

RO: 3 rigid bodies: AC, CE, EF.

Method: statics

Bodies are fixed:

AC: A-roller support  $R_A$

B-support  $R_{Bx}, R_{By}$

C-pin  $R'_{cx}, R'_{cy}$

CE: C-pin  $R_{cx}, R_{cy}$

D-roller support  $R_D$

E-pin  $R'_{ex}, R'_{ey}$

EF: E-pin  $R_{ex}, R_{ey}$

F-roller support  $R_F$

Force analysis:

AC:  $R_A \rightarrow R_A \cos \alpha$   
 $R_A \rightarrow R_A \sin \alpha$

$R'_{cy} = -R_{cy}; R'_{cx} = R_{cx}$

$R'_{ey} = R_{ey}; R'_{ex} = -R_{ex}$

Solution:

$$\text{AC: } \begin{cases} x: R_A \cos \alpha + R_{Bx} - R'_{cx} = 0 \\ y: R_A \sin \alpha + R_{By} + R'_{cy} - q \cdot BC - P_1 = 0 \\ M_A: -P_1 \cdot AG + R_{By} \cdot AB - q \cdot BC \cdot (AB + \frac{BC}{2}) + R'_{cy} \cdot AC = 0 \end{cases}$$

$$\text{CE: } \begin{cases} x: R_{cx} - R'_{ex} = 0 \\ y: -R_{cy} + R'_{ey} + R_D - q \cdot CE = 0 \\ M_E: -R_D \cdot DE + q \cdot CE \cdot \frac{CE}{2} + R_{cy} \cdot CE = 0 \end{cases}$$

$$\text{EF: } \begin{cases} x: R_{ex} - P_2 \cdot \cos \beta = 0 \\ y: -R_{ey} - P_2 \cdot \sin \beta + R_F = 0 \\ M_E: -P_2 \cdot (EK \sin \beta) \cdot EK - M_1 + R_F \cdot EF = 0 \end{cases}$$

$$-R_D \cdot DE + q \cdot \frac{CE^2}{2} + R_D \cdot CE - 7.372 \cdot CE = 0$$

$$R_D = \frac{7.372 \cdot CE - q \cdot \frac{CE^2}{2}}{CE - DE} = 7.5996$$

# Answer:

$$R_A = 4.68$$

$$R_{Bx} = 5.69$$

$$R_{By} = 14.38$$

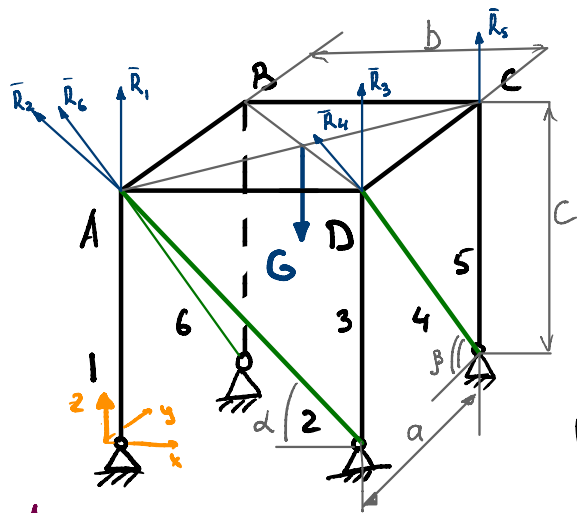
$$R_{cx} = 9$$

$$R_{cy} = -1.487$$

$$R_D = 3.74$$

$$R_{ex} = 9.0 \quad R_{ey} = 1.072$$

$$R_F = 16.66$$



**Answer:**

$$\begin{aligned} R_1 &= -37.6 \\ R_2 &= 38.005848 \\ R_3 &= 23.3 \\ R_4 &= -35.43382 \\ R_5 &= 9.0 \\ R_6 &= 35.4338 \end{aligned}$$

**RO:** 1 rigid body ABCD, 1-6 rods.

**Method:** statics

**Body is fixed:** A - rod 1  $R_1$  rod 2  $R_2$  rod 6  $R_6$  B - rod 3  $R_3$  rod 4  $R_4$  C - rod 5  $R_5$

**Force analysis:**

$$\begin{aligned} R_2 \rightarrow x: R_2 \cos \alpha \quad R_6 \rightarrow y: -R_6 \cos \beta \quad R_4 \rightarrow y: -R_4 \cos \beta \\ z: R_2 \sin \alpha \quad z: R_6 \sin \beta \quad z: R_4 \sin \beta \end{aligned}$$

**Solution:**

$$\begin{cases} x: -R_2 \cos \alpha + P = 0 \\ y: -R_6 \cos \beta - R_4 \cos \beta = 0 \\ z: R_6 \sin \beta + R_4 \sin \beta + R_2 \sin \alpha + R_1 + R_3 + R_5 - G = 0 \\ M_{Ax}: R_5 \cdot a - G \cdot \frac{a}{2} = 0 \\ M_{Ay}: -(R_5 \cdot b + R_3 \cdot b + R_4 \cdot b \sin \beta) + G \cdot \frac{b}{2} = 0 \\ M_{Az}: -R_4 \cdot \cos \beta \cdot b - P \cdot a = 0 \end{cases}$$