

STT 465

Bayesian Multiple Linear Regression:

- Mixed Effects Models
- Gibbs Sampler with blocked or scalar updates of effects.

Bayesian Multiple Linear Regression

- Gaussian Linear Regression Model

$$y_i = \sum_{j=1}^p x_{ij} \beta_j + \varepsilon_i$$

- Matrix representation

Stack equations 1-n to get $y = X\beta + \varepsilon$

- Likelihood (assuming iid normal errors) $\varepsilon \sim MVN(0, I\sigma_\varepsilon^2)$

$$\begin{aligned} p(y|X, \beta, \sigma_\varepsilon^2) &= N(y|X\beta, I\sigma_\varepsilon^2) \\ &= (2\pi)^{-n/2} \|I\sigma_\varepsilon^2\|^{-1/2} \text{Exp} \left\{ -\frac{1}{2\sigma_\varepsilon^2} (y - X\beta)' (y - X\beta) \right\} \end{aligned}$$

Prior Distribution

- ⇒ So far we have assumed that effects come all from the same prior.
- ⇒ However, in practice we may need to assign different priors to different sets of effects.
- ⇒ For instance: (i) we may want to estimate some effects (e.g., age, etc.) without shrinkage (i.e., using a flat prior) and (ii) we may want to estimate different variances for different sets of predictors.
- ⇒ Suppose we define K groups of effects, according to the following partition of the columns of X

$$X = (X_1, X_2, \dots, X_K) \quad \beta = (\beta_1, \beta_2, \dots, \beta_K)'$$

$$X\beta = X_1\beta_1 + X_2\beta_2 + \dots + X_K\beta_K$$

Bayesian Multiple Linear Regression

- If we group predictors in k sets we can write the regression as follows

$$y = \sum_{k=1}^K X_k \beta_k + \varepsilon$$

- And the likelihood can be expressed as

$$\begin{aligned} p(y | X, \beta, \sigma_\varepsilon^2) &= N\left(y \mid \sum_{k=1}^K X_k \beta_k, I \sigma_\varepsilon^2\right) \\ &= (2\pi)^{-n/2} \|I \sigma_\varepsilon^2\|^{-1/2} \text{Exp} \left\{ -\frac{1}{2\sigma_\varepsilon^2} \left(y - \sum_{k=1}^K X_k \beta_k \right)' \left(y - \sum_{k=1}^K X_k \beta_k \right) \right\} \end{aligned}$$

Prior Distribution

=> Assume that effects are independent, each following a normal distribution with mean zero and group-specific variance, that is

$$\beta_{kj} \sim N(0, \sigma_{\beta_k}^2) \quad [\text{group-specific variances}]$$

=> If we assign scaled-inverse chi-squared priors to each of these variances the joint prior becomes

$$p(\beta, \sigma_{\varepsilon}^2, \sigma_{\beta_1}^2, \dots, \sigma_{\beta_K}^2) = \prod_{k=1}^K N(\beta_k | 0, I \sigma_{\beta_k}^2) \chi^{-2}(\sigma_{\beta_k}^2 | df_k, S_k) \\ \times \chi^{-2}(\sigma_{\varepsilon}^2 | df_{\varepsilon}, S_{\varepsilon})$$

Posterior Density

Joint Posterior Density

$$\begin{aligned} p(\beta, \sigma_\varepsilon^2, \sigma_{\beta_1}^2, \dots, \sigma_{\beta_K}^2 \mid y) &\propto N\left(y \mid \sum_{k=1}^K X_k \beta_k, I \sigma_\varepsilon^2\right) \\ &\times \prod_{k=1}^K N\left(\beta_k \mid 0, I \sigma_{\beta_k}^2\right) \chi^{-2}\left(\sigma_{\beta_k}^2 \mid df_k, S_k\right) \\ &\times \chi^{-2}\left(\sigma_\varepsilon^2 \mid df_\varepsilon, S_\varepsilon\right) \end{aligned}$$

Fully Conditionals

Marker Effects

$$\begin{aligned} p(\beta_k | ELSE) &\propto N\left(y \mid \sum_{l=1}^K X_l \beta_l, I \sigma_\varepsilon^2\right) \times N\left(\beta_k \mid 0, I \sigma_{\beta_k}^2\right) \\ &\propto N\left(y - \sum_{l \neq k} X_l \beta_l \mid X_k \beta_k, I \sigma_\varepsilon^2\right) \times N\left(\beta_k \mid 0, I \sigma_{\beta_k}^2\right) \\ &\propto N\left(\tilde{y}_{(k)} \mid X_k \beta_k, I \sigma_\varepsilon^2\right) \times N\left(\beta_k \mid 0, I \sigma_{\beta_k}^2\right) \quad \text{where: } \tilde{y}_{(k)} = y - \sum_{l \neq k} X_l \beta_l \end{aligned}$$

Using previous results we can show that

$$\begin{aligned} p(\beta_k | ELSE) &\propto N\left(\beta_k \mid C_k^{-1} rhs_k, C_k^{-1}\right) \\ C_k &= \left[X_k' X_k \sigma_\varepsilon^{-2} + I \sigma_{\beta_k}^{-2} \right] \\ rhs_k &= X_k' \tilde{y}_{(k)} \sigma_\varepsilon^{-2} \end{aligned}$$

Fully Conditionals

Error Variances

$$\begin{aligned} p(\sigma_\varepsilon^2 \mid ELSE) &\propto (\sigma_\varepsilon^2)^{-n/2} \text{Exp}\left\{-\frac{\varepsilon'\varepsilon}{2\sigma_\varepsilon^2}\right\} \left[(\sigma_\varepsilon^2)^{-(1+df_\varepsilon/2)} e^{-\frac{S_\varepsilon}{2\sigma_\varepsilon^2}} \right] \\ &\propto (\sigma_\varepsilon^2)^{-[1+(n+df_\varepsilon)/2]} \text{Exp}\left\{-\frac{\varepsilon'\varepsilon + S_\varepsilon}{2\sigma_\varepsilon^2}\right\} \\ &= \chi^{-2} \left(\sigma_\varepsilon^2 \mid S = \varepsilon'\varepsilon + S_\varepsilon, df = n + df_\varepsilon \right) \quad [2] \end{aligned}$$

Gibbs Sampler

Variances of effects

$$p\left(\sigma_{\beta_k}^2 \mid ELSE\right) \propto N\left(\beta_k \mid 0, I\sigma_{\beta_k}^2\right) \chi^{-2}\left(\sigma_{\beta_k}^2 \mid df_{\beta_k}, S_{\beta_k}\right)$$

Using previous results we can show that

$$p\left(\sigma_{\beta_k}^2 \mid ELSE\right) \propto \chi^{-2}\left(\sigma_{\beta_k}^2 \mid df_{\beta_k} + p_k, S_{\beta_k} + \beta_k' \beta_k\right)$$

Gibbs Sampler

Gibbs sampler with scalar updates (sampling one effect at a time)

- Among the computations we need to perform, inverting the the matrix of coefficients (C_k) is the most demanding.

- This inversion needs to be performed at every iteration of the sampler.

- We can avoid doing this by sampling effects one at a time.

- Suppose that the k^{th} group contains only one predictor, then

$p(\beta_k | ELSE) \propto N(\beta_k | C_k^{-1} rhs_k, C_k^{-1})$ the fully conditional is a normal density, not a multivariate normal.

- And $C_k = [X_k' X_k \sigma_\varepsilon^{-2} + I \sigma_{\beta_k}^{-2}]$ $rhs_k = X_k' \tilde{y}_{(k)} \sigma_\varepsilon^{-2}$ are scalar.

- Therefore $C_k^{-1} = 1 / C_k$.

Sample code

```
z<-rnorm(ncol(X))
for(j in 1:ncol(X)){
  xj=X[,j]
  error<-error+xj*beta[j]
  C=sumSqX[j]/varE[i]+1/varB[i,groups[j]]
  rhs<-sum(xj*error)/varE[i]
  sol<-rhs/C
  beta[j]<-sol+z[j]/sqrt(C)
  error<-error-xj*beta[j]
}
```

Dealing with missing values

Types of missing values

- Non-informative (e.g., completely at random)
- Informative (e.g., censoring)

Non-informative missings can be simply removed, e.g.,

```
isNA=is.na(y)

y_no_NA=y[!isNA]
X_no_NA=X[!isNA,]
## now regress y_no_NA on X_no_NA
```

But we can also deal with NAs in different manner: that is by sampling the unobserved values from fully conditionals.

Sampling Non-Informative Missing Values

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