

```
Plots.GRBackend()
```

```
• begin
•   using PlutoUI
•   using Images
•   using ImageMagick
•   using Plots
•   gr()
• end
```

A1: Plot an exponential curve with parameter τ and the numerical solution of the leaky bucket model with parameters C and λ on the same axes, with $u = 0$ and the same initial state

```
bucket_state_step (generic function with 1 method)
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```
• function bucket_state_step(v, Δt, C, λ, v0, u) # set up function bucket_state_step
  with parameters v, Δt, C, λ, v0, u
• Δv = (u - λ*(v - v0))*Δt/C # such that Δv = (u - λ*(v - v0))*Δt/C
• end
```

```
0.0
```

```
• begin #establish first set of parameters for first plot
• C = pi*r^2 # C = pi*radius^2 where radius = r slider value
• Δt = 0.05 # simulate in 50ms steps
• T = 600.0 # duration of simulation in seconds
• t = 0:Δt:T; # time iterator from 0 seconds to 600 seconds in 50ms steps
• v = zeros(length(t)) # vector container for computed water level
• v[1] = 11.0 # initial height = 11.0cm
• v_rest = 0.0 # leak height = 0.0cm
• u = 0.0 # input current = 0.0
• end
```

```
C = 201.06192982974676
```

```
r slider, r = 8
```



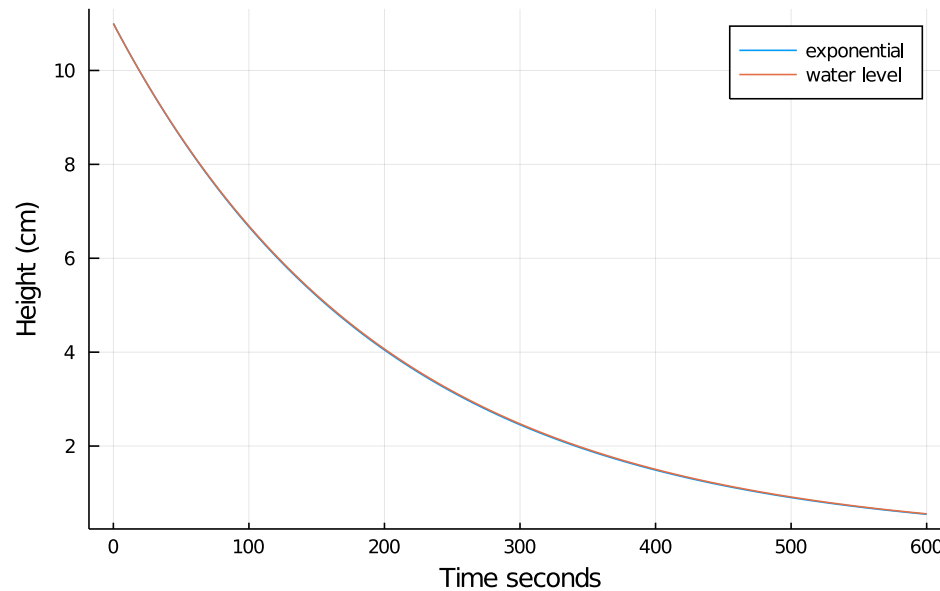
```
λ slider, λ = 1
```



```
τ slider, τ = 200
```



Exponential curve and water level



```

• begin
•     plot(t, v[1]*exp.(-t./τ), # plot time iterator vs exponential curve multiplied by
      initial height
•     xlabel = "Time seconds", ylabel = "Height (cm)", label = "exponential", title
      = "Exponential curve and water level")
•     for i in 2:length(t) # for each iteration from the 2nd to the last iterations
•         v[i] = v[i-1] + bucket_state_step(v[i-1], Δt, C, λ, v_rest, u) # each iteration of v =
      the previous iteration + the bucket_state_step function
•     end
•     plot!(t, v, label = "water level") # add a plot of the time iterator vs water level to
      the same axes
• end

```

A1.1: What is the relationship of the time constant τ of the analytical solution to the "biophysical" parameters C and λ ? (Show this empirically)

By observation, as τ increases, C increases and/or λ decreases.

τ and C are directly proportional ($\tau = R \cdot C$) while τ and λ are inversely proportional (since $R = 1/\lambda$).

A1.2: What is the height of the water column above the leak channel at time $t=\tau$ relative to its initial height? (show this analytically and confirm by simulation)

Analytically: at $t=\tau$ the water column is 36.8% ($0.36787944117 = 1/e$) of its initial height above the leak channel

By simulation: when $\tau=300$ and $t=300$, and when $\tau=200$ and $t=200$, and when $\tau=100$ and $t=100$, approximately 4.05cm out of 11cm remains, $4.05/11 = 0.368$.

A2: Create an interactive simulation of a leaky bucket neuron that starts at rest potential and receives a 30-second burst of "synaptic input" after 30 seconds. Use a slider to control the amplitude of the input current. Allow the input to be positive or negative, ie it is possible to suck water out of the bucket. Assume that the bucket is tall enough and the leak channel is far enough up the side that the bucket cannot run dry or overflow. Note that water will leak backwards through the leak channel, into the bucket, if the water level drops below the channel. Note that we are starting to stretch the analogy between buckets and neurons. Soon it will break.

bucket_state_step_ (generic function with 1 method)

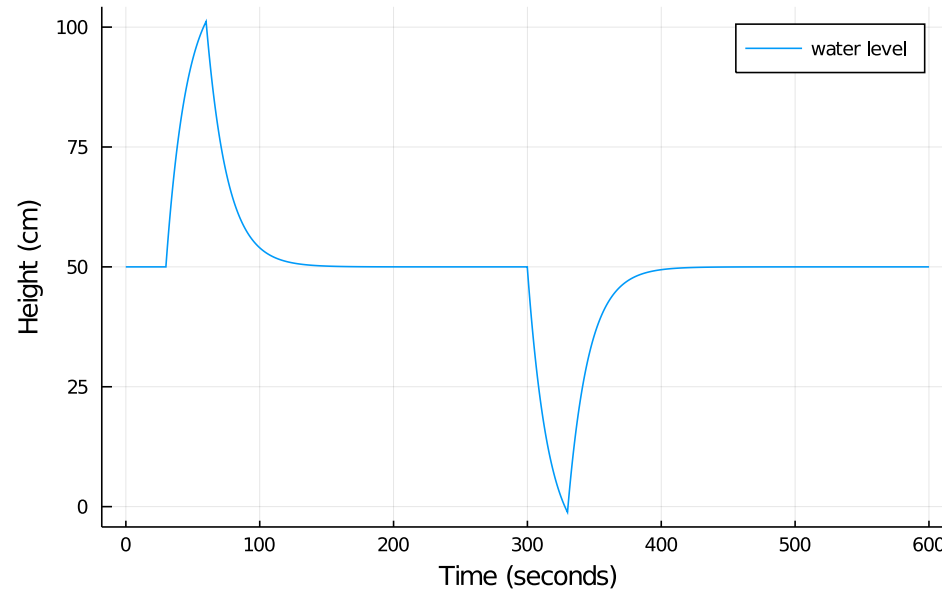
```
• function bucket_state_step_(v_, Δt_, C_, λ_, v0_, u_) # set up function
  bucket_state_step_ with parameters v_, Δt_, C_, λ_, v0_, u_
• Δv_ = (u_ - λ_*(v_ - v0_))*Δt_/C_ # such that Δv_ = (u_ - λ_*(v_ - v0_))*Δt_/C_
• end
```

```
• begin #establish second set of parameters for second plot
• C_ = π*5.0^2 # C_ = pi*radius^2 where radius = 5.0
• λ_ = 5.0 # λ_ = 5.0
• Δt_ = 0.05 # simulate in 50ms steps
• T_ = 600.0 # duration of simulation in seconds
• t_ = 0:Δt_:T_; # time iterator from 0 seconds to 600 seconds in 50ms steps
• v_ = zeros(length(t_)) # vector container for computed water level
• v_[1] = 50.0 # initial height = 50.0cm
• v_rest_ = 50.0 # leak height = 50.0cm
• u_ = zeros(length(t_)) # vector container for variable input
•   for i in 600:1200 # between 30 seconds and 60 seconds
•     u_[i] = 1.0 # input is 1.0*"the value of the u slider"
•   for i in 6000:6600 # between 300 and 330 seconds
•     u_[i] = -1.0 # input is -1.0*"the value of the u slider"
•   end
• end
• end
```

u slider, u = 300



Water level over time



```

• begin
•     for i in 2:length(t_) # for each iteration from the 2nd to the last iterations
•         v_[i] = v_[i-1] + bucket_state_step_(v_[i-1], Δt_, C_, λ_, v_rest_, u_[i]*u_--)
•         # each iteration of v_ = the previous iteration + the bucket_state_step_ function
•         # where the input is 1.0*"the value of the u slider" for 30s < t < 60s and -1.0*"the
•         # value of the u slider" for 300s < t < 330s
•     end
•     plot(t_,v_, xlabel = "Time (seconds)", ylabel = "Height (cm)", label = "water
•         level", title = "Water level over time") # plot t_ vs v_
• end

```