

Machine Learning

Dual Linear Regression

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Introduction

$$p(x_1, x_2) = \mathcal{N}\left(\begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}, \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}\right)$$

- Marginal

$$p(x_2) = \int p(x_1, x_2) dx_1 = \mathcal{N}(\mu_2, \Sigma_{22})$$

- Conditional

$$p(x_1|x_2) = \frac{p(x_1, x_2)}{p(x_2)} = \mathcal{N}(\mu_1 + \Sigma_{21}\Sigma_{22}^{-1}(x_2 - \mu_2), \Sigma_{11} - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21})$$

$$p(x_1|x_2) = \frac{p(x_1, x_2)}{p(x_2)} = \mathcal{N}(\mu_1 + \Sigma_{21}\Sigma_{22}^{-1}(x_2 - \mu_2), \Sigma_{11} - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21})$$

Independent variables

$$\Sigma_{12} = \Sigma_{21} = \mathbf{0}$$

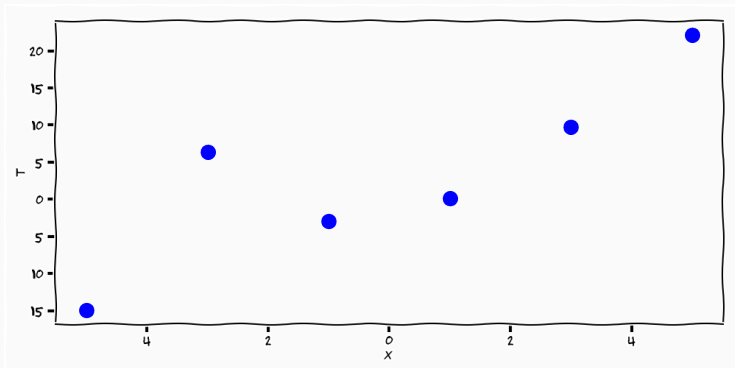
$$p(x_1|x_2) = \mathcal{N}(\mu_1 + \mathbf{0}\Sigma_{22}^{-1}(x_2 - \mu_2), \Sigma_{11} - \mathbf{0}\Sigma_{22}^{-1}\mathbf{0}) = \mathcal{N}(\mu_1|\Sigma_{11}) = p(x_1)$$

Completely Dependent

$$\Sigma_{12} = \Sigma_{21} = \Sigma_{22} = \Sigma_{11}$$

$$\begin{aligned} p(x_1|x_2) &= \mathcal{N}(\mu_1 + \Sigma_{11}\Sigma_{11}^{-1}(x_2 - \mu_2), \Sigma_{11} - \Sigma_{11}\Sigma_{11}^{-1}\Sigma_{11}) \\ &= \mathcal{N}(x_2 + \mu_1 - \mu_2|\mathbf{0}) \end{aligned}$$

Linear Regression [1] Ch 3.1



- Linear function in both parameters and data

$$y(\mathbf{x}, \mathbf{w}) = w_0 + w_1 x_1 + \dots + w_D x_D = \mathbf{w}^T \mathbf{x} + w_0 = \{D = 1\} = \mathbf{w}^T \phi(\mathbf{x})$$

$$t = f(\mathbf{x}) + \epsilon$$

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$$t - f(\mathbf{x}) = \epsilon$$

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$$t - f(\mathbf{x}) \sim \mathcal{N}(\epsilon|0, \beta^{-1}I) = \frac{\beta}{(2\pi)^{\frac{1}{2}}} e^{-\frac{1}{2}(\epsilon-0)\beta(\epsilon-0)}$$

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$$\Rightarrow \mathcal{N}(t - f(\mathbf{x})|0, \beta^{-1}I) \frac{\beta}{(2\pi)^{\frac{1}{2}}} e^{-\frac{1}{2}(t-f(\mathbf{x}))\beta(t-f(\mathbf{x}))}$$

$$t = f(\mathbf{x}) + \epsilon$$

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$$\Rightarrow \mathcal{N}(t - f(\mathbf{x})|0, \beta^{-1}I) = \mathcal{N}(t|f(\mathbf{x}), \beta^{-1}I)$$

$$\Rightarrow p(t|f, \mathbf{x}) = \mathcal{N}(t|f(\mathbf{x}), \beta^{-1}I)$$

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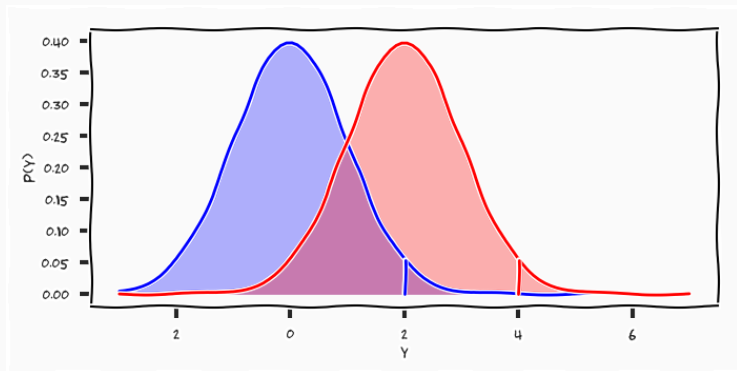
$$\Rightarrow \mathcal{N}(t - f(\mathbf{x})|0, \beta^{-1}I) \frac{\beta}{(2\pi)^{\frac{1}{2}}} e^{-\frac{1}{2}(t-f(\mathbf{x}))\beta(t-f(\mathbf{x}))}$$

$$\Rightarrow \mathcal{N}(t - f(\mathbf{x})|0, \beta^{-1}I) = \mathcal{N}(t|f(\mathbf{x}), \beta^{-1}I)$$

$$\Rightarrow p(t|f, \mathbf{x}) = \mathcal{N}(t|f(\mathbf{x}), \beta^{-1}I)$$

- By making an assumption of the noise we have reached a conditional distribution over the output given the model, i.e. the likelihood function

Likelihood



$$\mathcal{N}(y = 4 - 2 | \mu = 0, 1.0) = \mathcal{N}(y = 4 | \mu = 2, 1.0)$$

Vectors	Matrices
$\mathbf{x}_1 = \begin{bmatrix} x_{11} \\ x_{12} \\ \vdots \\ x_{1D} \end{bmatrix}$	$\mathbf{X} = \begin{bmatrix} x_{11} & x_{12} & \dots & x_{1D} \\ x_{21} & x_{22} & \dots & x_{2D} \\ \vdots & \vdots & \vdots & \vdots \\ x_{N1} & x_{N2} & \dots & x_{ND} \end{bmatrix}$

Why?

```
int *m = &matrix;
int* v1,v2;
for(int i=0; i<nr_points;i++)
{
    v1 = &vector;
    v2 = &vector_res;
    for(int j=0; j<nr_dimensions; j++)
    {
        *(v2++) += (*(v1++))*(*(m++))
    }
}
```


One point

$$t_1 = \mathbf{w}^T \mathbf{x} = [w_0, w_1] \cdot \begin{bmatrix} 1 \\ x_1 \end{bmatrix} = w_0 + w_1 \cdot x_1$$

Multiple points

$$\begin{bmatrix} t_1 \\ t_2 \\ \vdots \\ t_N \end{bmatrix} = \begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_N \end{bmatrix} \cdot \begin{bmatrix} w_0 \\ w_1 \end{bmatrix}$$

- Model

$$t = y(\mathbf{x}, \mathbf{w}) + \epsilon = \mathbf{w}^T \phi(\mathbf{x}) + \epsilon$$

$$\epsilon \sim \mathcal{N}(0, \beta^{-1} I)$$

- Model

$$t = y(\mathbf{x}, \mathbf{w}) + \epsilon = \mathbf{w}^T \phi(\mathbf{x}) + \epsilon$$

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- Likelihood

$$p(t|\mathbf{x}, \mathbf{w}, \beta) = \mathcal{N}(t|\mathbf{w}^T \phi(\mathbf{x}), \beta^{-1})$$

- Model

$$t = y(\mathbf{x}, \mathbf{w}) + \epsilon = \mathbf{w}^T \phi(\mathbf{x}) + \epsilon$$
$$\epsilon \sim \mathcal{N}(0, \beta^{-1} I)$$

- Likelihood

$$p(t|\mathbf{x}, \mathbf{w}, \beta) = \mathcal{N}(t|\mathbf{w}^T \phi(\mathbf{x}), \beta^{-1})$$

- Independence

$$p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \beta) = \prod_{n=1}^N \mathcal{N}(t_n|\mathbf{w}^T \phi(\mathbf{x}_n), \beta^{-1})$$

Linear Regression

- Model

$$t = y(\mathbf{x}, \mathbf{w}) + \epsilon = \mathbf{w}^T \phi(\mathbf{x}) + \epsilon$$
$$\epsilon \sim \mathcal{N}(0, \beta^{-1} I)$$

- Likelihood

$$p(t|\mathbf{x}, \mathbf{w}, \beta) = \mathcal{N}(t|\mathbf{w}^T \phi(\mathbf{x}), \beta^{-1})$$

- Independence

$$p(\mathbf{t}|\mathbf{X}, \mathbf{w}, \beta) = \prod_{n=1}^N \mathcal{N}(t_n|\mathbf{w}^T \phi(\mathbf{x}_n), \beta^{-1})$$

- Prior (Conjugate)

$$p(\mathbf{w}|m_0, S_0) = \mathcal{N}(\mathbf{w}|m_0, S_0)$$

- Posterior

$$p(\mathbf{w}|\mathbf{X}, \mathbf{t}) = \mathcal{N}(\mathbf{w}|\mathbf{m}_N, \mathbf{S}_N)$$

$$\mathbf{m}_N = (\mathbf{S}_0^{-1} + \beta \phi(\mathbf{X})^T \phi(\mathbf{X}))^{-1} (\mathbf{S}_0^{-1} \mathbf{m}_0 + \beta \phi(\mathbf{X})^T \mathbf{t})$$

$$\mathbf{S}_N = (\mathbf{S}_0^{-1} + \beta \phi(\mathbf{X})^T \phi(\mathbf{X}))^{-1}$$

- Posterior

$$p(\mathbf{w}|\mathbf{X}, \mathbf{t}) = \mathcal{N}(\mathbf{w}|\mathbf{m}_N, \mathbf{S}_N)$$

$$\mathbf{m}_N = (\mathbf{S}_0^{-1} + \beta \phi(\mathbf{X})^T \phi(\mathbf{X}))^{-1} (\mathbf{S}_0^{-1} \mathbf{m}_0 + \beta \phi(\mathbf{X})^T \mathbf{t})$$

$$\mathbf{S}_N = (\mathbf{S}_0^{-1} + \beta \phi(\mathbf{X})^T \phi(\mathbf{X}))^{-1}$$

- Assumption Zero mean isotropic Gaussian

$$p(\mathbf{w}|\alpha) = \mathcal{N}(\mathbf{w} | \underbrace{\mathbf{0}}_{\mathbf{m}_0}, \underbrace{\alpha^{-1} \mathbf{I}}_{\mathbf{S}_0})$$

- Posterior

$$p(\mathbf{w}|\mathbf{X}, \mathbf{t}) = \mathcal{N}(\mathbf{w}|\mathbf{m}_N, \mathbf{S}_N)$$

$$\mathbf{m}_N = (\mathbf{S}_0^{-1} + \beta \phi(\mathbf{X})^T \phi(\mathbf{X}))^{-1} (\mathbf{S}_0^{-1} \mathbf{m}_0 + \beta \phi(\mathbf{X})^T \mathbf{t})$$

$$\mathbf{S}_N = (\mathbf{S}_0^{-1} + \beta \phi(\mathbf{X})^T \phi(\mathbf{X}))^{-1}$$

- Assumption Zero mean isotropic Gaussian

$$p(\mathbf{w}|\alpha) = \mathcal{N}(\mathbf{w} | \underbrace{\mathbf{0}}_{\mathbf{m}_0}, \underbrace{\alpha^{-1} \mathbf{I}}_{\mathbf{S}_0})$$

- Feature mapping

$$\phi(x_i) = \begin{bmatrix} 1 \\ x_i \end{bmatrix} \quad \phi(\mathbf{X}) = \begin{bmatrix} 1 & x_1 \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_N \end{bmatrix}$$

Task 1 define a likelihood ✓

- what output do I consider likely under a given model?

Task 2 define an assumption of the model ✓

- what types of models do I think are more probable than others
- \Rightarrow what are my beliefs, i.e formulate prior

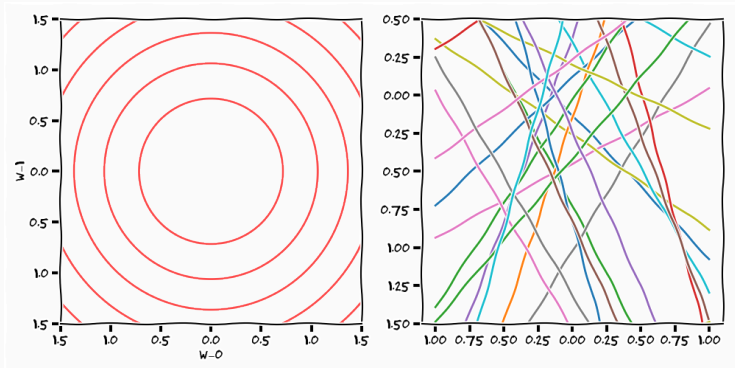
Task 3 update my belief with new observations ✓

- formulate posterior

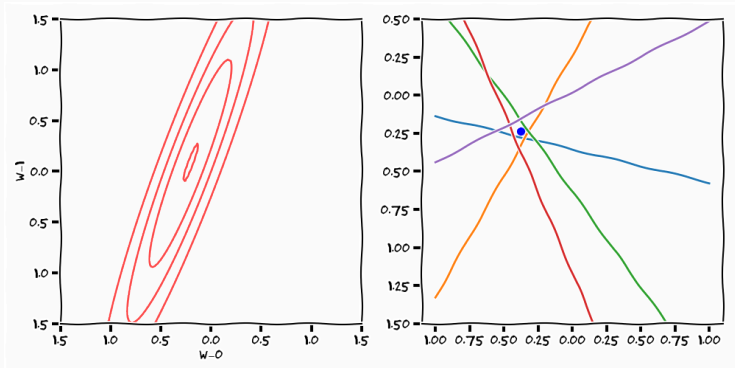
Task 4 predict using my new belief

- formulate predictive distribution

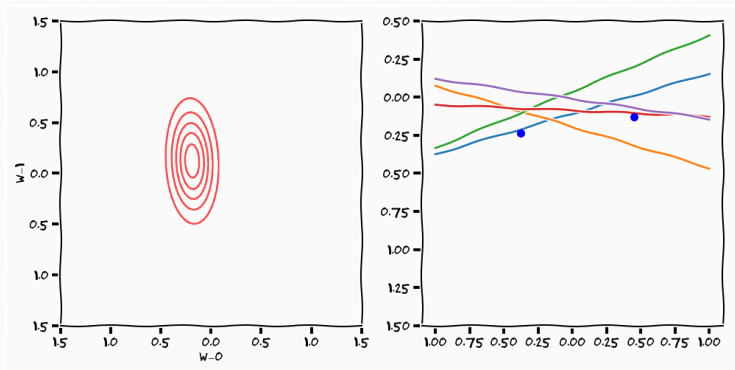
Linear Regression Example



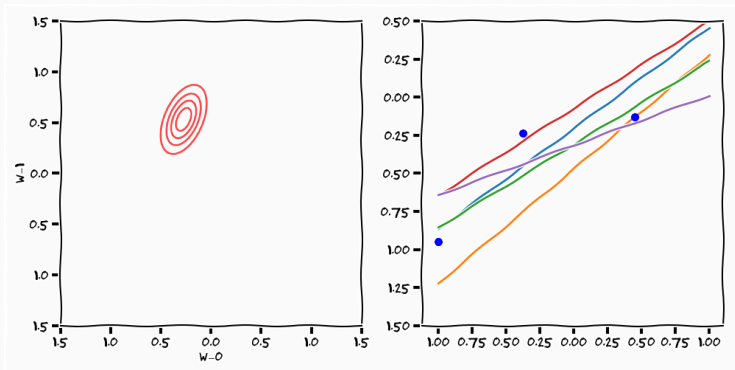
Linear Regression Example



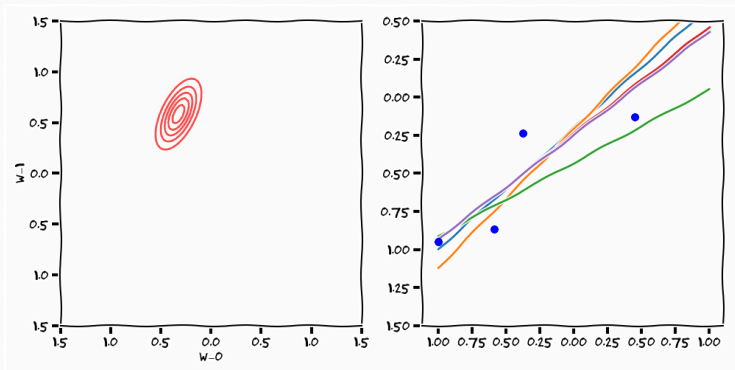
Linear Regression Example



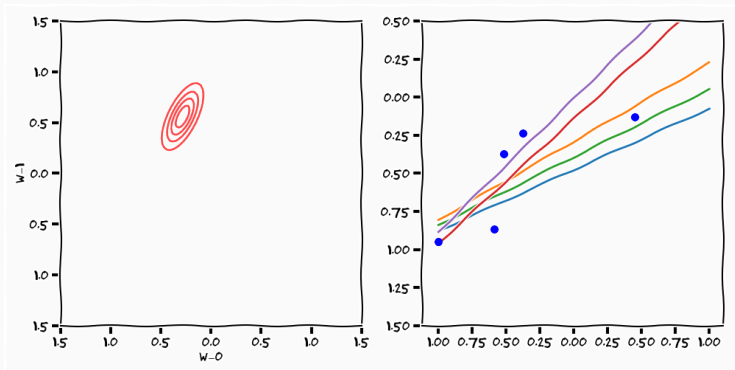
Linear Regression Example



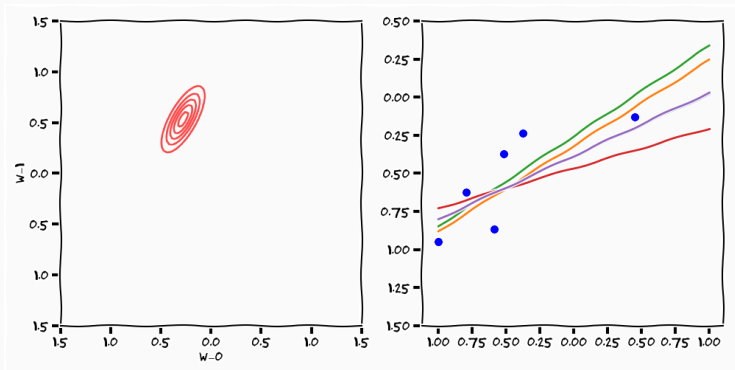
Linear Regression Example



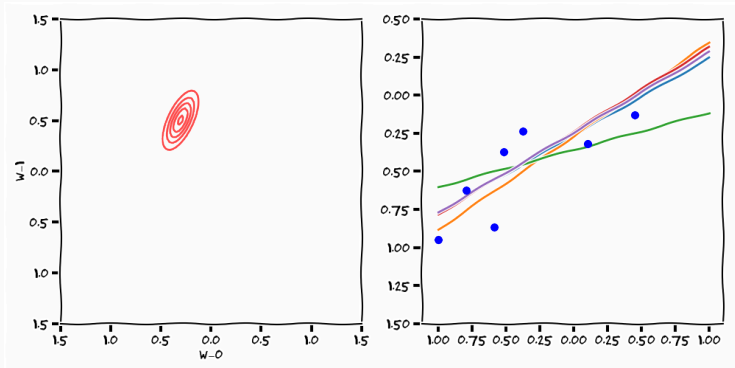
Linear Regression Example



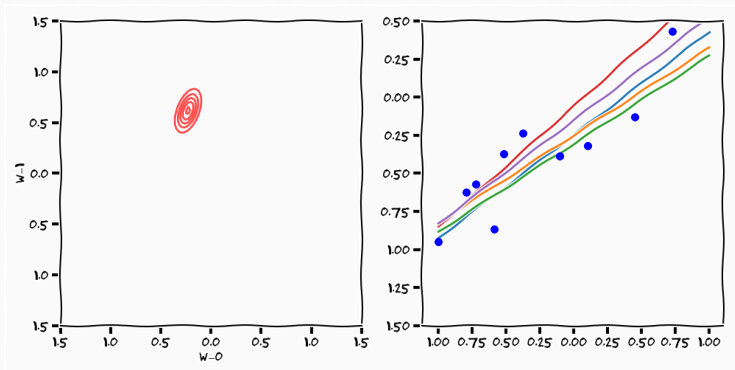
Linear Regression Example



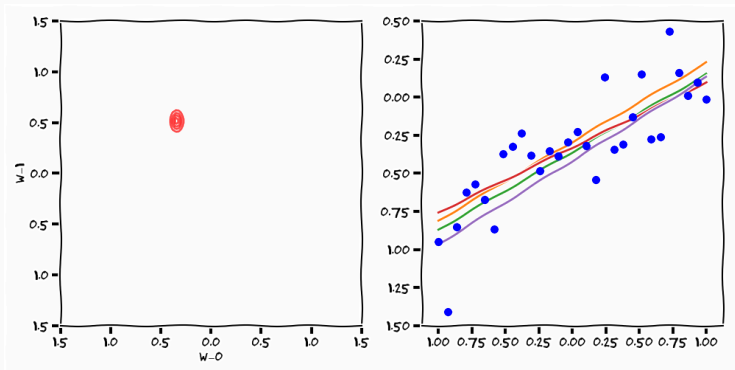
Linear Regression Example



Linear Regression Example



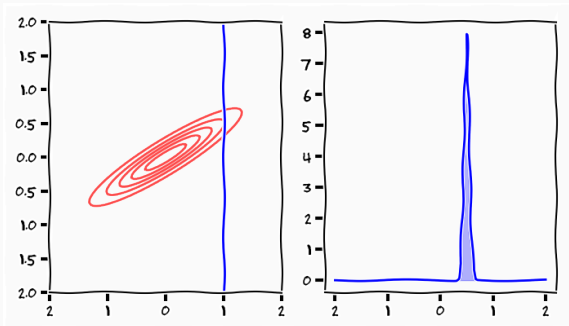
Linear Regression Example



$$\begin{aligned} p(t_*|\mathbf{t}, \mathbf{x}_*, \mathbf{X}, \alpha, \beta) &= \int p(t_*|\mathbf{x}_*, \mathbf{w}, \beta) p(\mathbf{w}|\mathbf{t}, \mathbf{X}, \alpha, \beta) d\mathbf{w} \\ &= \mathbb{E}[p(t_*|\mathbf{x}_*, \mathbf{w}, \beta)] \end{aligned}$$

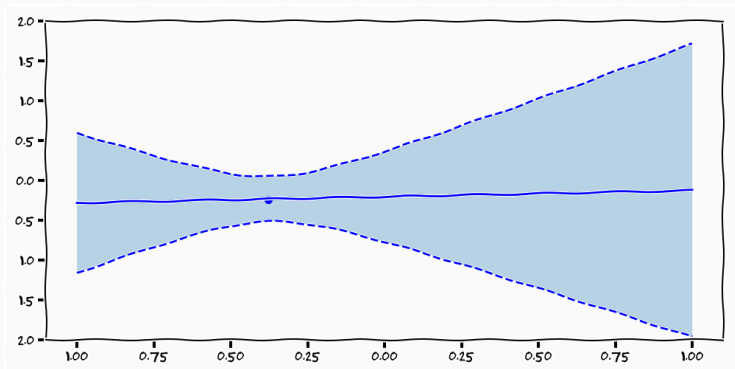
- we do not really care about \mathbf{w} we care about new prediction t_* at location \mathbf{x}_*
- look at the marginal distribution, i.e. when we average out the weight
- integrate a Gaussian over a Gaussian \Rightarrow Gaussian identities

Prediction

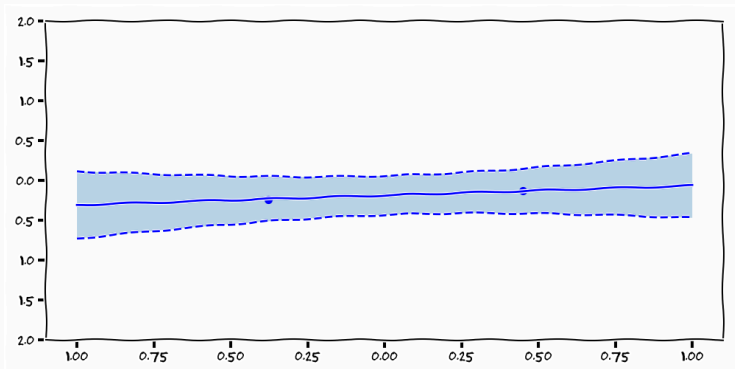


$$\begin{aligned} p(t_*|\mathbf{t}, \mathbf{x}_*, \mathbf{X}, \alpha, \beta) &= \int p(t_*|\mathbf{x}_*, \mathbf{w}, \beta) p(\mathbf{w}|\mathbf{t}, \mathbf{X}, \alpha, \beta) d\mathbf{w} \\ &= \mathcal{N}(t_* | \mathbf{m}_N^T \phi(\mathbf{x}_*), \frac{1}{\beta} + \phi(\mathbf{x}_*)^T \mathbf{S}_N \phi(\mathbf{x}_*)) \end{aligned}$$

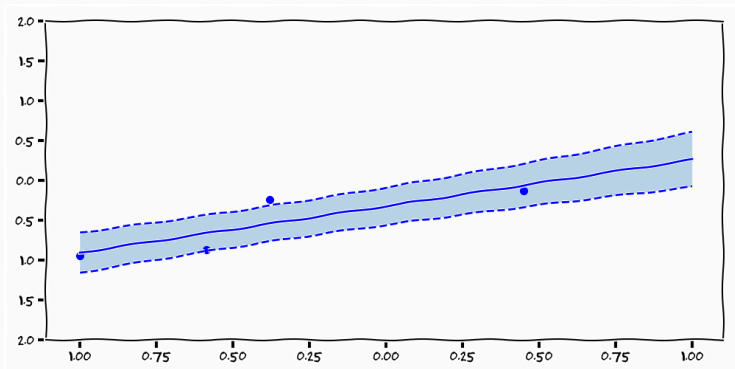
Predictive Posterior



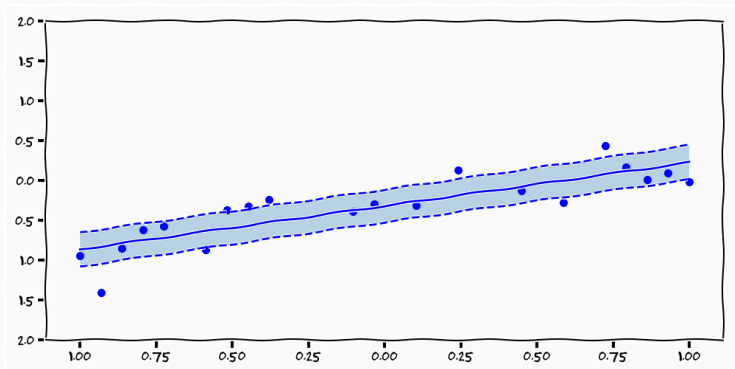
Predictive Posterior



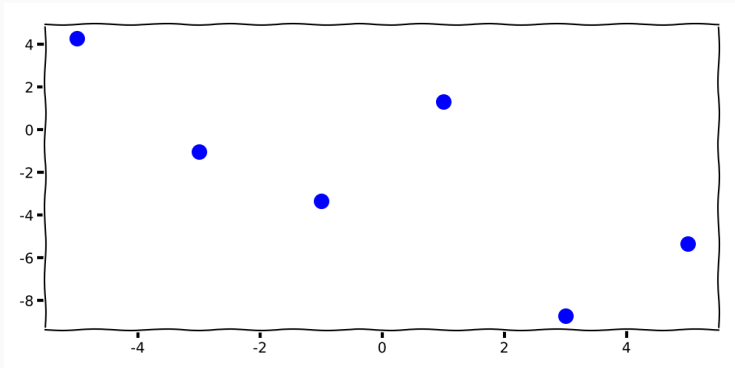
Predictive Posterior



Predictive Posterior



Linear Regression

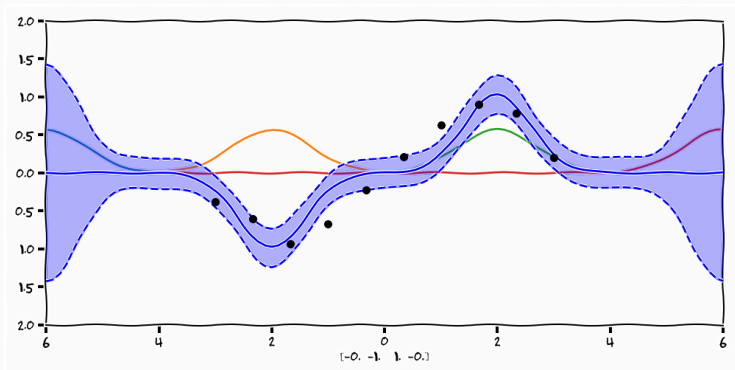


- Linear function only in parameters

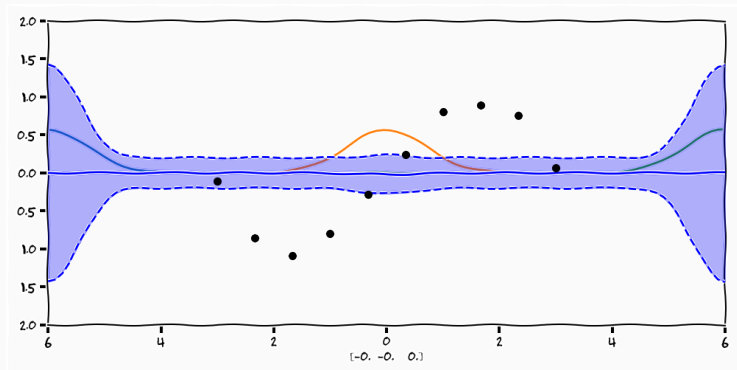
$$y(\mathbf{x}, \mathbf{w}) = w_0 + \sum_{j=1}^{M-1} w_j \phi_j(\mathbf{x}) = \{\phi_0(\mathbf{x}) = 1\} = \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x})$$

- We can choose many types of basis functions $\phi(\mathbf{x})$

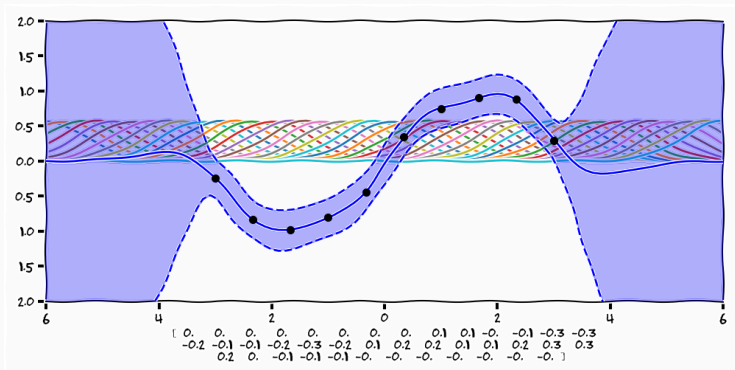
Non-Linear Basis Functions



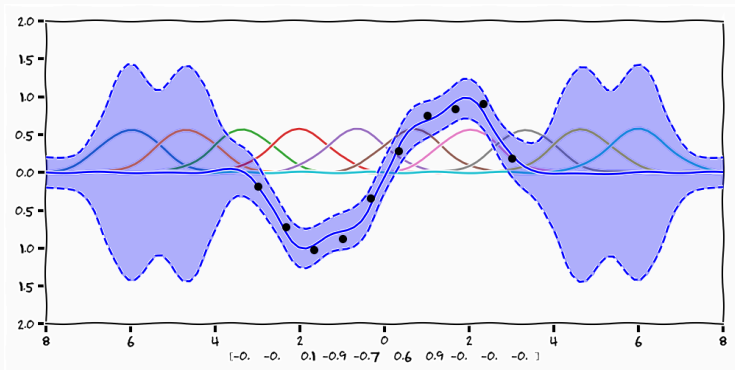
Non-Linear Basis Functions



Non-Linear Basis Functions



Non-Linear Basis Functions



Dual Linear Regression

$$p(\mathbf{w}|\mathbf{t}, \mathbf{x}) = \frac{p(\mathbf{t}|\mathbf{w}, \mathbf{x})p(\mathbf{w})}{p(\mathbf{t})}$$

$$p(\mathbf{t}|\mathbf{w}, \mathbf{x}) = \prod_n^N p(t_n|\mathbf{w}, \mathbf{x}) = \prod_n^N \mathcal{N}(t_n|\mathbf{w}^T \mathbf{x}_n, \sigma^2 \mathbf{I})$$

$$p(\mathbf{w}) = \mathcal{N}(\mathbf{0}, \tau^2 \mathbf{I})$$

$$p(\mathbf{w}|\mathbf{t}, \mathbf{x}) = \frac{p(\mathbf{t}|\mathbf{w}, \mathbf{x})p(\mathbf{w})}{p(\mathbf{t})}$$

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$$p(\mathbf{w}) = \mathcal{N}(\mathbf{0}, \tau^2 \mathbf{I})$$

$$p(\mathbf{w}|\mathbf{t}, \mathbf{x}) \propto p(\mathbf{t}|\mathbf{w}, \mathbf{x})p(\mathbf{w})$$

- Through conjugacy we know the form of the posterior

Dual Linear Regression

$$\begin{aligned} p(\mathbf{w}|\mathbf{t}, \mathbf{x}) &\propto \prod_n \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(\mathbf{w}^T \mathbf{x}_n - t_n)^T(\mathbf{w}^T \mathbf{x}_n - y_n)} \frac{1}{\sqrt{2\pi\tau^2}} e^{-\frac{1}{2\tau^2}(\mathbf{w}^T \mathbf{w})} \\ &= \frac{1}{(\sqrt{2\pi\sigma^2})^N} e^{-\frac{1}{2\sigma^2} \text{tr}((\mathbf{X}\mathbf{w} - \mathbf{t})^T(\mathbf{X}\mathbf{w} - \mathbf{t}))} \frac{1}{(\sqrt{2\pi\tau^2})^N} e^{-\frac{1}{2\tau^2}(\mathbf{w}^T \mathbf{w})} \end{aligned}$$

- Lets maximise the above to find a point estimate (not a distribution) of \mathbf{w}

$$-\log p(\mathbf{w}|\mathbf{t}, \mathbf{x}) = J(\mathbf{w}) = \frac{1}{2}(\mathbf{X}\mathbf{w} - \mathbf{t})^T(\mathbf{X}\mathbf{w} - \mathbf{t}) + \frac{\lambda}{2}\mathbf{w}^T\mathbf{w}$$

- Find a stationary point in \mathbf{w}

$$-\log p(\mathbf{w}|\mathbf{t}, \mathbf{x}) = J(\mathbf{w}) = \frac{1}{2}(\mathbf{X}\mathbf{w} - \mathbf{t})^T(\mathbf{X}\mathbf{w} - \mathbf{t}) + \frac{\lambda}{2}\mathbf{w}^T\mathbf{w}$$
$$\frac{\delta}{\delta \mathbf{w}} J(\mathbf{w}) = \frac{1}{2}2\mathbf{X}^T(\mathbf{X}\mathbf{w} - \mathbf{t}) + \frac{\lambda}{2}2\mathbf{w}$$

- Find a stationary point in \mathbf{w}

$$\begin{aligned} -\log p(\mathbf{w}|\mathbf{t}, \mathbf{x}) &= J(\mathbf{w}) = \frac{1}{2}(\mathbf{X}\mathbf{w} - \mathbf{t})^T(\mathbf{X}\mathbf{w} - \mathbf{t}) + \frac{\lambda}{2}\mathbf{w}^T\mathbf{w} \\ \frac{\delta}{\delta \mathbf{w}} J(\mathbf{w}) &= \frac{1}{2}2\mathbf{X}^T(\mathbf{X}\mathbf{w} - \mathbf{t}) + \frac{\lambda}{2}2\mathbf{w} \\ \mathbf{w} &= -\frac{1}{\lambda}\mathbf{X}^T(\mathbf{X}\mathbf{w} - \mathbf{t}) \end{aligned}$$

- Find a stationary point in \mathbf{w}

$$\begin{aligned}-\log p(\mathbf{w}|\mathbf{t}, \mathbf{x}) &= J(\mathbf{w}) = \frac{1}{2}(\mathbf{X}\mathbf{w} - \mathbf{t})^T(\mathbf{X}\mathbf{w} - \mathbf{t}) + \frac{\lambda}{2}\mathbf{w}^T\mathbf{w} \\ \frac{\delta}{\delta \mathbf{w}} J(\mathbf{w}) &= \frac{1}{2}2\mathbf{X}^T(\mathbf{X}\mathbf{w} - \mathbf{t}) + \frac{\lambda}{2}2\mathbf{w} \\ \mathbf{w} &= -\frac{1}{\lambda}\mathbf{X}^T(\mathbf{X}\mathbf{w} - \mathbf{t}) \\ &= \mathbf{X}^T\mathbf{a} = \sum_n^N \alpha_n \mathbf{x}_n\end{aligned}$$

- Find a stationary point in \mathbf{w}

$$J(\mathbf{w}) = \frac{1}{2}(\mathbf{X}\mathbf{w} - \mathbf{t})^T(\mathbf{X}\mathbf{w} - \mathbf{t}) + \frac{\lambda}{2}\mathbf{w}^T\mathbf{w}$$
$$\mathbf{w} = \mathbf{X}^T\mathbf{a}$$

- Rewrite objective in terms of \mathbf{a}

$$J(\mathbf{w}) = \frac{1}{2}(\mathbf{X}\mathbf{w} - \mathbf{t})^T(\mathbf{X}\mathbf{w} - \mathbf{t}) + \frac{\lambda}{2}\mathbf{w}^T\mathbf{w}$$

$$\mathbf{w} = \mathbf{X}^T\mathbf{a}$$

$$J(\mathbf{a}) = \frac{1}{2}\mathbf{a}^T\mathbf{X}\mathbf{X}^T\mathbf{X}\mathbf{X}^T\mathbf{a} - \mathbf{a}^T\mathbf{X}\mathbf{X}^T\mathbf{t} + \frac{1}{2}\mathbf{t}^T\mathbf{t} + \frac{\lambda}{2}\mathbf{a}^T\mathbf{X}\mathbf{X}^T\mathbf{a}$$

- Rewrite objective in terms of \mathbf{a}

$$[K]_{ij} = \mathbf{x}_i^T \mathbf{x}_j$$

$$J(\mathbf{a}) = \frac{1}{2} \mathbf{a}^T \mathbf{K} \mathbf{K} \mathbf{a} - \mathbf{a}^T \mathbf{K} \mathbf{t} + \frac{1}{2} \mathbf{t}^T \mathbf{t} + \frac{\lambda}{2} \mathbf{a}^T \mathbf{K} \mathbf{a}$$

- \mathbf{K} is a matrix with all inner-products between the data points

$$\alpha_n = -\frac{1}{\lambda}(\mathbf{w}^T \mathbf{x}_n - t_n)$$
$$\mathbf{w} = \sum_n^N \alpha_n \mathbf{x}_n = \mathbf{X}^T \mathbf{a}$$

- Eliminate \mathbf{w} and rewrite in terms of \mathbf{a}

$$\begin{aligned}\alpha_n &= -\frac{1}{\lambda}(\mathbf{w}^T \mathbf{x}_n - t_n) \\ \mathbf{w} &= \sum_n^N \alpha_n \mathbf{x}_n = \mathbf{X}^T \mathbf{a} \\ \Rightarrow \mathbf{a} &= (\mathbf{K} + \lambda \mathbf{I})^{-1} \mathbf{t}\end{aligned}$$

- Eliminate \mathbf{w} and rewrite in terms of \mathbf{a}

$$[\mathbf{K}]_{ij} = \mathbf{x}_i^T \mathbf{x}_j$$

$$J(\mathbf{a}) = \frac{1}{2} \mathbf{a}^T \mathbf{K} \mathbf{K} \mathbf{a} - \mathbf{a}^T \mathbf{K} \mathbf{t} + \frac{1}{2} \mathbf{t}^T \mathbf{t} + \frac{\lambda}{2} \mathbf{a}^T \mathbf{K} \mathbf{a}$$

$$\mathbf{a} = (\mathbf{K} + \lambda \mathbf{I})^{-1} \mathbf{t}$$

$$[\mathbf{K}]_{ij} = \mathbf{x}_i^T \mathbf{x}_j$$

$$J(\mathbf{a}) = \frac{1}{2} \mathbf{a}^T \mathbf{K} \mathbf{K} \mathbf{a} - \mathbf{a}^T \mathbf{K} \mathbf{t} + \frac{1}{2} \mathbf{t}^T \mathbf{t} + \frac{\lambda}{2} \mathbf{a}^T \mathbf{K} \mathbf{a}$$

$$\mathbf{a} = (\mathbf{K} + \lambda \mathbf{I})^{-1} \mathbf{t}$$

$$\begin{aligned} y(\mathbf{x}_*) &= \mathbf{w}^T \mathbf{x}_* = \mathbf{a}^T \mathbf{X}^T \mathbf{x}_* = \mathbf{a}^T k(\mathbf{x}, \mathbf{x}_*) = \\ &= ((\mathbf{K} + \lambda \mathbf{I})^{-1} \mathbf{t})^T k(\mathbf{x}, \mathbf{x}_*) = k(\mathbf{x}_*, \mathbf{x})(\mathbf{K} + \lambda \mathbf{I})^{-1} \mathbf{t} \end{aligned}$$

What have we actually done

- Linear Regression
 - See data
 - Encode relationship between variates using parameters \mathbf{w}
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 - *Model complexity depends on data*
 - Non-parametric model

$$\phi : \mathbf{x}_i \rightarrow \mathbf{f}_i$$

$$\mathbf{y}(\mathbf{x}_*) = \mathbf{w}^T \phi(\mathbf{x}_*) = \mathbf{a}^T \phi(\mathbf{X}) \phi(\mathbf{x}_*) = k(\mathbf{x}_*, \mathbf{X})(\mathbf{K} + \lambda \mathbf{I})^{-1} \mathbf{y}$$

$$k(\mathbf{x}, \mathbf{x}') = \phi(\mathbf{x})^T \phi(\mathbf{x}')$$

- we actually never need to know $\phi(\mathbf{x})$ only $\phi(\mathbf{x}_i)^T \phi(\mathbf{x}_j)$
- functions that describes inner-products are called *kernel-functions*

$$\mathbf{x} \in \mathbb{R}^2$$

$$(\mathbf{x}_i^T \mathbf{x}_j)^2$$

- Kernel functions need to forefill certain properties and is a subclass of functions
- Can be incredibly useful, think similarity rather than location

$$\mathbf{x} \in \mathbb{R}^2$$

$$(\mathbf{x}_i^T \mathbf{x}_j)^2 = (x_{i1}x_{j1} + x_{i2}x_{j2})^2$$

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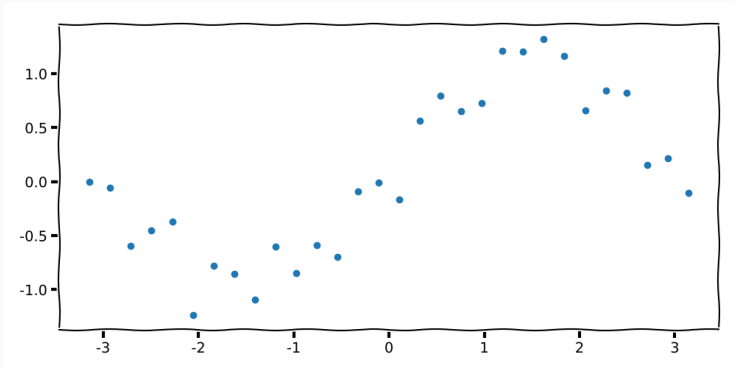
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- More next lecture, these things are very powerful

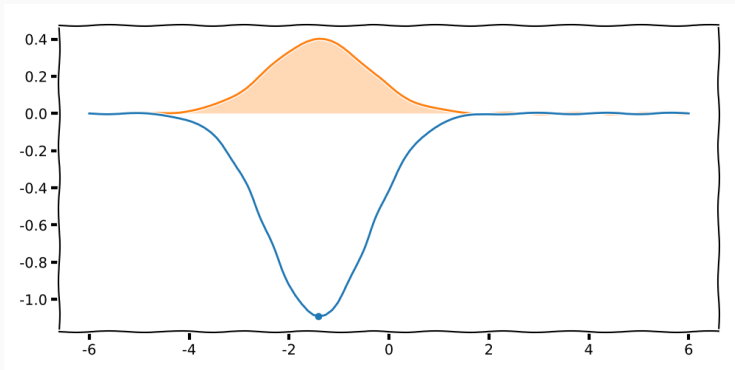
Kernel Functions



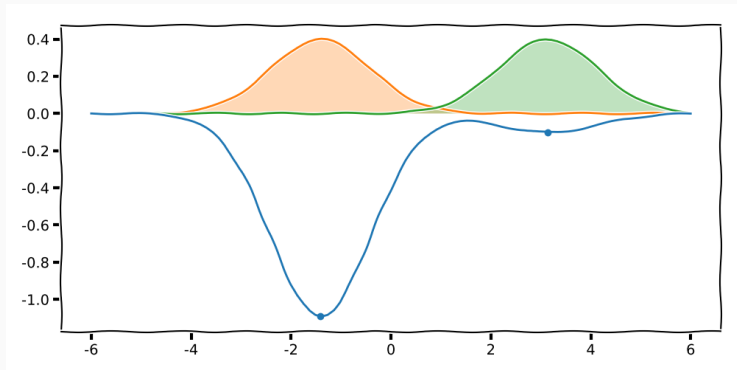
$$t = f(x) + \epsilon$$

$$k(x_i, x_j) = e^{-\frac{1}{2} \frac{(x_i - x_j)^2}{l}}$$

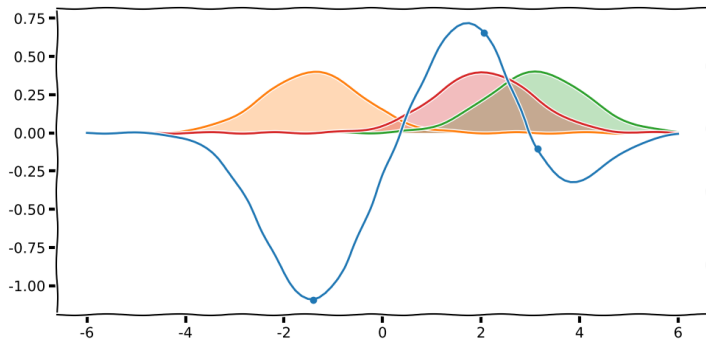
Kernel Regression



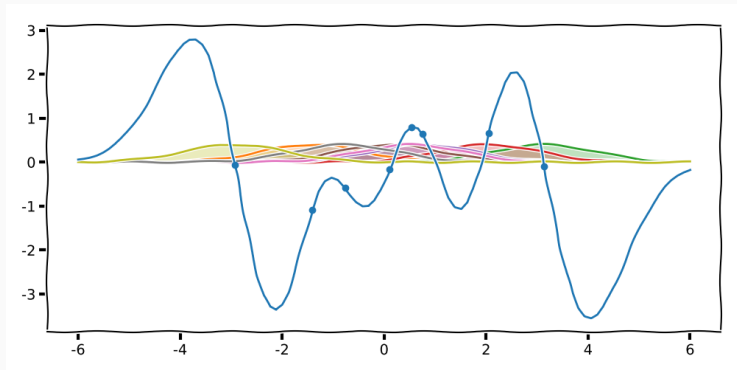
Kernel Regression



Kernel Regression

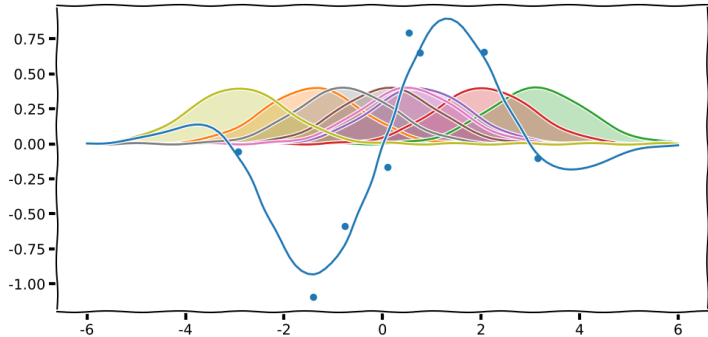


Kernel Regression

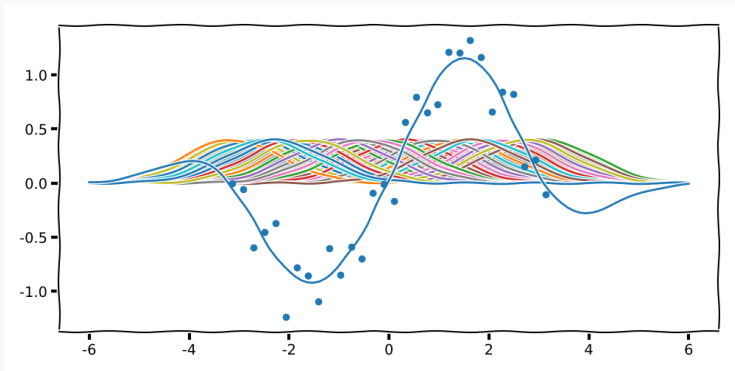


$$y(\mathbf{x}_*) = k(\mathbf{x}_*, \mathbf{x})(\mathbf{K} + \lambda \mathbf{I})^{-1} \mathbf{t}$$

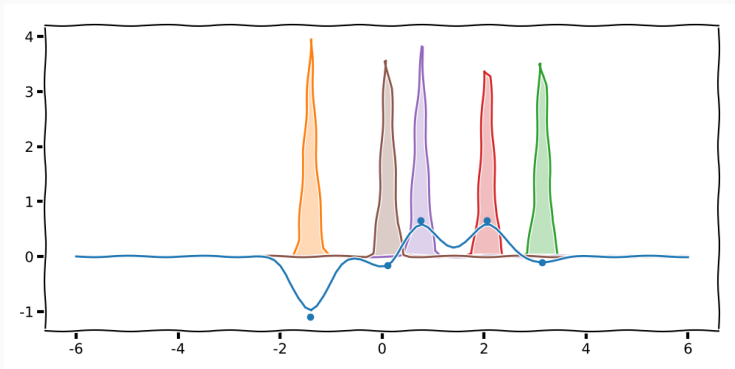
Kernel Regression



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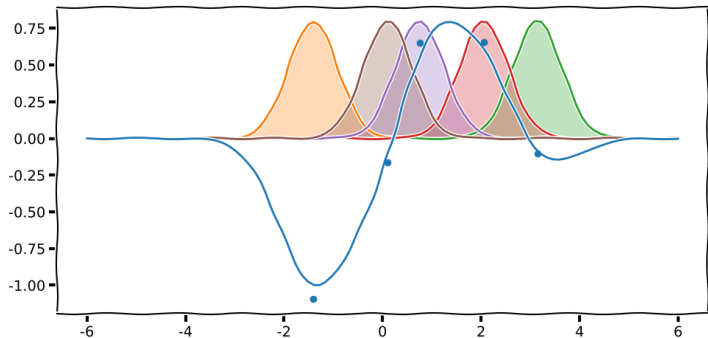


Kernel Regression

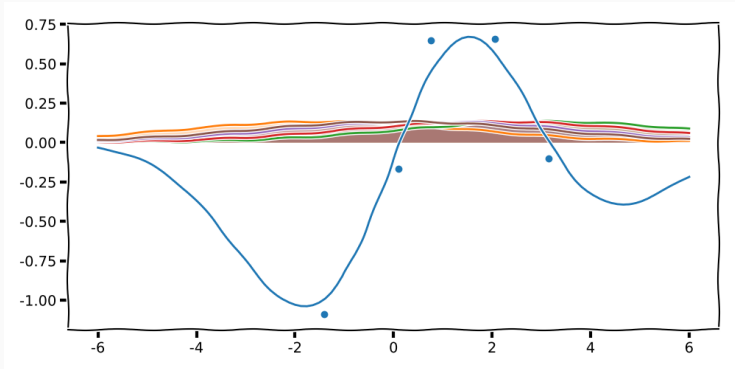


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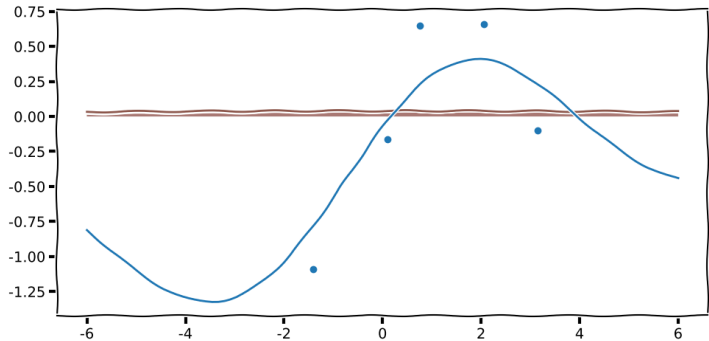
Kernel Regression



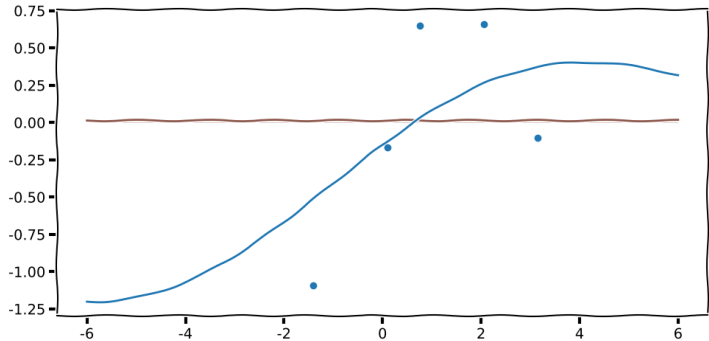
Kernel Regression



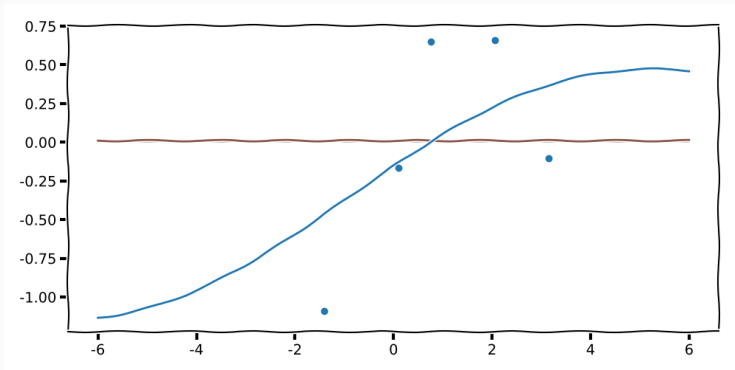
Kernel Regression



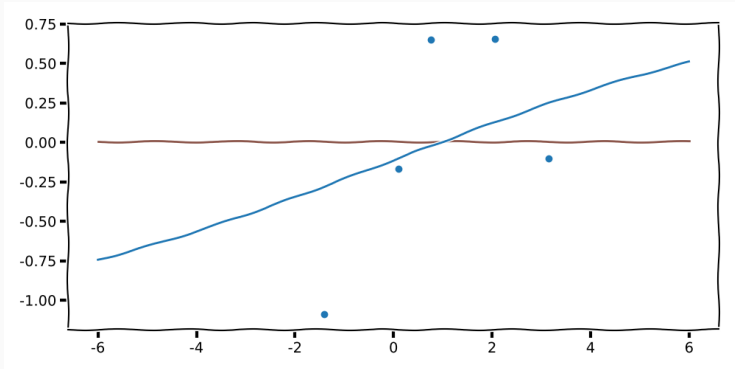
Kernel Regression



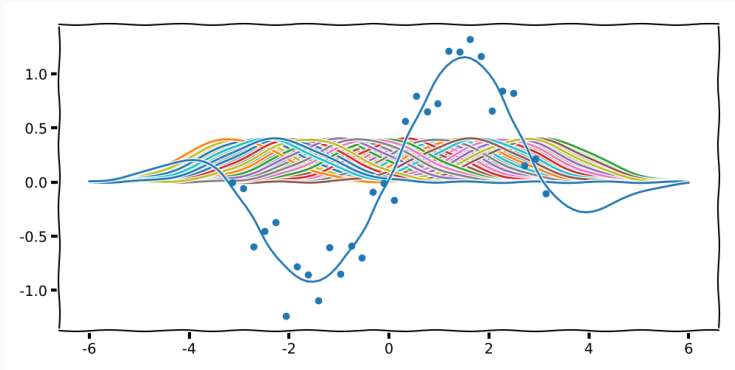
Kernel Regression



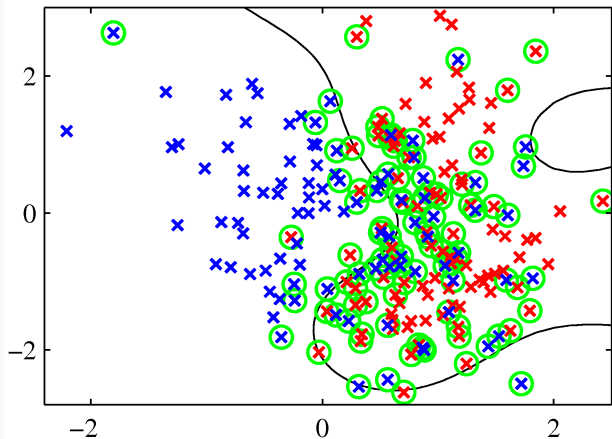
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Kernel Regression



Support Vector Machines [1] Figure 7.4



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 - how to set kernel width
 - how to set noise assumption
- Tomorrow we will learn these

Summary

- Repeat of the machine learning procedure
 - assumption + data + compute \rightarrow updated assumption
 - don't worry it will become clear eventually
- Non-parametrics
 - kernel regression
 - dual formulation
 - *the problem is still linear*

eof

References



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