mu_i = \mathbb{E}[x_i]$$



Summary

Summary

- Variational methods can be **very** efficient
 - really fun to work with
- Can be made black-box [2]
- Will never be correct
- Provides us with approximative posterior for inference

- No lectures or lab next week

eof

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