

# **Machine Learning**

**Dual Linear Regression** 

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#### Office Hours



MVB 1.11 Thursday 17-19

# Introduction

#### Gaussian Identities

$$p(x_1, x_2) = \mathcal{N}\left(\left[\begin{array}{c} \mu_1 \\ \mu_2 \end{array}\right], \left[\begin{array}{cc} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{array}\right]\right)$$

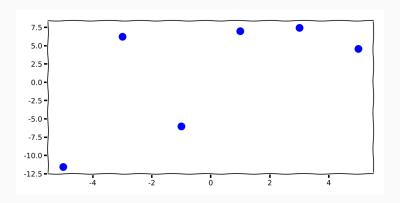
Marginal

$$p(x_2) = \int p(x_1, x_2) dx_1 = \mathcal{N}(\mu_2, \Sigma_{22})$$

Conditional

$$p(x_1|x_2) = \frac{p(x_1, x_2)}{p(x_2)} = \mathcal{N}(\mu_1 + \Sigma_{21}\Sigma_{22}^{-1}(x_2 - \mu_2), \Sigma_{11} - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21})$$

# Linear Regression [1] Ch 3.1



• Linear function in both parameters and data

$$y(\mathbf{x}, \mathbf{w}) = w_0 + w_1 x_1 + \dots + w_D x_D = \mathbf{w}^{\mathrm{T}} \mathbf{x} + w_0 = \{D = 1\} = w_0 + w_1 x_1$$

Model

$$t = y(\mathbf{x}, \mathbf{w}) + \epsilon = \mathbf{w}^{\mathrm{T}} \phi(\mathbf{x}) + \epsilon$$
$$\epsilon \sim \mathcal{N}(0, \beta^{-1} I)$$

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Likelihood

$$p(t|\mathbf{x}, \mathbf{w}, \beta) = \mathcal{N}(t|\mathbf{w}^{\mathrm{T}}\phi(\mathbf{x}), \beta^{-1})$$

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Independence

$$p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \beta) = \prod_{n=1}^{N} \mathcal{N}\left(t|\mathbf{w}^{\mathrm{T}}\boldsymbol{\phi}(\mathbf{x}), \beta^{-1}\right)$$

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• Prior (Conjugate)

$$p(\mathbf{w}|m_0,S_0) = \mathcal{N}(\mathbf{w}|m_0,S_0)$$

#### **Posterior**

#### Posterior

$$\mathbf{m}_{\mathcal{N}} = \left(\mathbf{S}_0^{-1} + \beta \phi(\mathbf{X})^{\mathrm{T}} \phi(\mathbf{X})\right)^{-1} \left(S_0^{-1} \mathbf{m}_0 + \beta \phi(\mathbf{X})^{\mathrm{T}} \mathbf{t}\right)$$
$$\mathbf{S}_{\mathcal{N}} = \left(\mathbf{S}_0^{-1} + \beta \phi(\mathbf{X})^{\mathrm{T}} \phi(\mathbf{X})\right)^{-1}$$

#### Posterior<sup>1</sup>

Posterior

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Assumption Zero mean isotropic Gaussian

$$p(\mathbf{w}|\alpha) = \mathcal{N}(\mathbf{w}|0, \alpha^{-1}\mathbf{I})$$

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Posterior

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Posterior

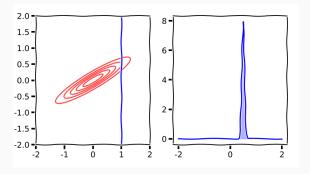
$$p(\mathbf{w}|\mathbf{t}, \mathbf{X}) = \mathcal{N}(\mathbf{w}|\beta \left(\alpha \mathbf{I} + \beta \phi(\mathbf{X})^{\mathrm{T}} \phi(\mathbf{X})\right)^{-1} \phi(\mathbf{X})^{\mathrm{T}} \mathbf{t},$$
$$\left(\alpha \mathbf{I} + \beta \phi(\mathbf{X})^{\mathrm{T}} \phi(\mathbf{X})\right)^{-1})$$

#### Prediction

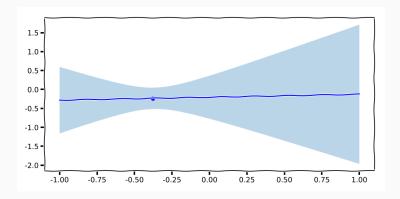
$$p(t_*|\mathbf{t}, \mathbf{x}_*, \mathbf{X}, \alpha, \beta) = \int p(t_*|\mathbf{x}_*, \mathbf{w}, \beta) p(\mathbf{w}|\mathbf{t}, \mathbf{X}, \alpha, \beta) d\mathbf{w}$$

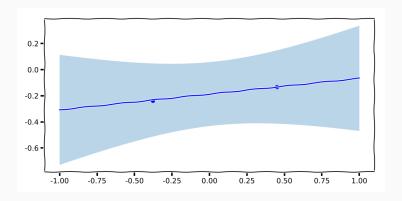
- ullet we do not really care about w we care about new prediction  $t_*$  at location  ${f x}_*$
- look at the marginal distribution, i.e. when we average out the weight
- integrate a Gaussian over a Gaussian ⇒ Gaussian identities

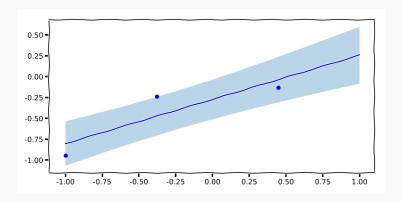
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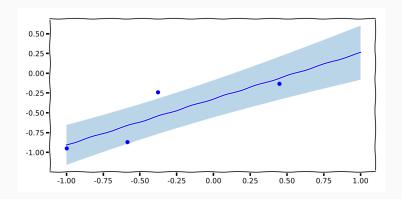


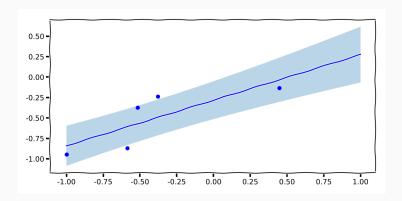
$$p(t_*|\mathbf{t}, \mathbf{x}_*, \mathbf{X}, \alpha, \beta) = \int p(t_*|\mathbf{x}_*, \mathbf{w}, \beta) p(\mathbf{w}|\mathbf{t}, \mathbf{X}, \alpha, \beta) d\mathbf{w}$$
$$= \mathcal{N}(t_*|\mathbf{m}_N^{\mathrm{T}} \phi(\mathbf{x}_*), \frac{1}{\beta} + \phi(\mathbf{x}_*)^{\mathrm{T}} \mathbf{S}_N \phi(\mathbf{x}_*))$$

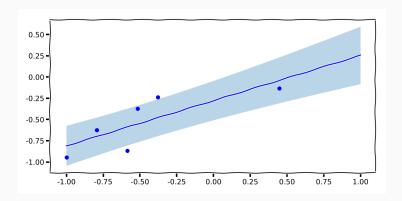


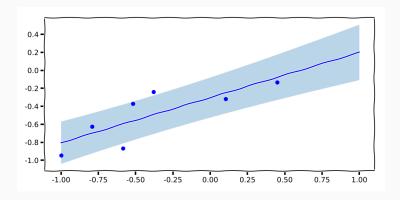


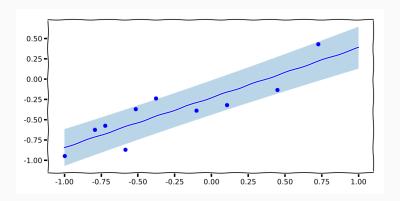


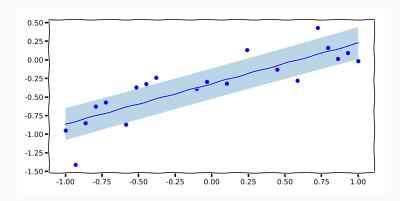


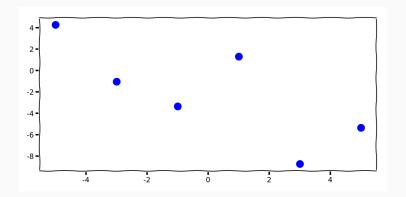








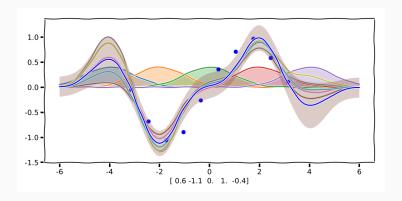


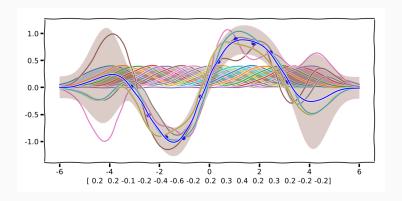


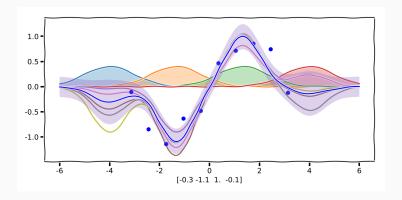
• Linear function only in parameters

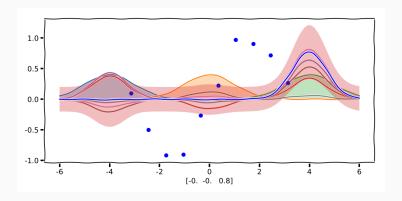
$$y(\mathbf{x}, \mathbf{w}) = w_0 + \sum_{j=1}^{M-1} w_j \phi_j(\mathbf{x}) = \{\phi_0(\mathbf{x}) = 1\} = \mathbf{w}^{\mathrm{T}} \phi(\mathbf{x})$$

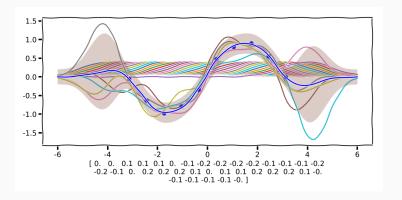
• We can choose many types of basis functions  $\phi(x)$ 

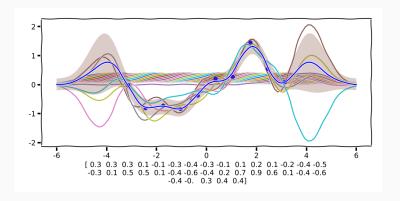


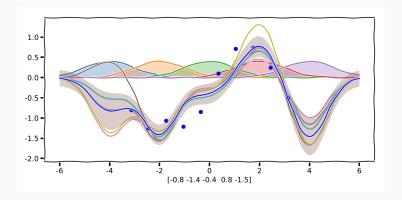












$$\begin{aligned} p(\mathbf{w}|\mathbf{t}, \mathbf{x}) &= \frac{p(\mathbf{t}|\mathbf{w}, \mathbf{x})p(\mathbf{w})}{p(\mathbf{t})} \\ p(\mathbf{t}|\mathbf{w}, \mathbf{x}) &= \prod_{n}^{N} p(t_{n}|\mathbf{w}, \mathbf{x}) = \prod_{n}^{N} \mathcal{N}(t_{n}|\mathbf{w}^{\mathrm{T}}\mathbf{x}_{n}, \sigma^{2}\mathbf{I}) \\ p(\mathbf{w}) &= \mathcal{N}(\mathbf{0}, \tau^{2}\mathbf{I}) \end{aligned}$$

$$p(\mathbf{w}|\mathbf{t}, \mathbf{x}) = \frac{p(\mathbf{t}|\mathbf{w}, \mathbf{x})p(\mathbf{w})}{p(\mathbf{t})}$$

$$p(\mathbf{t}|\mathbf{w}, \mathbf{x}) = \prod_{n}^{N} p(t_{n}|\mathbf{w}, \mathbf{x}) = \prod_{n}^{N} \mathcal{N}(t_{n}|\mathbf{w}^{\mathrm{T}}\mathbf{x}_{n}, \sigma^{2}\mathbf{I})$$

$$p(\mathbf{w}) = \mathcal{N}(\mathbf{0}, \tau^{2}\mathbf{I})$$

$$p(\mathbf{w}|\mathbf{t}, \mathbf{x}) \propto p(\mathbf{t}|\mathbf{w}, \mathbf{x})p(\mathbf{w})$$

Through conjugacy we know the form of the posterior

$$\begin{split} p(\mathbf{w}|\mathbf{t},\mathbf{x}) &\propto \prod_{n}^{N} \frac{1}{\sqrt{2\pi\sigma^{2}}} e^{-\frac{1}{2\sigma^{2}}(\mathbf{w}^{\mathrm{T}}\mathbf{x}_{n} - t_{n})^{\mathrm{T}}(\mathbf{w}^{\mathrm{T}}\mathbf{x}_{n} - y_{n})} \frac{1}{\sqrt{2\pi\tau^{2}}} e^{-\frac{1}{2\tau^{2}}(\mathbf{w}^{\mathrm{T}}\mathbf{w})} \\ &= \frac{1}{(\sqrt{2\pi\sigma^{2}})^{N}} e^{-\frac{1}{2\sigma^{2}}(\mathbf{w}^{\mathrm{T}}\mathbf{x} - \mathbf{t})^{\mathrm{T}}(\mathbf{w}^{\mathrm{T}}\mathbf{X} - \mathbf{t})} \frac{1}{(\sqrt{2\pi\tau^{2}})^{N}} e^{-\frac{1}{2\tau^{2}}(\mathbf{w}^{\mathrm{T}}\mathbf{w})} \end{split}$$

 Lets maximise the above to find a point estimate (not a distribution) of w

$$-\mathrm{log} p(\mathbf{w}|\mathbf{t}, \mathbf{x}) = J(\mathbf{w}) = \frac{1}{2} (\mathbf{w}^{\mathrm{T}} \mathbf{x} - \mathbf{t})^{\mathrm{T}} (\mathbf{w}^{\mathrm{T}} \mathbf{x} - \mathbf{t}) + \frac{\lambda}{2} \mathbf{w}^{\mathrm{T}} \mathbf{w}$$

• Find a stationary point in w

$$-\log p(\mathbf{w}|\mathbf{t}, \mathbf{x}) = J(\mathbf{w}) = \frac{1}{2}(\mathbf{w}^{\mathrm{T}}\mathbf{x} - \mathbf{t})^{\mathrm{T}}(\mathbf{w}^{\mathrm{T}}\mathbf{x} - \mathbf{t}) + \frac{\lambda}{2}\mathbf{w}^{\mathrm{T}}\mathbf{w}$$
$$\frac{\delta}{\delta \mathbf{w}}J(\mathbf{w}) = \frac{1}{2}2\mathbf{x}^{\mathrm{T}}(\mathbf{w}^{\mathrm{T}}\mathbf{x} - \mathbf{t}) + \frac{\lambda}{2}2\mathbf{w}$$

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$$\frac{\delta}{\delta \mathbf{w}} J(\mathbf{w}) = \frac{1}{2} 2 \mathbf{x}^{\mathrm{T}} (\mathbf{w}^{\mathrm{T}} \mathbf{x} - \mathbf{t}) + \frac{\lambda}{2} 2 \mathbf{w}$$
$$\mathbf{w} = -\frac{1}{\lambda} \mathbf{x}^{\mathrm{T}} (\mathbf{w}^{\mathrm{T}} \mathbf{x} - \mathbf{t})$$

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$$= \mathbf{x}^{\mathrm{T}} \mathbf{a} = \sum_{n=1}^{N} \alpha_{n} \mathbf{x}_{n}$$

Find a stationary point in w

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$$\mathbf{w} = \mathbf{x}^{\mathrm{T}} \mathbf{a}$$

• Rewrite objective in terms of a

$$J(\mathbf{w}) = \frac{1}{2} (\mathbf{w}^{\mathrm{T}} \mathbf{x} - \mathbf{t})^{\mathrm{T}} (\mathbf{w}^{\mathrm{T}} \mathbf{x} - \mathbf{t}) + \frac{\lambda}{2} \mathbf{w}^{\mathrm{T}} \mathbf{w}$$

$$\mathbf{w} = \mathbf{x}^{\mathrm{T}} \mathbf{a}$$

$$J(\mathbf{a}) = \frac{1}{2} \mathbf{a}^{\mathrm{T}} \mathbf{x} \mathbf{x}^{\mathrm{T}} \mathbf{x} \mathbf{x}^{\mathrm{T}} \mathbf{a} - \mathbf{a}^{\mathrm{T}} \mathbf{x} \mathbf{x}^{\mathrm{T}} \mathbf{t} + \frac{1}{2} \mathbf{t}^{\mathrm{T}} \mathbf{t} + \frac{\lambda}{2} \mathbf{a}^{\mathrm{T}} \mathbf{x} \mathbf{x}^{\mathrm{T}} \mathbf{a}$$

• Rewrite objective in terms of a

$$egin{aligned} [\mathsf{K}]_{ij} &= \mathsf{x}_i^\mathrm{T} \mathsf{x}_j = \phi(\mathsf{x}_i)^\mathrm{T} \phi(\mathsf{x}_j) \ J(\mathsf{a}) &= rac{1}{2} \mathsf{a}^\mathrm{T} \mathsf{K} \mathsf{K} \mathsf{a} - \mathsf{a} \mathsf{K} \mathsf{t} + rac{1}{2} \mathsf{t}^\mathrm{T} \mathsf{t} + rac{\lambda}{2} \mathsf{a}^\mathrm{T} \mathsf{K} \mathsf{a} \end{aligned}$$

• K is a matrix with all inner-products between the data points

$$\alpha_n = -\frac{1}{\lambda} (\mathbf{w}^{\mathrm{T}} \mathbf{x}_n - t_n)$$

$$\mathbf{w} = \sum_{n=1}^{N} \alpha_n \mathbf{x}_n = \mathbf{x}^{\mathrm{T}} \mathbf{a}$$

• Eliminate w and rewrite in terms of a

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$$\mathbf{w} = \sum_{n=1}^{N} \alpha_n \mathbf{x}_n = \mathbf{x}^{\mathrm{T}} \mathbf{a}$$

$$\Rightarrow \mathbf{a} = (\mathbf{K} + \lambda \mathbf{I})^{-1} \mathbf{t}$$

Eliminate w and rewrite in terms of a

$$\begin{split} [\mathsf{K}]_{ij} &= \mathsf{x}_i^\mathrm{T} \mathsf{x}_j = \phi(\mathsf{x}_i)^\mathrm{T} \phi(\mathsf{x}_j) \\ J(\mathsf{a}) &= \frac{1}{2} \mathsf{a}^\mathrm{T} \mathsf{K} \mathsf{K} \mathsf{a} - \mathsf{a} \mathsf{K} \mathsf{t} + \frac{1}{2} \mathsf{t}^\mathrm{T} \mathsf{t} + \frac{\lambda}{2} \mathsf{a}^\mathrm{T} \mathsf{K} \mathsf{a} \\ \mathsf{a} &= (\mathsf{K} + \lambda \mathsf{I})^{-1} \mathsf{t} \end{split}$$

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- Linear Regression
  - See data
  - ullet Encode relationship between variates using parameters ullet
  - ullet Make predictions using ullet

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  - Model complexity depends on data
  - Non-parametric model

$$\begin{split} \phi: \mathbf{x}_i &\to \mathbf{f}_i \\ \mathbf{y}(\mathbf{x}_*) &= \mathbf{w}^{\mathrm{T}} \phi(\mathbf{x}_*) = \mathbf{a}^{\mathrm{T}} \phi(\mathbf{X}) \phi(\mathbf{x}_*) = k(\mathbf{x}_*, \mathbf{X}) (\mathsf{K} + \lambda \mathsf{I})^{-1} \mathbf{y} \\ k(\mathbf{x}, \mathbf{x}') &= \phi(\mathbf{x})^{\mathrm{T}} \phi(\mathbf{x}') \end{split}$$

- we actually never need to know  $\phi(\mathbf{x})$  only  $\phi(\mathbf{x}_i)^{\mathrm{T}}\phi(\mathbf{x}_j)$
- functions that describes inner-products are called kernel-functions

$$\mathbf{x} \in \mathbb{R}^2$$
  $(\mathbf{x}_i^{\mathrm{T}} \mathbf{x}_j)^2$ 

- Kernel functions need to forefill certain properties and is a subclass of functions
- Can be incredibly useful, think similarity rather than location

$$\mathbf{x} \in \mathbb{R}^2$$
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$$= (x_{i1}^{2}, \sqrt{2}x_{i1}x_{i2}, x_{i2}^{2})(x_{i1}^{2}, \sqrt{2}x_{j1}x_{j2}, x_{i2}^{2})^{\mathrm{T}}$$

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$$= \phi(\mathbf{x}_{i})^{T}\phi(\mathbf{x}_{i})$$

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$$= \phi(\mathbf{x}_{i})^{T}\phi(\mathbf{x}_{j})$$

$$\phi(\mathbf{x}) = ((\mathbf{e}_{1}^{T}\mathbf{x})^{2}, \sqrt{2}\mathbf{e}_{1}^{T}\mathbf{x}\mathbf{e}_{2}^{T}\mathbf{x}, (\mathbf{e}_{2}^{T}\mathbf{x})^{2})$$

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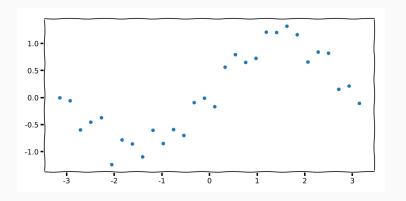
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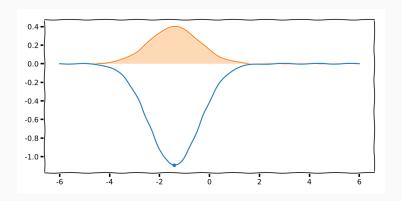
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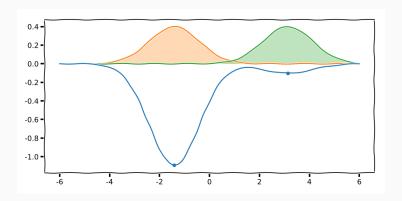
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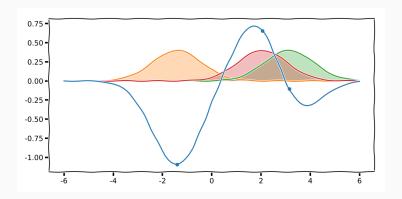
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- The mapping can be non-linear but the problem is still linear!
- Allows for putting weird things like, strings (DNA) in a vector space
- More next lecture, these things are very powerful

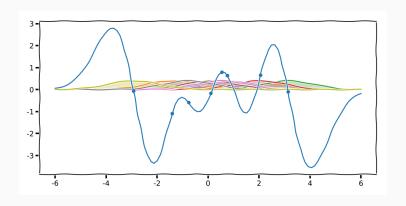


$$t = f(x) + \epsilon$$
$$k(x_i, x_j) = e^{-\frac{1}{2} \frac{(x_i - x_j)^2}{l}}$$

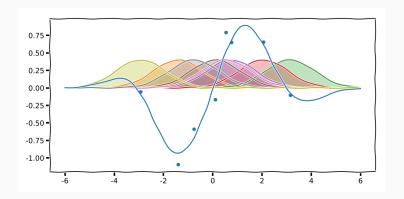


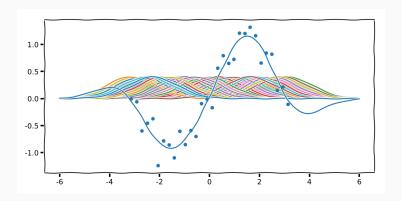


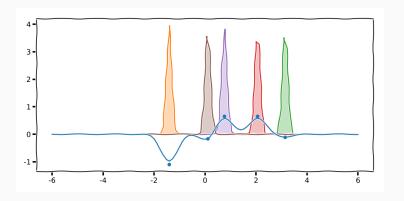




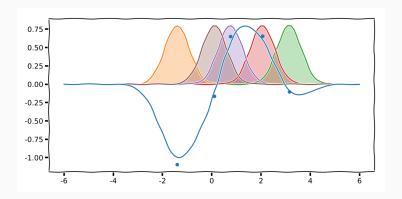
$$\mathbf{y}(\mathbf{x}_*) = k(\mathbf{x}_*, \mathbf{x})(\mathbf{K} + \lambda \mathbf{I})^{-1}\mathbf{t}$$

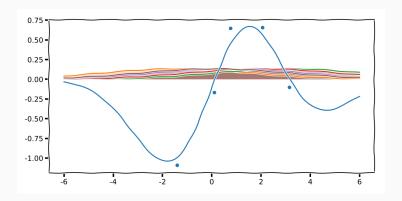


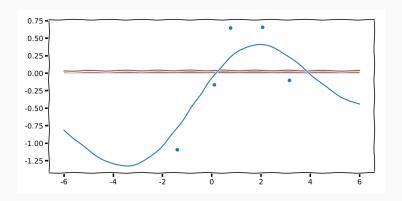


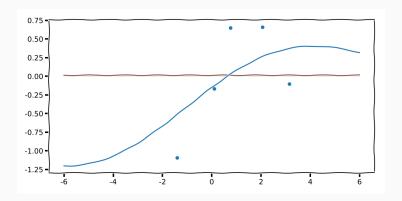


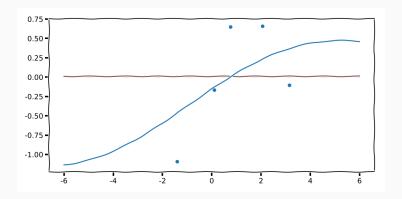
$$k(x_i, x_j) = e^{-\frac{1}{2} \frac{(x_i - x_j)^2}{l}}$$

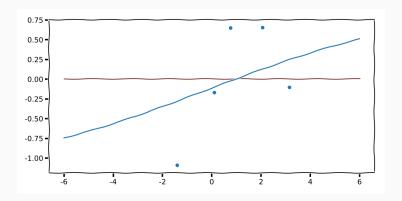


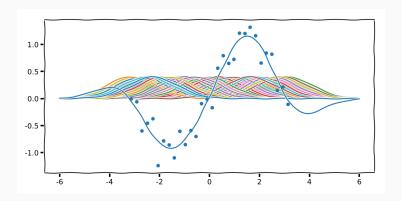




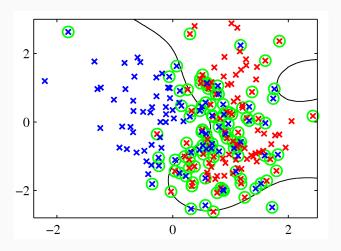








# Support Vector Machines [1] Figure 7.4



#### **Kernel Machines**

- Allows us to
  - let the model complexity adapt to data
  - to put non vectorial data in a vector space
  - problem is still linear

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- But
  - how to set kernel width
  - how to set noise assumption
- Tomorrow we will learn these

# Summary

#### Summary

- Repeat of the machine learning proceedure
  - assumption + data + compute → updated assumption
  - don't worry it will become clear eventually
- Non-parametrics
  - kernel regression
  - dual formulation
  - the problem is still linear

eof

# References



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