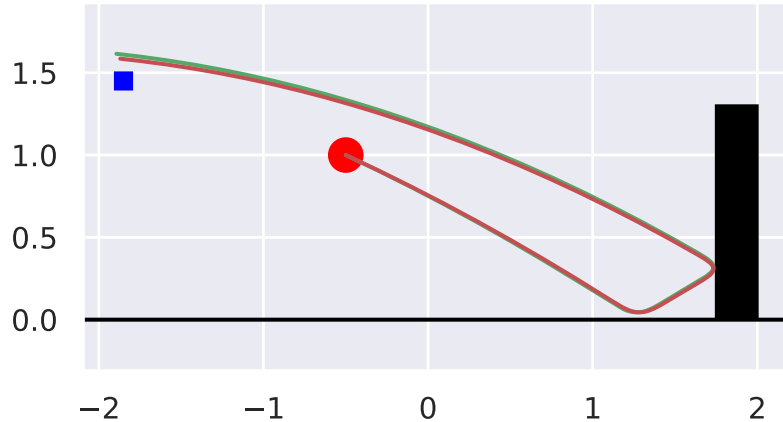


Final trajectories



Optimization landscape

