

Comm\_GPS\_Get\_Position

```
graph LR; A[Comm_GPS_Get_Position] --> B[Is_Battery_Mode_Demo]; A --> C[Send_Comm_Queue];
```

A diagram showing a central node on the left, 'Comm\_GPS\_Get\_Position', which is a dark gray rectangle. Two blue arrows originate from its right side. The top arrow points to a white rectangle labeled 'Is\_Battery\_Mode\_Demo'. The bottom arrow points to a white rectangle labeled 'Send\_Comm\_Queue'.

Is\_Battery\_Mode\_Demo

Send\_Comm\_Queue